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1		Artificial Intelligence Performance in Testing Microfluidics for Point-of-Care	
2		Mert Tunca Doganay ¹ , Purbali Chakraborty ¹ , Sri Moukthika Bommakanti ¹ , Soujanya	
3	Jammalamadaka ¹ , Dheerendranath Battalapalli ¹ , Anant Madabhushi ^{2,3} , Mohamed S. Draz ^{1,4,5}		
4 5	1.	Department of Medicine, Case Western Reserve University School of Medicine, Cleveland, OH, 44106, USA.	
6	2.	Department of Biomedical Engineering, Emory University, Atlanta, GA, USA.	
7	3.	Atlanta Veterans Administration Medical Center, Atlanta, GA, USA.	
8 9	4.	Department of Biomedical Engineering, Case Western Reserve University, Cleveland, OH, USA.	
10 11	5.	Department of Biomedical Engineering, Cleveland Clinic, Cleveland, OH, 44106, USA.	
12			

- 13
 - 14 Corresponding author: Mohamed S. Draz. Email: <u>mohamed.draz@case.edu</u>

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15 ABSTRACT

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Artificial intelligence (AI) is revolutionizing medicine by automating tasks like image 16 segmentation and pattern recognition. These AI approaches support seamless integration with 17 existing platforms, enhancing diagnostics, treatment, and patient care. While recent advancements 18 have demonstrated AI superiority in advancing microfluidics for point of care (POC) diagnostics, 19 a gap remains in comparative evaluations of AI algorithms in testing microfluidics. We conducted 20 21 a comparative evaluation of AI models specifically for the two-class classification problem of identifying the presence or absence of bubbles in microfluidic channels under various imaging 22 conditions. Using a model microfluidic system with a single channel loaded with 3D transparent 23 24 objects (bubbles), we challenged each of the tested machine learning (ML) (n = 6) and deep learning (DL) (n = 9) models across different background settings. Evaluation revealed that the 25 Random Forest ML model achieved 95.52% sensitivity, 82.57% specificity, and 97% AUC, 26 outperforming other ML algorithms. Among DL models suitable for mobile integration, 27 DenseNet169 demonstrated superior performance, achieving 92.63% sensitivity, 92.22% 28 specificity, and 92% AUC. Remarkably, DenseNet169 integration into a mobile POC system 29 demonstrated exceptional accuracy (> 0.84) in testing microfluidics at under challenging imaging 30 settings. Our study confirms the transformative potential of AI in healthcare, emphasizing its 31 32 capacity to revolutionize precision medicine through accurate and accessible diagnostics. The integration of AI into healthcare systems holds promise for enhancing patient outcomes and 33 streamlining healthcare delivery. 34

35 INTRODUCTION

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The convergence of artificial intelligence (AI) and healthcare has opened up a new era of 36 possibilities, particularly in detection diagnostics and treatment. With AI algorithms continuously 37 advancing, the integration of these approaches into healthcare systems holds immense promise for 38 transforming traditional practices and addressing longstanding challenges in healthcare delivery.¹⁻ 39 ³ Healthcare applications driven by sophisticated machine learning (ML) and deep learning (DL) 40 algorithms stand at the forefront of modern healthcare innovation.⁴⁻⁶ These algorithms empower 41 machines to obtain insights from vast datasets, predict clinical outcomes, and assist healthcare 42 providers in making informed decisions.⁶ From medical imaging analysis to personalized 43 treatment strategies, AI-driven approaches have demonstrated significant efficacy in improving 44 diagnostic precision and ultimately enhancing patient outcomes.⁷⁻¹⁰ 45

POC diagnostics represent a cornerstone of modern healthcare, offering timely and 46 accessible testing solutions, particularly in resource-limited settings.¹¹⁻¹³ The integration of AI into 47 48 microfluidic systems presents a promising avenue for enhancing the accessibility and efficiency of POC testing.^{14, 15} By harnessing advanced ML and DL algorithms, AI enhances the sensitivity, 49 specificity, and multiplexing capabilities of microfluidic devices, enabling rapid and accurate 50 detection of a wide range of diseases and biomarkers directly at the POC.¹⁶⁻¹⁸ An important 51 approach where AI is utilized to enhance microfluidic systems is in image processing. ML and DL 52 53 learning models excel at image classification and pattern recognition tasks and can support microfluidic devices to perform rapid and multiplex assays, allowing for comprehensive screening 54 or testing using minimal resources.¹⁹⁻²¹ This integration addresses critical gaps in healthcare access 55 56 and empowers a new level of POC diagnostics, equipping frontline providers with actionable insights and revolutionizing the delivery of healthcare services. 57

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Recent advancements have demonstrated superior performance in identifying disease 58 biomarkers, detecting cancer,²² viruses,²³ bacteria,²⁴ and other pathogens,²⁵ underscoring the 59 robustness and clinical relevance of AI-integrated microfluidic platforms in modern healthcare 60 settings. However, despite these advancements, there remains a gap in the comparative evaluations 61 of different AI algorithms in testing microfluidics, and the optimal approach for maximizing their 62 performance in this context remains unclear, particularly in the POC diagnostics.²⁶⁻³¹ In POC 63 settings, practical constraints such as cost, power consumption, memory limitations, and 64 computational efficiency are crucial, making the choice of algorithm highly impactful. For 65 instance, logistic regression is relatively simple, with a complexity of $O(n \times m)$, where n is the 66 number of samples and *m* the number of features. It requires moderate computational power and 67 memory, making it a good fit for POC settings that have limited Central Processing Unit (CPU) 68 power and memory.³² Decision trees, with complexity $O(n \times m \times \log(n))$,³³ and random forests, 69 which add an additional factor for the number of trees $(O(k \times n \times m \times \log(n)))^{34}$, where k is the number 70 of trees), require moderate resources. They build tree structures that evaluate multiple features at 71 once. While computationally more demanding than logistic regression, they can still be feasible in 72 many POC setups, especially with fewer trees. Naive Bayes classifiers are computationally 73 efficient due to their independence assumption for features, with complexity $O(n \times m)$. This makes 74 them ideal in resource-limited environments. However, this simplification can sometimes reduce 75 predictive performance if feature independence is not a valid assumption.³⁵ On the other hand, 76 77 Support Vector Machines (SVMs), especially with non-linear kernels, can have significantly higher complexities ($O(n^2)$ to $O(n^3)$), making them less suitable for constrained environments 78 without powerful CPUs or Graphics Processing Units (GPUs). However, using linear kernels or 79 approximation methods (e.g., LinearSVM or Fast SVM) can reduce the computational load, 80

making SVMs a more viable option for POC.³⁶ K-Nearest Neighbors (K-NN), while simple in 81 terms of training complexity $(O(n \times m))$, can become computationally intensive during inference 82 due to distance calculations between all data points. Optimization techniques like KD-trees (K-83 Dimensional trees) or Ball-trees can speed up inference, making K-NN more feasible for real-time 84 POC applications.³⁷ Neural networks and deep learning models (e.g., Convolutional Neural 85 86 Networks (CNNs)) typically have a higher complexity of $O(n \times m \times d)$, where d is the depth of the network. These models require substantial memory and processing power, particularly using 87 GPU/TPU resources (where TPU stands for Tensor Processing Units), which are not commonly 88 89 available in POC devices. However, methods like dropout, batch normalization, weight pruning, and model distillation can help reduce the computational burden, allowing for more lightweight 90 versions of these models to be deployed on smaller devices.³⁸ Foundation models, like large-scale 91 AI models (e.g., Generative Pre-trained Transformers (GPT), Bidirectional Encoder 92 Representations from Transformers (BERT)), present an even bigger challenge due to their high 93 computational demands during both training and inference. These models often require substantial 94 GPU clusters or high-performance computing (HPC) environments, making them impractical for 95 resource-constrained POC settings. In such cases, pre-trained models fine-tuned for specific tasks 96 or more compact versions of these models (e.g., TinyBERT, DistilBERT) might be used instead.³⁹ 97 This trade-off between computational demands and resource availability emphasizes the 98 importance of balancing model performance with resource constraints in POC settings. 99

We employed a model microfluidic system, featuring a single microfluidic channel loaded with 3D transparent objects of bubbles. This model is designed to rigorously challenge the performance of commonly used AI models and provide insights into their effectiveness in realworld diagnostic scenarios. We integrated various ML and DL algorithms into our study, including

CNNs like MobileNetV2, ResNet101V2, and DenseNet169, alongside commonly used ML 104 models in healthcare applications such as Naive Bayes, logistic regression, KNN, SVM, and 105 Random Forest.⁴⁰⁻⁴⁴ Among the six evaluated ML algorithms, the Random Forest model performed 106 best, achieving 95.52% sensitivity, 82.57% specificity, and 97% AUC. Similarly, among the nine 107 DL models, DenseNet169 stood out, achieving 92.63% sensitivity, 92.22% specificity, and 92% 108 109 AUC. Such a comparative study is critical in gaining a comprehensive understanding of the strengths and weaknesses of different algorithms, informing algorithm selection, optimization, and 110 deployment decisions across diverse domains and applications.⁴⁵⁻⁴⁸ 111

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114 RESULTS AND DISCUSSION

The integration of AI in medicine is driven by its remarkable ability to analyze and classify 115 images and datasets. This computational capability of AI algorithms is foundational across diverse 116 domains, prominently within diagnostics and medical testing, where AI-driven image analysis 117 stands as a transformative force, providing rapid data processing and precise assessment devoid of 118 infrastructure constraints or specialized human oversight.^{3, 49, 50} This technological paradigm bears 119 profound implications, particularly on POC diagnostics, through its role in facilitating the 120 integration of microfluidics into POC applications.⁵¹ By harnessing sophisticated ML and DL 121 algorithms, AI streamlines the imaging and analysis of microfluidic devices, such as smartphone-122 captured assays, reducing the total testing cost and time, enhancing accuracy, and expanding 123 utility.^{19, 52, 53} This convergence of AI and microfluidics within POC holds immense potential to 124

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democratize healthcare access, particularly in underserved regions, by providing affordable,

accurate, and accessible diagnostic solutions.^{14, 19, 54, 55}

127 In our study, we investigated the efficacy of AI algorithms, including both ML and DL, to facilitate the process of testing microfluidics within POC settings. We employed a microfluidic 128 system comprising a single microfluidic channel to rigorously assess a set of 15 AI models 129 130 recognized for data analysis and image classification across biomedical and diagnostic domains. Our experimental setup incorporated testing configurations featuring varying densities of bubbles. 131 Bubbles as a readout was selected to probe the imaging and analytical performance of the 132 examined algorithms. Despite bubbles being less prevalent than conventional color-based or 133 fluorescence-based readouts, their inherent 3D transparency poses challenges, as they may be 134 mistaken for non-targeted constituents within the sample matrix, microfluidic system or the testing 135 environment and background. In addition, transparent bubbles can introduce challenges such as 136 refraction and variable light scattering, which may impact imaging accuracy and algorithm 137 138 performance. By using these bubbles, we aimed to simulate complex real-world imaging conditions and evaluate how well the AI models could handle such complexities. Colorimetric 139 readouts, though linear and would allow comparatively easier workflow, fail to sufficiently 140 141 encapsulate the intricacies necessary for discerning strengths and weaknesses of the tested algorithms. Meanwhile, fluorescence, although know to support high specificity and sensitivity 142 testing, remains impractical for widespread POC adoption due to the need for bulky equipment 143 and specialized setup to achieve the required sensitivity and specificity in most analyses. 144

Our set of AI algorithms included ML models, such as Naive Bayes, logistic regression, kNearest Neighbors (KNN), Support Vector Machines (SVM), and Random Forest, alongside DL
CNNs such as MobileNetV2, ResNet101V2, and DenseNet169. By combining traditional ML

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algorithms with state-of-the-art CNN architectures, we created a diverse ensemble of models that 148 can collectively leverage different aspects of the data. This ensemble approach is essential to 149 enhance robustness and generalization performance, particularly in scenarios where the dataset 150 may be limited or the target features are challenging to discern (i.e., bubbles). The incorporation 151 of traditional ML algorithms stemmed from their robustness in handling various types of features, 152 153 including those extracted from images, and their suitability for the often constrained datasets characteristic of microfluidic diagnostics at POC settings. The CNN architectures like 154 MobileNetV2, ResNet101V2, and DenseNet169 have unparalleled ability to capture intricate 155 156 spatial relationships within images, which is crucial for discerning subtle patterns like challenging signals such as bubbles. This aligns with the evolving field of diagnostics, which is moving 157 towards inventing and incorporating more versatile readouts like bubbles to allow for more 158 sensitive and unique detection capabilities, distinct from common ones like color and fluorescence. 159 These CNN architectures offer distinct trade-offs in terms of model size, computational efficiency, 160 and classification accuracy, offering flexibility in addressing the specific nuances of the dataset. 161

To investigate the capabilities of the selected set of ML and DL algorithms in testing 162 microfluidics, we captured 19,097 images of our microfluidic model with bubbles in various 163 164 settings, including different environments, lighting conditions, times of the day, and backgrounds (Figure 1). We labeled the captured images either positive or negative, based on the number of 165 bubbles, around a threshold value of 10 bubbles per microchip, to train our ML and DL models 166 (Figure 1a). Out of the 19,097 labelled images (Figure 1b), 15,530 images were utilized for 167 training using Python running on Lambda Vector GPU Workstation (Intel i9-10900x CPU, 168 NVIDIA RTX A6000 GPU) system. 169

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To test the performance of ML models, we used 1595 randomly selected images. excluding 170 those used for training, to evaluate their classification accuracy. We employed standard 171 performance metrics, including accuracy, precision, recall (i.e., sensitivity), specificity, F1 score, 172 and Matthews's correlation coefficient (MCC) (Supplementary Table 1), obtained from each 173 model to determine their effectiveness.⁵⁶ We conducted all statistical analyses and data 174 visualizations using TensorFlow and TensorBoard tools with necessary Python libraries as 175 matplotlib, NumPy, Keras, Sklearn, pandas, torch.^{57, 58} The comparison primarily centered around 176 specificity and sensitivity values, which are metrics influencing overall performance and gives 177 178 information about other metrics.

Our analysis of the ML models revealed that logistic regression and Random Forest models 179 exhibited exceptional sensitivity (>90%), while K-nearest neighbors and Random Forest models 180 demonstrated high specificity (>80%) (Figure 2a). The results showed that the highest sensitivity 181 value was obtained from the Random Forests (95.52%) and the highest specificity value was 182 obtained from K-nearest neighbors (89.68%) ML models. we assessed the confusion matrix to 183 better understand the positive and negative predictions. Out of 1595 images, 1447 were classified 184 correctly, with 45 false negatives and 103 false positives. The model primarily made errors in the 185 186 classification of negative samples. (Figure 2b and Supplementary Figure 1). The ROC analysis of the trained models indicated that the Random Forest (AUC: 97%) (Figure 2c) and K-nearest 187 neighbors (AUC: 90%) have highest area under the ROC, which represents the diagnostic ability 188 of the model (Supplementary Figure 2). Additionally, the Random Forest model outperformed 189 others in terms of F1 score (92.8%) and accuracy (90.72%). This shows that the Random Forest 190 provides most balanced results between precision and sensitivity with highest accuracy. 191 Consequently, the most effective model was observed as Random Forest with notable metrics as 192

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95.52% sensitivity, 82.57% specificity, 90.72% accuracy, 90.3% precision, 92.8% F1 score,
79.95% MCC, and 97% AUC (Supplementary Table 1).

195 To test the performance of DL models, we continued by evaluating the performance of the 196 selected CNNs architectures using the same dataset of 1595 images. The performance evaluation step was conducted using developed Python algorithms with the help of Pandas, NumPy, Sklearn, 197 198 Matplotlib, Keras and Tensorflow libraries.⁵⁷ The deep learning models utilized for this evaluation included MobileNetV2, EfficientNetV2B0, EfficientNetV2B2, DenseNet169, DenseNet201, 199 InceptionV3, ResNet50V2, EfficientNetB5, and ResNet101V2. In selecting these deep learning 200 models, we prioritized those that does not require significant computing power and thus ensure 201 compatibility for evaluation and testing microfluidics at POC. We also ensured that the chosen 202 models were commonly employed for computer vision tasks, prioritizing ease of integration and 203 robust performance on POC compatible mobile devices.¹⁹ 204

Our results indicated that DenseNet169, EfficientNetB5, and EfficientNetV2B0 exhibited 205 outstanding sensitivity values of 92.63%, 95.82%, and 91.93%, respectively (Figure 3a and 206 Supplementary Figure 3-5). ResNet50V2 (89.17%) and InceptionV3 (88.49%) demonstrated 207 high specificity values, while DenseNet169 displayed an exceptional specificity of 92.22% 208 (Supplementary Table 2). The confusion matrix revealed further insights into the performance 209 of these algorithms. DenseNet169 algorithm excelled in detecting negative samples, accurately 210 classifying 545 out of 591, while also achieving the second-highest performance in positive 211 classification with 930 out of 1004, resulting in the highest overall performance at 92% (Figure 212 3b). Other algorithms including EfficientNetB5 correctly identified 962 out of the tested 1004 213 214 positive samples. However, it misclassified 293 negative samples as positive, resulting in a 50.4% performance rate for negative samples and an overall performance rate of 79%. EfficientNetV2B0 215

exhibited similar performance, albeit with a 7% overall performance rate downgrade, reflecting a 216 4% difference in true positive performance rate and an 11% decrease in true negative performance 217 rate. The results of MobileNetV2, EfficientNetV2B2, DenseNet201, InceptionV3, ResNet50V2, 218 and ResNet101V2 algorithms are shown in Supplementary Figure 4, 5 with misclassification rates 219 < 38%. The ROC analysis of the trained DL models, ResNet50V2 (AUC: 96%), ResNet101V2 220 221 (AUC: 96%), InceptionV3 (AUC: 95%) and DenseNet169 (AUC: 92%) and DenseNet201 (AUC: 90%) had the highest area under the ROC (Supplementary Figure 6, 7). Additionally, the 222 DenseNet169 model outperformed other models in terms of F1 score (93.94%) and accuracy 223 224 (92.48%) (Supplementary Table 2). Overall, DenseNet169 outperformed other models with the performance metrics and gives the applicable model with 0.92 AUC (Figure 3c). 225

We compared the performance of Random Forest and DenseNet169, as these models had 226 outperformed others in our evaluations. To challenge them further, we used a set of 184 microchips 227 prepared with varying numbers of bubbles. A new test set of images was created under different 228 environmental conditions than those used during training. This test set included images taken 229 against different backgrounds (including black, red, brown, metallic grey, and dark blue), rotation, 230 and brightness. This approach allowed us to assess user experience in suboptimal conditions, 231 232 ensuring a thorough and comprehensive evaluation of the models' performance in real-world microchip testing scenarios. The generated positive and negative prediction rates were analyzed 233 against the ground truth values of bubbles per chip to evaluate the performance of each model. The 234 results revealed that the DenseNet169 DL model achieves prediction rates with better performance 235 compared to the Random Forest ML model with 80.4% and 88.2% accuracy; 77.98% and 91.81% 236 precision: 81.51% and 87.84% F1 score; 75.3% and 92.31% specificity; and 61.03% and 76.69% 237 MCC for Random Forest and DenseNet169, respectively. The confusion matrix and ROC analyses, 238

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on the other hand, confirmed that the DenseNet169 DL algorithm is the optimal prediction model
for testing our microfluidic model, outperforming the Random Forest ML algorithm by 87% in
AUC and 92% in accuracy classifying true positive and true negative (Figure 4b, c).

To demonstrate the effectiveness of incorporating AI in real-world sample testing scenarios 242 using POC-compatible systems, a mobile application capable of running the DenseNet169 model 243 244 seamlessly was developed, without the need for further optimization. The application features a simple interface for initiating model evaluation and presents results in terms of positive and 245 negative prediction rates, along with images of the tested microfluidic chips (Supplementary 246 Figure 8). Out of 250 images, 212 were classified correctly, 29 were classified as false negatives, 247 and 9 were classified as false positives. The model primarily made errors in classifying positive 248 samples. The performance metrics were as follows: Accuracy: 84.8%, Precision: 93.23%, 249 Sensitivity/Recall: 81.05%, F1 Score: 86.71%, Specificity: 90.72%, and MCC: 70.09. The deep 250 learning model achieved an AUC value of 0.90, highlighting its superiority in testing our 251 microfluidic model with bubbles (Figure 5b). Furthermore, upon examining the confusion matrix 252 alongside sensitivity and specificity values. Results showed that the DenseNet169 deep learning 253 254 model achieved 81.05% sensitivity and 90.72% specificity (Figure 5a). Heatmap analysis was 255 conducted using images with bubble counts ranging from 0 to 100. The results indicated a higher margin of error around the threshold of 10 bubbles, particularly chips with around 20 to 30 bubbles 256 are ~ 30 % misclassified as negative. 257

Our study provides a comprehensive evaluation of both ML and deep learning DL algorithms in the context of microfluidics testing under POC settings. Among the ML models, Random Forest emerged as the top performer with a sensitivity of 95.52%, specificity of 82.57%, and an AUC of 97%, showcasing its strong capability in accurately classifying microfluidic device Page 13 of 28

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images. The high sensitivity and specificity values underscore Random Forest's effectiveness in 262 distinguishing positive from negative samples even in challenging imaging conditions. However, 263 the higher rate of false positives indicates a potential area for improvement. In contrast, DL models, 264 particularly DenseNet169, exhibited outstanding performance with sensitivity and specificity 265 values of 92.63% and 92.22%, respectively. DenseNet169's consistent high performance across 266 267 different testing conditions, including variations in background and lighting, highlights its robustness and adaptability, making it highly suitable for real-world POC diagnostics where 268 consistent and reliable performance is crucial. 269

Despite the promising results, several challenges must be addressed to facilitate the 270 widespread adoption of AI in microfluidic POC diagnostics. One key issue is the misclassification 271 of samples with a marginal number of bubbles, especially around the threshold of 10 bubbles, 272 which was evident in the heatmap analysis. Further refinement of the AI models and incorporating 273 additional features or training data will be necessary to enhance accuracy in borderline cases. 274 275 Combining multiple algorithms can also help overcome these challenges. For example, employing ensemble techniques that integrate models like U-Net for image segmentation and Canny edge 276 277 detection for edge detection could improve precision in detecting subtle features. Additionally, 278 integrating algorithms such as YOLO (You Only Look Once) for real-time object detection and HOG (Histogram of Oriented Gradients) for robust feature extraction can further enhance the 279 accuracy and reliability of microfluidic POC diagnostics. Such hybrid approaches can leverage the 280 strengths of different algorithms, providing a more comprehensive and accurate analysis. 281

Moreover, integrating AI models into mobile applications for POC testing will necessitate ensuring seamless operation across a wide range of devices and environmental conditions, with a strong emphasis on user-friendliness and reliability. This integration is pivotal for achieving the a Chip Accepted Manuscript

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robustness required for practical deployment in diverse healthcare settings. The successful 285 implementation of AI in microfluidic POC diagnostics has far-reaching implications for the 286 healthcare industry, especially in resource-limited settings where access to sophisticated medical 287 infrastructure is often constrained. By enabling rapid, accurate, and on-site testing, AI-driven POC 288 systems address one of the most pressing challenges in modern medicine: the need for timely and 289 290 precise diagnostics. By democratizing access to high-quality diagnostic tools, AI-integrated POC systems empower frontline healthcare providers with actionable insights, fostering a more 291 equitable distribution of medical resources. This shift supports personalized medicine approaches, 292 293 tailoring treatment plans to individual patient profiles based on accurate and immediate diagnostic data. Ultimately, the widespread adoption of AI-enhanced microfluidic POC diagnostics can 294 transform healthcare delivery, making it more accessible, efficient, and responsive to the needs of 295 diverse populations worldwide. 296

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298 Conclusion

The transformative impact of AI on healthcare is rapidly increasing, particularly in 299 advancing precision medicine through accurate and accessible diagnostics. By conducting a 300 comprehensive comparative evaluation of AI models in testing microfluidics, we have 301 demonstrated the superiority of AI-driven approaches over traditional methods, particularly in the 302 context of POC diagnostics. Through the integration of ML and DL algorithms, we created a 303 diverse ensemble of models capable of leveraging various aspects of the data, thereby enhancing 304 305 robustness and generalization performance. Our results revealed that the Random Forest ML model and the DenseNet169 DL model exhibited exceptional performance, surpassing other 306

algorithms in terms of sensitivity, specificity, and AUC values. DenseNet169 integration into a 307 mobile POC system demonstrated exceptional accuracy, outperforming traditional visual 308 interpretation by a significant margin. This confirms the potential of AI to revolutionize 309 diagnostics, offering more accurate and efficient testing solutions in resource-limited settings. 310 Moreover, our findings highlight the significant role that AI can play into healthcare systems, as 311 312 it holds promise for enhancing patient outcomes, streamlining healthcare delivery, and ultimately, democratizing access to high-quality diagnostic services. Moving forward, further research and 313 development efforts are warranted to optimize AI algorithms for real-world deployment, ensuring 314 their seamless integration into clinical practice and maximizing their impact on global health 315 316 outcomes.

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318 Data availability

The data supporting this article have been included as part of the ESI.

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321 Conflicts of interest

322 There are no conflicts to declare.

323

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327 MATERIAL AND METHODS

328 Microfluidic chip model design and fabrication.

We developed a microfluid chip system that features a single microfluidic channel. The 329 microchip was designed using the vector graphics editor CorelDRAW Graphics suite software, 330 and fabricated of polymethyl methacrylate (PMMA) (3.125 mm thick), DSA film (100 um thick, 331 3M, USA), and glass slides (25 mm x 75 mm). The fabrication process starts by cutting PMMA 332 and DSA film using a laser cutter (Boss Laser LS-1416, USA). The PMMA was prepared to 333 contain the microfluidic channel inlet and outlet, while DSA film included the main testing 334 channel. All materials were precleaned with 70% ethanol, and deionized water using lint-free 335 tissue. The surface of the cleaned glass slides was treated and cleaned using oxygen plasma (PE-336 337 25, 100 mW, 15% oxygen; Plasma Etch Inc.) for 10 minutes. Then PMMA and DSA film were assembled on the modified glass slide, forming the model microfluidic chip system. Each system 338 was loaded with platinum nanoparticle-seeded bubbles. PtNPs synthesized using our previously 339 published protocol were mixed with a peroxide-containing solution (5% hydrogen peroxide and 340 20% glycerol) and loaded on chip system. The concentration of added PtNPs was controlled to 341 prepare systems with variable numbers of bubbles $(0 - \ge 200)$ bubbles per chip), randomly 342 distributed within the microfluidic channel. 343

344 AI models selection, training and performance testing

We selected a set of 15 models that encompass a number of machine learning and deep learning models, widely reported to have high performance in image classification and pattern recognition. The machine learning models included Naive Bayes, Logistic Regression, Decision Tree, K-Nearest Neighbors, Support Vector Machine and Random Forest, while the deep learning ab on a Chip Accepted Manuscript

models of MobileNetV2, EfficientNetV2B0, EfficientNetV2B2, DenseNet169, DenseNet201, 349 InceptionV3, ResNet50V2, EfficientNetB5 and ResNet101V2, were selected to support workflow 350 running on mobile devices and systems. We generated a dataset of 19,097 images of the model 351 microfluidic system captured using Moto XT1575, iPhone X and Vivo smartphones. The dataset 352 comprises two groups, i.e., positive (with > 10 bubbles per microchip) and negative (in range of <353 354 10 bubbles per microchip) sample images. The microfluidic system imaging was performed at different angles $(0 - 360^{\circ})$ and backgrounds and environments to maximize the variations, and 355 make our dataset more robust and comprehensive. We used 15530 images for training, 1788 356 357 images for validation and 1012 images for testing the performance of the selected ML and DL models in testing the model microfluidic system and classifying samples into positive and negative 358 based on bubble signal. We started the process by importing pre-trained models available from 359 Scikit-learn and Keras libraries to develop the selected ML and DL models, respectively. In the 360 pre-processing step, the images of our training dataset were resized to the input dimensions of the 361 selected models, leveraging the features learned by ImageNet pretrained network. We performed 362 the batch normalization then used Adam optimizer to fine-tune the network using a global learning 363 rate of 0.001. In addition, we employed a varied number of epochs to test the algorithms optimal 364 365 performance and we set the number to 50 epochs. Then we performed the transfer learning by removing the final classification layer from the chosen networks and trained with our dataset. All 366 the algorithms were trained on Vector Workstation (Intel i9-10900x CPU and NVIDIA RTX 367 368 A6000 GPU, Lambda) and after training, we tested the performance of the best-performing ML and DL algorithms individually using a challenging dataset of 400 images. This testing dataset 369 370 included rotated images, images with various colored backgrounds (matte, bright, reflective), and 371 images with lens distortion and brightness variations. The ML algorithms were evaluated using

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the sklearn and torch libraries, while the DL algorithm was evaluated using the TensorFlow library.
Performance metrics such as accuracy, precision, sensitivity, and F1-score were employed to
quantitatively measure classification accuracy and the ability of each model to correctly identify
the tested microchip.

376 AI testing on a POC compatible system.

We utilized the open-source platform Android Studio (version Giraffe 2022.3.1) to develop 377 an AI-enabled mobile application. Android Studio offers an integrated development environment 378 379 (IDE) tailored for Android application development. The application facilitates the capture of sensor images through the smartphone's built-in camera or from images stored in the device's 380 memory. A trained DL model, DenseNet169, was converted to TensorFlow Lite and integrated 381 382 into the application, which was developed for Android 6.0 (API level 23). This application was installed on a Moto XT1575 and used as a proof-of-concept system for testing microfluidics with 383 images simulating real-world conditions. We evaluated the performance of the AI model using a 384 testing set of 250 images, each featuring 0-100 bubbles per chip. This testing set included images 385 with challenging backgrounds and imaging conditions, such as noise, blur, hand interaction, 386 daylight, artificial light, natural and artificial occlusion, resolution variability, and the presence of 387 small bubbles. The classification results, displayed on the user interface, indicate the probability 388 of a sample being positive (>50%) or negative (<50%). The correlation between AI-generated 389 classification results and the number of bubbles per chip was analyzed, and prediction accuracy 390 rates were employed to generate performance metrics. 391

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396 Figure 1. AI algorithms integration and the tested microfluidic model system. (a) Microfluidics testing using an integrated POC compatible system running AI algorithm on a 397 398 cellphone. The system supports a broad range of AI algorithms including both machine learning (ML) and deep learning (DL) models. (b) The developed microfluidic model with a single 399 microfluidic channel (length 42 mm, width 5 mm and height 100 µm) containing platinum 400 nanoparticle-seeded bubbles of variable shapes and sizes. (c) Snapshot of the image library of the 401 tested microfluidic model collected using cellphone POC system (161 randomly selected images 402 403 out of 19,097), illustrating the diversity of color, background and brightness.

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Figure 2. Performance evaluation of machine learning in testing microfluidics. (a) Barplots 407 showing the performance (sensitivity and specificity) of the tested ML algorithms (n = 6). All 408 algorithms were trained on our dataset of 15,530 images to classify the model microfluidic chip 409 410 system with bubble signal into positive or negative around the threshold value of 10 bubbles. (b) Confusion matrix showing the number of true negative, false positive, false negative and true 411 positive results when comparing the interpretation of Random Forest ML algorithm to the ground 412 truth classification results. (c) ROC analysis of Random Forest performance in testing the model 413 414 microfluidic chip with bubble signal.

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Figure 3. Performance evaluation of deep learning in testing microfluidics. (a) Barplots showing the performance (sensitivity and specificity) of the tested DL algorithms (n = 5). All algorithms were trained on our dataset of 15,530 images to classify the model microfluidic chip system with bubble signal into positive or negative around the threshold value of 10 bubbles. (b) Confusion matrix showing the number of true negative, false positive, false negative and true positive results when comparing the interpretation of DenseNet169 DL algorithm to the ground truth classification results. (c) ROC analysis of DenseNet169 performance in testing the model microfluidic chip system with bubble signal.

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Figure 4. Performance evaluation of machine learning compared to deep learning in testing 430 microfluidics under POC settings. (a) Performance matrices (accuracy, precision, sensitivity, F1 431 432 score, specificity, and MCC) of the Random Forest ML and the DenseNet169 DL in testing the model microfluidic chip system under challenging imaging conditions that simulate POC testing 433 settings (i.e., different backgrounds, brightness, resolution, cameras, and rotations). (b) Confusion 434 matrices showing the number of true negative, false positive, false negative and true positive 435 results when comparing the interpretation of the Random Forest ML and the DenseNet169 DL 436 algorithms to the ground truth classification results. (c) ROC analysis of the Random Forest ML 437 and the DenseNet169 DL algorithms performance in testing the model microfluidic chip system 438 with bubble signal. 439

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Figure 5. Performance evaluation of AI in testing microfluidics under POC settings using a compatible cellphone system. (a) The confusion matrix showing the number of true negative, false positive, false negative and true positive results when comparing AI (i.e., the DenseNet169 DL algorithm) interpretation to the ground truth classification results based on the number of bubbles per microchip. (b) ROC analysis of AI performance in testing the model microfluidic chip system with bubble signal. (c) Heatmap plot of the probability values of the model microfluidic testing interpretation by AI performance based on the number of bubbles per microchip.

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Artificial Intelligence Performance in Testing Microfluidics for Point-of-Care

Mert Tunca Doganay¹, Purbali Chakraborty¹, Sri Moukthika¹, Soujanya Jammalamadaka¹,

Dheerendranath Battalapalli¹, Anant Madabhushi^{2,3}, Mohamed S. Draz^{1,4,5*}

- 1. Department of Medicine, Case Western Reserve University School of Medicine, Cleveland, OH, 44106, USA.
- 2. Department of Biomedical Engineering, Emory University, Atlanta, GA, USA.
- 3. Atlanta Veterans Administration Medical Center, Atlanta, GA, USA.
- 4. Department of Biomedical Engineering, Case Western Reserve University, Cleveland, OH, USA.
- 5. Department of Biomedical Engineering, Cleveland Clinic, Cleveland, OH, 44106, USA.

Corresponding author: Mohamed S. Draz. Email: mohamed.draz@case.edu

Data Availability

The authors confirm that all data supporting the findings of this study are included within the article and its supplementary information (ESI).