




 Cite this: *Lab Chip*, 2023, 23, 2577

Microfluidic viscometer by acoustic streaming transducers†

 Ruoyu Jiang,  ‡^a Paul Yoo,  ‡^a Abhinand M. Sudarshana, ^a
 Emma Pelegri-O'Day,^c Sandeep Chhabra,^c Marissa Mock^c and Abraham P. Lee *^{ab}

Measurement of fluid viscosity represents a huge need for many biomedical and materials processing applications. Sample fluids containing DNA, antibodies, protein-based drugs, and even cells have become important therapeutic options. The physical properties, including viscosity, of these biologics are critical factors in the optimization of the biomanufacturing processes and delivery of therapeutics to patients. Here we demonstrate an acoustic microstreaming platform termed as microfluidic viscometer by acoustic streaming transducers (μ VAST) that induces fluid transport from second-order microstreaming to measure viscosity. Validation of our platform is achieved with different glycerol content mixtures to reflect different viscosities and shows that viscosity can be estimated based on the maximum speed of the second-order acoustic microstreaming. The μ VAST platform requires only a small volume of fluid sample ($\sim 1.2 \mu\text{L}$), which is 16–30 times smaller than that of commercial viscometers. In addition, μ VAST can be scaled up for ultra-high throughput measurements of viscosity. Here we demonstrate 16 samples within 3 seconds, which is an attractive feature for automating the process flows in drug development and materials manufacturing and production.

 Received 4th February 2023,
 Accepted 17th April 2023

DOI: 10.1039/d3lc00101f

rsc.li/loc

Introduction

Precise measurement of viscosity is critical to characterize and determine fluidic behavior. In many biomedical applications, viscosities of therapeutic proteins or monoclonal antibody (mAb) solutions are routinely monitored to ensure drug developability.¹ Viscous mAb solutions are not suitable for subcutaneous injection and are also difficult to produce and process during manufacturing.^{2,3} Since often highly concentrated monoclonal antibody drugs are needed to maximize therapeutic efficacy, viscosity becomes a limiting factor when designing the dosing concentrations for patient injection. In a clinical setting, blood viscosity increases blood coagulation and continuous monitoring of blood viscosity is crucial for routine clinical tests such as the activated clotting time (ACT), the thrombin clotting time (TCT) and thromboelastography (TEG).^{4,5} Traditional viscometers, such as cone and plate, falling ball, and capillary sensing, are

generally used to measure fluid viscosities.^{6,7} However, most of the conventional viscometers are extremely bulky, and require precise balance such as perfectly leveled flatbed to avoid error in the results.^{8,9} These techniques typically require large sample volumes on the order of milliliters and time-consuming data acquisition and sample handling steps. In the event of early drug screening, such as engineered mAb drug solutions during optimization, producing large quantities of drug candidates is not feasible. Furthermore, most conventional approaches to viscosity measurement are limited to measuring one sample at a time, further reducing throughput. Therefore, it is desirable to develop high throughput viscometers that consume minimal sample volumes while measuring multiple samples within one system.

With the help of the recent development of microfluidic technologies, various approaches have been introduced to measure fluid viscosity at the micro-scale and can be categorized as whether a given pressure is applied or a given flow rate is applied externally to induce fluid transport to correlate with viscosity. Viscometers based on capillary-pressure-driven principle have been used as a pressure driven method to measure the traveling speed of the liquid head within a polydimethylsiloxane (PDMS) or paper-based channel to correlate with liquid viscosity.^{10–12} Although this method requires a very small amount of liquid, the meniscus is sensitive to the channel wetting condition, and the

^a Biomedical Engineering, University of California, Irvine, CA 92697, USA

^b Mechanical and Aerospace Engineering, University of California, Irvine, CA 92697, USA

^c Amgen Research, Biologics Therapeutic Discovery, 1 Amgen Center Drive, Thousand Oaks, California 91320, USA

 † Electronic supplementary information (ESI) available. See DOI: <https://doi.org/10.1039/d3lc00101f>

‡ These authors contributed equally to this work.

resulting measurement is prone to distortion. Another pressure-driven approach is to use a microcantilever and analyze the responses of the cantilever under resonance vibrations.^{13–15} Viscosities can be extracted by tracking the vibrational particle/liquid movements *via* droplet vibration. However, like previously mentioned capillary viscometers, these methods require complex calculations/derivation and are limited by wetting conditions of the surface. A droplet-based microfluidic system is a common type of flow rate driven approach that can be used to continuously measure fluid viscosity.¹⁶ The velocity of the droplets when entering the constriction channel can be correlated with fluid viscosity and volume ratio of oil to droplets can also be used to measure viscosity ranges.^{17–21} These methods require complicated calibration and have limitations in viscosity ranges and types of fluids such as non-Newtonian fluids. Li *et al.* developed another system to measure viscosity by

droplet length.²² Under constant pressure, the viscosity of both Newtonian and non-Newtonian fluids can be measured under such system and the measurement needs as low as 1 μL volume. Nevertheless, the system lacks in sensitivity and can only distinguish samples that possess large range of viscosity differences rather than samples that share close viscosities (*e.g.* 4 and 5 cP). Additionally, diffusion microfluidic viscometers have also been developed to measure the diffusive motion of tracer particles to quantify fluid viscosity using Stokes–Einstein–Sutherland relation. They require low sample volume and offer high sensitivity in measurement.^{23–25} However, the choice of the probe sizes and unwanted interaction between probes and liquid material need to be considered.²⁶

Acoustic-based microfluidics offers high particle controllability and low sample volume requirement to address the challenges above and has been reported for

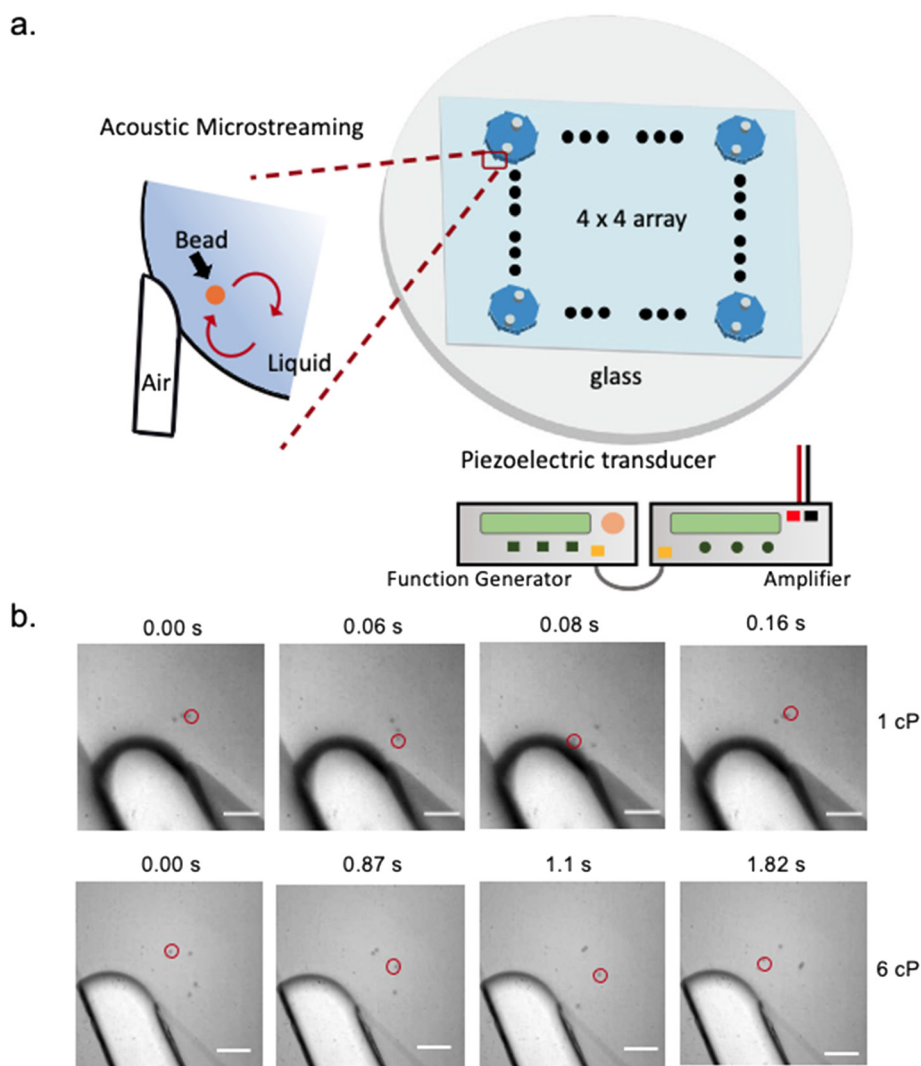


Fig. 1 Device design and operation. a. Schematic diagram of the microfluidic viscometers in a 4×4 array. The direction of the arrow indicates the direction of the bead movement within the acoustic microstreaming. b. Time lapse showing beads traveling under different viscosity fluids (0% glycerol mixture vs. 50% glycerol mixture). The red circles show the tracking location of the same bead. Scale bar: 50 μm .

precise spatial and temporal particle manipulation such as translation, rotation, mixing, trapping, and sorting.^{27,28} Specifically, localized acoustic microstreaming generated from oscillating bubbles has been used to achieve multimodal control over the object orientations and the magnitude of the object moving velocity and its position can be controlled by the acoustic voltage and frequency.^{29–31} In this work, we present a microfluidic platform termed microfluidic viscometer by acoustic microstreaming transducers (μ VASTs) consisting of 16 independent wells, with each well capable of measuring the viscosity of different fluids using volumes as low as 1.2 μ L, and each well containing 8 lateral cavity acoustic transducers (LCATs). LCATs are dead-end side channels that produce microstreaming patterns at the air–liquid interface powered by an activated piezoelectric transducer (PZTs). To minimize the fluid volume while maximizing the number of measured samples, a well-shaped design is incorporated (Fig. 1a). Using this design, we show that micrometer beads can be trapped within the microstreaming vortices with traveling velocities near the air–liquid interface precisely that correlate with a wide range of viscosities (1–50 cP). At low Reynolds number and Stokes flow regime we demonstrate that the bead velocity is in inverse relationship with the fluid viscosity (Fig. 1b).^{26,32,33}

When beads are traveling within the microstreaming vortices, the μ VASTs can continuously record bead velocity over 3 seconds and a regression model is constructed ($R^2 = 0.96$) correlating fluid viscosity to bead velocities. By measuring the bead velocities, it is practical to estimate viscosities of other types of fluids based on a regression model. We further demonstrate the device's accuracy in sample fluids such as bovine serum albumin (BSA) and dextran under different concentrations, and our estimated viscosities match well with those from cone-and-plate viscometers. Overall, this work demonstrates a high-throughput, highly precise, and portable microfluidic viscometer platform for the measurement of a wide range of viscosities that has broad applications toward point-of-care testing, blood tests, and antibody/protein therapy.

Materials and methods

Microfluidic chip fabrication

In this study, devices were fabricated using the standard soft lithography process on a 4 inch silicon wafer. Channel layer was spin coated with SU-8 2075 (MicroChem, USA) at 500 rpm for 10 s, followed by 2150 rpm for 30 s to obtain 100 μ m height. SU-8 molds were soft baked at 65 °C for 5 min and 95 °C for 15 min and cooled for 3 min. They were exposed and patterned by ultraviolet light at 23 s with a chrome mask (Front Range, USA). The wafer was then post exposure baked at 65 °C for 5 min and 95 °C for 10 min. While the wafer is submerged in the developer solution, a sonicator was used for 40 s to remove unexposed photoresist. The molds were then cure baked at 150 °C for 10 min. μ VAST devices were

fabricated with the polymer polydimethylsiloxane (PDMS) and Sylgard 184 silicone elastomer curing agent and base (Dow Corning, USA) at 1:11.5 ratio and poured on the mold. After setting at room temperature overnight, the PDMS channel was peeled off and bonded to the glass by oxygen plasma treatment. The bonded devices were placed on a hotplate at 90 °C overnight.

Liquid sample preparation

Liquid samples with different viscosities ranging from \sim 1 to 50 cPs were prepared from glycerol–PBS (without Ca^{2+} and Na^+) (STEMCELL, Canada) mixtures of different mixing ratios according to manufacture protocol. Polystyrene (Spherotech, USA) beads with diameters of 5 μ m were mixed with glycerol as the final solution for the microfluidic viscometer device. Bovine serum albumin (Sigma, A1900) was weighed and dissolved completely in 1 mL water before each experiment. The dextrans (MW 70 000) were obtained from Sigma Co. (St. Louis, MO) (produced by *Leuconostoc mesenteroides*) and dissolved in water as wt/wt percentage. Viscosity results for BSA and dextran using cone and plate rheometer were collected from literature.^{34,35}

Experimental setup

This setup was placed onto an upright microscope for analysis. A high-speed camera (Phantom v310, Vision Research Inc., USA) was used to record videos of the motion of polystyrene beads (Degradex, USA) in the viscometer. The videos were recorded at a frame rate of 1000 frames per second to study bead motion in high temporal resolutions. This was particularly important in capturing the velocity changes at the air–liquid interface of LCATs in the device. For the experiments studying air–liquid interface oscillation amplitude and periodicity, the video frame rate was increased to 100 000 fps due to the rapid oscillation of the interface. To generate the acoustic energy field, a square wave signal of 50.2 kHz was delivered to the PZT using a function generator (Agilent Technologies, USA). The function generator was coupled with a power amplifier (Micromechatronics, Inc., USA) to read out the specific voltages used in the experiments. Acoustic streaming velocity distribution of particles was analyzed using the PIVLab toolbox in Matlab.³⁶

Image processing

Fiji³⁷ was used to visualize the particle movement and to perform most of the image processing and analyses. Particle traveling distance was measured using Fiji and velocity is calculated as: $\frac{\text{Distance that beads travelled}}{\text{the time spent}}$. The frame rate used for calculating maximum streaming speed is 1000 frames per second.

Results

We have previously established acoustic microstreaming platform used for rapid bead/cell trapping, separation, mixing and pumping applications.^{38–41} Operations of the LCATs rely on oscillation of trapped microbubbles in lateral slanted dead-end side channels to generate a first order oscillatory flow at the air–liquid interface.^{41–44} The first order oscillatory flow induces a second order streaming flow that consists of an open microstreaming flow and a closed loop microstreaming vortex. The dead-end side channels were designed to have a 15° slanted angle so that the microstreaming generates the maximum flow speed that traps particles.^{42,45} The velocity of the acoustic microstreaming (u) is generated due to the first order oscillation flow from the oscillating air–liquid interface given by:^{32,46}

$$u_s = \frac{r_a^4}{d^5} \omega \varepsilon^2 \quad (1)$$

The acoustic microstreaming generates Stokes' drag force on the:

$$F_{\text{drag}} = 6\pi\mu r_b u_b \quad (2)$$

where r_a , d , ω , ε from eqn (1) are the radius of the air–liquid interface, distance between the interface and bead center, interface oscillation angular frequency, and interface oscillation amplitude, respectively; r_b , μ , u_b from eqn (2) are bead radius, dynamic viscosity of the fluid, and microstreaming velocity of the microbead in respect to the fluid, respectively.

Eqn (1) and (2) suggests positive correlation between the oscillation of the air–liquid interface and the microstreaming velocity: larger oscillation amplitude of the air–liquid interface leads to higher microstreaming velocity and lower amplitude leads to lower microstreaming velocity. We selected beads size ($\sim 5 \mu\text{m}$) and low bead concentrations (3–10 beads per vortex) to minimize bead-to-bead interference so that velocity of the microbead approaches the velocity of the acoustic microstreaming under low Reynolds number ($u_s \approx u_p$).³² Hence, at low Reynolds number and Stokes flow regime, each position of a given acoustic microstreaming pattern produces a drag force that dictates the bead velocity is in inverse relationship with the fluid viscosity. That is, higher viscosity leads to lower microbead speed and lower viscosity leads to higher particle speed (Fig. 1a).

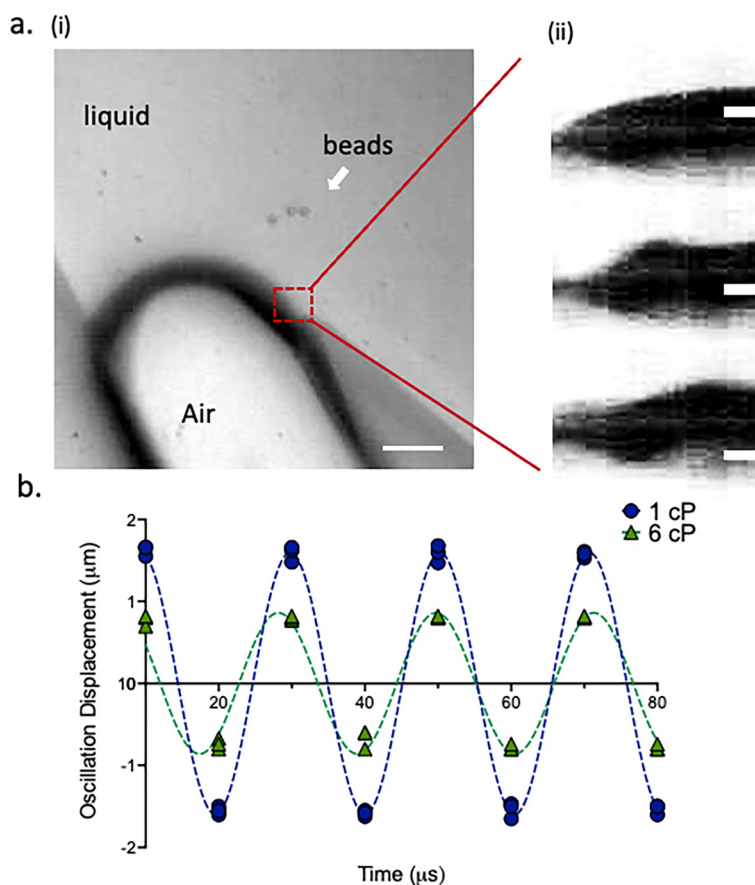


Fig. 2 Characterization of first order oscillation flow. a. Experimental image of acoustic microstreaming and first order oscillation at the air–liquid interface. i. Beads were trapped within acoustic microstreaming. Scale bar: 50 μm . ii. First order oscillation displacement showing one cycle of the oscillation. Scale bar: 2 μm . b. Oscillation displacement under different viscosity fluids (1 cP vs. 6 cP).

Characterization of first-order oscillation flow and second order acoustic microstreaming

A 1 mL glycerol–PBS mixture was prepared and 5 μm beads were added to have the final concentration 3×10^5 beads per mL (original bead stock to sample volume ratio: 1:1000). A 1.2 μL aliquot of each sample fluid was then injected into the μVAST device *via* the inlet. Air–liquid interfaces were formed due to priming of the aqueous solution. The angles of the dead-end side channels were approximately 19° , slightly different from previously reported straight 15° channel angle due to the circular and round shape of the reported design⁴⁷ (Fig. S1†). Fig. 2a demonstrates the oscillation patterns of the air–liquid interface, the oscillating amplitudes and frequency under different viscosities. The static air–liquid interface showed no sign of oscillation when PZT was not excited and its

oscillation motion behaved in a sinusoidal fashion when PZT was excited.

Furthermore, all eight air–liquid interfaces within one well were excited to oscillate with the same pattern (Fig. S2†). It is shown that higher viscosity fluid (50% glycerol mixture) generated from glycerol–PBS mixture causes air–liquid interface to oscillate much less compared with the oscillation displacement generated from the lower viscosity fluid (1 \times PBS without glycerol) (Fig. 2b). Interface oscillation amplitude is directly proportional to applied voltage and inversely proportional to viscosity (Fig. S3†). The inverse relationship between oscillation amplitude and viscosity is especially apparent as voltage increases. At each voltage level, solutions of higher viscosity displayed lower interface oscillation amplitudes than solutions of lower viscosity. These amplitude differences typically increased at higher voltages. Therefore, applying a high voltage, such as 20 V,

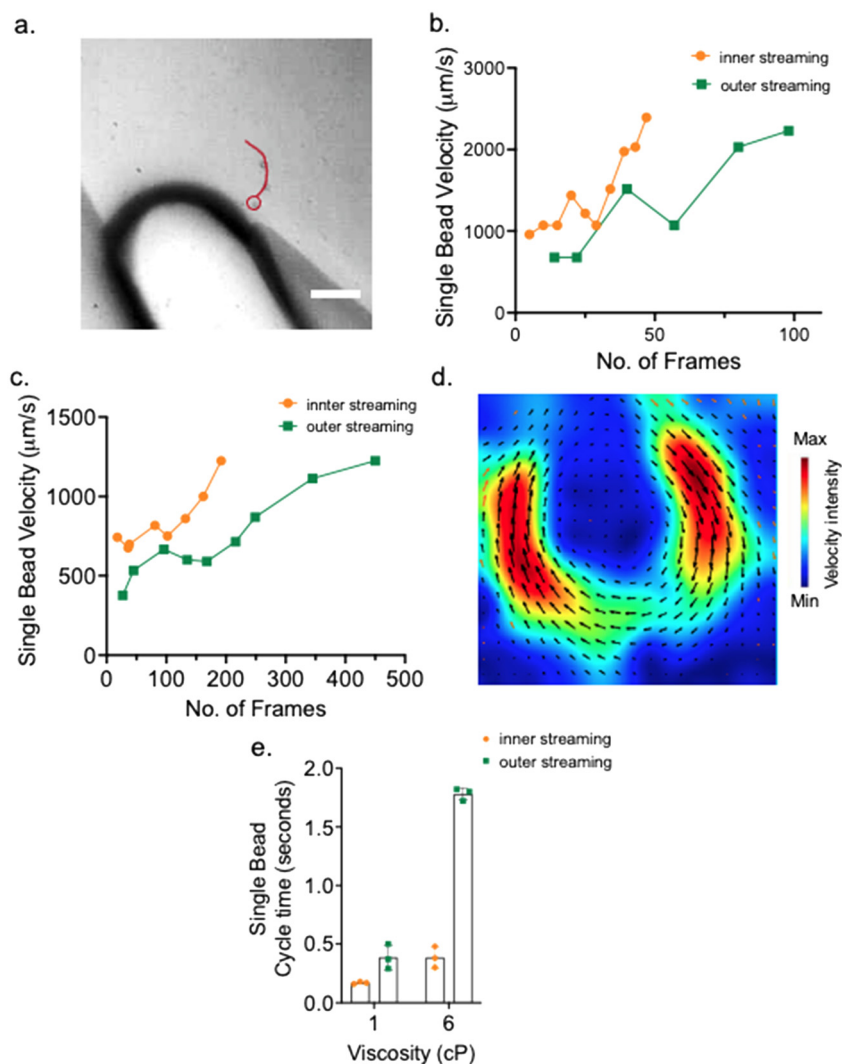


Fig. 3 Characterization of second order acoustic microstreaming. a. Single bead movement tracking. The red dots show the location of a single bead. b. Velocity profiling of one single bead within one cycle of acoustic microstreaming. c. Single bead velocity profiling under 6 cP. d. Particle image velocimetry (PIV) characterization of the acoustic microstreaming. The direction of the arrow indicates the direction of the bead movement. e. Cycle time of single bead within one cycle of the acoustic microstreaming under 1 and 6 cP.

may facilitate the differentiation of fluids by viscosity. The general trend of amplitude *versus* voltage was similar between the solutions, demonstrating the consistency in the relationship between amplitude and viscosity (Fig. S4†). The correlation between fluid viscosity and oscillation amplitude suggests that viscosity resists the motion of the interface. However, the changes in fluid viscosity did not affect the frequency of the oscillation. These results show at a fundamental level how fluid viscosity affects oscillation amplitude of the air–liquid interface, which ultimately determines the formation of the acoustic microstreaming pattern in the μ VAST chamber.

The high-speed Phantom camera was used to capture the movement of beads within the acoustic microstreaming vortices. The movement of the beads was tracked frame by frame and used the distances traveled between each frame divided by the time interval (Fig. 3a and S5†). Calculations were paused when beads encountered the air–liquid interface (Fig. 3a, red circle), since the dark contrast prevented us from conducting an accurate reading of the particle speed. We profiled the single bead velocity from the point further away from the air–liquid interface to regions close to the interface at the sharp tip. Fig. 3b showed that beads travelled much faster under 1 cP fluid (0% glycerol mixture with 1 \times PBS) compared with the beads from 6 cP (50% glycerol mixture) fluid (Fig. 3c). Furthermore, the velocity profile showed more fluctuation at regions farther away from the air–liquid interface and particle speed tended to vary (Fig. 3b). In contrast, when beads moved near the air–liquid interface (approximately 30–40 μ m away), the speeds were consistently

increasing without variation. Furthermore, particles located in the inner streaming have similar speed compared with particles located in the outer streaming traces when they move near the air–liquid interface (Fig. 3b and c). Therefore, we selected this region near the air–liquid interface to track the particle speed and correlate with fluid viscosity. Particle image velocimetry (PIV) confirms our single particle tracking within the acoustic microstreaming and near the air–liquid interface appears to have maximum streaming speed of the complete one cycle indicated by the red intensity of traveling speed (Fig. 3d).

Since the particle speed reflects the relative value of the fluid viscosity, beads traveled faster in low viscosity fluids and took less time to complete one cycle within the acoustic microstreaming. Higher viscosity fluids required beads to spend more time to travel one cycle of the acoustic microstreaming (Fig. 3e).

Estimation of fluid viscosity using acoustic microstreaming

We investigated particle velocity measurement from glycerol–PBS mixture to verify our device's ability to measure fluid viscosity. In this experiment, PBS–glycerol mixture containing 5 μ m beads that have the same volume ($1.2 \pm 0.2 \mu$ L) but viscosity values ranging from 1 to 50 cP were tested. The sample and beads preparation and viscosity measurement processes are described in the methods section. The experiment was performed at room temperature. First, the sample liquid was gently injected into inlet of the μ VAST array to form hydrophobic air–liquid interfaces at the dead-

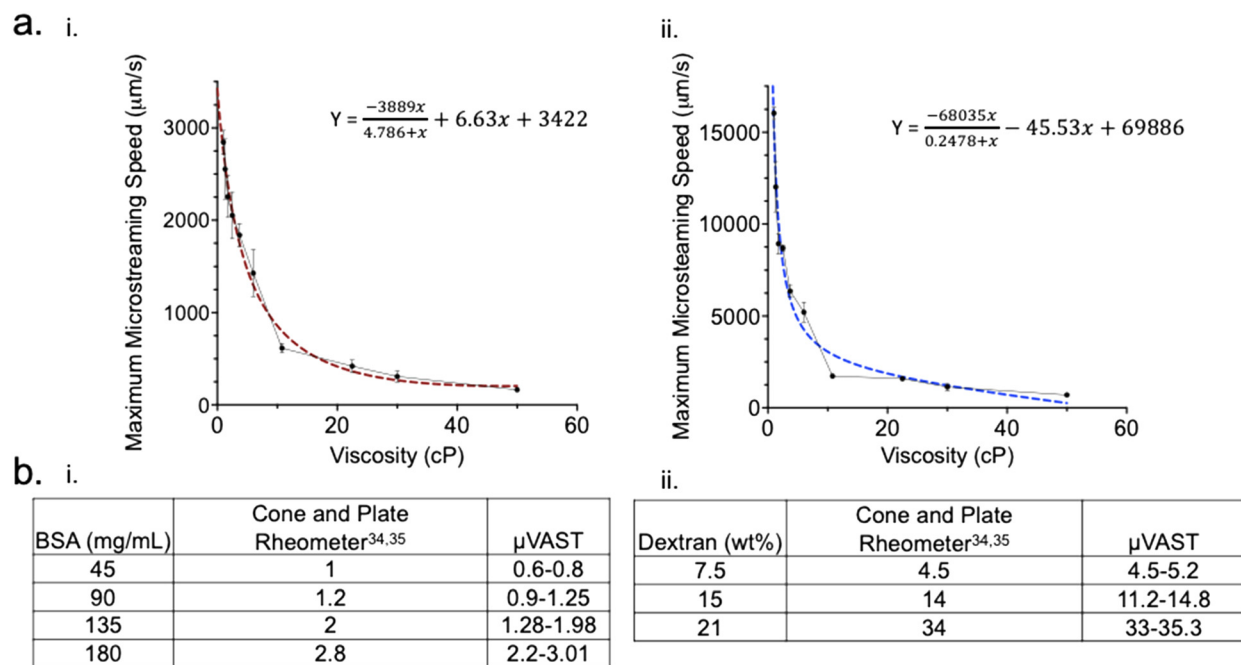


Fig. 4 Measurement of fluid viscosity. a. Viscosity (1–50 cP) of glycerol mixture measurement under (i.) 4 V_{p-p} and (ii.) 8 V_{p-p} . b. Other types of sample fluid viscosity measurement (i). BSA from 45 to 180 mg ml^{-1} and (ii). Dextran from 7.5 to 21 wt%. At least three independent replicates were conducted during the measurements.

end side channels. Bead movements were captured using high-speed camera as noted above.

Fig. 4a and b show the maximum microstreaming speed of beads from 1 cP to 50 cP using different percentages of PBS–glycerol mixture at 4 V_{p-p} and 8 V_{p-p} respectively. When the PZT actuator was applied, the oscillation of the air–liquid interface was instantaneously excited to generate acoustic microstreaming where speed decreased with increasing viscosity of the fluid. The bead speeds were estimated to reflect the microstreaming speed as mentioned previously. The beads speed were obtained across a wide range of viscosities, with speed apparently exponentially decreasing as a function of viscosity. As we increased the input acoustic voltage from 4 V_{p-p} to 8 V_{p-p} , the acoustic microstreaming speed also increased. Bead velocity also decreased as a function of viscosity in a similar pattern under 8 V_{p-p} . We then conducted regression models to these two voltage conditions and fitted our speed with an exponential decay function ($y = (y_0 - \text{plateau}) \times \exp(-K \times t)$), as shown Fig. 4a and b. The best fitted values of K were 0.165 and 0.317 for the 4 V_{p-p} and 8 V_{p-p} and the R -squared were 0.96 and 0.94, respectively. The viscosity of other sample fluids such as BSA and dextran were also obtained by plotting the relationship between the bead maximum speed and fluid viscosity. Because the correlation of bead maximum speed at the air–liquid interface under 4 V_{p-p} generated higher equation fitness (0.96 vs. 0.94), we used this voltage condition to test BSA and dextran. Fig. 4c and d show viscosity measurement for BSA at 45, 90, 135 and 180 mg ml⁻¹ and dextran at 7.5, 15 and 21 wt%. The results show that our estimated values align closely with those of the reported values from cone and plate rheometers.^{34,35}

Discussion

In this paper, we presented an acoustic microstreaming platform, μ VAST, for rapid viscosity measurement and addressed several key limitations of traditional viscometers. One critical challenge to measure viscosity is the requirement of large volumes of sample fluids. μ VASTs only require 1.2 μ L of fluid sample to conduct viscosity measurement while traditional cone-and-plate viscometers require more than 100 μ L in volume. Other miniaturized viscometers available on the market, such as the Honeybun released in 2022 by Unchained Labs®, which requires 35 μ L of sample, still needs nearly 30 times more sample than μ VASTs.

Furthermore, another advantage of μ VASTs is its throughput, as many paralleled samples can be measured without laborious instrument loading in individual capillaries. Further, each μ VAST measurement is rapid since multiple beads velocities can be collected within 3–5 s regardless of viscosity values. For comparison, the Honeybun takes 1 minute per sample at <10 cP but needs up to 8 min to measure more viscous samples, which limits measurement throughput. Although the Honeybun can measure 10 samples per device and it is one of the highest numbers of paralleled

samples reported from a viscometer, μ VASTs can measure 16 independent samples per chip and can easily be scaled up to a 24 well or 48 well system that requires less than 1 μ L of fluid samples.

In addition to practical advantages as a tool for viscosity measurement, μ VAST devices also provide a versatile platform to study the physics of fluids. It should also be noted that the maximum streaming speed examined in this study is different from the maximum streaming velocity defined at the boundary layer.^{48,49} As the viscosity of the fluid increases, the boundary layer thickness also increases; this layer has a thickness of $\sqrt{2\nu/\omega}$, where ν and ω are the kinematic viscosity of the fluid and angular frequency of the acoustic wave.^{50,51} Therefore, our measurement region was not directly at the boundary layer interface of the air–liquid interface. Furthermore, the microfluidic device has been designed and validated for Newtonian liquids. Since the viscosity of Newtonian fluids does not vary with applied shear rate, the pressure generated from acoustic microstreaming does not affect the viscosity measurement, which enables consistent measurement of the bead streaming speed. Conversely, the apparent viscosity depends on the applied shear rate for non-Newtonian fluids,⁵² which is proportional to the amount of shear that the acoustic streaming generates. Thus, by varying the input acoustic power as shown in Fig. 4b, μ VASTs have the potential to decipher the relationship between the fluid viscosity and the applied shear rate.

Uniform dispersion of the beads in the μ VASTs is important in determining the bead traveling speed, as uneven distribution within the sample liquid greatly affects the measurement accuracy. In the experiments at high viscosities (>15 cP), we found the beads do not mix uniformly in the solution, resulting in high concentrations near the air–liquid interface, making it challenging to localize single beads. On the other hand, low bead concentrations in this region results in insufficient data from small numbers of slow-traveling beads. To avoid this problem, the beads should be carefully mixed with PBS buffer and then mixed with glycerol to produce more uniform distributions.

Conclusion

In conclusion, we developed an acoustic microstreaming method to measure viscosity requiring low volumes of sample fluids. The proposed microfluidic platform had 16 independent μ VAST chambers to maximize the number of samples that can be measured. With acoustic microstreaming, the oscillation of the air–liquid interface and the speed of the beads following the fluid streaming patterns were investigated. We show that the oscillation amplitudes of the first order oscillation decreased in high viscosity fluids. Thus, the second order microstreaming velocity also decreased and the relationship between the particle speed within the microstreaming and the fluid

viscosity can be correlated. Finally, we demonstrate that the viscosity of small volume fluids, ranging from 0% to 78% glycerol mixture (1 to 50 calculated cP), can be estimated from the maximum streaming speed of beads near the air-liquid interface. The proposed method to measure viscosity requires a sample volume of approximately 1.2 μL , which is 30-fold lower than commercial viscometers.¹⁴ Moreover, the number of samples that can be measured on a single chip is 16 and future chips could be designed to accommodate even more independent wells. The operation procedure and the viscometer set-up are simple and does not require complex tubing or external syringe pumps to initiate fluid movement. We envision the μVAST viscometer can be broadly used in many applications such as antibody/protein manufacturing, point-of-care testing, blood tests or other applications in the characterization of complex fluids.

Author contributions

R. J., P. B. Y. and A. P. L. designed experiments. R. J., P. B. Y., A. M. S. conducted microfluidic device design validation, characterization, and investigation; R. J., P. B. Y. wrote the manuscript. E. P.-O., S. C. and M. M. mentored and edited manuscript. A. P. L. supervised and edited the manuscript.

Conflicts of interest

R. J., A. M. S., P. B. Y. and A. P. L. are inventors of US patent application related to this work.

Acknowledgements

The authors would like to acknowledge support from the National Science Foundation and the industrial members of the Center for Advanced Design and Manufacturing of Integrated Microfluidics (NSF I/UCRC award number IIP-1841509).

References

- 1 A. C. Anselmo, Y. Gokarn and S. Mitragotri, *Nat. Rev. Drug Discovery*, 2019, **18**, 19–40.
- 2 J. Jezek, M. Rides, B. Derham, J. Moore, E. Cerasoli, R. Simler and B. Perez-Ramirez, *Adv. Drug Delivery Rev.*, 2011, **63**, 1107–1117.
- 3 J. S. Kingsbury, A. Saini, S. M. Auclair, L. Fu, M. M. Lantz, K. T. Halloran, C. Calero-Rubio, W. Schwenger, C. Y. Airiau, J. Zhang and Y. R. Gokarn, *Sci. Adv.*, 2020, **6**, eabb0372.
- 4 G. J. Despotis and L. T. Goodnough, *Ann. Thorac. Surg.*, 2000, **70**, S20–S32.
- 5 E. W. Davie, K. Fujikawa and W. Kisiel, *Biochemistry*, 1991, **30**, 10363–10370.
- 6 F. Ciornei, S. Alaci, D. Amarandei, L. Irimescu, I. Romanu and L. Acsinte, *IOP Conf. Ser.: Mater. Sci. Eng.*, 2017, **174**, 012041.
- 7 P. Singh, K. Sharma, I. Puchades and P. B. Agarwal, *Sens. Actuators, A*, 2022, **338**, 113456.
- 8 A. Manz, D. J. Harrison, E. M. J. Verpoorte, J. C. Fettinger, A. Paulus, H. Lüdi and H. M. Widmer, *J. Chromatogr. A*, 1992, **593**, 253–258.
- 9 S. B. Puneeth, M. B. Kulkarni and S. Goel, *Eng. Res. Express*, 2021, **3**, 022003.
- 10 A. Grupi and A. P. Minton, *Anal. Chem.*, 2012, **84**, 10732–10736.
- 11 N. Srivastava and M. A. Burns, *Lab Chip*, 2006, **6**, 744–751.
- 12 I. Jang, K. E. Berg and C. S. Henry, *Sens. Actuators, B*, 2020, **319**, 128240.
- 13 B. A. Bircher, R. Krenger and T. Braun, *Sens. Actuators, B*, 2016, **223**, 784–790.
- 14 T.-V. Nguyen, M.-D. Nguyen, H. Takahashi, K. Matsumoto and I. Shimoyama, *Lab Chip*, 2015, **15**, 3670–3676.
- 15 K. Fukada and S. Shiratori, *RSC Adv.*, 2016, **6**, 38475–38480.
- 16 S.-Y. Teh, R. Lin, L.-H. Hung and A. P. Lee, *Lab Chip*, 2008, **8**, 198–220.
- 17 S. E. Mena, Y. Li, J. McCormick, B. McCracken, C. Colmenero, K. Ward and M. A. Burns, *Biomicrofluidics*, 2020, **14**, 014109.
- 18 W. Zeng and H. Fu, *Phys. Fluids*, 2020, **32**(4), 042002.
- 19 H. Chen, J. Man, Z. Li and J. Li, *ACS Appl. Mater. Interfaces*, 2017, **9**, 21059–21064.
- 20 E. Livak-Dahl, J. Lee and M. A. Burns, *Lab Chip*, 2013, **13**, 297–301.
- 21 J. Carneiro, J. B. L. M. Campos and J. M. Miranda, *Chem. Eng. Sci.*, 2019, **195**, 442–454.
- 22 Y. Li, K. R. Ward and M. A. Burns, *Anal. Chem.*, 2017, **89**, 3996–4006.
- 23 P. Arosio, K. Hu, F. A. Aprile, T. Müller and T. P. J. Knowles, *Anal. Chem.*, 2016, **88**, 3488–3493.
- 24 P. Arosio, T. Müller, L. Rajah, E. V. Yates, F. A. Aprile, Y. Zhang, S. I. A. Cohen, D. A. White, T. W. Herling, E. J. De Genst, S. Linse, M. Vendruscolo, C. M. Dobson and T. P. J. Knowles, *ACS Nano*, 2016, **10**, 333–341.
- 25 K. M. Schultz and E. M. Furst, *Lab Chip*, 2011, **11**, 3802–3809.
- 26 S. Gupta, W. S. Wang and S. A. Vanapalli, *Biomicrofluidics*, 2016, **10**, 043402–043402.
- 27 C. Chen, Y. Gu, J. Philippe, P. Zhang, H. Bachman, J. Zhang, J. Mai, J. Rufo, J. F. Rawls, E. E. Davis, N. Katsanis and T. J. Huang, *Nat. Commun.*, 2021, **12**, 1118.
- 28 P. Zhang, H. Bachman, A. Ozcelik and T. J. Huang, *Annu. Rev. Anal. Chem.*, 2020, **13**, 17–43.
- 29 Y. Gao, M. Wu, Q. Luan, I. Papautsky and J. Xu, *Lab Chip*, 2022, **22**, 805–813.
- 30 J. Zhang, S. Yang, C. Chen, J. H. Hartman, P.-H. Huang, L. Wang, Z. Tian, P. Zhang, D. Faulkenberry, J. N. Meyer and T. J. Huang, *Lab Chip*, 2019, **19**, 984–992.
- 31 W. Zhang, B. Song, X. Bai, L. Jia, L. Song, J. Guo and L. Feng, *Lab Chip*, 2021, **21**, 4760–4771.
- 32 D. Ahmed, A. Ozcelik, N. Bojanala, N. Nama, A. Upadhyay, Y. Chen, W. Hanna-Rose and T. J. Huang, *Nat. Commun.*, 2016, **7**, 11085.
- 33 P. A. Janmey, P. C. Georges and S. Hvidt, in *Methods in Cell Biology*, Academic Press, 2007, vol. 83, pp. 1–27.

- 34 F. Carrasco, E. Chornet, R. P. Overend and J. Costa, *J. Appl. Polym. Sci.*, 1989, **37**, 2087–2098.
- 35 S. Yadav, S. Shire and D. Kalonia, *Pharm. Res.*, 2011, **28**, 1973–1983.
- 36 W. Thielicke and R. Sonntag, *J. Open Res. Softw.*, 2021, **9**(1), 12.
- 37 J. Schindelin, I. Arganda-Carreras, E. Frise, V. Kaynig, M. Longair, T. Pietzsch, S. Preibisch, C. Rueden, S. Saalfeld, B. Schmid, J. Y. Tinevez, D. J. White, V. Hartenstein, K. Eliceiri, P. Tomancak and A. Cardona, *Nat. Methods*, 2012, **9**, 676–682.
- 38 M. Aghaamoo, Y.-H. Chen, X. Li, N. Garg, R. Jiang, J. T.-H. Yun and A. P. Lee, *Adv. Sci.*, 2022, **9**, 2102021.
- 39 N. Garg, T. M. Westerhof, V. Liu, R. Liu, E. L. Nelson and A. P. Lee, *Microsyst. Nanoeng.*, 2018, **4**, 17085.
- 40 R. Jiang, S. Agrawal, M. Aghaamoo, R. Parajuli, A. Agrawal and A. P. Lee, *Lab Chip*, 2021, **21**, 875–887.
- 41 M. V. Patel, I. A. Nanayakkara, M. G. Simon and A. P. Lee, *Lab Chip*, 2014, **14**, 3860–3872.
- 42 A. R. Tovar, M. V. Patel and A. P. Lee, *Microfluid. Nanofluid.*, 2011, **10**, 1269–1278.
- 43 P. Marmottant and S. Hilgenfeldt, *Nature*, 2003, **423**, 153–156.
- 44 P. Marmottant and S. Hilgenfeldt, *Proc. Natl. Acad. Sci. U. S. A.*, 2004, **101**, 9523–9527.
- 45 A. R. Tovar and A. P. Lee, *Lab Chip*, 2009, **9**, 41–43.
- 46 D. L. Miller, *J. Acoust. Soc. Am.*, 1988, **84**, 1378–1387.
- 47 N. Garg, D. Boyle, A. Randall, A. Teng, J. Pablo, X. Liang, D. Camerini and A. P. Lee, *Lab Chip*, 2019, **19**, 1524–1533.
- 48 N. F. Läubli, J. T. Burri, J. Marquard, H. Vogler, G. Mosca, N. Vertti-Quintero, N. Shamsudhin, A. deMello, U. Grossniklaus, D. Ahmed and B. J. Nelson, *Nat. Commun.*, 2021, **12**, 2583.
- 49 N. F. Läubli, M. S. Gerlt, A. Wüthrich, R. T. M. Lewis, N. Shamsudhin, U. Kutay, D. Ahmed, J. Dual and B. J. Nelson, *Anal. Chem.*, 2021, **93**, 9760–9770.
- 50 C. Chen, S. P. Zhang, Z. Mao, N. Nama, Y. Gu, P.-H. Huang, Y. Jing, X. Guo, F. Costanzo and T. J. Huang, *Lab Chip*, 2018, **18**, 3645–3654.
- 51 M. Wiklund, R. Green and M. Ohlin, *Lab Chip*, 2012, **12**, 2438–2451.
- 52 F. Del Giudice, G. D'Avino, F. Greco, I. De Santo, P. A. Netti and P. L. Maffettone, *Lab Chip*, 2015, **15**, 783–792.