Volume 1 | Number 1 | Jan 2013 | Pages 1–100

Analyst

www.rsc.org/analyst

ROYAL SOCIETY OF CHEMISTRY

ROYAL SOCIETY OF CHEMISTRY

www.rsc.org/analyst

Graphical Abstract

Magnetic Optical Sensor Particles: A Flexible Analytical Tool for Microfluidics

Birgit Ungerböck,[a] Siegfried Fellinger,[a] Philipp Sulzer,[a] Tobias Abel[a] and Torsten Mayr*

[a] Applied Sensors, Institute of Analytical Chemistry and Food Chemistry, Graz University of Technology, Stremayrgasse 9/3, 8010 Graz, Austria. Fax: +43 (0) 316 873 32502; Tel: +43 (0) 316 873 32504; E-mail: torsten.mayr@tugraz.at

Magnetic optical sensor particles are used to generate *in-situ* sensor spots within microfluidic channels and serve as flexible analytical tools.

ARTICLE TYPE
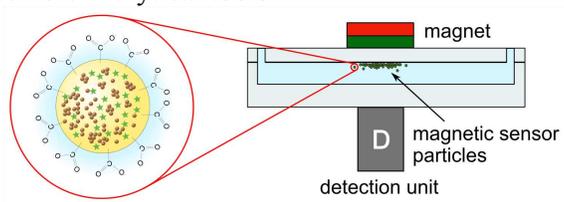
Magnetic Optical Sensor Particles: A Flexible Analytical Tool for Microfluidics

Birgit Ungerböck,[a] **Siegfried Fellinger,**[a] **Philipp Sulzer,**[a] **Tobias Abel**[a] **and Torsten Mayr***[a]

In this study we evaluate magnetic optical sensor particles (MOSePs) with incorporated sensing functionality regarding their applicability in microfluidic devices. MOSePs can be separated from the surrounding solution to form *in-situ* sensor spots within microfluidic channels, while read-out is accomplished outside the chip. These magnetic sensor spots exhibit benefits of sensor layers (high 10 brightness, convenient usage) combined with the advantages of dispersed sensor particles (ease of integration). The accumulation characteristics of MOSePs with different diameters were investigated as well as the *in-situ* sensor spot stability under varying flow rates. Magnetic sensor spots were stable under flow rates specific to microfluidic applications. Furthermore, MOSePs were optimized regarding fiber optic and imaging read-out systems, and different referencing schemes were critically discussed on the 15 example of oxygen sensors. While the fiber optic sensing system delivered precise and accurate results for measurement in microfluidic channels, limitations due to analyte consumption were found for microscopic oxygen imaging. A compensation strategy is provided, which utilizes simple pre-conditioning by exposure to light. Finally, new application possibilities were addressed, being enabled by the use of MOSePs. They can be used for microscopic oxygen imaging in any chip with optically 20 transparent covers, can serve as flexible sensor spots to monitor enzymatic activity or can be applied to form fixed sensor spots inside microfluidic structures, which would be inaccessible to integration of sensor layers.

Introduction

The integration of luminescent chemical sensors into 25 microfluidics is deemed considerably promising due to their features, which are advantageous for their application in microfluidic environments: they are easy to miniaturize, can be highly sensitive, generally do not consume the analyte under investigation and are relatively low-cost devices compared to 30 other sensing technologies.

A variety of microfluidic devices with integrated luminescent chemical sensors have already been developed. Commonly, the "off-chip-approach" is used, where microscale sensing materials are combined with macro-scale off-chip detection systems[1]. The 35 sensing material usually consists of a luminescent indicator dye immobilized in a polymer or sol-gel matrix, allowing adjustment of sensor performance and minimization of interferences with other components of the investigated sample. Due to the flexibility of the matrices, these sensing materials have been 40 integrated into microfluidic environments in different formats such as sensor layers[2–8] or sensor beads[9–11], each of these formats exhibiting advantages as well as disadvantages. Microfluidic chips with integrated sensor layers are user friendly and probably the most convenient way to measure an analyte concentration. 45 However, their integration is an additional step for the

microfluidic chip processing. Sensor particles exhibit the advantage of simply adding them to the fluid in the microfluidic channels and therefore their use is a possibility to avoid additional effort of chip development. However, they suffer from 50 disadvantages like low light intensities at low channel depths.

Magnetic optical sensor particles, which have been published by Mistlberger et al.[12], represent a promising strategy to combine the advantages of sensor layers and sensor beads while reducing the disadvantages of each sensor format: on the one hand they 55 can be simply added to the fluid in the microfluidic channels. On the other hand they can be collected inside a microfluidic channel from outside by a magnet, which allows the *in-situ* generation of sensor spots with brightness independent of microfluidic channel depths. They can be combined with oxygen sensing, biosensing 60 and pH sensing functionalities or be used as magnetic photodynamic therapy agents or stimuli-responsive magnetic optical sensors.

The applicability of magnetic chemical sensor particles to microfluidic devices has not been studied yet, although magnetic 65 forces are utilized in various microfluidic applications[13] and several reviews have summarized technical approaches of particle trapping[14,15] or the application of magnetic particles with biological sensing or catalyzing functionalities[16] in microfluidics. One important feature for magnetic particle manipulation is the 70 size of the applied particles: on the one hand, they should be as

small as necessary to prevent blocking of microfluidic components and interference with microfluidic flow characteristics. On the other hand, adequate accumulation properties, which strongly depend on the particle size, are absolutely essential for generation and stability of *in-situ* sensor spots.

A further important evaluation criterion for the application of MOSePs is the reliability of the measurement method. This study investigates this aspect using the example of oxygen sensors. Although a variety of read-out methods for luminescent oxygen sensors exists, read-out of magnetic sensor particles has to be chosen carefully due to highly varying luminescence intensities between different magnetic sensor spots or even within one generated sensor spot. The measurement of luminescence lifetime τ is the most accurate method to reference for these variations of luminescence intensity. Thus fiber optic read-out is usually performed using lifetime based methods. Imaging applications, however, have been realized applying different measurement methods, mainly for cost reasons. Meier et al. compared different imaging methods including intensity imaging, referenced intensity imaging, luminescence lifetime imaging and ratiometric RGB imaging[17]. They stated that lifetime imaging is the most accurate and precise method, while ratiometric imaging using the color channels of a RGB camera represents a less expensive read-out possibility, which is still adequate for certain sensor applications.

The aim of this study is to evaluate the applicability of MOSePs[12] to microfluidic devices. Important features like accumulation characteristics and measuring reliability are investigated. Read-out possibilities of MOSePs are discussed critically by the example of oxygen sensors. Furthermore, new application possibilities of luminescent sensors - enabled through the use of MOSePs – are addressed. Interesting applications of magnetic sensor particles include microscopic imaging in any chip with optically transparent covers, parallel monitoring of multiple analytes, flexible sensor spots or their application to form fixed sensor spots inside microfluidic structures, which would be inaccessible to integration of sensor layers.

Materials and Methods

Materials

PSMA93 (7% maleic anhydride; $M_w = 224\,000$ g·mol^{-1}) and glucose oxidase from Aspergillus niger (211 U·mg^{-1}) were obtained from Sigma Aldrich (www.sigmaaldrich.com); L-MNP (polymer-coated magnetite nanoparticles ''EMG1300'' from MNP-kit) were purchased from FerroTec GmbH (www.ferrotec-europe.de). THF and glucose were obtained from Carl Roth GmbH (www.carl-roth.de); Platinum(II)-5,10,15,20-tetrakis-(2,3,4,5,6-pentafluorphenyl)-porphyrin (PtTFPP), Macrolex Fluorescent Yellow (MFY) and Lumogen Red F300 (LR) were bought from Frontier Scientific (www.frontiersci.com), Simon and Werner GmbH (www.simon-und-werner.de) and Kremer Pigmente (kremer-pigmente.de), respectively; The oxygen-sensitive dyes PtTpTBPF[18] and Ir(Cs)$_2$(acac)[19] were synthesized in our laboratory.

For investigation of formation and stability of *in-situ* generated sensor spots, microfluidic chips were custom ordered from ix-factory (ix-factory.de), each exhibiting one powder blasted microfludic channel of 15 mm length and different depths and widths. Thin bottom flowcells from Micronit Microfluidics (www.micronit.com) were used for singlet oxygen experiments. Straight channel chips made from PMMA (product code: 01-0174-0138-01) were recieved from Microfluidic Chip Shop (www.microfluidic-chipshop.com).

NdFeB disc/cylinder and block magnets (material grade N38) were purchased from Chen-Yang Technologies (www.chenyang.de).

Sensing setup and data evaluation

Sensor signals of fiber optic measurements were read out using a Firesting oxygen meter (Firesting, http://www.pyro-science.com).

Microscopic oxygen imaging was performed on a Zeiss Axiovert 25 CFL (microscopy.zeiss.com). A blue ultrabright LED with emission maximum at $\lambda = 450$ nm (Luxeon lambert emitter, blue, 5 W) was applied as excitation light source and combined with a filter set-up consisting of Linos DT blue, Linos DC blue and Schott OG 515 (www.qioptiq.de; www.schott.com) as the excitation filter, dichromatic mirror and barrier filter, respectively. Image read-out was performed using a PCO SensiCam (www.pco.de) for rapid lifetime determination (RLD) as described by Moser et al.[20] or using an AVT Marlin F-201C color camera (www.alliedvisiontec.com) for ratiometric imaging as already published elsewhere4.

Fitting was performed using OriginLab 8.6 (www.originlab.com). Original images were processed to oxygen images by Matlab R2008a (www.mathworks.com) using the respective calibration data.

Preparation of MOSePs

Synthesis of MOSePs was performed via an optimized nano precipitation method described by Mistlberger et al.[12]. In a typical synthesis PSMA93 (53.4 mg), L-MNP (10.7 mg) and dye (0.267 mg) were dissolved or dispersed in THF (5.0 mL). This ''cocktail'' was then added slowly (approximately 1 mL·s^{-1}) to deionized water (10 mL) under vortexing (1200 min^{-1}). Under a stream of air, THF was evaporated from the mixture over a period of 25 min. Aggregates were removed by filtration through a syringe filter (Rotilabo, 0.8 mm). Different particle sizes were obtained by varying the polymer concentration from 0.2 – 1.2% (w/w) polymer/THF.

Generally particle suspensions were diluted 1:10 for application in microfluidics. Particle sizes were measured with a particle size analyzer Zetasizer Nano ZS.

Sensor characterization

Full calibration of the MOSePs was performed outside the chip by flushing the particle suspension with gaseous air-nitrogen mixtures. For each measurement, they were recalibrated by determining τ_0 and τ_{air} under deoxygenated and fully air-saturated conditions inside the microfluidic chip. As the calibration function shows slightly nonlinear behavior, the full calibration was then adapted to τ_0 / τ_{air} obtained from the recalibration.

Microfluidic measurements

For operation under flow the chips were connected to a programmable syringe pump (TSE systems GmbH, www.tse-

systems.com).

To study separation of different particle sizes from nano sensor dispersions, a custom ordered microfluidic chip from ix-factory (width: 4000 μm, depth: 300 μm) was filled with aqueous [5] dispersions containing MOSePs with different particle diameters. Light intensities were observed during separation of the particles by a cylindrical magnet from outside the channel.

Separate luminescent spots were generated by using luminescent magnetic nano particles stained with Lumogen Red [10] (3% (w/w) dye/polymer) and Macrolex Yellow (3% (w/w) dye/polymer). A microfluidic channel was filled with the first particle suspension, stained with Lumogen Red (LR), and particles were collected from outside by a magnet, which was placed next to the inlet. After removal of not-collected LR [15] particles, a second magnet was placed next to the other inlet. Drops of a second particle dispersion, stained with Macrolex Yellow (MFY), were disposed at the second inlet to avoid accumulation of the MFY particles at the LR spot. Due to diffusion the particle suspension slowly seeped into the channel [20] and MOSePs were collected by the second magnet. This procedure was repeated multiple times until sufficient luminescent intensity of the MFY spot was achieved (~ 10 min). Images of the spots were acquired applying the color camera to determine the quality of separation.

[25] Investigations on application of flexible sensor spots to determine intensity loss during spot movement and to follow the oxidation reaction of β-D-glucose to hydrogen peroxide and δ-D-gluconolactone by molecular oxygen in the presence of glucose oxidase were performed inside a straight channel chip [30] made from PMMA (width: 1000 μm, depth: 200 μm, cover lid thickness: 175 μm). MOSePs stained with PtTpFPTBP (0.5% (w/w)) were collected to form a magnetic sensor spot inside a microfuidic channel and read-out by a miniaturized phase fluorimeter. Two syringes containing a 20 g·L^{-1} glucose solution [35] and a 0.05 g·L^{-1} GOX solution were mounted on syringe pumps (TSE systems; model 540060; http://www.tse-systems.com/) and connected to the microfluidic channel with a T-shaped connection piece. During fluid flow of 60 μl·min^{-1} (30 μL·min^{-1} per syringe) the magnetic sensor spot and the optic fiber were moved along [40] the channel (Fig. 1 E).

To integrate fixed sensor spots into a microfluidic channel made from glass, powder blasted microfluidic chips were filled with a MOSePs stained with PtTpFPTBP (0.5% (w/w)) mixed with THF (1:1). Different magnets were used to collect the [45] swollen polymer particles. After several hours single sensor spots as well as sensor layers were formed. Full calibration of one sensor spot was performed inside the microfluidic chip by flushing it with gaseous air–nitrogen mixtures. For obtaining aqueous measuring curves the chip was flushed with [50] deoxygenated and air-saturated water. Deaerated water was obtained by deoxygenation reaction of glucose (10 mg·mL^{-1}) with oxygen in the presence of glucose oxidase (0.05 mg·mL^{-1}).

Results and Discussion

Concept of magnetic sensor particles in microfluidics

[55] The use of luminescence sensing methods in combination with magnetic bead manipulation paves the way for an advanced
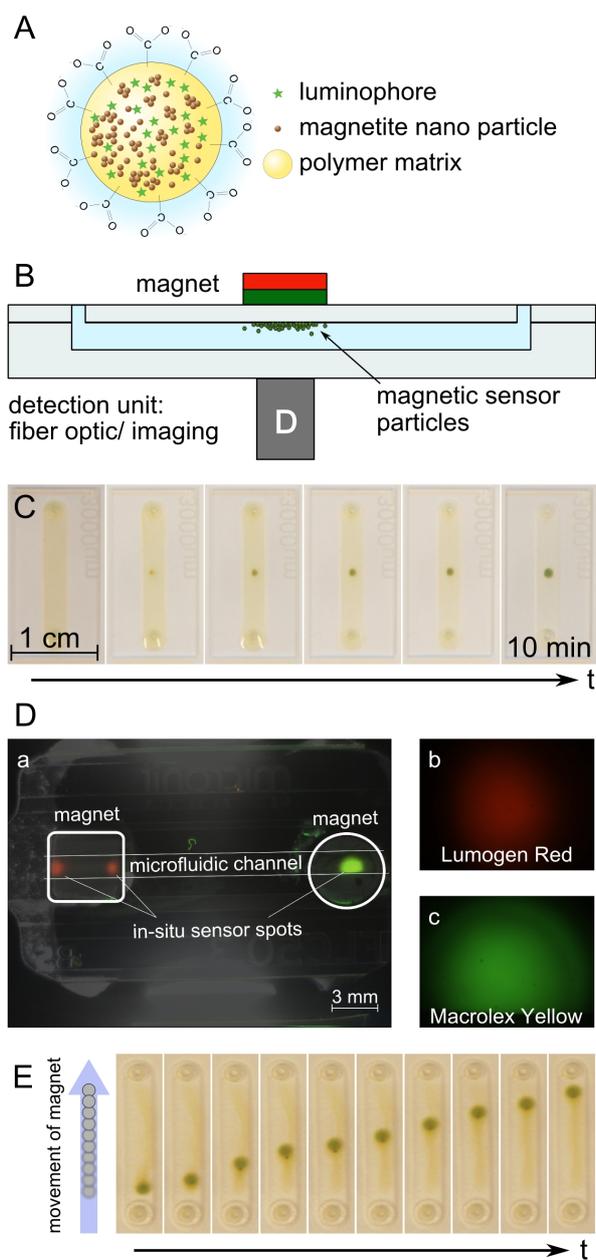

Fig. 1 Concept of MOSePs in microfluidics. (A) Scheme of a magnetic particle with incorporated luminophores (adapted from Mistlberger et [60] al.[12]). (B) Schematic cross section of a chip with separated MOSePs. (C) Time course of particle separation. (D) Formation of multiple nano particle spots inside one microfluidic channel. (E) Movement of a magnetic sensor spot along a microfluidic channel.

application of luminescence sensors in microfluidics. MOSePs [65] can be separated from a magnetic particle dispersion to form *in-situ* sensor spots – including the possibility to generate multiple spots inside one device – or can be transported along a microfluidic channel.

The concept of MOSePs in microfluidics is presented in Fig. 1. [70] Magnetite nano particles and luminescent dye molecules are incorporated into a PSMA nano particle (Fig. 1 (A)). These particles can be collected by a magnet, which is placed above a microfluidic channel, to form a magnetic sensor spot, while sensor signals are read-out from the opposite side of the chip
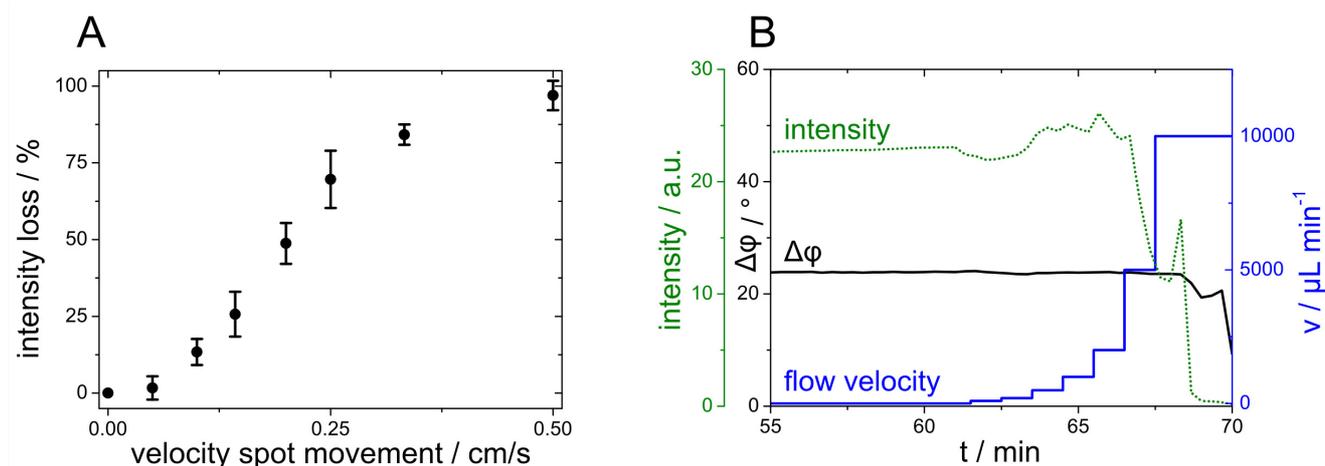
Fig. 2 (A) Intensity loss during movement of a magnetic sensor spot along a 5 cm distance in a microfluidic channel at varying spot movement velocities. The error bars show standard deviations derived from 5 independent measurements. (B) Stability of a magnetic sensor spot to different flow velocities. The experiment showed reliably measurable phase shifts up to 5 ml·min^{-1} ($\triangleq$ 287 cm·min^{-1}).

(Fig. 1 (B)). This assembly allows fiber optic as well as imaging sensor read-out. Fiber optic assemblies have also been realized with magnetic adapters, which allow read-out and separation from the same side[21]. However, for microfluidic applications it turned out to be more convenient to use the two-sided separation/read-out approach because of limited available space.

Fig. 1 (C) shows a photo series of the separation of MOSePs from a homogeneous particle dispersion in water inside a microfluidic channel with a magnet placed underneath the chip. The particles are usually separated from the surrounding solution at zero fluid flow within 10 min. *In-situ* formed sensor spots exhibited around 10 times higher emission intensities than particle dispersions before separation was induced. After separation the surrounding solution showed no luminescence emission, indicating, that a neglegible portion of the magnetic particles was lost during this process. The shape of a sensor spot can be adjusted by the choice of the magnet shape reaching from small single sensor spots to sensor lines or covering the whole channel area for imaging applications. Particles are concentrated at regions of high magnet field density. Taking the added volume of the particles, an ellipsoidal shape of the generated spots and sphere packing into account, the height of the spots was calculated to range between 5 and 10 µm. Computational Fluid Dynamics simulation studies revealed that the formed sensing spots do not cause turbulences (†, S4).

MOSePs can also be used to form multiple sensor spots, e.g. for different analytes inside one microfluidic channel. Fig. 1 (D) shows the successful generation of separate luminescent spots. Their color values were recorded applying the color camera to determine the quality of separation. These color values indicate very good separation of the two spots. In this way MOSePs can be used to generate magnetic sensor spots, which are sensitive to different analytes or which expand the dynamic range of optical sensors (e.g. pH or temperature sensing particles or particles with higher oxygen sensitivity).

Magnetic sensor spots can be used as flexible sensor spots, because these spots follow the movement of a magnet outside a microfluidic channel after particle separation (Fig. 1 E). A cylindrical magnet was slowly moved along the channel length at

the backside of the microfluidic chip (total duration around 3 s). This allows for example to study the concentration of an analyte along a microfluidic channel. The perpetuation of spot size and of measurable intensity is decreased with increasing velocity of spot movement. Fig. 2 (A) presents the relative intensity loss, when a magnetic sensor spot is moved along a 5 cm distance in a microfluidic channel at varying spot movement velocities.

Through providing these interesting features MOSePs enlarge the application possibilities of luminescent sensors: they can be used inside an arbitrary microfluidic chip with optically transparent covers, enable the formation of multiple sensor spots inside microfluidics, can be used as flexible sensor spot inside one microfluidic channel or can be fixed after their integration to any position where information about a certain analyte is needed. Microfluidic applications of MOSePs will be discussed later.

Separation speed and stability of *in-situ* sensor spots

Separation speed and stability of *in-situ* sensor spots inside microfluidic channels play a critical role regarding their applicability in microfluidics, because these features determine the time for generating a magnetic sensor spot and influence the maximum flow velocity inside microfluidic channels.

Separation speed

Theoretically, separation behavior is governed, *inter alia*, by the diameter of such a particle due to the directly proportional relationship between the velocity of a magnetic particle and the volume of this particle.

To study separation of different particle sizes from nano sensor dispersions, a microfluidic channel was filled with aqueous dispersions containing MOSePs of different hydrodynamic diameters. Light intensities were observed during separation of the particles by a cylindrical magnet from outside the channel. As expected from theory, the velocity of particles showed to be proportional to the particle size. Particles with z-av = 159 nm showed higher separation speed than particles with z-av = 110 nm. Exemplary intensity curves illustrating the separation behavior of different particle sizes from a MOSeP dispersion are presented in the supporting information (†, S1).

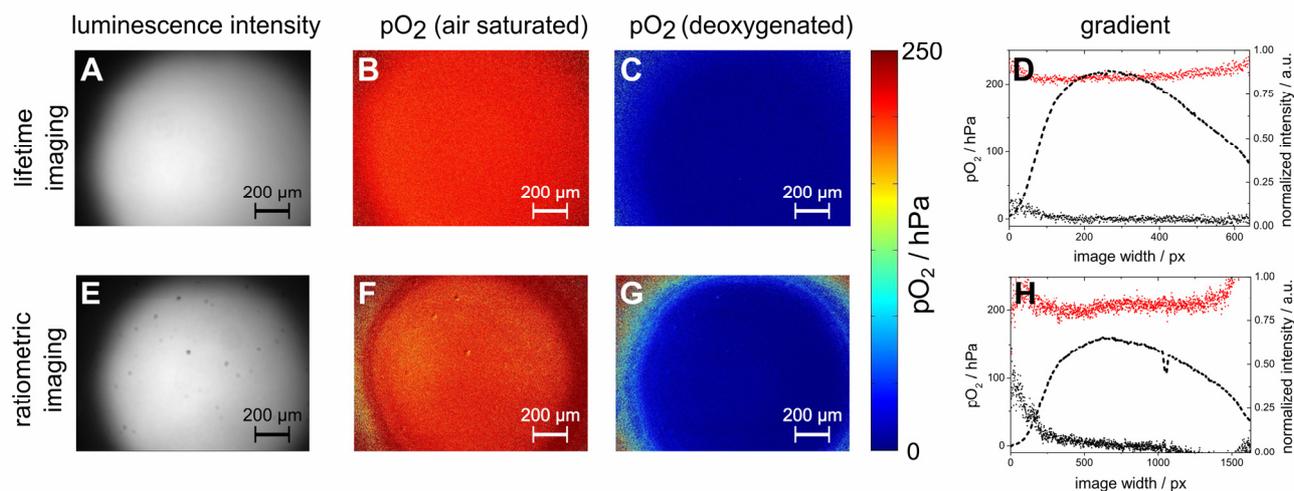This finding reveals that choosing a suitable particle size is an

Fig. 3 Comparison of referencing quality between lifetime imaging and ratiometric imaging; Images of a deoxygenated luminescent magnetic spot inside a microfluidic channel employing the principle of light harvesting were recorded using (A) - (D) RLD (lifetime) imaging and (E) - (H) RGB imaging. (A) and (E) show the intensity images, (B) and (F) the referenced air saturated images and (C) and (G) the referenced deoxygenated images. (D) and (H) display the horizontal image gradients of images (A) - (C) and (E) – (G) respectively.

important factor leading to an optimized sensing set-up. On the one hand, adequate accumulation properties are absolutely essential for generation and stability of *in-situ* sensor spots. These properties can be enhanced by increasing the particle diameter. On the other hand, magnetic particles should be as small as necessary to prevent blocking of microfluidic components and interference with microfluidic flow characteristics. Also for imaging applications it is important to have particles with a size smaller than the resolution of the imaging set-up. For this study MOSePs with z-av = 159 nm were used for further application in microfluidic channels.

Stability of magnetic sensor spots

Magnetic sensor spots should be stable at flow rates typically applied in microfluidic applications ranging from $v = 6\text{-}60 \text{ cm·min}^{-1}$ [22]. Otherwise sensor particles are washed out of the chip during measurements.

The *in-situ* formed sensor spots displayed suitable stability during investigation of different fluid velocities. In Fig. 2 (B) a fluid flow with increasing flow velocity, starting from 100 µL·min⁻¹ ($\triangleq 5.74 \text{ cm·min}^{-1}$), was applied to a microfluidic channel with a magnetic sensor spot. The flow velocity was increased to 2 mL·min⁻¹ ($\triangleq 115 \text{ cm·min}^{-1}$) without loss of luminescence intensity – indicating excellent stability of the sensor spot. When fluid velocity was then further increased to 5 mL·min⁻¹ ($\triangleq 287 \text{ cm·min}^{-1}$), a drop of signal intensity was observed, whereas the measured phase shift $\Delta\varphi$ was still stable (discussed later in detail). Fluid flows of 10 mL·min⁻¹ ($\triangleq 574 \text{ cm·min}^{-1}$) led to complete elution of the *in-situ*-formed sensor spot.

It is important to note, that separation and sensor spot stability not only depend on particle size, but also on magnetic field strength. This parameter can be influenced by choice of the magnet and by the thickness of the microfluidic cover lid influencing the distance between magnet and formed sensor spot[23], but was not investigated in detail during this study.

Sensor read-out

Several considerations have to be addressed in finding the most suitable sensing set-up for the respective measurement requirement. First, in some cases information about averaged values inside a microfluidic channel, in other cases more detailed information about the spatial distribution of the analyte may be needed. Second, MOSePs have to be adapted to the respective measurement requirement through the choice of the indicator dye. Third, the measurement method has to be chosen carefully, because the use of MOSePs entails a particular challenge due to highly varying luminescence intensities between different magnetic sensor spots or even within one generated sensor spot. Other considerations include a specification concerning accurancy and precision and the prize of the sensor set-up. A variety of measurement methods for luminescent sensors exists: in general, the measurement of luminescence lifetime is the most reliable method to reference for variations of luminescence intensity. However, luminescence lifetime imaging systems are expensive. Alternatively, ratiomatric imaging using the color channels of a color CCD-camera is less expensive, yet less accurate, read-out possibility. To show the flexibility of the presented analytical tool and to discuss different referencing schemes regarding their combination with MOSePs, magnetic particles for fiber optic read-out and imaging applications using different referencing possibilities were prepared and optimized in this study. Stern-Volmer plots and characteristic calibration data for different oxygen sensing systems are presented in the supporting information (†, S2 and S3).

Fiber optic read-out

The fiber optic read-out represents a straightforward method for automatable oxygen sensing without the need for spatial resolution of oxygen values in a microscopic range. A benzoporphyrine dye (PtTpFPTBP) was chosen for fiber optic read-out, which is known for high photostability and phosphorescence emission in the NIR spectrum[18]. It is compatible with a commercially available read-out system, which is based on lifetime measurement using the frequency domain method. The luminophore is excited by a sinusoidal modulated light source

and the phase shift $\Delta\varphi$ between excitation and emission, depending on the oxygen concentration, is recorded. The measured phase shift remains stable even if luminescence intensity exhibits high fluctuations as already shown in Fig. 2 (B). The spectral characteristics of benzo-porphyrine dyes (absorption of red light and emission in the NIR) especially fit the needs for biological applications because of the increased penetration depth in high scattering media such as cell cultures and because of reduced background due to lower scattering and autofluorescence.

Microfluidic imaging

High varying intensities within one sensing spot due to varying numbers of luminescent particles make intensity based imaging insufficient. Thus MOSePs were combined with well-established referencing schemes – rapid lifetime determination (RLD) imaging or ratiometric RGB imaging. While RLD imaging is characterized by its precision and insensitivity to disturbances like light scattering, inhomogenous illumination and dye bleaching, RGB imaging setups are incomparably cheap and simple, but limited to suppress certain interferences.

RLD imaging employing the indicator dye $(Ir(C_s)_2(acac))$[19] is recommended for short-term application with the need for high emission intensities due to the exceptional brightness but low photostability of $Ir(C_s)_2(acac)$. Particles employing PtTFPP and MFY were chosen for long-term RLD or RGB imaging applications, providing an adequate photostability with still high brightness due to the principle of light harvesting[24]. The characteristics of this sensor chemistry and the choice of the dye system have already been discussed elsewhere[4].

In order to address the reliability of lifetime imaging and ratiometric imaging, a magnetic sensor spot was generated inside a microfluidic channel and investigated using lifetime imaging and ratiometric imaging. Fig. 3 provides the results derived from this investigation. It is important to note, that after preconditioning the MOSePs as described later, the particles had to be recalibrated for both RLD (lifetime) imaging as well as RGB (ratiometric) imaging by determining τ_0 and τ. RLD (lifetime) imaging yielded homogeneous pO_2 images for air saturated and deoxygenated images. Only at regions with very low emission intensities stronger deviations from expected results can be observed (Fig. 3 (D)). Ratiometric imaging yielded pO_2 images with stronger deviations than lifetime imaging over the image area (Fig. 3 (H)). However, ratiometric imaging represents a simple and cheap method, which can be used in cases when differences in oxygen levels are big enough to be determined by this method.

Pre-treatment for microscopic imaging applications

Reduced sample volume and hence low number of analyte molecules inside a microfluidic channel lead to important aspects for microfluidic sensing devices: as already stated in the introduction, optical sensors generally do not consume the analyte under investigation. However, highly reactive singlet oxygen is produced during the dynamic quenching process. Subsequent oxidation of sensor matrix components can lead to oxygen consumption severely affecting the oxygen concentration inside microfluidics. In our case this effect is further intensified
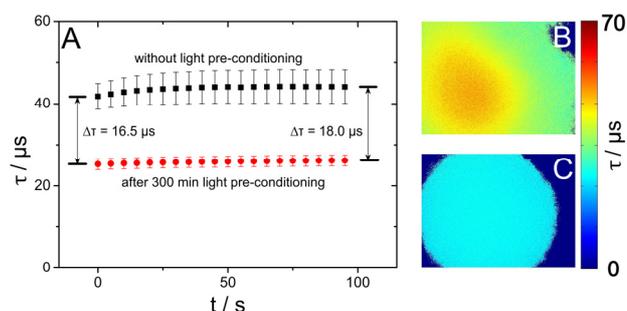

Fig. 4 Oxygen depletion during microscopic oxygen imaging inside a microfluidic chip filled with air saturated DI water. (A) Magnetic sensor spots without pre-conditioning delivered unexpected high lifetimes ($\Delta\tau = 16.5$ µs), which further increased during the investigation. The error bars show the standard deviation of all pixel lifetimes of the image area. (B) Microscopic oxygen imaging of a magnetic sensor spot without pre-conditioning showed higher lifetimes in the middle of one image with decreasing lifetimes towards image areas with lower particle densities. (C) Microscopic oxygen imaging of a magnetic sensor spot with pre-conditioning delivered homogenous distributed lifetime images with invariant values over the whole sensing spot area.

by the high excitation light densities produced by the fluorescent microscope, leading to an increased production of singlet oxygen.

Actually, our investigations on oxygen consumption of a magnetic sensor spot employing the light harvesting system (PtTFPP and MFY) showed, that luminescence lifetime for air saturated DI water was 15 to 20 µs higher than expected from the calibration data recorded outside a microfluidic chip. It further increased during the measurement although no change of oxygen concentration was expected. Moreover, the lifetime images showed higher lifetimes in the middle of one image with decreasing lifetimes towards image areas with lower particle densities (Fig. 4 (B)). When compared to particles homogeneously dispersed inside the microfluidic chip, the described effect was further intensified by concentrating the MOSePs to one sensor spot. A possible explanation for this might be that the accumulation of particles leads to an increased local production of singlet oxygen as well as reduced diffusion of oxygen to the inner part of the collected spot.

Enko et al.[25] suggest to reduce oxygen consumption via deactivation of singlet oxygen by adding physical quenching additives. However, the high volatility and water solubility make additives useless for nano particles. To make magnetic particles applicable to microfluidic imaging, they were pre-conditioned by continuous irradiation with a blue LED in order to saturate reactive binding sites of the polymer. As a consequence singlet oxygen can no longer react with these binding sites and returns to its ground state again without being consumed. After 300 min pre-conditioning the same investigation showed stable luminescence lifetime values over time (Fig. 4 (A)) and homogeneous lifetime images with invariant values over the whole sensing spot area (Fig. 4 (C)). The pre-conditioning also led to a decreased sensing sensitivity of approximately 75% compared to calibration data before pre-conditioning presented in the supporting information (†, S2 and S3). This means, that a recalibration after this procedure is necessary.

One general issue, which emerges from these findings, is that microfluidic oxygen measurements should be conducted carefully with regard to these outcomes, especially when MOSePs are
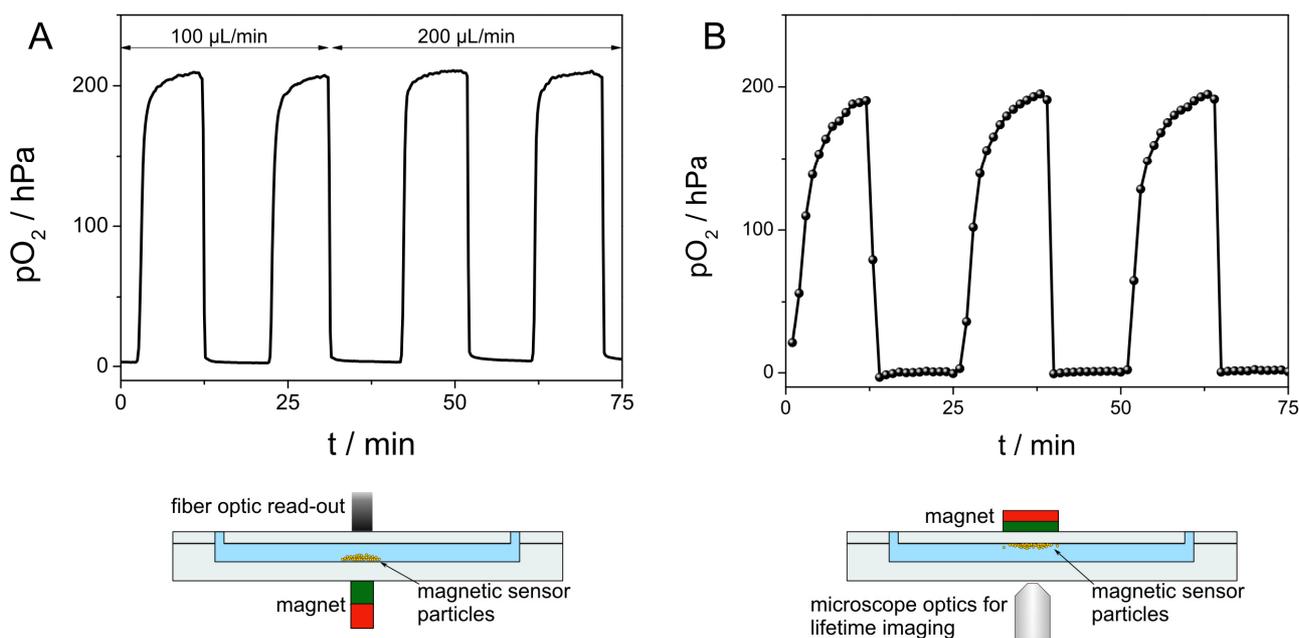
Fig. 5 Measurement inside a microfluidic chip applying (A) fiber optic and (B) lifetime imaging read-out. Magnetic sensor spots were formed before the measurement was started. Deoxygenated and airsaturated water was pumped through the microfluidic chip alternately. Different apparent response times were observed for fiber optic and imaging read-out due to different microfluidic set-ups.

[5] applied in microfluidic channels and under extreme conditions with high light intensities on a fluorescence microscope. Whenever possible, excitation time and intensity should be reduced to a necessary minimum value to reduce production of singlet oxygen and to prevent subsequent reaction of singlet [10] oxygen.

Microfluidic measurements and further applications

Online monitoring inside microfluidic channels

Magnetic nano particles enable measurements inside any microfluidic chip with optically transparent covers. The [15] performance of an *in-situ* formed sensor spot was investigated for fiber optic measurement in Fig. 5 (A). A microfluidic chip equipped with a cylindrical magnet was first filled with a MOSeP dispersion. Magnetic particles were collected for 60 min. Then deoxygenated and air saturated DI water was pumped through the [20] microfluidic chip alternately at different flow rates. Fig. 5 (A) shows a measurement inside a microfluidic chip at 100 µL·min⁻¹ and 200 µL·min⁻¹. The response curve shows excellent signal reversibility. Calculated pO_2 levels are stable although the signal intensity showed high deviations. The relatively long apparent [25] response time can be explained by the time needed to equilibrate the whole chip set-up, that means to exchange the whole liquid in the connection tubing and the microfluidic channel. Hence, the equilibration time decreases with an increasing flow rate. Fig. 5 (B) presents the results obtained for microfluidic lifetime [30] imaging at 100 µL·min⁻¹. The dots represent averaged values over the entire sensing spot area. The different apparent response time of Fig. 5 (B) compared to Fig. 5 (A) (left two peaks) can be traced back to different microfluidic set-ups including different chip geometries and connection tubing causing different [35] adsorption of deoxygenizing reagents to channel and tubing walls.

In this context it should be emphasised, that the apparent response times in Fig. 5 do not display the actual sensor particle or sensor spot response time. The response time of a particle spot [40] to a rapid change in oxygen concentration was reported by Mistlberger et al.[12] to have a t_{90} of 1.4 s, while they assumed the response of single particles to be much faster. Thus magnetic sensor spots can be considered to respond in real-time.

Spatially resolved respiratory cell activity

[45] MOSePs containing $Ir(C_s)_2(acac)$ as oxygen indicator were used for imaging of cell respirometry within a microfluidic chip. 20 µL magnetic particle suspension were inserted into the chip and collected by a magnet from outside before the chip was inoculated with *E. coli*. Luminescent signals were read out by [50] application of lifetime imaging. Fig. 6 (A) shows a microfluidic channel with a magnetic sensor layer. Dark spots at the luminescent intensity image inside the microfluidic channel (Fig. 6 (A) inlay) mark areas of *E. coli* cell aggregates. The pO_2 image shows lowest oxygen levels at areas where cell aggregates [55] are located.

Flexible sensor spots for use in microreactors

Flexible sensor spots can be used to study the concentration of an analyte along a microfluidic channel. This is especially interesting for microfluidic reactions, where the analyte is [60] consumed over the channel length, with the channel length corresponding to reaction time.

Fig. 6 (B) shows the principle of a flexible sensor spot applied in a microfluidic channel. When the magnet outside a microfluidic channel is moved along the channel length, the [65] magnetic sensor spot follows the movement of the magnet inside the channel from one inlet to the other. The oxidation reaction of β-D-glucose to hydrogen peroxide and δ-D-gluconolactone by molecular oxygen in the presence of glucose oxidase was followed by measuring the pO_2 along the channel length by
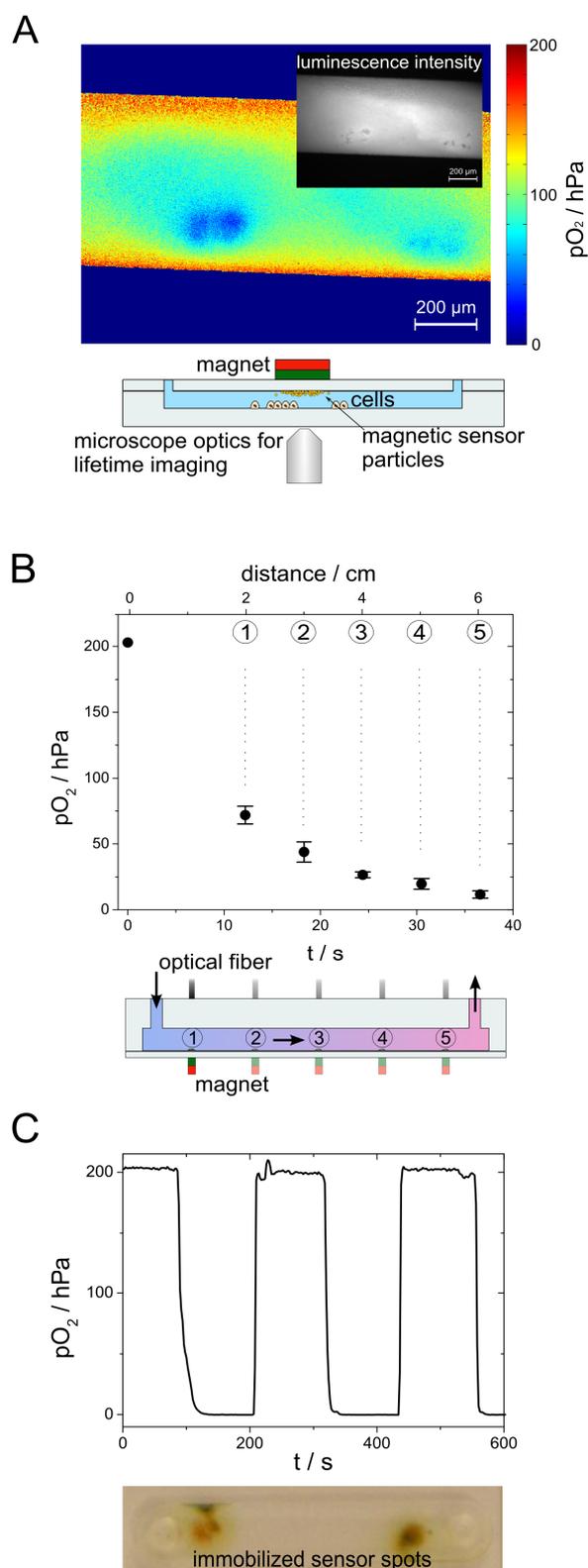
Fig. 6 Applications of MOSePs in microfluidics; (A) pO$_2$ image of E.coli in a microfluidic channel of a PDMS chip applying luminescent magnetic nano sensor particles. (B) Application of flexible sensor spots with a concentration gradient along the channel length. The error bars show the standard deviation derived from 3 independent measurements (C) Response curve of an immobilized sensor spots inside a microfluidic device.

applying a flexible sensor spot. A glucose solution and a solution containing glucose oxidase were mixed short before the microfluidic inlet. Fig. 6 (B) presents the obtained measured oxygen concentrations at distances d = 2, 3, 4, 5 and 6 cm from mixing area (≙ retention time of 12.2, 18.3, 24.4, 30.5 and 36.6 s).

Generation of fixed sensor spots

MOSePs can also be used to form fixed sensor spots inside microfluidic structures, which would be inaccessible to integration of sensor layers. This can be especially helpful, when microfluidic structures made of glass are used. The abrasive methods, which are used for microfluidic glass structuring or as bonding procedures, would destroy the sensing chemistry of sensor spots or layers integrated into microfluidic structures during fabrication of a microfluidic device.

Fixed sensor spots were integrated into a microfluidic channel made from powder blasted microfluidic glass chips. The addition of THF to a MOSeP suspension (1:1) leads to swelling of the particles. These particles are transferred into a microfluidic chip and magnetically separated. The magnetic force acting on soft particle shells leads to particle adhesion to the channel wall. Different magnets were used to form single sensor spots as well as sensor layers, which can then be used without magnetic support.

Fixed sensor spots showed to behave similar to flexible sensor spots. A measuring curve with air saturated and deoxygenated water was recorded (Fig. 6 (C)), exhibiting shorter response times compared to diffusion limited magnetic sensor spots. Furthermore, fixed sensor spots were stable beyond flow velocities of 2 000 cm·min^{-1}.

Conclusion

Magnetic separation of MOSePs leads to the generation of *in-situ* sensor spots with different shapes. These sensor spots can be moved along microfluidic channels following the position of a magnet outside the channel. An investigation of magnetic sensor spot stability towards different flow velocities showed reliable lifetime measurements up to flow velocities of 5 mL·min^{-1} (≙ 287 cm·min^{-1}). Summing up, the stability of *in-situ* formed sensor spots showed to be sufficiently stable at flow rates typically applied in microfluidic applications.

MOSePs can be easily adapted to the respective measurement requirement. They enable fiber optic as well as imaging read-out by adapting luminescent indicators and referencing schemes to the respective measurement requirement. Fiber optic oxygen measurements as well as oxygen imaging inside microfluidic channels turned out to be straightforward. The measurement of luminescence lifetime was shown to be the most accurate and precise methods to reference for these variations, while for imaging applications ratiometric imaging using the color channels of a RGB camera may be the less expensive but still adequate read-out possibility.

However, microscopic oxygen imaging with high excitation light intensities must be performed with caution paid to singlet oxygen production and subsequent reactions, which can lead to underestimated pO$_2$ levels. Nevertheless, microscopic oxygen imaging was also reliably performed after preconditioning of the particle dispersion by irradiation with light.

Analyst Accepted Manuscript

MOSePs were also demonstrated to serve as useful tool for a variety of new and flexible applications inside microfluidic devices. They can be used for microscopic oxygen imaging applied in microfluidic cell culture, to form multiple separated sensor spots, e.g. for different analytes inside one microfluidic channel, serve as flexible sensor spots to study analyte gradients along a microfluidic channel or can be used to form fixed sensor spots inside microfluidic structures, which would otherwise be inaccessible to integration of sensor layers.

All these findings suggest that in general MOSePs are an interesting tool to be applied in microfluidic environments and can facilitate further integration and new applications of luminescent sensors in this research field.

Acknowledgements

Notes and references

[a] Applied Sensors, Institute of Analytical Chemistry and Food Chemistry, Graz University of Technology, Stremayrgasse 9/3, 8010 Graz, Austria. Fax: +43 (0) 316 873 32502; Tel: +43 (0) 316 873 32504; E-mail: torsten.mayr@tugraz.at
† Electronic Supplementary Information (ESI) available: See DOI: 10.1039/b000000x/

1   B. Kuswandi, Nuriman, J. Huskens, and W. Verboom, *Anal. Chim. Acta*, 2007, **601**, 141–155.
2   V. Nock, R. J. Blaikie, and T. David, *Lab. Chip*, 2008, **8**, 1300–1307.
3   H. Zhu, X. Zhou, F. Su, Y. Tian, S. Ashili, M. R. Holl, and D. R. Meldrum, *Sens. Actuators B Chem.*, 2012, **173**, 817–823.
4   B. Ungerböck, V. Charwat, P. Ertl, and T. Mayr, *Lab. Chip*, 2013.
5   L. Gitlin, C. Hoera, R. J. Meier, S. Nagl, and D. Belder, *Lab. Chip*, 2013.
6   S. Jezierski, D. Belder, and S. Nagl, *Chem. Commun.*, 2013, **49**, 904–906.
7   A. P. Vollmer, R. F. Probstein, R. Gilbert, and T. Thorsen, *Lab. Chip*, 2005, **5**, 1059–1066.
8   R. H. W. Lam, M.-C. Kim, and T. Thorsen, *Anal. Chem.*, 2009, **81**, 5918–5924.
9   M. A. Acosta, P. Ymele-Leki, Y. V. Kostov, and J. B. Leach, *Biomaterials*, 2009, **30**, 3068–3074..
10 B. Ungerböck, A. Pohar, T. Mayr, and I. Plazl, *Microfluid. Nanofluidics*, 2012.
11 D. Aigner, B. Ungerböck, T. Mayr, R. Saf, I. Klimant, and S. M. Borisov, *J. Mater. Chem. C*, 2013, **1**, 5685–5693.
12 G. Mistlberger, K. Koren, E. Scheucher, D. Aigner, S. M. Borisov, A. Zankel, P. Pölt, and I. Klimant, *Adv. Funct. Mater.*, 2010, **20**, 1842–1851.
13 N. Pamme, *Lab. Chip*, 2006, **6**, 24.
14 M. A. M. Gijs, *Microfluid Nanofluid*, 2004, **1**, 22–40.
15 J. Nilsson, M. Evander, B. Hammarström, and T. Laurell, *Analytica Chimica Acta*, 2009, **649**, 141–157.
16 M. A. M. Gijs, F. Lacharme, and U. Lehmann, *Chem. Rev.*, 2010, **110**, 1518–1563.
17 R. J. Meier, L. H. Fischer, O. S. Wolfbeis, and M. Schäferling, *Sens. Actuators B Chem.*, 2013, **177**, 500–506.
18 S. M. Borisov, G. Nuss, W. Haas, R. Saf, M. Schmuck, and I. Klimant, *J. Photochem. Photobiol. Chem.*, 2009, **201**, 128–135..
19 S. M. Borisov and I. Klimant, *Anal. Chem.*, 2007, **79**, 7501–7509.
20 C. Moser, T. Mayr, and I. Klimant, *Anal. Chim. Acta*, 2006, **558**, 102–109.
21 G. Mistlberger, P. Chojnacki, and I. Klimant, *J. Phys. Appl. Phys.*, 2008, **41**, 085003.
22 H. A. Stone, A. D. Stroock, and A. Ajdari, *Annu. Rev. Fluid Mech.*, 2004, **36**, 381–411.
23 P. Zhang, S. Park, and S. H. Kang, *Chem. Commun.*, 2013, **49**, 7298–7300.
24 T. Mayr, S. M. Borisov, T. Abel, B. Enko, K. Waich, G. Mistlberger, and I. Klimant, *Anal. Chem.*, 2009, **81**, 6541–6545.
25 B. Enko, S. M. Borisov, J. Regensburger, W. Bäumler, G. Gescheidt, and I. Klimant, *J. Phys. Chem. A*, 2013, **117**, 8873–8882.