



## Preparation and Rheological Properties of Whey Protein Emulsion Fluid Gels

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Complete List of Authors:	Moakes, Richard; University of Birmingham, School of Chemical Engineering Sullo, Antonio; University of Birmingham, School of Chemical Engineering Norton, I; The University of Birmingham, School of Engineering



25 Whey Protein Isolate/WPI; Emulsion; Fluid/Shear Gels; Encapsulation; Material  
26 Properties; Rheology

27

## 28 **1. Introduction**

29       The use of particulates as rheological modifiers spans across multiple  
30 industries: paint, cosmetic, food etc. For this reason, systems such as colloidal  
31 suspensions and emulsions have been well documented. However, more recently  
32 microparticulate gel suspensions have received increasing interest for their  
33 ability to create weakly structured fluids, with rheological properties  
34 characterised between those for colloidal particles and polymeric gels; pseudo-  
35 solid behaviour at rest, but flow above a critical stress<sup>1-4</sup>. Enhanced flow  
36 behaviours have been observed in polysaccharide fluid gels where, at volume  
37 fractions as low as  $\phi$  0.2 suspensions showed high viscosities and marked shear  
38 thinning behaviour, typical of highly aggregated systems<sup>5, 6</sup>. The observed  
39 changes in flow properties were assigned to the particle microstructures, where,  
40 as a result of incomplete gelation at the particle surface, interactions between  
41 microgel spheres resulted in a degree of structuring. Additionally, the  
42 deformability of such soft hydrogel particles led to volume fractions that  
43 exceeded those typical for hard spheres. At such high volume fractions particles  
44 become sterically confined, thus rheology became more closely governed by the  
45 particle moduli<sup>7-9</sup>.

46       Particle intrinsic properties such as strength and deformability can be  
47 better understood by looking at a comparable quiescently formed gel. Again,  
48 mechanical properties are closely linked to the gel microstructure<sup>10-14</sup>. Complex  
49 microstructures therefore provide another means of controlling a gel's

50 physicochemical properties. Besides polymer mixes where two or more  
51 polymers undergo a sol-gel transition, filler particles can be used to prepare gel  
52 composites<sup>15</sup>. These composites display viscoelastic properties as a function of  
53 the gel matrix, volume fraction and rigidity of the filler. Chemical affinity  
54 between the filler and surrounding substrate is also very important<sup>16</sup>. Typically,  
55 where the filler interface is included into the gelled network strengthening of the  
56 matrix occurs<sup>17</sup>. It was demonstrated that increasing the time scale between  
57 emulsification and gelation resulted in a shift from stronger to weaker gels. Here,  
58 polymerisation of the emulsifier lowered the affinity between oil filler and  
59 substrate matrix, causing inherent weak spots within the gel<sup>17-19</sup>.

60 Processing is therefore a major consideration in the preparation of gels,  
61 on both a macro and micro-scale. Microgels are typically formed by confining the  
62 polymer during the sol-gel transition. This can be achieved by means of  
63 chemical<sup>20</sup> or mechanical<sup>1</sup> separation. Controlled microstructures and further  
64 rheological properties can be achieved by a microstructural design approach;  
65 whereby changing the formulation, *i.e.* composition, degree of cross-linking and  
66 system pH, leads to careful control over the gelled network<sup>4,21</sup>. Additionally, in  
67 the case of shear gels, modulating the two processing parameters shear and  
68 thermal history can lead to controlled particle size and morphology. When the  
69 separation applied to the system is such that it becomes comparable to the  
70 timescale for polymer ordering, random coil to helix transition and subsequent  
71 gelation through the formation of junction sites, thermodynamically favourable  
72 spherical particles ( $\sim 1 \mu\text{m}$ ) are formed: where the enthalpies of melting are  
73 much smaller to comparable quiescently prepared gels<sup>22</sup>. The rate of particle  
74 growth therefore becomes key. Large anisotropic ( $\sim 100 \mu\text{m}$ ) particles form

75 when structuring is so rapid that initial gels are able to form, becoming  
76 subsequently broken down in the shear flow. However, in whey protein systems  
77 an inverse relationship between aggregation kinetics and system elasticity was  
78 observed, showing faster rates to yield weaker suspensions, with lower yield  
79 stresses and viscosities<sup>23</sup>.

80 Supramolecular chemistry has also shown a viable route to the  
81 preparation of micro-composites<sup>24-26</sup>. These particles are formed through  
82 electrostatic bonding of the polymers. The particulates are formed by carefully  
83 controlling the pH so that the zeta-potential of both polymers is of an opposite  
84 charge, with a potential great enough to drive complexation. Such micro-  
85 particulates, based on an O/W<sub>1</sub>/W<sub>2</sub> system, exhibited a several fold increase in  
86 viscosity when compared to a simple O/W emulsion<sup>24</sup>. These viscosity changes  
87 were attributed to a change in the effective phase volume of the hydrogel  
88 spheres, which were further increased through the inclusion of an oil filler.  
89 However, interactions between the particles were not observed.

90 We report here the preparation of emulsion fluid gel (EmFG) particles, a  
91 micro-composite of whey protein gel and oil. The research builds on work  
92 presenting O/W<sub>1</sub>/W<sub>2</sub> filled hydrogel systems by applying a “shear gel approach”  
93 to promote interactions between resulting particles. As such, it takes an  
94 additional step to surfactant or Pickering stabilised emulsions by gelling a  
95 continuous WPI layer around an oil core. The technique applied results in an  
96 elastic suspension, whereby the particles become trapped, suspended in an  
97 aqueous phase. Unlike similar studies<sup>27</sup> the final systems act in a pseudo-solid  
98 fashion until a great enough stress is applied to induce flow, thinning the  
99 suspension into a liquid-like state. The microparticles thus offer the capacity to

100 act as a multifunctional composite, for both controlled rheological applications  
101 and pose the potential to encapsulate poorly soluble molecules.

102 The work focuses on whey protein isolate (WPI) as the coating material  
103 owing to its thermo-denaturation and subsequent hydrophobic aggregation, to  
104 form a gel layer on the surface of an oil substrate. Shear separation will then be  
105 applied to prevent complete gelation, promoting particle-particle interactions.  
106 Therefore the production of emulsion fluid gels has been investigated, with  
107 particular attention to the resulting rheological properties.

108

## 109 **2. Materials and Methods**

### 110 **2.1. Materials**

111 Whey protein isolate (WPI) was obtained from Kerry Ingredients,  
112 Listowel, Ireland (WPI, W994, S-493391) and used without further purification.  
113 WPI composition as stated by the supplier was 91.0% protein, moisture 4.0%, fat  
114 1.0%, ash 3.5% and lactose 0.5%. Mineral content of the WPI was: Ca – 0.50, P –  
115 0.65, Na – 0.10, K – 0.15, Mg – 0.02 and Cl - 0.02%. High oleic sunflower oil was  
116 obtained from Cargill (Cargill Inc., BE). Sodium azide, hydrochloric acid, silicon  
117 oil, Nile Red and Rhodamine B were purchased from Sigma-Aldrich (Sigma-  
118 Aldrich, UK).

119

### 120 **2.2. Preparation of oil filled fluid gels**

121 Preparation of the oil filled fluid gels involved a three-step process.  
122 Primary solutions of WPI were firstly prepared and used to form O/W emulsions.  
123 The emulsions were then heat treated under shear conditions resulting in  
124 emulsion fluid gels (EmFG).

125

126 2.2.1. Preparation of WPI stock solutions

127           Whey protein stock solutions (5 to 30 **wt%** on a protein basis) were  
128 prepared by dispersing WPI in deionised water. An anti-microbial, sodium azide  
129 (0.02 **wt%**) was added to all solutions to enhance storage times. Solutions were  
130 stirred overnight at ambient conditions until completely hydrated and stored at  
131 5 °C until further usage. For the preparation of stained samples Rhodamine B  
132 (0.015 mM) was added to stain the protein. Stained samples were kept covered  
133 to prevent photo bleaching.

134

135 2.2.2. Preparation of emulsions

136           Oil in water emulsions were prepared by the addition of high oleic oil to  
137 WPI primary solution (Protein concentration ranging from 5 to 30 **wt%**) so that  
138 total volumes resulted in oil fractions ranging from 5 to 20 **vol%**. The mixtures  
139 were subsequently mixed in a high shear mixer (Silverson, SL2T) at 4000 rpm  
140 for 10 minutes. System pH was adjusted to pH 4.6 with concentrated  
141 hydrochloric acid (12 M) and aged for 72 hours before gelling under shear.  
142 Stained EmFG were prepared with the addition of Nile Red (0.015 mM) to the oil  
143 phase and kept covered to prevent photo bleaching.

144

145 2.2.3. Preparation of oil filled fluid gels

146           A jacketed vessel and overhead stirrer equipped with pitched blade  
147 impeller was used to prepare all WPI emulsion fluid gels (EmFG). Aliquots of  
148 emulsion were added to a jacketed vessel set to 50 °C, controlled through a  
149 circulating water bath. Shear was applied through the stirrer and impeller at 450

150 rpm. Once thermal equilibrium was obtained (Ca. 10 minutes), emulsions were  
151 heated at a rate of 0.5 °Cmin<sup>-1</sup> to 80 °C. Suspensions were subsequently decanted  
152 and left to cool quiescently under ambient conditions. Cooled EmFG were further  
153 stored at 5 °C for seven days until rheologically tested. In all experiments a cover  
154 was applied to minimise water loss. When staining, the system was covered in  
155 aluminium foil to avoid fluorescence quenching.

156

### 157 **2.3. Static light scattering (SLS)**

158 A MS2000 Mastersizer with attached Hydro SM manual small volume  
159 dispersion unit (Malvern Instruments Ltd, UK) was used to obtain size  
160 distributions for EmFG particles. Distributions are the average of three repeats.  
161 Particle size calculations were based upon the Mie theory, thus particles were  
162 assumed to be monodisperse, homogenous spheres. Additionally, once coated,  
163 particles were a binary system of protein and oil; as such the refractive index of  
164 the shell was used.

165

### 166 **2.4. Microscopy**

#### 167 **2.4.1. Optical light microscopy**

168 Samples were prepared by first diluting the EmFG in deionised water (7.5  
169 vol%). A Brunel SP300-fl (Brunel Microscopes Ltd, UK) optical light microscope  
170 fitted with an SLR camera (Cannon EOS Rebel XS, DS126 191) at 20 and 40x  
171 optical magnification was used to image the particles. Slides were prepared by  
172 addition of 50 µL of sample to a microscope slide (VWR, UK) and covered with a  
173 coverslip (Thickness no.1, VWR, UK).

174



175 2.4.2. Confocal Laser scanning microscopy (CLSM)

176 Stained samples prepared with both Rhodamine B and Nile Red were  
177 imaged using concave microscope slides (60  $\mu$ L), with a coverslip sealed using  
178 super glue. Fluorescence free, UV transparent immersion oil (Sigma-Aldrich, UK)  
179 was used to bridge the gap between coverslip and objective lens (40x  
180 magnification). A Leica TCS-SPE confocal microscope (Leica Microsystems Ltd,  
181 UK) fitted with an argon laser was used for all CLSM analysis. Rhodamine B  
182 stained protein was excited at 532 nm and detected at 560-600 nm, and Nile Red  
183 was excited at 488 nm and detected at 680-700 nm respectfully. 3-dimensional  
184 images were obtained using 0.5  $\mu$ m slices throughout. Further image processing  
185 was undertaken using an image software package (ImageJ).

186

187 2.5. Rheological Analysis

188 Rheometry was conducted using a Bohlin Gemini HR Nano stress-  
189 controlled Rheometer (Malvern Instruments Ltd, UK) equipped with serrated  
190 parallel plate (25 mm diameter) at 1 mm gap height. Experiments were  
191 undertaken at 25  $^{\circ}$ C using a silicon oil moisture trap. An equilibrium was  
192 achieved for 15 minutes prior to testing, allowing for consistent loading  
193 conditions. Particle phase volumes were obtained using a method outlined by  
194 Moakes, et al. <sup>23</sup>; whereby aliquots of a given volume were centrifuged, water  
195 phase separated and volumes obtained. Phase volumes were calculated as  
196 followed (equation 1):

197 
$$\text{Particle Phase Volume} = 1 - \left( \frac{\text{Volume of Water Removed}}{\text{Total Initial Volume}} \right) \quad \text{Eq. [1]}$$

198

199 2.5.1. Yield stress determination

200 Yield stresses were determined as the stress at which the transition from  
201 storage modulus ( $G'$ ) to loss modulus ( $G''$ ) dominance occurred; the  $G'/G''$  cross  
202 over point on a stress controlled amplitude sweep. Amplitude sweeps were  
203 conducted at 1 Hz from 0.1 to 400 Pa.

204

205 2.5.2. Dynamic oscillatory measurements

206 Frequency sweeps were obtained between 0.1 and 10 Hz at controlled  
207 stress. The stress was determined by amplitude sweeps as a value within the  
208 linear viscoelastic region (LVR) for all EmFG tested. For samples containing no  
209 oil a, couette, double gap geometry was used: as the large surface area allowed  
210 lower values of  $G'$  to be probed in the lower viscosity fluids.

211

212 2.5.3. Viscosity measurements

213 Dynamic viscosity measurements were undertaken between 0.1 and 400  
214  $s^{-1}$ . Shear sweep time was set to 10 minutes (ramp ascending and descending).  
215 Two consecutive sweeps were run with the second commencing immediately  
216 after the first having been completed.

217

218 2.5.4. Recovery analysis

219 EmFG recovery was probed by primarily rejuvenating the system. A pre-  
220 shear ( $10 s^{-1}$  for 10 s) was applied to the system and subsequent change in  
221 storage modulus ( $G'$ ) recorded over the following 30 min.  $G'$  was obtained at 1Hz  
222 and 1 Pa.

223

## 224 **2.6. Encapsulation efficiency**

225           Optical microscopy was used to analyse oil droplet entrapment for each  
226 system. Micrographs of the raw emulsion were obtained and emulsion droplets  
227 in each image manually counted to give an average droplet count ( $N_{em}$ )  
228 determined over 12 images. Values for uncoated emulsion droplets ( $N_{fo}$ ) in the  
229 final EmFG systems were then obtained in the same manner. An example of both  
230 a coated and uncoated droplet has been shown in figure 1. The ratio of the two  
231 was used to calculate the percentage of encapsulated oil, as shown in equation 2:

$$232 \quad \%_{Encapsulated} = \left(1 - \frac{N_{fo}}{N_{em}}\right) \times 100 \quad \text{Eq. [2]}$$

233 Encapsulation was averaged over 12 micrographs with error calculated as the  
234 95% confidence interval.

235

## 236 **3. Results and Discussion**

### 237 **3.1. Preparation of emulsion fluid gels (EmFG)**

238           An O/W system where the excess WPI emulsifier exceeded the critical  
239 gelling concentration<sup>28</sup> (> 1 wt%), was subjected to heat treatment under shear  
240 conditions. The shear flow exerted on the system during the sol-gel transition  
241 prevented the formation of a continuous gel network, resulting in single discrete  
242 particles/encapsulates.

243

#### 244 **3.1.1. Encapsulation efficiency**

245           Figure 2 shows the encapsulation efficiencies for systems with both  
246 increasing WPI concentration (a) and oil phase volume,  $\phi_{oil}$ , (b). It was observed  
247 that high levels of encapsulation, ~99%, were achieved in systems with lower

248 WPI concentrations, however as the WPI exceeded 20 wt%, entrapment  
249 decreased. It is argued that the degree of encapsulation is closely correlated to  
250 the flow behaviour of the system during the sol-gel transition. It has previously  
251 been reported that around the isoelectric point of WPI (ca. pH 5) a transition  
252 from Newtonian to pseudoplastic flow occurs in systems containing 20 wt%  
253 whey protein, with yield stresses observed on further concentrated solutions<sup>29</sup>,  
254 <sup>30</sup>. Such changes in the system viscosity retard or prevent the diffusion of  
255 denatured protein to the oil/water interface due to a reduction in mobility and  
256 increased collisions with other denatured polymer chains. In turn, both  
257 increased formation of WPI aggregates without included oil and free emulsion  
258 droplets were observed in the final suspensions.

259         Increasing the phase volume of the oil from 5 to 20% whilst retaining a  
260 standard WPI concentration (15 wt%) however, had little effect on the emulsion  
261 entrapment, yielding droplet entrapment in excess of 95%. Here, the increase in  
262 oil was not sufficient to raise the viscosity of the system, and hinder polymer  
263 diffusion. However, at low oil fractions increasing the WPI concentration from 5  
264 to 15 wt% caused an observed transition from suspension creaming to  
265 sedimentation, indicating a change in particle density, probably as a result of a  
266 change in shell thickness.

267

### 268 3.1.2. Particle morphology

269         Particle morphology was studied using confocal laser scanning  
270 microscopy (CLSM). Previous reports regarding the formation of WPI microgel  
271 particles through the application of shear<sup>23</sup>, show irregular shaped particles,  
272 characterised by a larger length to width ratio. However, the incorporation of oil

273 in to the system resulted in particles with spherical morphology, whereby a gel  
274 layer surrounded an oil substrate, as shown in figure 3.

275         Imaging the EmFG particles at 0.5  $\mu\text{m}$  intervals gave enhanced  
276 topographical detail (figure 3a), allowing the coating to be observed. A non-  
277 uniform shell with much greater thickness than expected for emulsified droplets  
278 was shown, inferring the presence of a gel layer. Additionally, cross-sections  
279 were obtained using CLSM, which again show shell thickness and non-  
280 uniformity, but also through negative staining and dyeing, oil reservoirs in the  
281 centre of the particles (figures 3b and 3c respectfully).

282         The mechanism for particle formation is thought to be based upon the oil  
283 acting as a substrate for shell growth. Growth occurs through enrichment from  
284 the surrounding un-gelled biopolymer. Primarily led by the  $\beta$ -lactoglobulin,  
285 heat induced denaturation of the native structure causes hydrophobic regions to  
286 become exposed<sup>31, 32</sup>. Hydrophobic interactions then dominate the gelation  
287 causing diffusion of the denatured polymer to the oil/water interface. The oil  
288 droplet thus acts as a point for nucleation and growth. Shear imposed upon the  
289 system then restricts particle-particle aggregation, preventing a continuous  
290 network from forming. As a result, particles grow to an extent permitted by the  
291 shear flow, however are primarily dictated by the size of the emulsion droplets.

292

### 293 3.1.3. EmFG particle size distributions

294         Particle size distributions for all EmFG systems are shown in figure 4. It is  
295 clear from figure 4a that increasing WPI concentration results in a shift towards  
296 smaller particle sizes. Particles are primarily a function of the emulsion droplet  
297 size, thus such observations would be expected as increasing the emulsifier

298 concentration causes the formation of smaller droplets<sup>33,34</sup>. However, by further  
299 increasing the protein concentration up to 30 wt%, the formation of a bimodal  
300 system centred at  $\sim 9 \mu\text{m}$ , with a second peak at much higher particle sizes  
301 ( $\sim 200 \mu\text{m}$ ) was observed. The shift from monomodal to bimodal is due to the  
302 formation of gelled particles where no oil has been entrapped as observed  
303 through microscopy. As previously described, the change in system flow results  
304 in aggregated protein, as diffusion of the denatured polymer becomes restricted,  
305 causing a transition from protein-substrate to protein-protein interactions. The  
306 extent of such a transition is thus reflected by the change in peak intensity  
307 observed in systems with 20 to 30 wt% WPI.

308 Figure 4b shows little effect on the resulting particle size as a function of  
309 oil fraction, as a result of consistent emulsifier concentrations and unrestricted  
310 diffusion of biopolymer to the substrate interface. Thus, all distributions are  
311 centred around 25-30  $\mu\text{m}$  complimenting sizes observed via microscopy (figures  
312 1 and 3).

313

### 314 **3.2. EmFG material properties**

#### 315 **3.2.1. Small deformation oscillation testing**

316 To further understand and characterise the EmFG physico-mechanical  
317 properties, small deformation rheology was carried out. Figure 5a shows  
318 frequency sweeps obtained for EmFG systems prepared with varying oil  
319 fractions from 0 to 20 vol%. Systems containing no oil displayed typical liquid-  
320 like behaviour where both moduli were dependent on frequency and  $G''$  is higher  
321 than  $G'$  throughout the measured frequency range<sup>35</sup>. The addition of oil caused a  
322 transition in rheological behaviour to pseudo-solid where  $G'$  is higher than  $G''$ ,

323 with both moduli becoming further independent to frequency as a function of the  
324 oil. Here particle proximity is such that inter-particle interactions arise as  
325 observed for WPI microgel particles<sup>23</sup>, however, as the shear and thermal history  
326 exerted was consistent across all systems, it is argued that system elasticity  
327 becomes a function of the oil content; where increasing oil fractions increase the  
328 effective phase volumes of the particles, as shown in figure 5b.

329 To better understand the mechanism through which system elasticity  
330 arises, the results obtained have been compared to models already proposed for  
331 particulate suspensions. The Krieger-Dougherty (KD) model is used to describe  
332 the relationship between relative viscosity ( $\eta_{rel}$ ) and particle phase volume for  
333 hard sphere suspensions<sup>36</sup>, equation 2.

$$334 \quad \eta_{rel} = \left(1 - \frac{\phi}{\phi_{max}}\right)^{-[\eta]\phi_{max}} \quad \text{Eq. [2]}$$

335 The equation relates the ratio between the phase volume of the suspension,  $\phi$ , to  
336 the maximum packing fraction for monodisperse hard spheres (0.64),  $\phi_{max}$ , as a  
337 function of the intrinsic viscosity,  $[\eta]$ . What is clear from equation 2 is that as the  
338 maximum packing fraction is approached the relative viscosity will asymptote  
339 and eventually the equation fail as the suspension reaches/surpasses the  
340 maximum packing. As such, the KD equation cannot be used to describe the  
341 correlation observed in figure 5b, where the maximum packing fraction for hard  
342 spheres has been exceeded.

343 Similar observations have been reported for agar microgel suspensions<sup>9</sup>,  
344 where above a critical volume fraction,  $\phi_c$ , elastic response was observed,  
345 becoming insensitive to phase volumes above  $\phi_{max}$ . It was explained that above  
346  $\phi_c$ , elasticity was a function of the particle modulus; hence particles were

347 typically acting as soft spheres, however the plateauing effect was left  
348 unexplained, suggested as an artefact of the phase volume calculation. EmFG are  
349 therefore assumed to act as soft spheres. It is suggested that the soft oil core and  
350 elastic whey protein shell allows for particle deformation when highly  
351 concentrated, reaching phase volumes that exceed those expected for rigid  
352 spheres. At such high phase volumes a jamming phenomenon is observed, thus  
353 particle rheology mainly represents a function of the shell<sup>37</sup>. Hence above a  
354 volume fraction of 0.64 particles are packed to an extent that system elasticity is  
355 close to those shown for filled quiescent gels<sup>38</sup>, hence frequency sweeps show  
356 gel-like behaviour (figure 5a).

357 EmFG prepared using 5 vol% oil showed marked storage moduli even  
358 though  $\phi_{max}$  had not been reached. Here, elastic response is observed not through  
359 the jamming of particles, but assumed to arise from particle trapping as a result  
360 of steric confinement through inter-particle interactions. Between  $\phi_c$  and  $\phi_{max}$  it  
361 is argued that EmFG act as a glass where particles become trapped allowing  
362 localised motion but not long range diffusion, similarly to results published by  
363 Koumakis, et al. <sup>37</sup> and Le Grand <sup>39</sup>. Therefore, the EmFG can be categorised into  
364 three regimes; suspended particles below  $\phi_c$ , glassy between  $\phi_c$  and  $\phi_{max}$ , and  
365 jammed above  $\phi_{max}$ .

366

### 367 3.2.2. Material yielding behaviour

368 The effect of oil fraction on material response was further probed through  
369 the use of stress sweeps. Figure 6 shows the data obtained for EmFG with  
370 increasing oil content (from (a) to (d)). The stress sweeps indicate that at a  
371 critical stress the network started to break down. Further increasing the stress



372 led to a transition at which point the loss modulus dominated the storage. At this  
373 point a change in material response occurs, where the system no longer  
374 resembles a pseudo-solid, but is much more fluid-like. For systems in a glassy  
375 state, where particles have become trapped through inter-particle interactions,  
376 the linear viscoelastic region (LVR) was observed to be much shorter than those  
377 that are jammed. Again, such observations can be interpreted through the  
378 deformability of the particles; where particles are in close proximity they  
379 become compressed and deform, a larger stress is needed to induce flow as  
380 observed for  $\kappa$ -carrageenan fluid gels<sup>6</sup>. However, for systems where  $\phi$  does not  
381 surpass  $\phi_{max}$ , particles appear to act as hard spheres, as such deformation does  
382 not occur which is reflected by the lower stresses required to induce flow<sup>39</sup>, as  
383 shown in figure 7. Here it is possible to see a similar correlation as observed for  
384 the frequency sweeps, where a plateau is reached for oil fractions above 10  
385 vol%. This yielding insensitivity towards increasing oil fractions again infers a  
386 network of deformed particles closely packed together, as previously  
387 suggested<sup>39</sup>.

388

### 389 3.2.3. Suspension flow behaviour

390 System flow behaviours for all WPI EmFG were studied and presented in  
391 figure 8. EmFG showed marked shear thinning behaviours typical of highly  
392 flocculated suspensions<sup>40</sup>. At very low shear rates ( $\sim 0.01 \text{ s}^{-1}$ ) an apparent shear  
393 thickening can be observed as a resultant effect of soft jamming. Continued  
394 increase in the applied strain resulted in thinning of the suspensions. The  
395 observed thinning is due to the inhomogeneous flow across the shear profile  
396 applied, as a result of the break down to the weakly flocculated network<sup>40</sup>. Thus

397 a degree of inter-particle interactions is suggested, where initially clusters of  
398 mesostructures are broken down to form single mesostructures (smaller flocs)  
399 and eventually microstructures (single particles). To analyse this further, data  
400 has been presented for the ramp up, down and additionally a second sweep  
401 taken immediately after the first.

402 The presence of hysteresis highlighted a thixotropic nature arising  
403 through the breakdown of floccules and inter-particle interactions, as seen in  
404 figure 9. The plot shows a similar correlation as previously observed for yield  
405 stresses and frequency sweeps whereby the highly packed systems (10 to 20  
406 vol% oil) have a greater hysteresis. This indicates that jammed systems have a  
407 much higher degree of inter-particle interactions as a result of greater packing  
408 arising through particle deformation. As expected, where the particles remain  
409 unjammed a lower degree of thixotropy is observed, as non-deformed particles  
410 present a smaller surface area for inter-particle interactions to occur. However,  
411 data obtained for the second sweep showed a similar thixotropic behaviour for  
412 all systems, irrespective of oil content. Additionally, a combination of microscopy  
413 and light scattering techniques showed that the applied shear was insufficient to  
414 break the single particles, with the same particle size distributions observed pre  
415 and post shear sweeps (data not shown). As such it is argued that the shear  
416 applied throughout the first sweep disrupts the network to an extent that all  
417 particles behave as independent spheres. This is followed by restructuring  
418 between the particles, but on a scale that is much slower than the break down.

419

420 *3.2.4. Material recovery*

421           The recovery was further probed using oscillatory rheology. Primarily the  
422 system underwent rejuvenation, whereby the flocculated structure is broken  
423 down at a shear rate found within the shear-thinning region for all systems ( $10 \text{ s}^{-1}$   
424 for 10 s). The structuring was then observed through the storage modulus ( $G'$ )  
425 over the subsequent 30 min, figure 10. The recovery curves show a two-step  
426 process, initially rapid, followed by a more gradual increase in elastic modulus,  
427 observed as a power function ( $0.45 \pm 0.7$ ). The same power law dependency  
428 observed across all systems can be argued as the same recovery mechanism  
429 being observed *ie.* Initially there is rapid formation of a large number of small  
430 flocs, as the flocs grow in size the change in  $G'$  slows as fewer larger particles are  
431 available to interact. The extent and rate of recovery however was dependent on  
432 the volume fraction of the particles. Volume fractions greater than 0.64 could not  
433 be significantly differentiated, with the extent and rate of recovery depending on  
434 the self-similarity of the shells. For  $\text{EmFG} < 0.64$ ,  $G'$  values were lower by a factor  
435 of 10; as is observed from the frequency sweep data, again due to much less  
436 interacting where particles are further apart in space. As such, the hysteresis  
437 observed through dynamic shear experiments is suggested to arise not through  
438 the rupturing of a weakly gelled structure, but from the break down of reversible  
439 interactions between the particles.

440

#### 441 **4. Conclusions**

442           This study has shown that oil droplets can be incorporated into a WPI gel  
443 layer by applying a shear-gel technique. Entrapment efficiency was observed to  
444 be dependant on the protein concentration, as a function of the viscosity and  
445 flow behaviours, reaching up to 99% encapsulation. By applying shear during the

446 WPI sol-gel transition discreet micron sized spherical capsules were obtained,  
447 with enhanced structuring properties. Small deformation rheology was used to  
448 characterise the suspensions, which showed pseudo-solid like behaviour at rest,  
449 however, by applying a shear force to the system that is greater than the yield  
450 stress, the suspensions could be made to flow. Suspension rheology highlighted a  
451 significant dependence on the oil fraction, with the addition of oil increasing the  
452 effective phase volume of the particles, resulting in an increase in particle  
453 proximity. Increasing the oil content to around 10 vol% led to packing fractions  
454 that exceeded those for hard spheres. As such, particle properties have been  
455 expressed as soft and deformable. Flow behaviours of the suspensions were  
456 indicative of highly flocculated systems, where marked shear thinning was  
457 observed through the break up of weakly aggregated flocs and mesostructures.  
458 Furthermore, when left under quiescent conditions the particulate suspensions  
459 showed significant recovery, displaying the occurrence of reversible interactions.

460

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468

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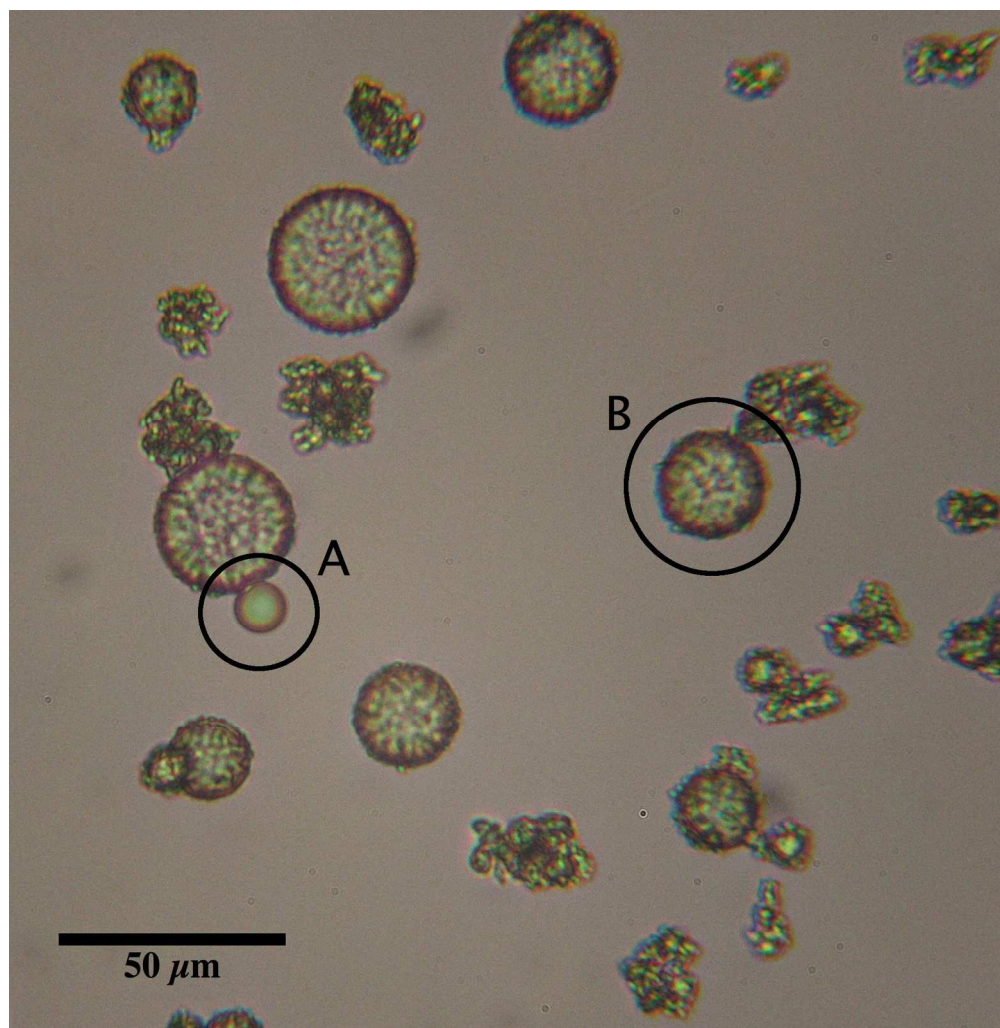


Figure 1: Optical micrograph highlighting (A) an uncoated oil droplet and (B) a coated EmFG particle.  
738x753mm (72 x 72 DPI)

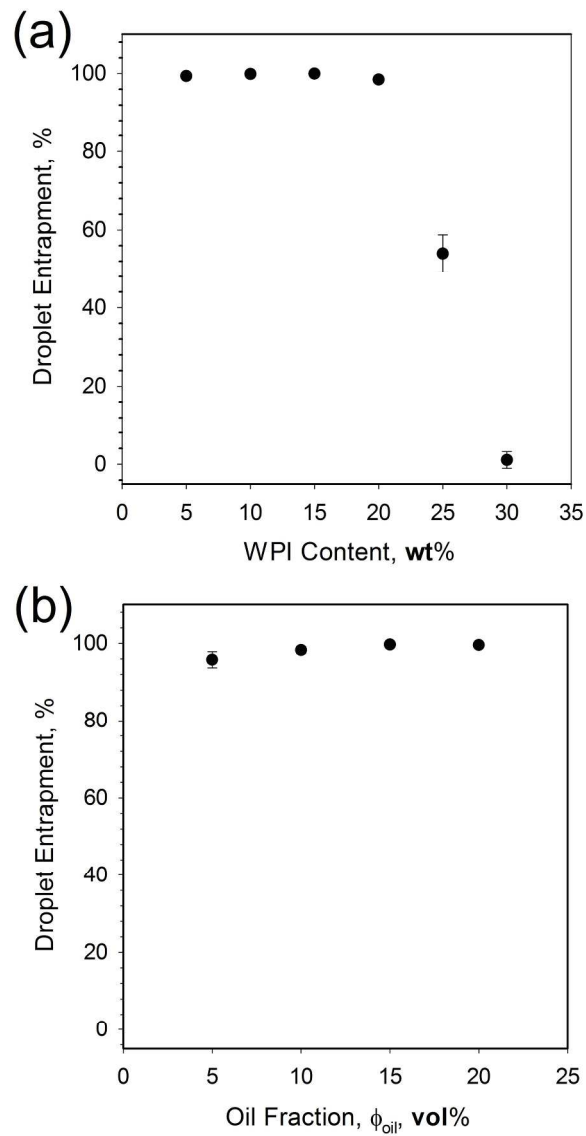


Figure 2: Oil droplet entrapment efficiencies for (a) EmFG systems prepared with increasing WPI concentrations ranging between 5 and 30 wt% at a fixed  $\phi_{oil}$  of 10 vol%, and (b) EmFG systems prepared with increasing  $\phi_{oil}$  between 5 and 20 vol% with a fixed WPI concentration of 15 wt%.  
188x330mm (300 x 300 DPI)



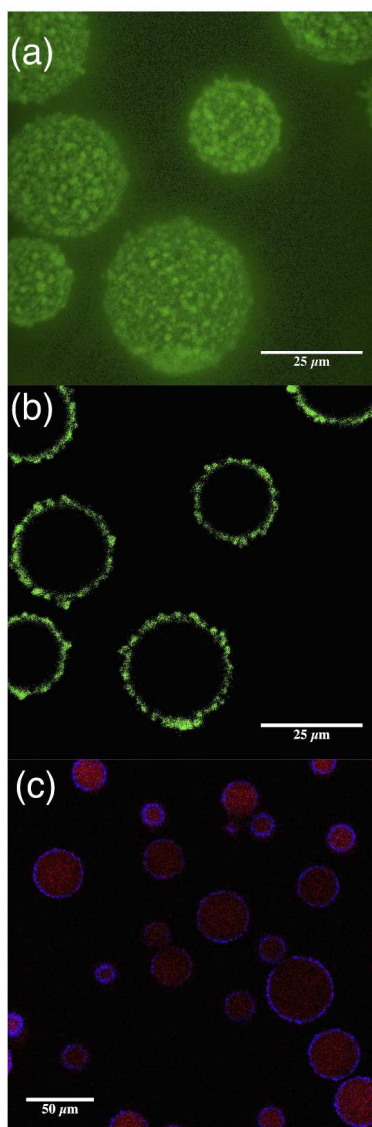


Figure 3: CLSM micrographs of EmFG particles. Gel phase has been stained using Rhodamine B (excitation wavelength: 532 nm, emission wavelength: 560-600 nm) and oil phase either negatively stained or stained using Nile red (excitation wavelength: 488 nm, emission wavelength: 690-700 nm). (a) 3D stack showing topographical detail of the EmFG particles, (b) cross section depicting stained gel layer surrounding a negatively stained oil core, and (c) stained cross section showing protein shell (blue) and oil core (red). Scale bars represent 25  $\mu\text{m}$  (a and b) and 50  $\mu\text{m}$  (c).  
256x658mm (300 x 300 DPI)

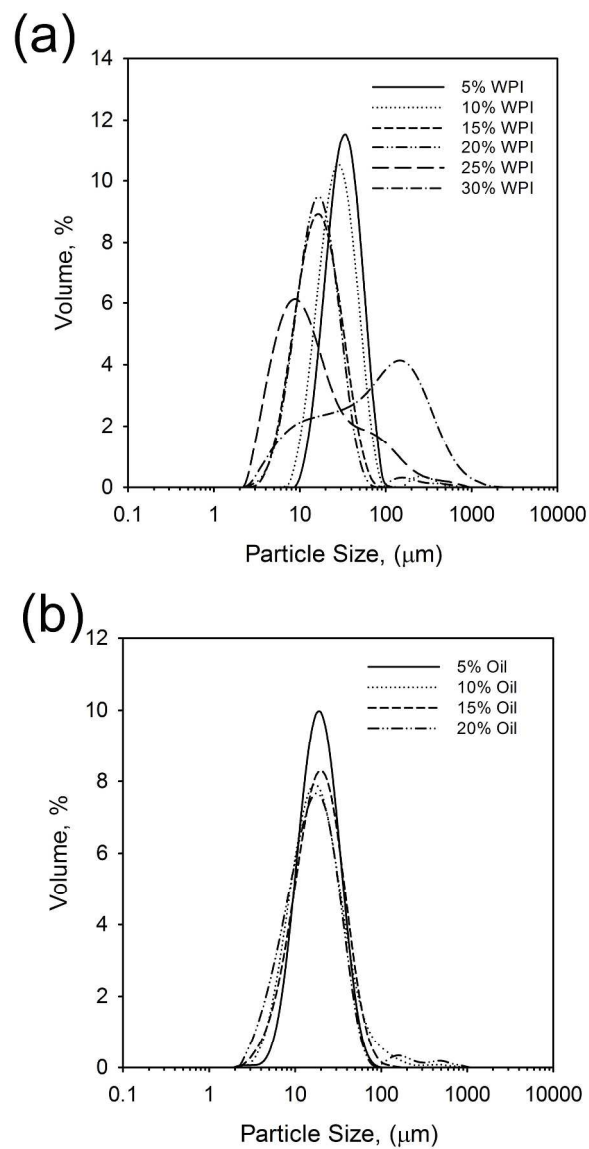


Figure 4: Particle size distributions for (a) EmFG prepared with a range of WPI concentrations between 5 and 30 wt% with a fixed  $\phi_{oil}$  of 10 vol%, and (b) EmFG prepared with a range of  $\phi_{oil}$  from 5 to 20 vol% with a fixed WPI content of 20 wt%.  
228x425mm (300 x 300 DPI)

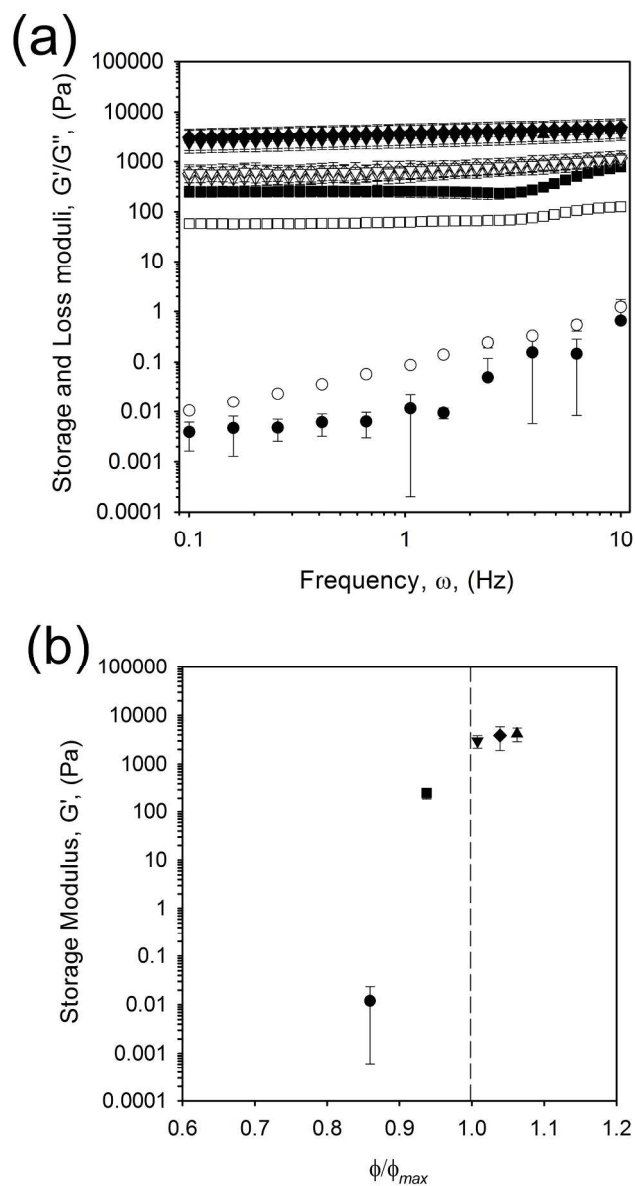


Figure 5: (a) Frequency sweeps obtained for EmFG prepared using 20 wt% WPI and ( $\square, \square$ ) no oil, ( $' \leq$ ) 5 vol% oil, ( $\theta, \sigma$ ) 10 vol% oil, ( $\downarrow, \downarrow$ ) 15 vol% oil, and ( $\pi, \rho$ ) 20 vol% oil. Open markers represent the storage moduli ( $G'$ ) and closed show loss moduli ( $G''$ ). (b) Storage modulus at 1 Hz versus particle phase volume for systems containing ( $\square$ ) no oil, ( $'$ ) 5 vol% oil, ( $\theta$ ) 10 vol% oil, ( $\downarrow$ ) 15 vol% oil, and ( $\pi$ ) 20 vol% oil. Dashed line represents maximum packing fraction for hard spheres.

214x352mm (300 x 300 DPI)

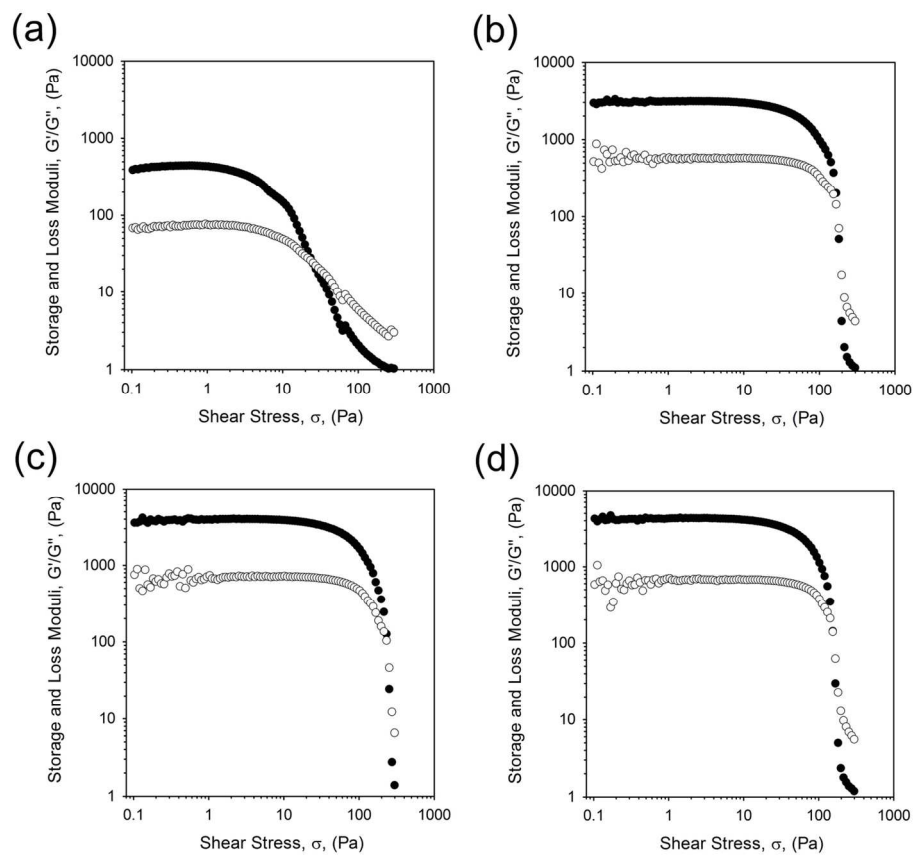


Figure 6: Stress sweeps obtained at 1 Hz for EmFG prepared with 20 wt% WPI and (a) 5 vol% oil, (b) 10 vol% oil, (c) 15 vol% oil, and (d) 20 vol% oil.  
141x132mm (300 x 300 DPI)

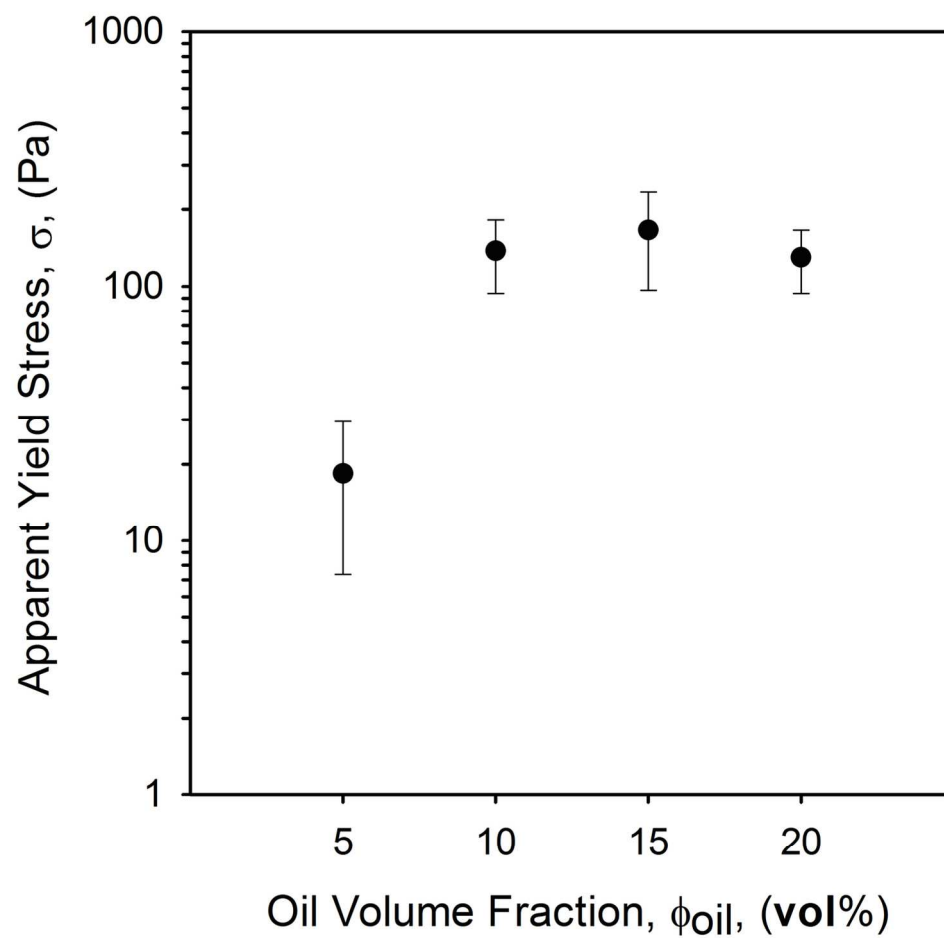


Figure 7: Apparent yield stresses determined using stress sweeps, as the point at which the storage modulus ( $G'$ ) cross the loss modulus ( $G''$ ) for EmFG systems prepared using 20 wt% WPI and oil fractions between 5 and 20 vol%.  
132x126mm (300 x 300 DPI)

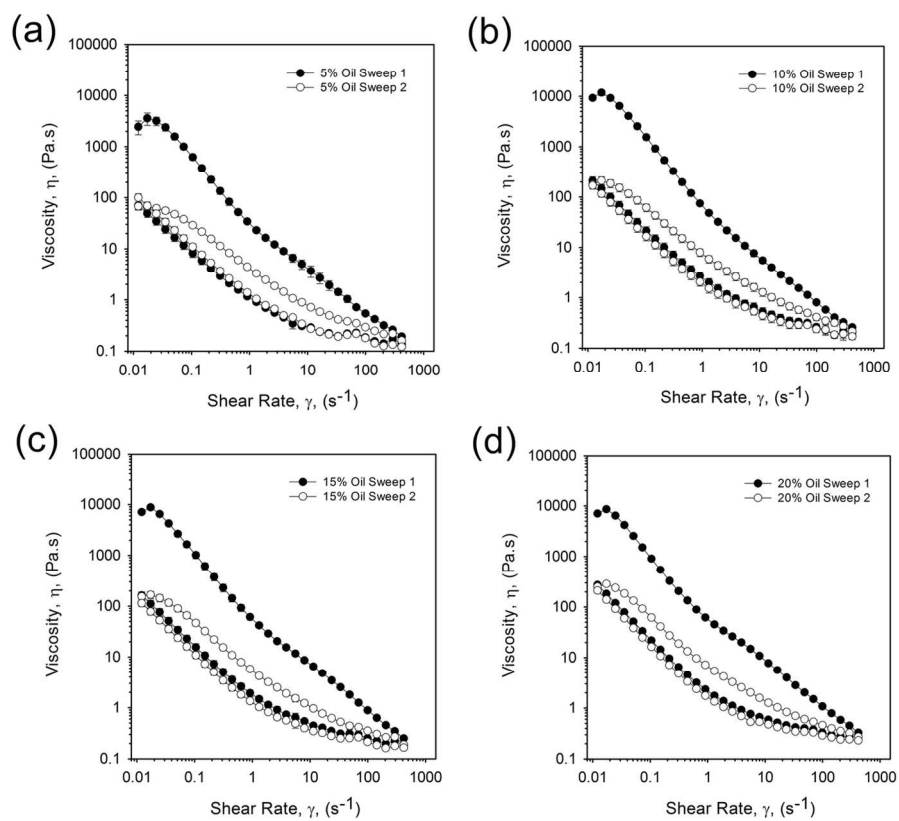


Figure 8: Viscosity profiles obtained for 20 wt% WPI EmFG containing (a) 5 vol% oil, (b) 10 vol% oil, (c) 15 vol% oil, and (d) 20 vol% oil. Closed markers represent sweep 1 and open, sweep 2.  
137x123mm (300 x 300 DPI)

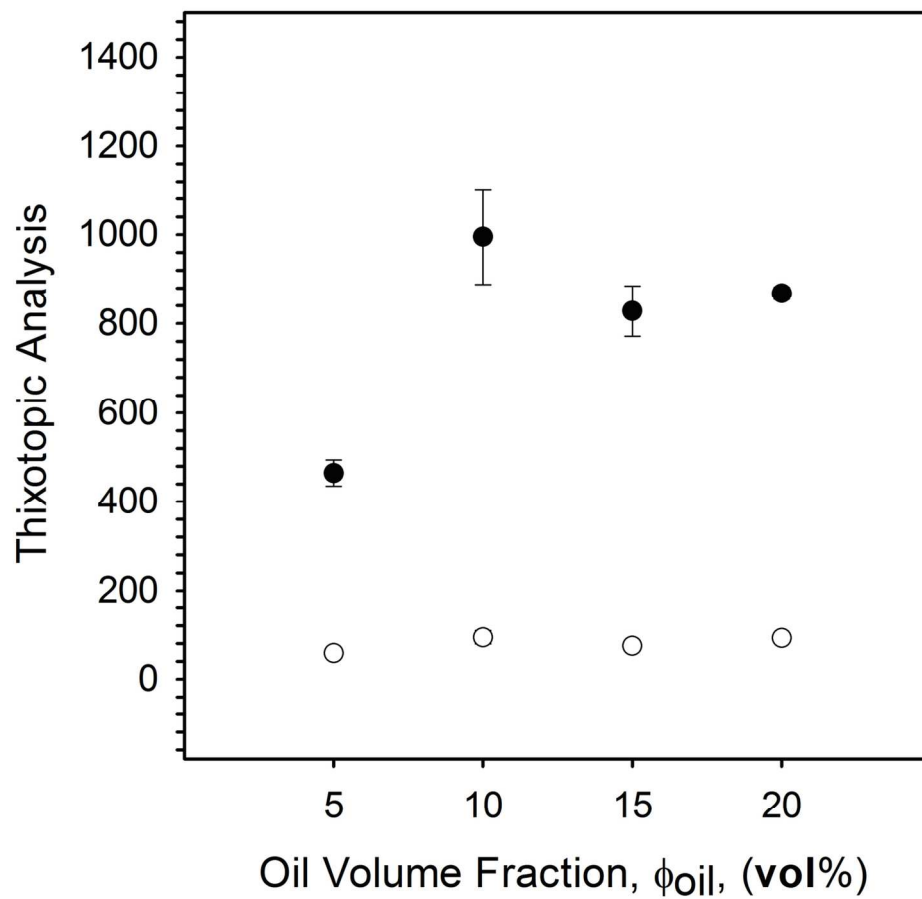


Figure 9: Thixotropic analysis obtained as the area between the viscosity profiles for 20 wt% WPI EmFG with increasing oil phase volumes from 5 to 20 vol% ( $\square$ ) denote thixotropic analysis for sweep 1 and ( $\bullet$ ) denotes values for sweep 2).

129x118mm (300 x 300 DPI)

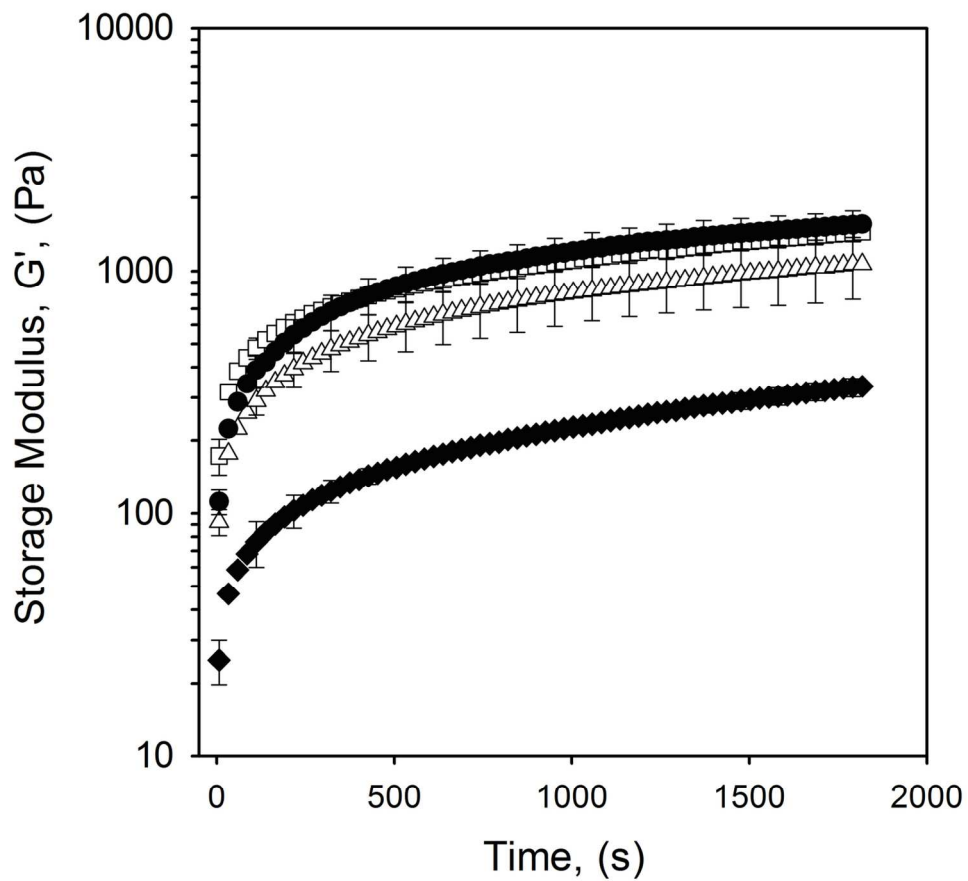
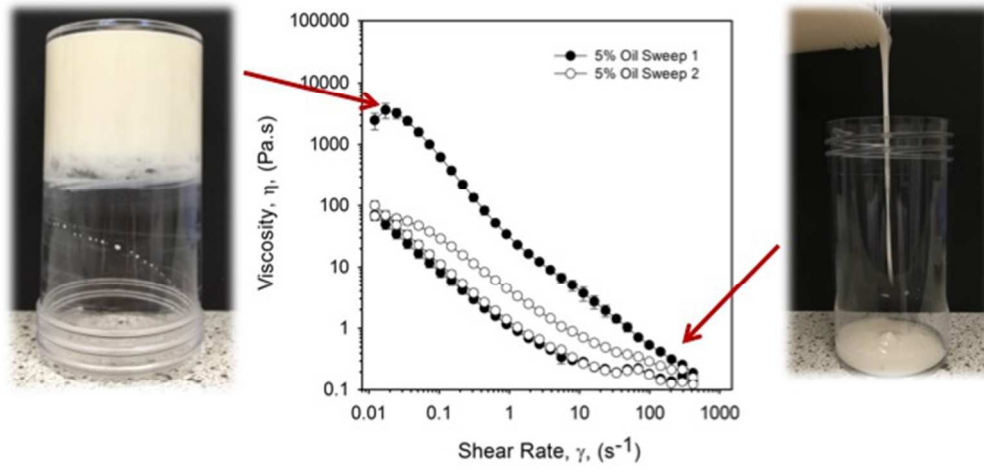


Figure 10: Storage modulus as a function of time for EmFG systems ( $\blacklozenge$ ) 5 vol% oil, ( $\triangle$ ) 10 vol% oil, ( $\bullet$ ) 15 vol% oil, and ( $\square$ ) 20 vol% oil. All EmFG underwent a rejuvenation process of  $10 \text{ s}^{-1}$  for 10 s before measuring  $G'$  at 1 Hz and 1 Pa stress for 30 minutes.  
127x114mm (300 x 300 DPI)





240x115mm (72 x 72 DPI)

The research uses a novel approach to tackle structuring in liquids through shear-gel technology, resulting in advanced material properties.