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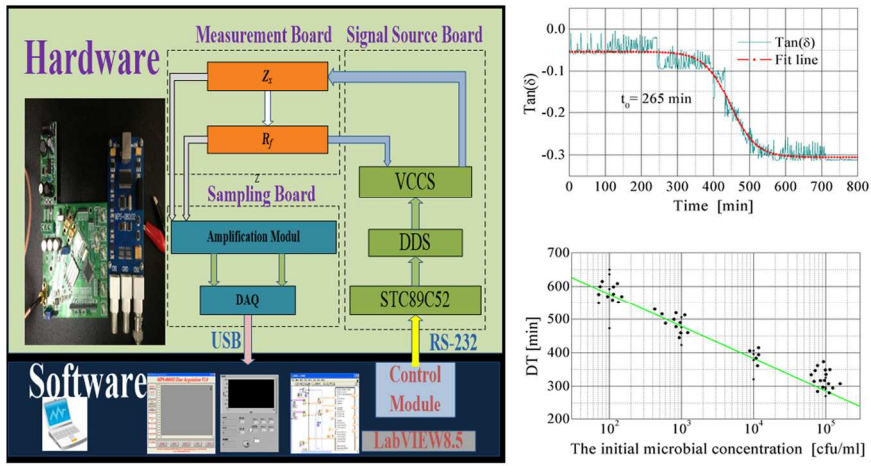


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Graphical Abstract  
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# Dielectric Loss Angle Based Portable Biosensor System for Bacterial Concentration Detection

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**Abstract:** A new type of portable sensor is proposed to detect bacterial concentration based on the change in dielectric loss angle  $\delta$ . The performance of the sensor is tested in four types of drinks, namely, milk, orange juice, peach juice, and tomato juice. Notably, the sensor can detect  $\delta$  when the bacterial concentration reaches a critical threshold value (approximately  $10^6$  cfu/mL) by applying 1 V peak-to-peak 200 Hz sinusoidal test signal of 0.25 mA at intervals of 10 min. This work introduces a portable and low-system for rapid detection. The system is a useful tool for microbial screening in industrial and commercial environments.

**Keywords:** Dielectric loss angle; Impedance; Portable biosensor; Bacterial count

## 23 1. Introduction

24 Several novel methods have been proposed and implemented to detect pathogenic  
25 bacteria over the past decades. However, people are still threatened by various bacterial  
26 pathogens. Billions of humans, particularly those in developing countries,<sup>1-4</sup> are facing health  
27 risks because of the lack of screening methods for pathogenic bacteria below threshold values  
28 in drinking water. A waterborne bacterium could kill off approximately 1.8 million people  
29 worldwide (U.S. Centers for Disease Control and Prevention, Atlanta, 2006). Traditional  
30 identification methods often involve complex procedures, and expensive instruments or  
31 reagents, rendering them unsuitable for applications outside microbiology.<sup>5-7</sup> The rapid and  
32 reproducible testing is essential in timely pathogen detection. Molecularly imprinted  
33 polymer techniques have emerged rapidly in the past decade and they made significant  
34 effects on various fields of food safety, particularly in the rapid determination of veterinary  
35 residues, pesticide residues, and microorganisms because of their low cost, selectivity and  
36 sensitivity.<sup>3, 4</sup> Several research works have reported that foodborne pathogenic bacteria  
37 mainly depend on the application of impedance techniques for screening.<sup>8, 9</sup> To date, most  
38 biosensors remain limited for unstable antibodies and replication, such as immunosensor<sup>10-12</sup>,  
39 DNA-based detection<sup>10,13-15</sup>, and surface plasmon resonance. Thus, a sensitive, rapid, easy-to-  
40 use, and cost-effective method for determining bacterial concentration must be developed.

41 The electrical nature and electrophysiology of bacterial cells are fundamental for  
42 developing impedance methods. An equivalent circuit is composed of resistances and  
43 capacitances for analyzing electrical properties of the microelectrode interface.<sup>16, 17</sup>  $C_i$  and  $R_i$   
44 represent the double-layer interface,<sup>18-20</sup> and  $R_m$  denotes the media.  $R_e$  and  $C_m$  are  
45 corresponding cell components in the tested media.  $C_i$  represents the cell membrane  
46 consisting of a lipid bilayer with many proteins, where lipid molecules are oriented with their  
47 polar groups facing outward into the aqueous environment, and whereas their hydrophobic

48 hydrocarbon chains are pointing inward to form the interior membrane.<sup>21-23</sup> The inside of a  
49 cell is complex and contains membrane-covered particulates, such as mitochondria, vacuoles,  
50 and nucleus, as well as many dissolved charged molecules.<sup>24,25</sup> However, when the frequency  
51 of the applied test signal sufficiently is low (<1 MHz),  $C_m$  can be neglected, and the  
52 equivalent circuit is simply reduced to a series of resistance ( $R_s$ ) and capacitances ( $C_s$ ). The  
53 electrical impedance of such circuit can be expressed as  $Z_s = R_s + 1/(j\omega C_s)$ .<sup>26</sup>

54 Based on the  $Z_s$  equivalent circuit, the impedance significantly changes after cell  
55 attachment and spreading because of an interference with the free space above the electrode.  
56 An air-filled parallel-plate capacitor  $C_0$  is considered as a device that stores electric charge.  
57 Capacitors vary in shape and size, but their basic configuration involves two conductors  
58 carrying equal but opposite charges. Capacitance  $C$  was found to increase experimentally  
59 when the space between the conductors is filled with dielectrics. When a dielectric material is  
60 inserted to fill the space completely between the plates, the capacitance increases to  $C=\kappa_e C_0$ ,  
61 where  $\kappa_e$  is the dielectric constant.<sup>27</sup> The increases of capacitance in the presence of a  
62 dielectric can be explained from a molecular point of view.  $\kappa_e$  is a measure of the dielectric  
63 response to an external electric field. Dielectrics consist of two types, namely, polar and non-  
64 polar. Polar dielectrics, such as water, have permanent electric dipole moments, whereas non-  
65 polar dielectrics do not. Electric dipole moments can be induced by placing the materials in  
66 an externally applied electric field.<sup>28-31</sup>

67 Electrons spend a bit more time near the oxygen atom than the hydrogen atom. Water  
68 has a dielectric constant of 80, but ice 40 °C has an even higher dielectric constant of  
69 100. Capacitance is the free charge divided by the potential difference on the plates. The  
70 average electric field produced by many tiny aligned electric dipoles is crucial to understand  
71 dielectric materials. However, the alignment is not complete because of random thermal  
72 motion. The aligned molecules then generate an electric field opposite to the applied field,

73 but smaller in magnitude. The electric field within the dielectric is  $\vec{E} = \frac{\vec{E}_0}{\kappa_e}$ .<sup>29-32</sup>

74 Maxwell already discussed dielectric properties of inhomogeneous systems, wherein the  
75 presence of a conducting phase in a medium often leads to dielectric loss. Maxwell derived a  
76 formula for the equivalent reactance of such a system, and providing the following equation

77 for the loss angle:  $\tan\delta = \frac{\vec{E}''}{\vec{E}'}$ .

78 In addition to its low cost, this circuit could prevent released metal ions from producing  
79 toxic bacteria, inhibiting their growth in the sample. Compared with silver and gold  
80 electrodes that exhibit bacteriostatic properties, stainless steel electrodes exhibit nonnegative  
81 effects at low applied fields. Given the different affected electrical forces on the electrode and  
82 bulk side of the structure, the ions form a double-layer region at the electrode/electrolyte  
83 interface of the electrolyte.<sup>32</sup>

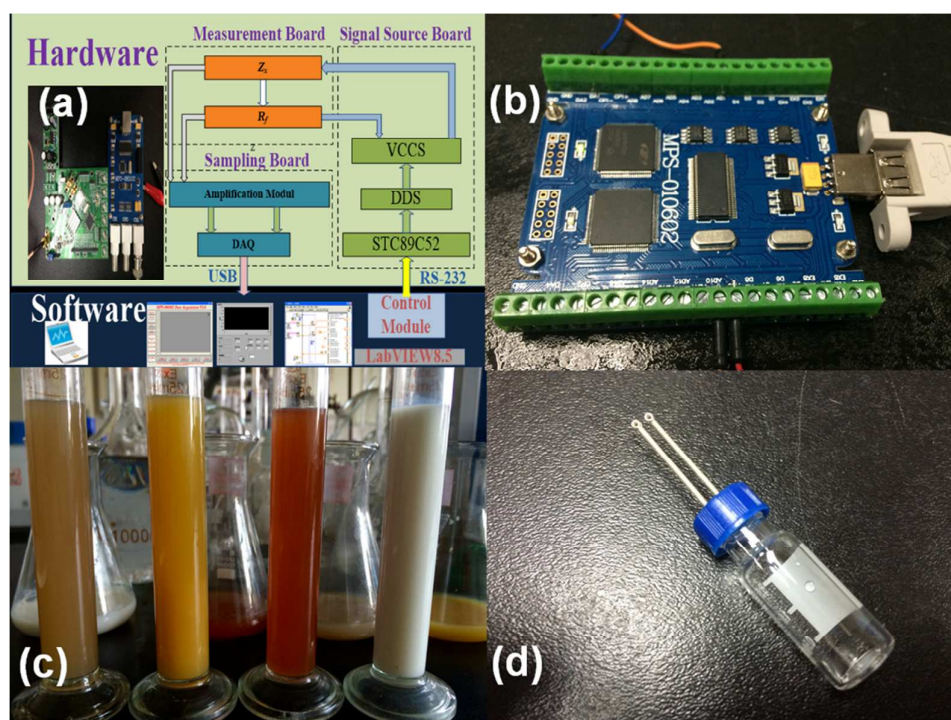
84 Electrical properties of microbial concentration, including impedance, conductivity, and  
85 surface interfacial physiology, have recently been investigated.<sup>23, 30-32</sup> However, the  
86 quantification of microbial concentration with dielectric loss angle (DLA)  $\delta$  in the culture  
87 process has not yet been reported. The cell membrane as a constant-phase element (CPE), is  
88 instated on a capacitance to simplify the equivalent circuit. Microbial concentration  
89 constantly increases in 24 h. Thus, when a critical threshold value is reached,  $C_s$  also  
90 increases. After a 24 h culture period, the phase dielectric loss angle  $\delta$  occurs in microbial  
91 doubling time. The microbial concentration can also respond with  $\delta$  in detection systems.  
92 Designing a reference resistor cascades the system to obtain dielectric loss angle, which  
93 adopts a sine-cosine sequence digital demodulation. Detection of soft drinks at low  
94 frequencies exhibits phase diversity with a 36 min lag at the beginning and increases in  $10^6$   
95 cfu/mL. This study describes a novel portable biosensor system for bacterial concentration  
96 detection based on the DLA. This system is simple, rapid and requires no particular

97 knowledge of microbiological techniques, making it particularly suitable for microbial  
98 screening during industrial mass production.

99

## 100 2. Experimental design

101 The portable biosensor-detected phase angle is mainly composed of a direct digital  
102 synthesizer (DDS) signal generator, voltage-controlled constant current source (VCCS), and  
103 DAQ card. DDS could transform the sine wave signal to the constant-current source. Thus,  
104 the contact impedance is reduced at the electrode/electrolyte interface, which is very  
105 important for system accuracy. The system design is illustrated in Figs. 1(a) and 1(b).



106

107

108 Fig. 1. Schematic (a) and photograph (b) of the biosensor system present in this work. The  
109 system is composed of an impedance measurement board, a software board and an incubation  
110 chamber containing the sample under test. Photograph (c) and photograph (d) respectively, (c)



111 different soft drink consists of peach juice, orange juice, tomato juice and milk. (d) The  
112 incubation chamber provided with a couple of stainless steel electrodes.

113

### 114 **2.1 Adding sine-cosine sequence digital demodulation based on RREF**

115 The measurement module contains two parts. Firstly, the measurement chamber features  
116 a 2 mL volume capacity. Secondly, a couple of stainless steel electrodes (conic electrodes  $\Phi$   
117 = 1 mm) is used [Fig. 2(d)]. The principle of equivalent RC circuit follows Ohm's law, in  
118 which a biological sample (adhered cell) can be treated as a resistor with resistance  $R$  and a  
119 capacitor with capacitance  $C$  connected in series. The impedance data calculated using the  $R$   
120 and  $C$  values are based on the operating frequency<sup>33</sup>. Thus, impedance is complex. An  
121 algorithm is presented to calculate the impedance. Considering important differences from  
122 the algorithm using non-inverting operational amplifier (op amp), output signals from the op  
123 amp could be calculated as follows:  $V_{out} = -(R_f/Z_s) \times V_{in}$ , where  $V_{Min}$  and  $V_{Mout}$  could be  
124 obtained from the sinusoidal voltage signal. The frequency of a measured signal is denoted as  
125  $f$ , and  $N$  represents the sampling points per cycle ( $f_s = N \times f$ ). The sampled  $q$  signal cycle and  
126 the total sampling points are calculated as  $M = N \times q$ , given that the signal is  $u(i)$ . The  
127 accurate digital signal processing is dependent on twice the sampling frequency, at least for  
128 recovering the original signal impedance. The applied active electrodes and cable driver can  
129 enhance the signal-to-noise ratio and solve the problem of phase shifting, but measuring  
130 unstable phase shifting is still required in practice.<sup>34</sup> When  $\theta'$  represents the phase shift,  $\theta = \theta$   
131 +  $\theta'$ . In this work, a method input reference resistor [Fig. 2(b)] is used to eliminate error  $\theta'$  in  
132 the measurement board, which is realized and verified on the platform.

133 The discrete Fourier transform (DFT) filter is commonly used in digital protection  
134 devices to remove the part of the signal not of interest. Voltage and current signals used in



135 protection devices may contain harmonics and decaying DC-offset in transient states.<sup>35</sup> In  
 136 this case, we presented an algorithm, the orthogonal digital demodulation method, to  
 137 calculate the cross-correlation functions of digital signal and digital reference sequences. This  
 138 method involves adding only the sine and cosine components to the selected voltage signal by  
 139 DAQ to reduce system error.

140 Digital signal processor (DSP) module automatically generates  $N$  points per cycle of  
 141 the sequence  $s(i)$  of sinusoidal reference and sequence  $c(i)$  of cosine reference. Given the two  
 142 sequences and the signal data for the correlation operation, the correlation functions  $R_{xrs}$  and  
 143  $R_{xrc}$  can be obtained. The method is as follows:

$$144 \quad u(i) = A \sin\left(\frac{2\pi i}{N} + \theta\right) (i = 0, 1, \dots, M-1)$$

145 The test signal  $y(i)$  is changed:  $y(i) = A \sin\left(\frac{2\pi i}{N} + \theta + \theta'\right) (i = 0, 1, \dots, M-1)$

$$146 \quad s(i) = \sin\left(\frac{2\pi i}{N}\right) ; c(i) = \cos\left(\frac{2\pi i}{N}\right)$$

$$147 \quad R_{xrs} = \frac{1}{M} \sum_{i=0}^{M-1} y(i) \cdot s(i) = \frac{A}{2} \cos \theta - \frac{A}{2M} \sum_{i=0}^{M-1} \cos\left(\frac{4\pi i}{N} + \theta\right)$$

$$148 \quad R_{xrc} = \frac{1}{M} \sum_{i=0}^{M-1} y(i) \cdot c(i) = \frac{A}{2} \sin \theta - \frac{A}{2M} \sum_{i=0}^{M-1} \sin\left(\frac{4\pi i}{N} + \theta\right)$$

$$149 \quad R_{xrs} = \frac{A}{2} \cos \theta ; R_{xrc} = \frac{A}{2} \sin \theta$$

150 So,

$$151 \quad A = 2\sqrt{R_{xrs}^2 + R_{xrc}^2}$$

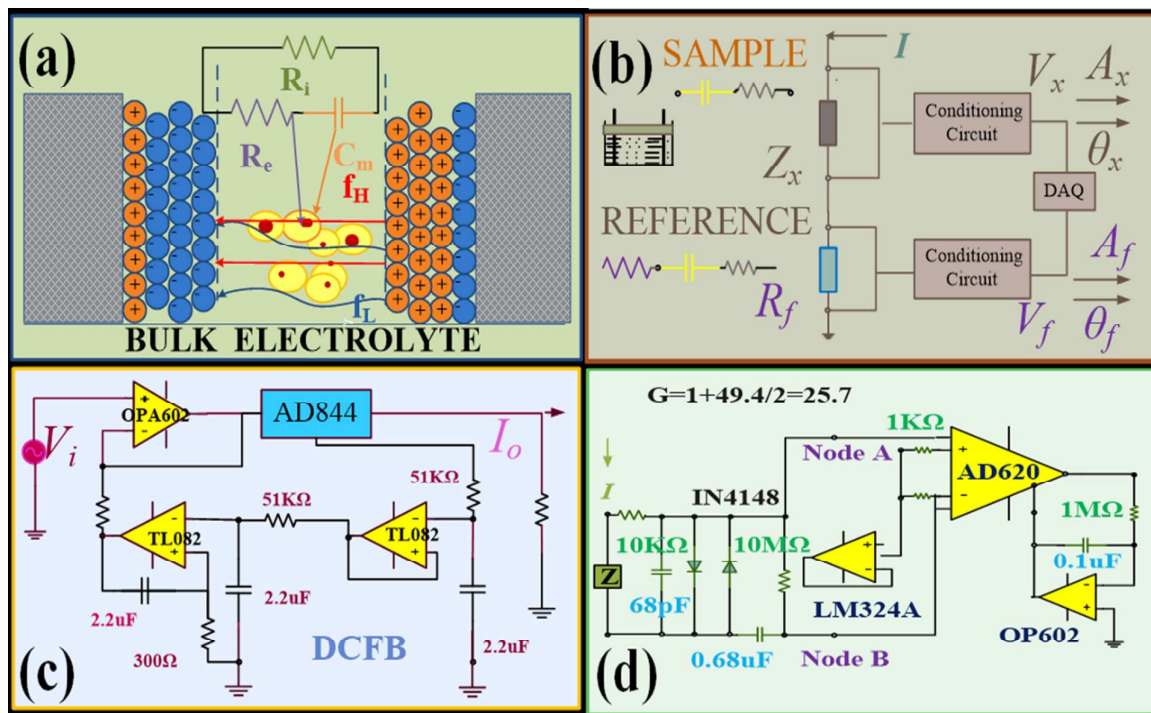
$$152 \quad \theta = \arctan \frac{R_{xrc}}{R_{xrs}}$$

153 Supposed current was  $I$ ,  $Z_x = V_x I_x$  ;  $V_r = R_r I$

$$154 \quad \text{So,} \quad Z_x = \frac{V_x}{V_r} R_r$$

$$155 \quad |Z_x| = \frac{A_x}{A_r} R_r ;$$

156 So the phase angle diversity  $\delta$ ,  $\delta = \angle Z_x = \theta_x - \theta_r$



157

158

159 Fig.2 Front and top view (a), (b), (c) and (d) respectively, (a) Electrical model for the system  
 160 electrodes-sample, the photo of the chamber in last Fig.1(d) is provided with a couple of  
 161 stainless steel electrodes, electrical model for the system electrodes-sample. (b) Schematic

162 diagram of measuring impedance. (c) Schematic of the VCCS board (d) amplified and  
163 filtered circuit for biosensor.

164

## 165 *2.2 VCCS mode*

166 Ions forming a double-layer region at the electrode/electrolyte interface produce contact  
167 impedance, which affects measurement. The contact impedance should be briefly considered  
168 in relation to the effects, which reflect the authenticity of the bacterial concentration-  
169 changing discipline. Forcing a current through the known electrical model is significant  
170 because the contact impedance produced by exciting the electrode current slightly effects for  
171 a system measuring current source. The mode then measures the voltage signal. The signal  
172 source board acquires a signal switchover circuit, VCCS, which transforms voltage signal  
173 into current signal to improve measuring signal reliability. The VCCS is an electric circuit  
174 that generates a steady flow of electrons proportional to an input voltage. A low noise VCCS  
175 provides the solenoid current flow regulation necessary to generate a stable static magnetic  
176 field ( $B_0$ )<sup>34</sup>.

177 Fig. 2(c) shows a schematic of the signal source board with its main components. With  
178 the development of DSP technology, DDS is adopted to generate a sine wave with high  
179 precision and stability. This sine wave is provided by the accurate sine wave signal used as  
180 the input AC signal of VCCS. The VCCS system design should solve two problems. Firstly,  
181 output impedance approach should be increased; thus, constant-current source can effectively  
182 improve the stability of its output current. Secondly, a specific process should be developed  
183 to reduce the polarization phenomenon by electrolysis and eliminate the DC component that  
184 affects the repeatability of measurements.<sup>36, 37</sup>

185 Bulk commutation technique is applied to suppress the substrate leakage current  
186 problem of CMOS rectifier.<sup>38</sup> The current-feedback amplifier AD844 (Analog Devices),  
187 whose internal structure is shown in Fig. 2(c) (dotted zone), is a suitable current conveyor  
188 because it reaches an internal high-impedance node for external frequency compensation.  
189 However, its gain accuracy is limited. Therefore, we built a non-inverting current circle by  
190 adding OPA602 as a voltage buffer and a series resistor  $R_f$  at the output.  $R_f$  cannot be  
191 optionally increased because the voltage at the non-inverting input must be maintained below  
192 1 V for optimal results, depending on the feature of AD844. OPA602 could also reduce the  
193 influence of output impedance of AD844 because of its high input impedance. Moreover, to  
194 avoid saturation of the DC-blocking capacitor because of residual DC currents, the DC-  
195 feedback circuit design is a composed of second-order active filter that serves as a virtual  
196 ground for the AC signal. The actual DC voltage at the Z node is approximately 0 V. The  
197 VCCS output current is calculated as follows:  $i = \frac{V_{in}}{R_f}$

198

### 199 **2.3 Decaying DC-offset filtering**<sup>36,37</sup>

200 Signal conditioning is a process of manipulating an analogue signal optimized for  
201 further processing to increase detection sensitivity. Signal conditioning has three stages,  
202 namely, filtration, amplification, and isolation. In designing these filters types determining  
203 the cut-off frequency and the stop band attenuation is important. The output from the  
204 analogue filter is fed as input into an analogue-digital converter. Fig. 2(d) shows a schematic  
205 of the signal conditioning circle and its main components. Prior to the amplification stage of  
206 signal conditioning, the signal must be filtered and optimized for DAQ reading. Filtering  
207 aimed to eliminate undesired noise from the signal of interest using passive filtering and  
208 protection circuit. The low- and high-pass passive filtering stages were designed to solve two

209 problems, namely, noise of electrodes and interference between hardware parts. The cut-off  
210 frequency of front-end low-pass filter was 200 kHz, where  $R_1 = 10 \text{ k}\Omega$  and  $C_1 = 68 \text{ pF}$ . The  
211 protection circuit consisting of two diodes (IN4148) could protect signal conditioning circle  
212 and the DAQ card. The cut-off the frequency of high-pass filter was 0.05 Hz, where  $C_2 =$   
213  $0.68 \text{ }\mu\text{F}$  and  $R_2 = 10 \text{ M}\Omega$ . After RC filtering, an appropriate buffer could be selected for  
214 either following voltage or inverting amplifier configuration. In this part, the OP602 was  
215 chosen as a buffer amplifier for the voltage follower. This amplifier exhibited a low common-  
216 mode rejection ratio (CMRR) and was used as a driver for DAQ card input capacitance. The  
217 OP602 also illustrated signal conditioning circuitry with OPA602 and RC filters applied.

218 General characteristics of a differential amplifier include a low DC offset, drift, and low  
219 noise, as well as high open-loop gain, CMRR, and input impedance. In this step, AD620  
220 (instrumentation amplifier) was selected for such purpose through the input buffer LM324A.  
221 The AD620 of  $10 \text{ G}\Omega$  input impedance is suitable for applications that require a small voltage  
222 with high accuracy and minimal influence from noise. To increase resolution and SNR, the  
223 AD620 amplified the voltage by obtaining approximately 26 gain to match the reference  
224 voltage of ADC because the maximum voltage difference between A and B was 91.94 mV.  
225 The gain of instrumental amplifier was set by adjusting the resistance  $R_G$  of the circuitry,  
226 where  $R_G = 2 \text{ k}\Omega$ , with two series resistors.

#### 227 **2.4 Microbial analyses**

228 At the working frequency,  $Z$  includes data from growth of equation modelled as RC circuit,  
229 whereas both types are measured separately in  $Z$  and  $\theta$ .<sup>39</sup> In this section, based on the sensors  
230 featuring the structure depicted in Fig. 1, the experimental set-up of microbial concentration  
231 was placed in an 8 mL container [Fig. 1(d)]. The combined cultures (2 mL each) were made  
232 in a glass covered with two identical stainless steel removable electrodes. The injected  
233 current working frequency was at a density not higher than  $J = 1$ . Before each experiment, the

234 cultures were washed and rinsed with distilled water and sterilized at 121 °C for 20 min in an  
235 autoclave.

236 Given the different conserving additive amounts and sugar concentrations present in  
237 various products, we selected milk and three concentrated juices (orange, peach, and tomato).  
238 Samples of different soft drinks were also tested to monitor the microbial concentration  
239 occasionally, as well as the inoculated species. For the latter, 25 mL of each soft drinks was  
240 incubated for 24 h with automatic thermostats set at 37 °C. Gradient dilution method was  
241 then used to determine bacterial concentrations in impedance mediums.<sup>40</sup> Subsequently, at  
242 sterile conditions, the samples were filled with 1 mL of sterilized culture medium and 1 mL  
243 of bacterial concentrations through gradient dilution. Finally, electrodes were fixed on the  
244 samples.

245

### 246 **3. Results and discussion**

#### 247 *3.1 Optimal characterization analyses*

248 This testing system should generally provide an accurate value in theoretical design and  
249 practical application. To avoid divergence decline testing accuracy, the resistance experiment  
250 was calibrated for error in the biosensor system described in Section 2. This present work  
251 reports the performance study of the sensor. Hence, characterization and subsequent  
252 standardization against the most feasible available instruments were conducted. The  
253 experiments were performed in three ways to select the sensor. The impedances of the  
254 sensors were measured (both  $Z$  and  $\theta$  at the entire frequency range of 10 Hz to 125 kHz).

255 White Gauss noise was initially added, and the simulation results displayed an  
256 orthogonal digital demodulation algorithm with a maximum error of 0.53%. Compared with  
257 other algorithms, this method is ideal for calculating phase angle diversity. Correlation

258 analysis confirmed that the physical environment barely affects accuracy. At the same  
259 frequency calibrating error, the phase shift could receive accurate values of different loads. In  
260 summary, testing results indicate that the impedance, maximum error and the phase angle of  
261 the actual maximum error are  $<0.93\%$ ,  $0.93\%$ , and  $<0.03^\circ$ , respectively. This method for  
262 removing the phase angle error has a high computational accuracy compared with other  
263 methods.

264 To validate the insensitivity of the sensor to temperature ( $0^\circ\text{C}$ ,  $15^\circ\text{C}$ ,  $30^\circ\text{C}$ , and  $45^\circ\text{C}$ )  
265 and four humidity values (40%, 50%, 60%, and 70%), the reading was directly obtained by  
266 testing the resistor ( $1\text{ k}\Omega$ ). The impedance magnitude ( $Z$ ) remained constant (within  $1.02\text{ k}\Omega$  -  
267  $1.06\text{ k}\Omega$ ). This finding shows that the sensor is insensitive to changes in temperature and  
268 humidity.

269 The phase angle with respect to the different humidity values (i.e. 40%, 50%, 60%, and  
270 70%) and frequency as parameter is shown in Fig. 3(a). The phase angle remained constant  
271 with increasing frequency and changed in humidity [Fig. 3(a)]. Thus, the sensor is insensitive  
272 to these changes. The phase angle was consistently recorded with respect to the four  
273 temperatures for the frequency range of 10 Hz to 125 kHz [Fig. 3(b)]. The phase angle  
274 expectedly increased with frequency increasing at different temperatures [Fig. 3(b)]. This  
275 finding shows that the sensor is insensitive to changes in temperature.

276 To ensure the reproducibility and consistency of the sensor, each reading was repeated  
277 thrice. Data provided in Fig. 3(c) represent the average values of the three sets of reading.  
278 The phase angle of these sensors remains almost constant within the frequency range of 10  
279 Hz to 100 kHz. The maximum error of phase was of  $0.07^\circ$  from 100 Hz to 50 kHz and  $0.31^\circ$   
280 from 50 kHz to 100 kHz. The results indicate that the phase angle remains almost constant  
281 within 12 kHz to 20 kHz. Thus, any frequency within this bandwidth can be selected as the



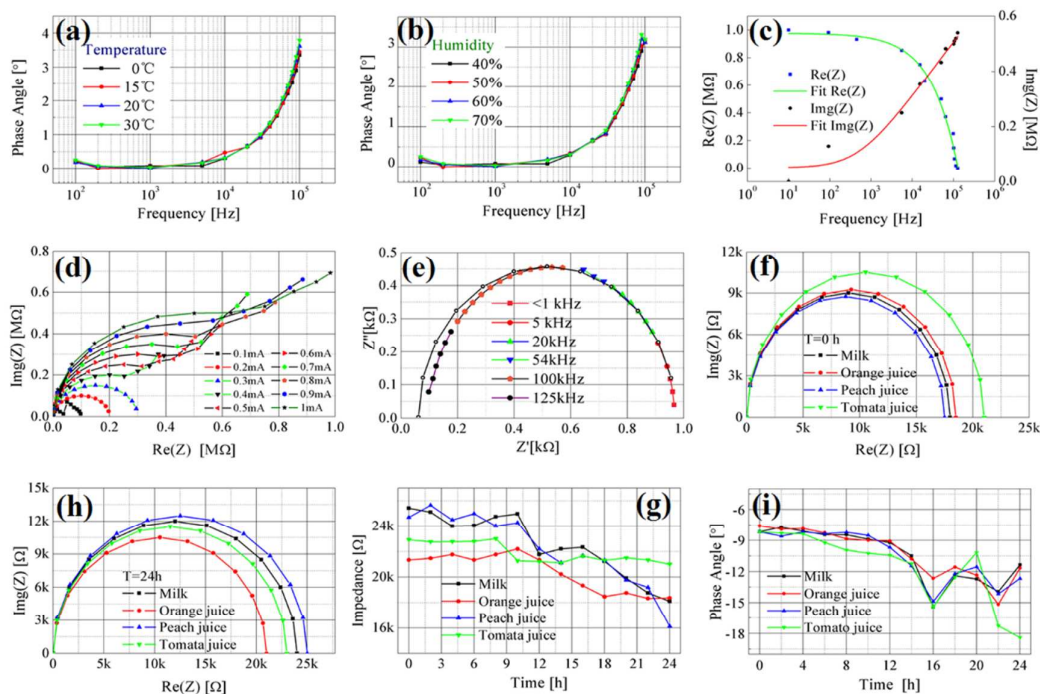
282 sensor performance. Moreover, the system provides a 1 V peak-to-peak 200 Hz voltage test  
283 signal ( $V_{in}$ ).

284 As previously demonstrated, the biosensor system requires a stable constant current  
285 source VCCS to ensure accuracy and stability. Logarithmic sweeping-frequency mode was  
286 used to test the RC model ( $R=1\text{ k}\Omega$ ,  $C=2.2\text{ }\mu\text{F}$ ) and an excited constant current from 0.1 mA  
287 to 1.0 mA was detected at a frequency of 200 Hz [Fig. 3(d)]. Each current was tested thrice.  
288 The phase value from 0.1 mA to 0.3 mA was stable even at floating current. The deviation  
289 with increasing current density ( $I \geq 0.4\text{ mA}$ ) is displayed. The average phase value was  $6^\circ$  at  
290 0.1 mA-0.3 mA, whereas the current changed from 0.3 mA to 0.4 mA. With increasing  
291 current, electrode polarization occurs on the electrode surface. As previously indicated, this  
292 finding affects the measurement results. When the current  $I > 0.3\text{ mA}$ , the results assume  
293 different trends. In this work, the optimal test current used was 0.1 mA to 0.3 mA to ensure  
294 measurement accuracy. The value of impedance was obtained from 0.1 mA to 0.4 mA and  
295 was fundamentally stable even at floating current. The deviation with increasing current  
296 density ( $I \geq 0.4\text{ mA}$ ) is displayed. Similar to the phase change, the impedance value  
297 decreased with increasing current. Given the combined effects of impedance and phase, the  
298 optimal excitation current was 0.1 mA to 0.3 mA.

299 The impedance magnitude also decreased with increasing frequency [Fig. 3(d)]. On the  
300 contrary, the phase angle increased with increasing frequency. In this experiment, the change  
301 curve of electrical impedance indicated different frequencies from 10 Hz to 125k Hz. The  
302 average of data were calculated. Thus, the whole test system  $Z$  was composed of electrical  
303 resistance and capacitance. The trend of the data changed at about 55 kHz, and above that  
304 frequency, considerable differences between the measured data and the Cole-Cole plot in Fig.  
305 3(c) were found. The fitted semicircle shown in Fig. 3(c) was determined using the data  
306 between 10 and 55 kHz and the RMSE value of  $0.7\text{ k}\Omega$  demonstrates that an excellent fit is

307 obtained within this range of frequencies.<sup>41</sup> However, at higher frequencies major  
 308 discrepancies were found between the measured data and the Cole- Cole plot determined  
 309 from low frequency data.

310 Specifically, when  $f < 1000$  Hz, the test system is characterized by resistance. The  
 311 magnitude impedance ( $Z$ ) and phase angle of all the cases were measured using the portable  
 312 biosensor in  $Z$  and  $\theta$  modes to study its performance. The biosensor was excited with VCCS  
 313 that supplied the content current for the system to provide accurate sampling. In these cases,  
 314 1 V peak-to-peak, 200 Hz voltage test signal ( $V_{in}$ ) was provided to avoid electrode  
 315 polarization effects and maintain the current at 0.25 mA.



316

317

318 Fig.3 (a) and (b) Variation of phase angle with temperature and humidity at 10Hz to 125kHz,  
 319  $R=10$ k $\Omega$ . (c) Measured and simulated values for  $Re[Z]$  and  $Img[Z]$  from the model of RC. (d)  
 320 Impedance spectrum of different samples changed with current amplitude. (e) Impedance

321 spectrum acquired, the black solid line is obtained from the model of RC between 10 and 125  
322 kHz. (f) and (h) Cole–Cole plots of different samples are obtained at 1 h and 20 h. (g) and (i)  
323 The plot of average value of  $|Z|$  and  $\text{Arg}(Z)$  are changed with time in different samples. In  
324 here Samples (milk, orange juice, peach juice and tomato juice) inoculated with  $10^5$  cfu/mL  
325 bacterial concentrations.

326

### 327 **3.2 Cole-cole graph analyses**

328 Fig. 3(e) shows a typical spectrum obtained using the sensor on an electronic circuit  
329 with  $R=1$  k $\Omega$  and  $C=2.2$   $\mu\text{F}$ . This finding demonstrates that the sensor provided excellent  
330 results with good fit to the Cole-Cole theory at all frequencies between 5 and 125 kHz. Minor  
331 discrepancies were observed above 150 kHz with slight deviations from the semi-circular fit.

332 Given phase angle change with the unit change of pH value,<sup>42</sup> before sensing bacterial  
333 concentration, pH value could be noted for reference. In this paper, each sample was  
334 maintained at  $\text{pH}=5\pm 1$ .

335 To determine the appropriate parameter to be monitored, impedance value  $Z$  and phase  
336 angle  $\theta$  were measured for all considered cases. Thus, the phase angle  $\theta$  is a reliable indicator  
337 in this study. The model of  $Z$  consists of capacitive and resistive components<sup>41</sup>, which could  
338 be attributed to the incipient phase separation of the samples during measurement. Figs. 3(f)  
339 and 3(g) show two Cole-Cole plots of the electrical impedance imaginary ( $Z$ ) versus real ( $Z$ )  
340 at initial time periods of 1 and 20 h. These plots are based on different samples subjected to a  
341 time series of AE activity recorded simultaneously with the AC-conductivity at different  
342 selected frequencies (10 Hz and 100 kHz). The Cole-Cole plot [Fig. 3(f)] exhibits strong  
343 resistance characteristics at the initial time leading to the impossible outcome of characteristic  
344 frequency. The Cole-Cole graph [Fig. 3(g)] consists of two superimposed depressed

345 semicircles and a tail at the low frequency range. The low-frequency tail at the right side of  
346 the plots is due to the undesirable electrode response result. The main complex impedance arc  
347 in the Cole-Cole plot observed at the arc at medium frequencies is ascribed to the grain  
348 boundary contribution.<sup>43</sup> In the present case, the contributions of measurements may be  
349 modelled via an equivalent circuit with two components in series, each consisting of a CPE  
350 connection with a resistance  $R$ . The CPE outcome could be equal to the bacterial  
351 concentration when it reaches a threshold value of  $10^6$  cfu/mL. Such equivalent circuit  
352 models were used to describe the electrical behavior of general bacterial concentration as a  
353 function of time.

354 The phase separation exhibits different effects on the interface and “bulk” properties of  
355 the sensors because it influences the solution conductivity more than the electrical properties  
356 of the electrode/solution interface. The real ( $Z$ ) and imaginary ( $Z$ ) are parts of the complex  
357 electrical impedance as a function of frequency during the sequential loading sine wave. Thus,  
358 the real ( $Z$ ) becomes unsuitable for detecting bacterial concentration. By contrast, the  
359 imaginary ( $Z$ ), essentially determined by interface characteristics, is insignificantly affected  
360 by the phase angle separation and exhibits a predictable behavior in all considered cases.

361 The system was used to prove determination the feasibility of bacterial contaminant in  
362 different samples. Nutrient media must then be added to the sample to allow the bacteria to  
363 reach the critical concentration of  $10^6$  cfu/mL. In summary, impedance method was shown to  
364 work in all appropriate cases. The four different samples (milk, orange juice, peach juice, and  
365 tomato juice) based on fruit or containing alcohol exhibited no significant bacterial growth  
366 because it was inhibited by high organic acid or alcohol in the product (former and latter case,  
367 respectively).

368

### 369 3.3 Detection of phase angle analyses

370 Typical values of dielectric loss angle  $\delta$  and  $|Z|$  extracted from our experimental data are  
371 shown in Fig. 3(g) and Fig. 3(i). These data, collected during 24 h assays, were obtained from  
372 different types of soft drinks with the same initial bacterial concentration of  $10^5$  cfu/mL. The  
373 average phase angle value changed with time when the biosensor was dipped into different  
374 samples (milk, orange juice, peach juice, and tomato juice) inoculated with the same  
375 percentage of bacterial concentrations [Fig. 3(g) and Fig. 3(i)]. The black, red, blue and green  
376 curves show the phase angle when the sensor was dipped into  $10^5$  cfu/mL each of milk,  
377 orange juice, peach juice and tomato juice. The plots demonstrate that the phase angle of the  
378 biosensor is remarkably different among the samples.

379 The change in electrical impedance could reflect the growth of bacterial communities.  
380 The present study focuses on improving the accuracy of phase angle using the RREF  
381 algorithm. The rate of the dielectric loss angle  $\delta$  increases in response to the bacterial  
382 concentration. Although the curves are noisier and exhibit smoother features than those  
383 obtained using suitable dilution media, the time (DT) at which  $\delta$  begins to increase can be  
384 accurately calculated by using an PC-implemented algorithm that effectively filters out the  
385 experimental. Fig. 4(a) shows the measured curve, as well as the fitting function in the case  
386 of  $\delta$  for a  $10^5$  cfu/mL milk sample. Each measurement is averaged over eight signal periods,  
387 which resulted in an electrical parameter (impedance and phase angle) estimation with  
388 precision  $> 99\%$ . Such algorithm is based on the shape of the experimental curves. Before the  
389 bacterial concentration reaches the critical threshold of  $10^6$  cfu/mL,  $\delta$  exhibits (at most) a  
390 slightly positive or negative drift [Fig. 3(i)]. Alternatively, when the threshold concentration  
391 is reached,  $\delta$  exhibits a steep increase. Thus, our algorithm approximates the measured  $\delta$   
392 curves. The specific algorithm for determining DT is defined. When the bacterial  
393 concentration reaches the threshold value, the  $\delta$  values can be expressed as:

394 
$$\delta(t) = A_2 + \frac{A_1 - A_2}{1 + e^{\frac{t-t_0}{dt}}} (A_1 < \delta < A_2)$$

395 Then the value DT is determined and it is assumed that:  $DT=t_0$ .

396 In the case of the four samples,  $\delta$  allowed the reliable measurement of bacterial  
397 concentration. In terms of percent variation, the dielectric loss angle  $\delta$  is plotted versus time  
398 for different samples inoculated with various concentrations of the diluting medium [Fig.  
399 4(a)]. The electrical parameters start to deviate from their baseline values at the time related  
400 to the initial bacterial concentration (higher contamination indicates lower DT). These  
401 parameters saturate when the bacterial population stabilizes. The stability of the population is  
402 attributed the cells, which no longer reproduce because of a lack of nutrients and the  
403 accumulation of toxic compounds in the media. The bacterial concentration upon electrical  
404 parameter saturation was approximately  $10^8$  cfu/mL using SPC and the value. The detection  
405 system must work independently to determine the possible presence of the unknown bacteria  
406 in the samples. Thus, a worst-case criterion must be adopted to discard samples contaminated  
407 by the slowest growing types of bacteria. Fig. 4(b) shows DT as a function of the initial  
408 microbial concentration for the different samples selected in this study. The linear regression  
409 line for the set of measures is  $DT = -96.5 \text{ Log}_{10}(x) + 769$ , and the coefficient of  
410 determination is  $R^2 = 0.8581$  (the figure also shows the lower and higher limits of DT as  
411 functions of the microbial concentration inferred by Student  $t$ -distribution with a 95%  
412 confidence level).

413 The phase angle  $\delta$  diversity exhibits an approximate growth from 0.02 to 0.36 in milk  
414 with different bacterial concentrations of [Fig. 4(c)]. The DT calculated from the  $\delta$  curves is  
415 significantly different. Thus, the total time required to detect microbial concentration of more  
416 than  $10^5$  cfu/mL ranges from 5 h to 6 h, including 30 min of initial delay needed for the  
417 sample to reach the target temperature after the threshold microbial concentration was

418 properly calculated to determine DT. The DT of the black curves ( $10^5$ ) is 296 min [Fig. 4(c)],  
419 and those of the first ( $10^4$ ), second ( $10^3$ ) and third red curve ( $10^2$ ) are 406, 476 and 636 min,  
420 respectively.

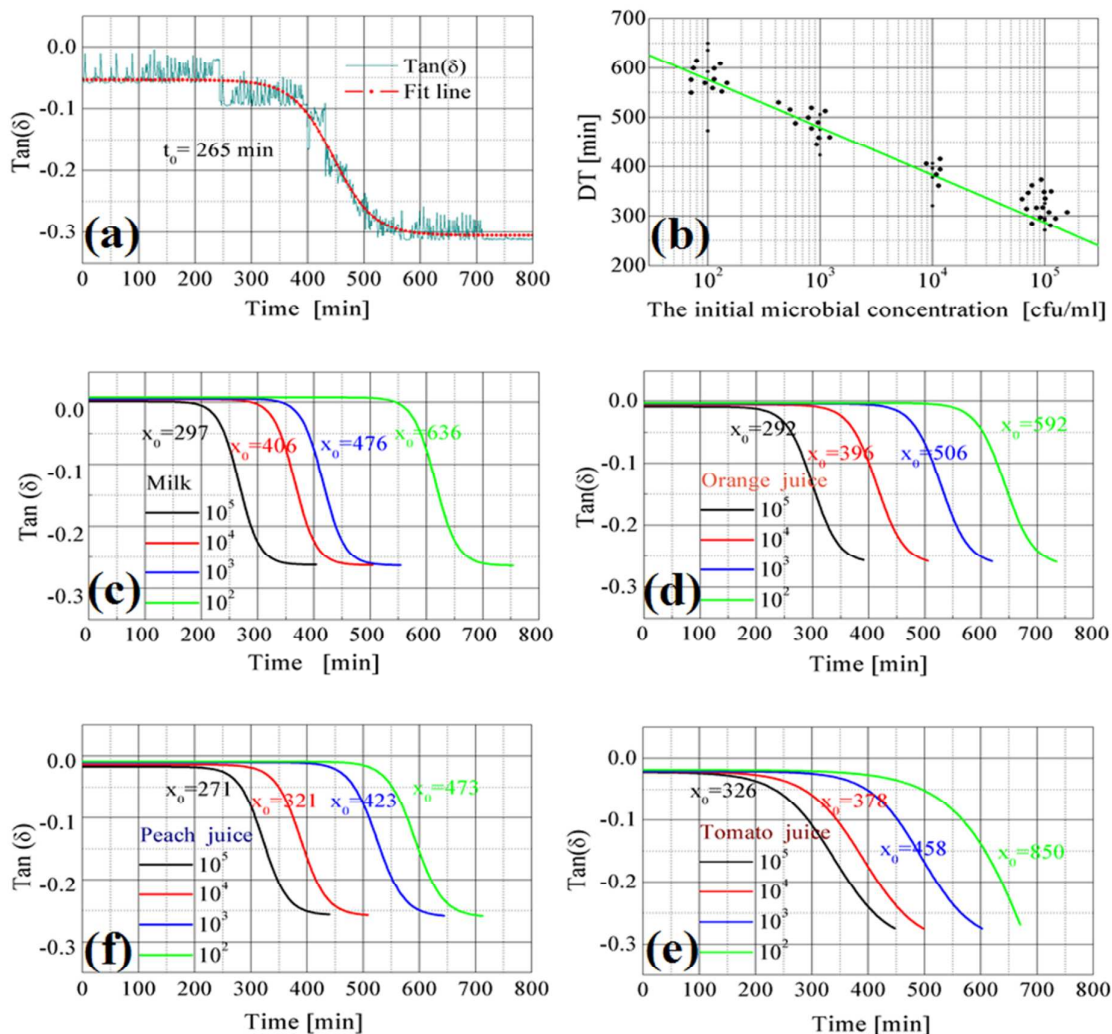
421 The dielectric loss angle  $\delta$  exhibits an estimated growth from 0.02 to 0.38 in the orange  
422 juice with different bacterial concentrations [Fig. 4(d)]. The DT of the black curves ( $10^5$ ) is  
423 292 min [Fig. 4(d)], and those of first ( $10^4$ ), second ( $10^3$ ), and third ( $10^2$ ) red curves are 396,  
424 506, and 592 min, respectively.

425 The dielectric loss angle  $\delta$  exhibits growth from about 0.02 to 0.3 in peach juice with  
426 different bacterial concentrations of [Fig. 4(e)]. The sugar concentration present in the  
427 samples can decrease  $\delta$ . The DT of the black curves ( $10^5$ ) is 271 min [Fig. 4(e)], and those of  
428 the first ( $10^4$ ), second ( $10^3$ ) and third ( $10^2$ ) red curves are 321, 423 and 473 min, respectively.

429 The  $\delta$  exhibits an approximate growth from 0.04 to 0.36 in tomato juice with different  
430 bacterial concentrations of [Fig. 4(f)], and those of the first ( $10^4$ ), second ( $10^3$ ) and third ( $10^2$ )  
431 red curves are 378, 458 and 650 min, respectively.

432 In summary, dealing with phase significantly adds sine-cosine sequence digital  
433 demodulation based on an easy reference resistor circuit. The different growth rates  $\delta(t)$  of  
434 the dielectric loss angle could reflect the microbial concentration in 24 h. Efficient growth  
435 media can support the recovery of stressed or injured bacterial cells. The test system was  
436 suitable for applications in the industrial field (particularly in dairy products) as well as for  
437 environmental monitoring (e.g. case of water microbial screening).





438

439 Fig. 4(a) Typical curve of the phase angle diversity  $\delta$  and time with  $\delta$  for best-fitting as a  
 440 function of the initial microbial concentration  $10^5$  cfu/mL milk sample. (b) Representation of  
 441 the DT obtained for the samples as a function of the initial microbial concentration (in log  
 442 scale). These data have been obtained with measurements at time intervals of 10 min during a  
 443 total time of 24 h. The samples have been incubated at a temperature of 39 °C. The obtained  
 444 regression line  $DT = -96.5 \text{ Log}_{10}(x) + 769$  is also presented. The corresponding correlation  
 445 coefficient is  $R^2 = 0.8581$ . (c) Scatter plot representing DT as function of microbial  
 446 concentration and phase angle growth curves for milk samples inoculated with known  
 447 concentration. (d) Scatter plot representing DT as function of microbial concentration and

448 phase angle growth curves for orange juice samples inoculated with known concentration. (e)  
449 Scatter plot representing DT as function of microbial concentration and phase angle growth  
450 curves for peach juice samples inoculated with known concentration. (f) Scatter plot  
451 representing DT as function of microbial concentration and phase angle growth curves for  
452 tomato juice samples inoculated with known concentration.

#### 453 **4. Conclusion**

454 In this study, a new type of portable biosensor system for determination bacterial  
455 concentration based on the change in value of dielectric loss angle  $\delta$  was reported. As for  
456 competitiveness, this sensor provides more rapid results than standard plate count techniques  
457 (3 h for  $10^6$  cfu/mL) and avoids limited use in the laboratory. The system is a useful tool for  
458 microbial screening in the industrial field (in particular the dairy one is of interest here), as  
459 well as commercial environments.

460

461

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