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an importance learning algorithm**

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Site-averaged kinetics for catalysts on amorphous supports: an importance learning algorithm

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Ab initio calculations have greatly advanced our understanding of homogeneous catalysts and crystalline heterogeneous catalysts. In contrast, amorphous heterogeneous catalysts remain poorly understood. The principal difficulties include (i) the nature of the disorder is quenched and unknown; (ii) each active site has a different local environment and activity; (iii) active sites are rare, often less than ~20% of potential sites, depending on the catalyst and its preparation method. Few (if any) studies of amorphous heterogeneous catalysts have ever attempted to compute site-averaged kinetics, because the exponential dependence on variable activation energy requires an intractable number of *ab initio* calculations to converge. We present a new algorithm using machine learning techniques (metric learning kernel regression) and importance sampling to efficiently learn the distribution of activation energies. We demonstrate the algorithm by computing the site-averaged activity for a model amorphous catalyst with quenched disorder.

Introduction

A recent surge of interest in atomically-dispersed “single atom” catalysts is driven by their unique and potentially selective reactivity,¹⁻³ and by sustainability efforts that seek to minimize use of scarce elements and maximize atom economy.⁴⁻⁶ Among single atom catalysts, those which are chemically bonded to a thermally robust oxide support like silica are especially resistant to deactivation by sintering.^{7, 8} Moreover, grafting strategies that promote selective reaction of the catalyst precursor at specific surface sites may help to minimize differences between grafted metal sites. Well-studied catalysts that are comprised of single metal atoms grafted onto amorphous silica include chromocenes or chromates for olefin polymerization,⁹⁻¹¹ titanium and tantalum complexes for olefin epoxidation,¹² molybdates for methanol dehydration,¹³ and vanadates for partial oxidation of methanol.¹⁴

Investigators have occasionally drawn comparisons between the metal atoms present in the active sites in enzymes, and metal atoms grafted onto silica surfaces.¹² There are similarities, but there are also important differences. Each enzyme molecule of a given type is the same, while each metal atom on amorphous silica resides in a unique ligand environment. These non-uniform environments can result in metal atoms with non-uniform catalytic properties, including a range of activities, selectivities, adsorption constants, and even different spectroscopic features. When the sites have variable activities,

a minority of the sites may contribute most of the overall catalyst activity. Indeed, active site counting experiments confirm that only a small fraction of sites in a heterogeneous catalyst is typically active.¹⁵⁻¹⁸ This poses an extraordinary difficulty in experimental as well as theoretical studies of these catalysts. Powerful characterization tools (NMR, EXAFS, IR, Raman, etc.) generally provide the strongest signals for the most common sites, and these are likely inactive.¹¹

If we could understand the mechanisms of these catalysts, we might systematically work to improve them.¹⁹ In some applications like olefin polymerization, where the catalysts are not recovered from the polymer product, one might even use mechanistic understanding to design catalysts with a desired activity distribution capable of generating polymer with a desired molecular weight distribution.

Our first paper introduced a method to predict the distribution of sites that emerges from grafting a precursor onto an amorphous support.²⁰ The simple model system consisted of a quenched-disordered lattice (to represent the amorphous silica support), surface functional groups (representing pairs or nests of hydroxyl groups) to which a metal complex can be grafted, and a microkinetic model for each grafted site with rate parameters that depend on the site characteristics. Much like in an *ab initio* study, computing activation barriers for the model system requires geometry optimizations of intermediates. Our realistic but simple model allowed us to focus on developing the importance sampling and machine learning tools, without being distracted by controversies about the mechanisms about the mechanisms of these catalysts.

Starting from the simple model and the grafted site population described in our first paper,²⁰ this second paper aims to compute an average over sites to predict the overall kinetics. Since the turnover frequencies at individual sites vary exponentially with the activation energy, even a small variance in the activation energy leads to an enormous variance in site-specific activities. Such exponential averages are notoriously difficult to converge

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with standard sampling tools,²¹⁻²³ but importance sampling methods can dramatically accelerate convergence. The ideal importance sampling algorithm²⁴ requires activation energies for each site, but these activation energies are not known *a priori*. Each activation energy must be obtained through costly *ab initio* calculations. Because of this limitation, typical approaches calculate just one^{25,26} or a small handful of sites²⁷⁻³⁴ – far too few to converge site-averaged predictions of kinetic properties.³⁵ Kernel regression tools can use a modest set of *ab initio* calculations to predict activation energies that have not actually been computed. This paper shows how importance sampling and machine learning can be combined to generate site-averaged predictions efficiently.

In the remainder of this paper, we discuss model elementary steps and a rate law for a catalytic reaction with our simple model system. We briefly review the kernel regression tools (from our first paper) that predict activation energies. We combine the importance sampling and kernel regression tools into an “importance learning algorithm”. We then use the new algorithm to identify characteristics of highly active sites and to estimate site-averaged activation energies. Finally, we compare the efficiency of importance sampling estimates to straightforward sampling.

Model for amorphous support and grafted sites

Our previous paper described the creation of a disordered, functionalized lattice model to approximate the non-uniform silanol sites and siloxane environments on the surface of amorphous SiO₂. That paper also considered a kinetic model for grafting of metal atoms onto the silanol sites. All sites with two silanol neighbors and two siloxane neighbors on opposite sides were eligible grafting sites in the model. A schematic of the simple model is shown in Fig. 1.

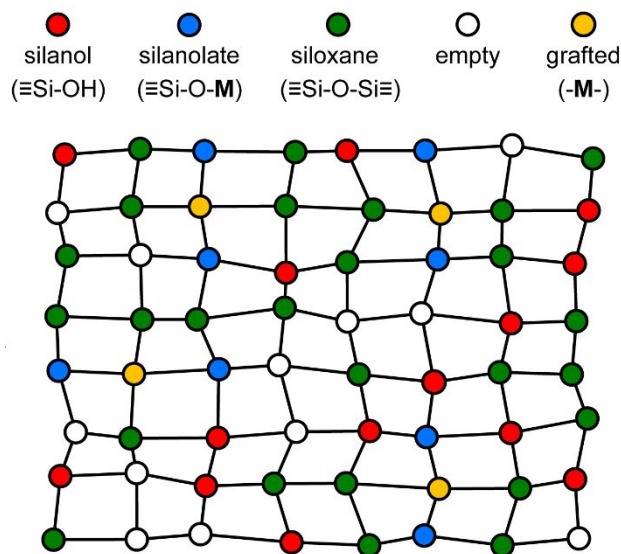


Fig. 1 Quenched disorder lattice model. Sites with a grafted metal center are shown in gold.

This paper uses the distribution of non-uniform grafted sites, like those shown in Fig. 1, as its starting point. We assume that grafting has occurred at all eligible sites, but one could modify the starting distribution (using methods in the previous paper²⁰) to investigate lower catalyst loadings.

The discussion below invokes bonds between metal atoms and adsorbates, as well as the oxygen atoms of the silanol and siloxane sites. However, the local environment of each site (before grafting and during catalysis) is described entirely by the positions of atoms in the silica support surrounding the metal center. The coordinates used to describe the local environment are shown in Fig. 2. They are: (i) the distance between siloxane groups, d_1 , (ii) the distance between silanolate groups, d_2 , and (iii) the angle between the silanolate and siloxane groups, θ .

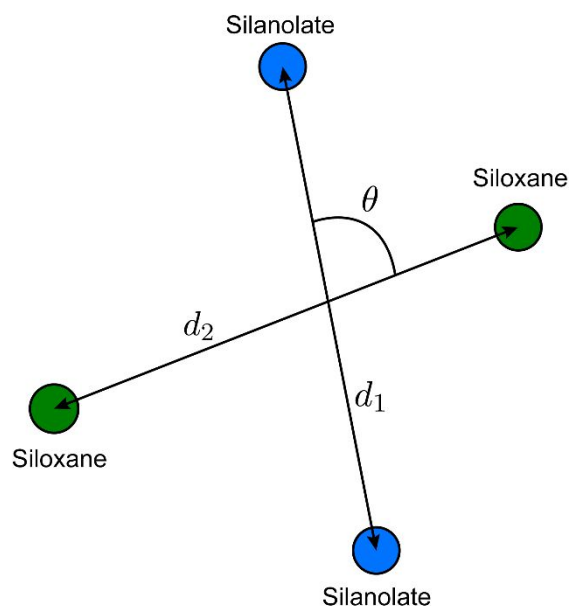


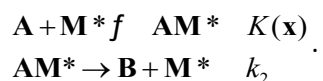
Fig. 2 Coordinates used to describe the local environment of a grafting site.

The selected coordinates are nearly orthogonal in the sense that their gradients have little or no overlap. Note, however, that the coordinates are incomplete. For a grafting site on our two dimensional surface model, the four nearest neighbors are fully described by five internal coordinates ($8 - 2 \times (\text{center of mass}) - 1 \times (\text{rotation})$). We use only three coordinates in the kernel regression model, and the results below will show that just two of these coordinates are sufficient to predict site-averaged kinetics. We also emphasize that some calculations below involve other coordinates at intermediate stages, but that the overall kinetics and the kinetics of individual sites ultimately depends only on the coordinates in Fig. 2.

Model for catalysis at grafted sites

We consider a simple model of a catalyst site, \mathbf{M}^* , comprised of a metal center \mathbf{M} and its surrounding support environment, $*$. We will consider the case in which the catalytic reaction at each site has the same rate-limiting step and the same most abundant

surface intermediate (MASI). We further assume that the site does not deactivate. The model reaction has a simple Langmuir-Hinshelwood mechanism:



We further assume that

- (i) the equilibrium constant K for adsorption of reactant \mathbf{A} depends on the local environment of site i , \mathbf{x}_i ,
- (ii) the adsorbed molecule \mathbf{A} (\mathbf{AM}^*) is irreversibly converted into the gas phase product \mathbf{B} and a bare site \mathbf{M}^* ,
- (iii) $K(\mathbf{x})c_A \ll 1$ for all sites, so that the bare site \mathbf{M}^* is the MASI.

The bond strengths chosen in this work, described below, ensure that these three assumptions are true for all sites. Fig. 3 depicts the Langmuir-Hinshelwood mechanism and the three simplifying assumptions for the simple model system in this work.

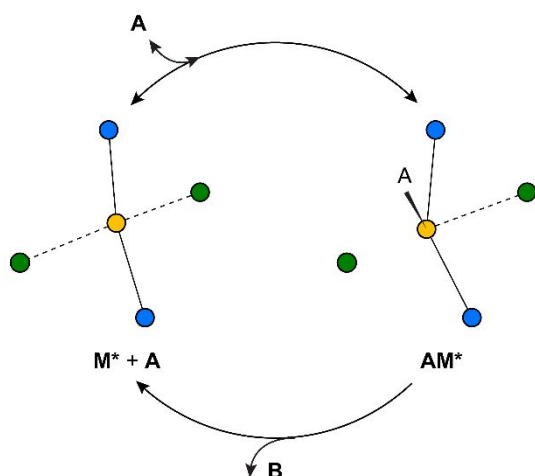


Fig. 3 The equilibrated adsorption step and irreversible chemical reaction steps for the model reaction $\mathbf{A} \rightarrow \mathbf{B}$, and the \mathbf{M}^* sites described in this work.

The Langmuir-Hinshelwood mechanism leads to a rate law of form

$$r = \frac{k_2 K(\mathbf{x}) c_A}{1 + K(\mathbf{x}) c_A} \quad (1)$$

Because of assumption (iii), the rate law simplifies to a power law rate expression of the form

$$r = k(\mathbf{x}) c_A \quad (2)$$

where the pseudo-first-order rate constant is:

$$k(\mathbf{x}) = k_2 K(\mathbf{x}) \quad (3)$$

Note that we have also assumed that the rate constant k_2 for the second step in the Langmuir-Hinshelwood mechanism is the

same for all sites. In principal, k_2 could also depend on \mathbf{x} , but a model for $k_2(\mathbf{x})$ would require additional parameters to create a model for the saddle region on the potential energy surface. The more elaborate model system with \mathbf{x} -dependence in k_2 would still lead to an apparent rate constant $k_2 K$ that is one function of \mathbf{x} .

The apparent rate constant $k(\mathbf{x})$ depends on the local site geometry through $K(\mathbf{x})$. The adsorption constant is

$$K(\mathbf{x}) = \exp\left[-\frac{\Delta H(\mathbf{x}) - T\Delta S}{k_B T}\right] \quad (4)$$

where $\Delta H(\mathbf{x})$ is a site-dependent adsorption enthalpy. $T\Delta S$ is assumed to be constant because its main contributions are the loss of translational and rotational freedom upon adsorption. The rate constant, according to transition state theory, will be of the form

$$k_2 = \frac{k_B T}{h} \exp\left[\frac{\Delta S^\ddagger}{k_B}\right] \exp\left[-\frac{\Delta H^\ddagger}{k_B T}\right] \quad (5)$$

Here, the entropy and enthalpy of activation for the reaction step are assumed to be the same for all sites.

The site-dependent enthalpy of adsorption, $\Delta H(\mathbf{x})$, is modeled by

$$\Delta H(\mathbf{x}) = V_{\mathbf{AM}^*}(\mathbf{x}) - (V_{\mathbf{M}^*}(\mathbf{x}) + \varepsilon_A + k_B T) \quad (6)$$

where \mathbf{x} is the position of \mathbf{M} , $V_{\mathbf{AM}^*}(\mathbf{x})$ is the energy with \mathbf{A} chemisorbed to the metal site, $V_{\mathbf{M}^*}(\mathbf{x})$ is the energy of the bare metal site, ε_A is the gas phase energy of \mathbf{A} , and $k_B T$ is the PV contribution to the gas phase enthalpy of \mathbf{A} . The same Morse potentials that we used to model grafting²⁰ are now used to describe the $\mathbf{M}\text{-OSi}\equiv$ bond energies and $\mathbf{M}\cdots(\text{OSi}\equiv)_2$ bond energies. Specifically, the individual interaction energies are

$$\varepsilon_i(r) = D_i \left(1 - \exp\left[-a_i(r - r_{i,eq})^2\right]\right) - D_i \quad (7)$$

where i is the bond type, D_i is the bond dissociation energy, a_i is inversely related to the vibrational well width, r is the bond length, and $r_{eq,i}$ is its equilibrium bond length. The energy of the bare metal site is

$$V_{\mathbf{M}^*}(\mathbf{x}) = \varepsilon_{\mathbf{M}\text{-O}}(r_1) + \varepsilon_{\mathbf{M}\text{-O}}(r_2) + \varepsilon_{\mathbf{M}\cdots\text{O}}(r'_1) + \varepsilon_{\mathbf{M}\cdots\text{O}}(r'_2) \quad (8)$$

where $\varepsilon_{\mathbf{M}\text{-O}}(r_i)$ is the energy of the $\mathbf{M}\text{-OSi}\equiv$ bonds, r_i is the metal-oxygen bond distance, $\varepsilon_{\mathbf{M}\cdots\text{O}}(r'_i)$ is the energy of the $\mathbf{M}\cdots(\text{OSi}\equiv)_2$ metal-siloxane bond, and r'_i is the metal-siloxane bond distance.

We model adsorption of \mathbf{A} onto the grafted metal center as an $\mathbf{M}\text{-A}$ bond with energy $\varepsilon_{\mathbf{M}\text{-A}}$. The length of the $\mathbf{M}\text{-A}$ bond is not explicitly optimized. Instead, we assume that the $\mathbf{M}\text{-A}$ bond displaces the longest and most weakly-coordinated siloxane ($\mathbf{M}\cdots(\text{OSi}\equiv)_2$) from \mathbf{M} . The displaced siloxane can still exert a

repulsive interaction on **M**. We model the close-range repulsion with a Weeks-Chandler-Andersen potential:³⁶

$$\varepsilon_{\text{AML O}}^{\text{WCA}}(r) = D_{\text{AML O}} \left(1 - \exp \left[-a_{\text{AML O}} (r - r_{\text{AML O,eq}})^2 \right] \right) \quad (9)$$

for $r \leq r_{\text{AM}\cdots\text{O,eq}}$ and $\varepsilon_{\text{AML O}}^{\text{WCA}}(r) = 0$ otherwise. Thus, the energy of state **AM*** is

$$V_{\text{AM}^*}(\mathbf{x}) = \varepsilon_{\text{M-A}} + \varepsilon_{\text{M-O}}(r_1) + \varepsilon_{\text{M-O}}(r_2) + \varepsilon_{\text{ML O}}(r_1^{\uparrow}) + \varepsilon_{\text{ML O}}^{\text{WCA}}(r^*) \quad (10)$$

where r^* is the longest **M**⋯**O** bond prior to the adsorption of **A**. With these definitions, eqn. (6) presents a geometry optimization problem much like that encountered in *ab initio* calculations. The interior atoms must be optimized subject to constraints on peripheral atoms around the metal center. The equilibrium configurations of **M*** and **AM*** are found by changing the **M** atom position with fixed silanolate and siloxane group positions to minimize (8) and (10), respectively. This procedure creates a collection of model sites with quenched disorder and limited local flexibility, somewhat like a real amorphous catalyst.

Parameter selection

The quenched disordered lattice was created by starting with a square lattice with spacing 1. Random displacements of the lattice sites were drawn from an isotropic 2D Gaussian distribution with $\sigma_{\text{lattice}}^2 = 0.00022$ in the x and y directions. We used the same fractions of silanol, siloxane, and empty sites ($f_{\text{silanol}} = 0.3$, $f_{\text{siloxane}} = 0.3$, and $f_{\text{empty}} = 0.4$) as our previous paper.²⁰ All rate calculations in this work were performed for a temperature of 300 K and a reactant pressure of 1 atm. The metal-adsorbate bond dissociation energy was modeled as the Cr-C bond dissociation energy for a $(\equiv\text{SiO})_2\text{Cr}^{\text{III}}$ alkyl site – the widely accepted active site for Cr/SiO₂ olefin polymerization catalysts.^{11, 37} Based on DFT calculations (Section S1) and reported values for the Cr-C bond,³⁸ we set $\varepsilon_{\text{M-A}} = 160$ kJ/mol. A list of the parameters and their values are summarized in Table 1.

Table 1: Parameter values for the quenched disorder lattice, Langmuir-Hinshelwood mechanism, and model chemistry

Parameter	Value
T	300K
P _A	1 atm
ΔH [‡]	65 kJ/mol
σ ² _{lattice}	0.00022
f _{Silanol}	0.3
f _{Siloxane}	0.3
f _{Empty}	0.4
D _{M-O}	120 kJ/mol
a _{M-O}	1.3
r [‡] _{M-O,eq}	1.16
D _{M-O}	500 kJ/mol
a _{M-O}	1.7
r [‡] _{M-O,eq}	1.0
ε _A	0
ε _{M-A}	160 kJ/mol

Site-averaged kinetics

Each metal site has a unique environment, and the different environments lead to a distribution of kinetic properties. For example, the sites will exhibit a distribution of turnover frequencies and activation energies. In contrast, a conventional experiment measures just one site-averaged value for each kinetic property. In this paper, we focus on the site-averaged activation energy. From eqns. (2)-(5), the activation energy for site *i* is

$$E_a(\mathbf{x}_i) = -\frac{d \ln r_i}{d\beta} = \Delta H(\mathbf{x}_i) + \Delta H^{\ddagger} + 2k_B T \quad (11)$$

where $\beta = 1/k_B T$. A derivation of eqn. (11) can be found in section S2 of the supplemental information. In this calculation, we assume that E_a , ΔS , ΔS^{\ddagger} , and ΔH^{\ddagger} are not functions of temperature.³⁹ For ΔH , the temperature dependence from $k_B T$ (eqn. 6) is considered, but other temperature-dependent terms such as partition functions are ignored. (In practice, all of these properties will probably exhibit some temperature dependence.)

Naively, one might estimate $E_a(\mathbf{x})$ for a large sample of sites and then average them to obtain the site-averaged activation energy. This straightforward average does not give the correct value, even in the limit of large sample sizes. The correct site-averaged activation energy,⁴⁰ $\langle E_a \rangle_k$ is obtained from a derivative of the site-averaged rate:

$$\begin{aligned}
 \langle E_a \rangle_k &\equiv -\partial \ln \langle r \rangle / \partial \beta \\
 &= -\frac{\partial}{\partial \beta} \ln \int d\mathbf{x} \rho(\mathbf{x}) k(\mathbf{x}) \prod_i c_i^{\alpha_i} \\
 &= -\frac{\int d\mathbf{x} \rho(\mathbf{x}) \partial k(\mathbf{x}) / \partial \beta}{\int d\mathbf{x} \rho(\mathbf{x}) k(\mathbf{x})} \\
 &= \frac{\int d\mathbf{x} \rho(\mathbf{x}) k(\mathbf{x}) \{E_a(\mathbf{x}) + \beta E_a(\mathbf{x}) \partial \ln E_a(\mathbf{x}) / \partial \beta\}}{\int d\mathbf{x} \rho(\mathbf{x}) k(\mathbf{x})} \\
 &= \langle E_a \{1 + \beta \cdot \partial \ln E_a / \partial \beta\} \rangle_{\rho(\mathbf{x})k(\mathbf{x})}
 \end{aligned} \tag{12}$$

In this work, we ignore the temperature dependence of E_a . In practice, the rates at individual sites cannot be probed, nor are the temperature intervals in which the rates are measured wide enough to see definitive curvature in the Arrhenius plot. We also expect the correction to be small. Using E_a from eqn. (11), $\beta \partial \ln E_a / \partial \beta = 2\beta^{-1}$, which will be relatively small compared to a typical $E_a(\mathbf{x})$. Moreover, we anticipate that $\beta \partial \ln E_a / \partial \beta$ term will be similar across different sites, so that conclusions about characteristics of highly active and abundant sites will be unaffected. Using eqns. (2)-(5), the derivatives and integrations yield:

$$\langle E_a \rangle_k = \langle \Delta H(\mathbf{x}) + \Delta H^\ddagger + 2k_B T \rangle_k \tag{13}$$

The subscript k indicates that the average is computed with probability weights $\rho(\mathbf{x})k(\mathbf{x})$, instead of $\rho(\mathbf{x})$. In practice, this average can be computed in two different ways.

The first strategy is to randomly choose sites from $\rho(\mathbf{x})$ and reweight each of them by $k(\mathbf{x})$ when computing the average:

$$\bar{E}_a^{\rho} = \sum_{i=1}^n k(\mathbf{x}_i) E_a(\mathbf{x}_i) / \sum_i k(\mathbf{x}_i) \tag{14}$$

The numerator and denominator are both exponential averages. As shown in previous work,³⁵ this strategy usually requires an enormous sample size to converge.

The second strategy is to directly sample sites according to probability weight $\rho(\mathbf{x})k(\mathbf{x})$. This is difficult, because we do not know $k(\mathbf{x})$ precisely prior to performing *ab initio* calculations at \mathbf{x} . However, if such a sampling algorithm could be devised (see below), the site-averaged activation energy would become a simple arithmetic average:

$$\bar{E}_a = \frac{1}{n} \sum_{i=1}^n E_a(\mathbf{x}_i) \tag{15}$$

This second strategy enables fast convergence to the site-averaged activation energy according to the central limit theorem. Confidence intervals on the precision of E_a follow from the usual statistical formulae

$$\langle E_a \rangle_k = \bar{E}_a \pm \frac{1}{\sqrt{n}} \hat{S}_{E_a} t_{X,n} \tag{16}$$

where $t_{X,n}$ is the student-t statistic for an $X\%$ confidence interval with sample size n , and where the standard error is:

$$\hat{S}_{E_a}^2 = \frac{n}{n-1} \left\{ \overline{E_{a,i}^2} - \overline{E_{a,i}}^2 \right\} \tag{17}$$

Of course, these estimates and error formulas do not account for systematic errors in the *ab initio* predictions. Moreover, to sample the distribution $\rho(\mathbf{x})k(\mathbf{x})$, we use a kernel regression model to predict $k(\mathbf{x})$ at sites that have not yet been investigated. The error formulas above also do not account for errors in the kernel regression estimates. In our calculations, the kernel regression errors are much smaller than the intrinsic width of the E_a -distribution, so they can probably be ignored. However, section S3 of the supplemental information shows how the typical kernel regression errors could be included in cases where they are large enough to be important.

Kernel regression

To sample the distribution $\rho(\mathbf{x})k(\mathbf{x})$ starting from a large collection of sites, *i.e.*, from $\rho(\mathbf{x})$, we require preliminary estimates for $k(\mathbf{x})$ at each site. Given *accurate* calculations as training data at a modest collection of sites, kernel regression can estimate $E_a(\mathbf{x})$ at all the remaining sites.^{41,42} The estimated activation energy at site with environment \mathbf{x}_i is a weighted average of the training data, eqn. (18):

$$\hat{E}_a(\mathbf{x}_i) = \frac{\sum_j E_a(\mathbf{x}_j) w_{ij}(d(\mathbf{x}_i, \mathbf{x}_j))}{\sum_j w_{ij}(d(\mathbf{x}_i, \mathbf{x}_j))} \tag{18}$$

Here $\hat{E}_a(\mathbf{x}_i)$ is the predicted activation energy, and the $E_a(\mathbf{x}_j)$ are computed activation energies. The w_{ij} are Gaussian kernels

$$w_{ij} = \exp[-d^2(\mathbf{x}_i, \mathbf{x}_j)] \tag{19}$$

that depend on a Mahalanobis distance,⁴³ d :

$$d^2(\mathbf{x}_i, \mathbf{x}_j) = (\mathbf{x}_i - \mathbf{x}_j)^T \mathbf{S}(\mathbf{x}_i - \mathbf{x}_j) \tag{20}$$

Here, \mathbf{S} is a $\dim(\mathbf{x}) \times \dim(\mathbf{x})$ dimensional, positive definite, and symmetric matrix. The kernel regression model is trained by finding the elements of \mathbf{S} which minimizes the leave-one-out loss to best fit the training data. We use Python library tools to implement the kernel regression.⁴⁴ Further details about the kernel regression procedures can be found in the companion paper and its supplemental information.²⁰

Importance learning algorithm

The sections above described rate calculations at individual sites, an importance sampling procedure, and a kernel regression (machine learning) procedure. This section integrates all of these components into one "importance learning" algorithm. Importance learning simultaneously accumulates training data, builds the kernel regression model, and focuses

computational effort on kinetically important sites with low activation barriers. The algorithm is shown in Fig. 4.

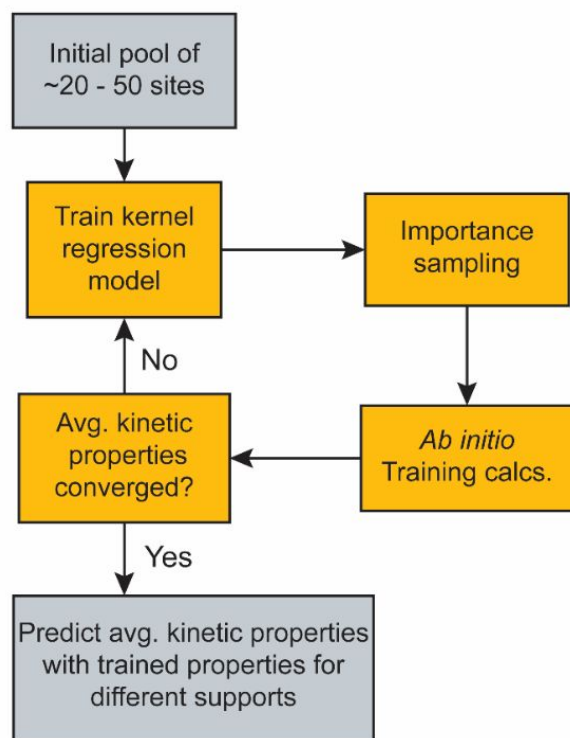


Fig. 4 The combination of efficient sampling techniques and a machine learning model leads to the “importance learning” algorithm. A set of sites trains a model to learn characteristics of highly active (*i.e.*, important) sites. Efficient sampling techniques select active sites to improve the model and to efficiently predict average kinetic properties. A test for convergence terminates the algorithm when the confidence interval on the site-averaged activation energy shrinks to a prescribed narrow size. In our calculations, the threshold confidence interval was set to 0.75 kJ/mol.

Note that the importance sampling and kernel regression procedures mutually depend on each other. The kernel regression model guides the importance sampling to kinetically important sites. Meanwhile, the accumulated sample of sites and rate calculations teach kernel regression to make accurate preliminary rate predictions.

To compute kinetic properties, precise rate calculations for less active sites are not important, but we need their populations to predict kinetic properties like the overall rate and the fraction of active sites. Therefore, the kernel regression model should also learn to make approximate predictions for inactive sites. For this reason, the importance learning algorithm begins with rate calculations at a collection of randomly sampled sites. We verified that an initial training set of 20-50 randomly chosen sites is adequate (section S4 in the supplemental information).

Results

Because the model system is extremely simple, an accurate site-averaged activation energy can be directly calculated without importance learning. Using results for ~20,000 sites, we computed the activation energy distribution:

$$\rho(E_a) = \int d\mathbf{x} \rho(\mathbf{x}) \delta[E_a(\mathbf{x}) - E_a] \quad (21)$$

and the $k(\mathbf{x})$ -weighted activation energy distribution:

$$\rho_k(E_a) = \frac{\int d\mathbf{x} \rho(\mathbf{x}) k(\mathbf{x}) \delta[E_a(\mathbf{x}) - E_a]}{\int d\mathbf{x} \rho(\mathbf{x}) k(\mathbf{x})} \quad (22)$$

Fig. 5 shows the essentially exact distributions $\tilde{\rho}(E_a)$ and $\tilde{\rho}_k(E_a)$. The activation energy distribution has support⁴⁵ over a range of about 40 kJ/mol. The site-averaged activation energy is 40.4 kJ/mol, about 13 kJ/mol below the (incorrect) average without k -weighting. These results serve as benchmarks for testing the importance learning algorithm.

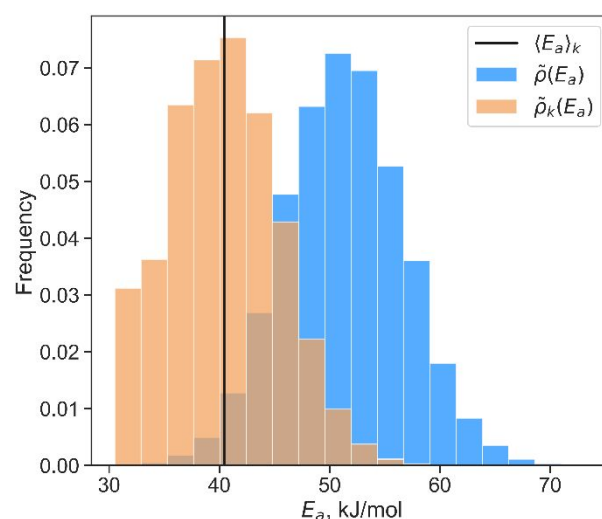


Fig. 5 Distribution of activation energies (blue) and the rate-weighted activation energy distribution (orange). The solid line shows the site-averaged activation energy.

To start the importance learning algorithm, we began with an initial training set of fifty randomly chosen sites. The initial kernel regression model was optimized to minimize the leave-one-out errors. Within this initial training set, the kernel regression model predicts activation energies with a standard error $\sigma \approx 0.8$ kJ/mol. Fig. 6 shows how the predicted activation energies compare to the true (precisely computed via eqn. 11) activation energies for individual sites.

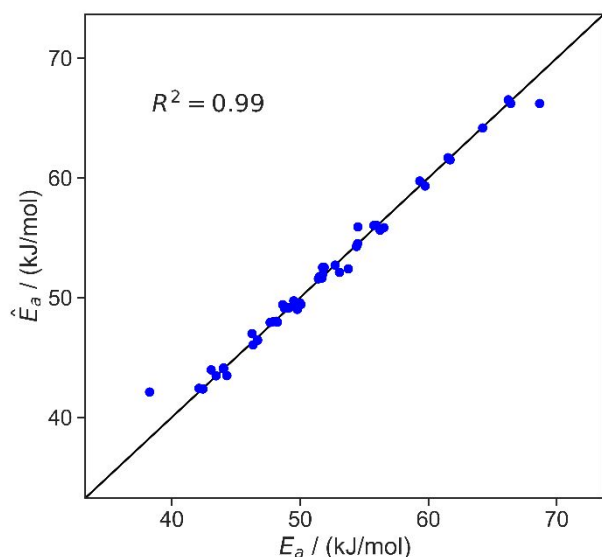


Fig. 6 Parity plot of predicted activation barriers vs true activation barriers at individual sites. Predictions are from leave-one-out optimization of kernel regression models based on the initial training set of 50 sites. The residuals for all ~20,000 sites are approximately Gaussian distributed, with a standard deviation of approximately 0.7 kJ/mol (Fig S3).

At each iteration of the importance learning algorithm, the activation energy distributions $\tilde{\rho}(E_a)$ and $\tilde{\rho}_k(E_a)$ can be predicted using the kernel regression model. After each iteration, the new calculations are appended to the training set. As more training data is accumulated (primarily at low activation energies), the estimated E_a distributions should become more like the true distribution in the kinetically important range of activation energies. As a corollary, the site-averaged activation energy should also converge to the correct value. Fig. 7 shows the predicted distributions at the 0th and 28th iterations of importance learning (the latter being the iteration at which the standard error decreases below 0.75 kJ/mol). A rug shows that the activation energies of the importance sampled sites are indeed centered over the main support of $\tilde{\rho}_k(\hat{E}_a)$.

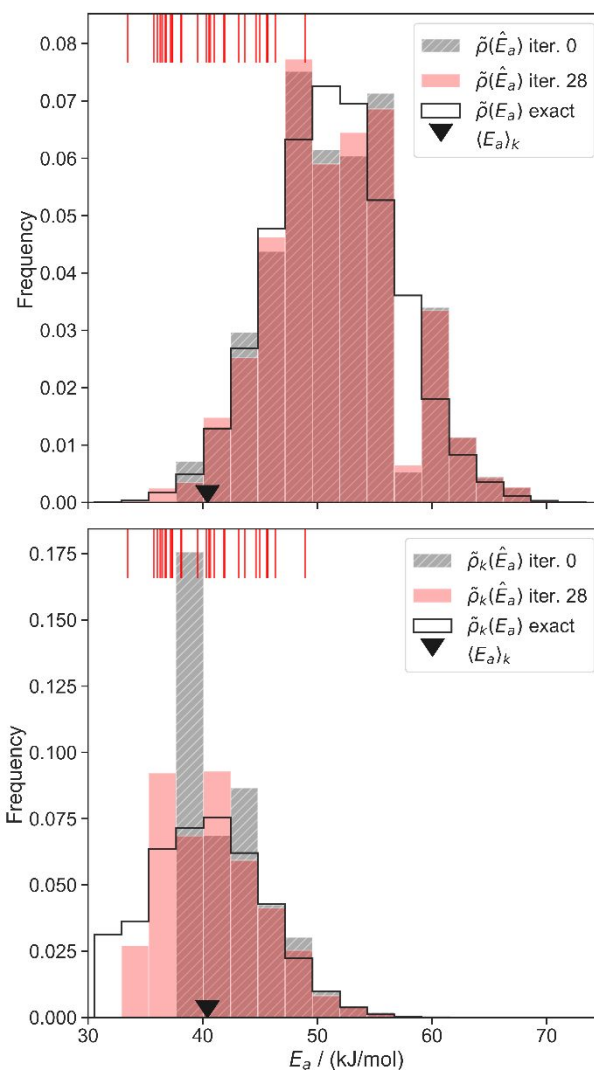


Fig. 7 Model-predicted activation energy distribution for the unweighted (top) and k-weighted (bottom) distributions at iteration 0 (grey, hatched) and 28 (red) of the importance learning algorithm. Apparent activation energies of importance sampled sites are shown as a rug at the top of each plot. The \blacktriangledown symbol shows the correct site averaged E_a .

Prior to importance learning, the initial training set contained only one site with an activation energy under 40 kJ/mol. Importance learning discovers sites with activation energies below 40 kJ/mol, which dominate the overall kinetics. After 28 iterations of importance learning, the low activation energy tail of the predicted $\tilde{\rho}(\hat{E}_a)$ closely resembles that of the exact $\tilde{\rho}(E_a)$. More importantly, the main support of the predicted $\tilde{\rho}_k(\hat{E}_a)$ closely resembles that of the exact $\tilde{\rho}(E_a)$. Both distributions are inaccurately predicted at high activation energies, but these sites make vanishingly small contributions to the observed kinetics. They only need to be counted in the normalization of $\tilde{\rho}(E_a)$ to predict the kinetic properties.

Fig. 8 shows the convergence of $\langle E_a \rangle_k$ estimates from importance sampling using standard errors. A higher degree of confidence could also be computed using eqn. (16).

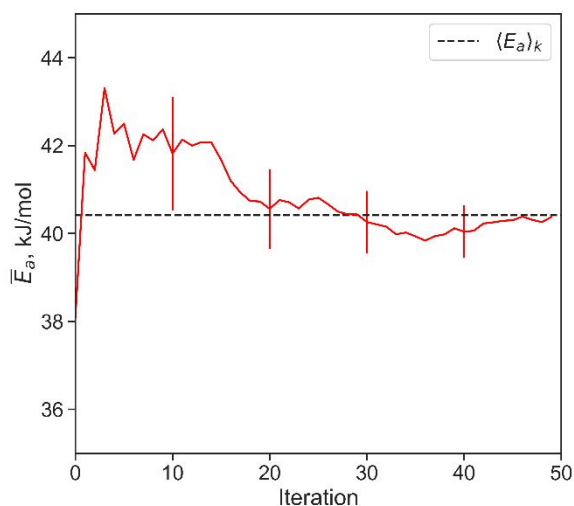


Fig. 8 The importance learning algorithm converges to within 0.75 kJ/mol of the correct site-averaged E_a in 28 iterations. By comparison, a reweighted random sample requires about 200,000 samples to compute \tilde{E}_a with the same level of confidence (section S5).

Identifying characteristics of active sites

In real applications, optimizing the Mahalanobis matrix is inexpensive compared to generating training data from *ab initio* calculations. Therefore, an importance learning calculation can include all potentially important coordinates. However, a central goal of these calculations is to discover those few key characteristics that distinguish active from inactive sites. Intuition would suggest that the most important coordinates can be identified from the largest diagonal elements in the Mahalanobis matrix. The optimized matrix obtained in this work, using d_1 , d_2 , and θ , is:

$$S = \begin{bmatrix} d_1 & & \\ & d_2 & \\ & & \theta \end{bmatrix} = \begin{bmatrix} 77068 & -56512 & -45 \\ -56512 & 41440 & 32 \\ -45 & 32 & 0 \end{bmatrix} \quad (23)$$

Coordinates d_1 and d_2 have the largest diagonal elements, and they indeed have the strongest influence on site activity. The coordinates d_1 and d_2 correspond to silanolate – silanolate distances and siloxane – siloxane distances, respectively. In hindsight, these coordinates should have primary importance because the potential energies are defined in terms of these coordinates.

In general, the diagonal matrix elements are not reliable indicators of the most important structural characteristics. For example, the diagonal matrix elements change magnitude depending on the units used to represent the coordinates. In

addition, diagonal matrix elements indicate sensitivity to local structural changes. They do not account for differences in the extent to which sites vary along different structural coordinates within the global ensemble of sites. Off-diagonal matrix elements may also be important. Large off-diagonal matrix elements may indicate that special combinations of the coordinates are important. Alternatively, off-diagonal elements may compensate for non-orthogonality or redundancy in the set of trial coordinates. The latter complications can be avoided by choosing coordinates that are orthogonal, in the sense:

$$\frac{\partial q_i}{\partial \mathbf{x}} \cdot \frac{\partial q_j}{\partial \mathbf{x}} \approx 0 \quad (24)$$

More general guidelines are that

- (i) Good coordinates should *suffice* to predict differences in activity over the region with support in distribution $\rho(\mathbf{x})k(\mathbf{x})$.
- (ii) The kernel regression model should predict activation energies with errors that are much smaller than the range of activation energies in $\tilde{\rho}_k(E_a)$.

These two guidelines suggest ranking models according to the fraction of the actual E_a variance that is explained by the model. In linear regression, this is the familiar R^2 statistic. Models that include more input coordinates will generally give larger R^2 values, but small models are preferred, as long as they give accurate site-averaged rate predictions. The fit quality of the kernel regression models trained on different sets of coordinates are shown in Fig 9.

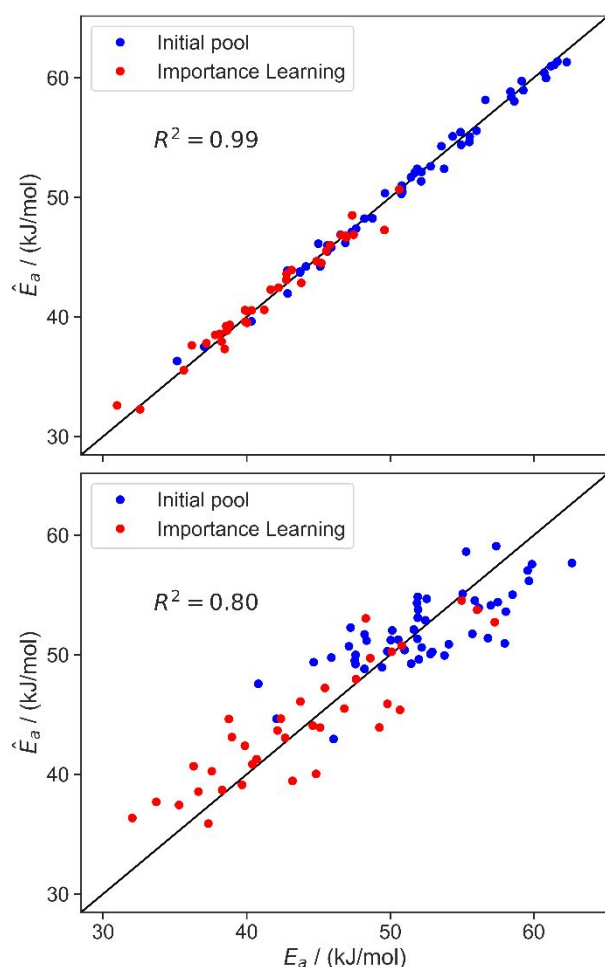


Fig. 9 Parity plot of model trained with d_1, d_2 (top) and d_1, θ (bottom) at iteration 30 of the importance learning algorithm. As shown in Table 2, d_1 and d_2 are sufficient (without the extra variable θ) to allow kernel regression to predict activation energies across the range of values.

Table 2: R^2 values of trained model with different combination of local coordinates at iteration 30 of the importance learning algorithm.

Coordinates	R^2
d_1	0.80
d_2	0.16
θ	-0.03
d_1, d_2	0.99
d_1, θ	0.82
d_2, θ	0.34
d_1, d_2, θ	0.99

The R^2 values identify θ as a kinetically unimportant structural characteristic. The kernel regression model trained only on θ completely fails to make predictions based on the local environment. Models based only on d_1 or d_2 begin to predict coarse trends in the activation energies. The model trained using d_1 and d_2 together makes extremely accurate predictions across the whole range of activation energies. Note that d_1 and d_2 are just two of the five total coordinates that define the local site environment. The model-predicted E_a is plotted as a function

of d_1 and d_2 in Fig. 10. This plot reveals that d_1 and d_2 compensate for each other in active sites. Among sites with the same activation energy, one length increases while the other decreases. Fig. 10 also illustrates that the most active sites have shorter d_1 (silanolate-silanolate) distances and longer d_2 (O-O distance of the siloxane ligands) distances relative to the unperturbed distance of 2.00.

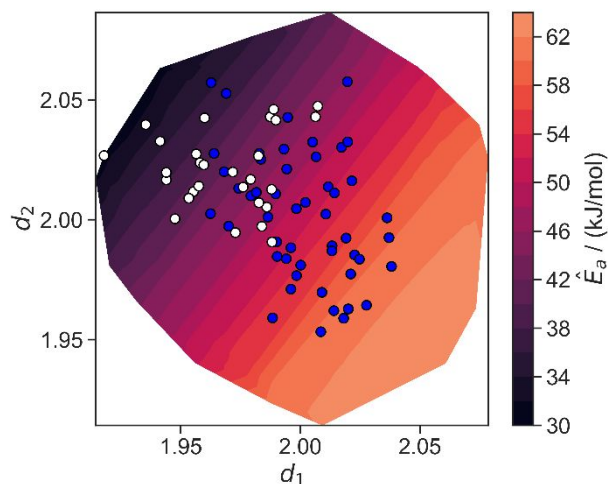


Fig. 10 Activity of sites as function of the local environment. The upper plot shows the true barriers and the bottom plot shows the model-predicted barriers at iteration 30 of the importance learning loop. Blue points correspond to the initial pool and white points are importance sampled sites.

Conclusions

Several industrially important or promising catalysts are single metal atoms grafted onto an amorphous support such as silica. These catalysts tend to be poorly understood because the amorphous support gives each site a unique local environment. Moreover, the distribution of disordered environments around each site is quenched, history dependent, and thus largely unpredictable. Each site has a different activation energy, and the variance in activation energies is exponentially magnified in the distribution of activities. Accordingly, active sites tend to be rare, with less than 20% of sites accounting for most of the catalytic activity. The small fraction of active sites hampers both experimental characterization and theoretical modeling efforts.

This paper presented an importance learning algorithm to overcome the theoretical challenges of modeling the activity of such catalysts. It combines machine learning techniques (kernel regression) and importance sampling techniques (to focus effort on the most active and abundant sites). To illustrate the algorithm, we developed a simple model of a Langmuir-Hinshelwood reaction at sites on a quenched and disordered support. We used the algorithm to compute the site-averaged activation energy.

The algorithm rapidly converged estimates of the site-averaged E_a with uncertainties less than 0.75 kJ/mol, even though the individual sites in the model have activation energies that span a range of nearly 40 kJ/mol. Estimating the site-averaged E_a with the same level of confidence as importance learning requires

through standard sampling methods requires 200,000 samples (compared to ~75 samples in the importance learning algorithm) for this system. Furthermore, the kernel regression model generated by the algorithm can accurately predict the activation energies using just two structural characteristics of the local environment. The new importance learning algorithm, if combined with *ab initio* calculations and realistic models of amorphous silica, should enable the first rigorous site-averaged computational studies and quantitative predictions for this important family of catalysts.

Conflicts of interest

There are no conflicts to declare.

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