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1 **Investigation of Demulsification Efficiency**
2 **in Water-in-Crude Oil Emulsions Using**
3 **Dissipative Particle Dynamics**

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10 **Keywords** Dissipative particle dynamics, Polyether demulsifiers, Different
11 hydrophobic block, ultra-heavy crude oil demulsification.

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1 **Abstract** In this study, simulations of dissipative particle dynamics (DPD) were
2 employed to investigate the efficiency of polyether demulsifiers, substituting
3 polyoxypropylene (PPO) hydrophobic blocks for polybutylene oxide (PBO) and
4 polytetrahydrofuran (PTF) in ultra-heavy crude oil emulsions. The simulation results
5 showed that the demulsifiers with polybutylene oxide (PBO) hydrophobic blocks
6 favor high level of demulsification while the demulsifiers with polyoxypropylene
7 (PPO) hydrophobic blocks exhibit better dehydration rates. The kinetics equation
8 demonstrates that the demulsification process is controlled by the combination of
9 flocculation and coalescence. As time progresses, the rate-controlling process of
10 demulsification changes from coalescence controlled to flocculation controlled.
11 Moreover, high performance demulsifiers which have higher rate constants for
12 coalescence could accelerate the rate of drainage of the film much faster, thereby
13 promoting coalescence. The root mean square end-to-end distance $\langle R \rangle$ for
14 demulsifiers continues to grow with time, such that their configurations become more
15 stretched. This results to interface arraying and demulsifiers build up a continuous
16 open network which leads to a higher possibility of droplet-droplet coalescence. The
17 variation in radial distribution function (RDF) indicates that there is a rather strong
18 and remarkably structured interaction between asphaltenes and demulsifiers,
19 corresponding to the radial distribution range from 10 Å to 50 Å.

1. Introduction

Water-in-oil emulsions formed during oil slicks or petroleum production are known to be stabilized by interfacially active substances that naturally occur in crude oil, such as, asphaltenes, resins, naphthenic acids, and fine solid [1-3]. Destabilization of emulsions is an essential step in obtaining water-free oil. There are various methods used to separate crude oil from oil-water emulsions, such as mechanical, electric, and chemical [4], but the addition of chemical demulsifiers is the most widely practiced method [5].

Demulsifiers, an amphiphilic and surface-active polymers, can absorb at the water/oil interface and change water/oil interfacial properties, such as, interfacial tension [6], interfacial dilational viscoelasticity [7-8], and interfacial rheological properties [9]. Currently, the main focus is on use of non-ionic demulsifiers, especially polyoxypropylene-polyoxyethylene (PPO-PEO) polyether demulsifiers, where the propylene oxide (PO) blocks provide the hydrophobic component of the demulsifiers and the propylene oxide (EO) blocks function as the hydrophilic component [10]. By varying the number and arrangement of the ethylene oxide (EO) and propylene oxide (PO) groups, amphiphilic copolymer demulsifiers having different structures and molecular weights were synthesized and widely used in oilfields [11-12]. Unfortunately, the higher level of heavy fractions of crude oil usually lead to the formation of highly stable oil-water emulsions [13]. Conventional demulsifiers failed to solve the above problem in oilfields. Thus, it remains a

1 challenge to design other highly effective demulsifiers to be used in oilfield
2 stimulation. In this paper, some novel polyether demulsifiers, in which the
3 hydrophobic groups PPO blocks are replaced by poly butylene oxide (PBO), and
4 polytetrahydrofuran (PTF), are designed and discussed in detail.

5 In the past decades, a large number of theoretical researches had been dedicated to
6 the study of microstructures of amphiphilic copolymers using computer simulations. It
7 is in principle, viable to study the efficiency of the demulsifiers at the atomistic level
8 using molecular dynamics (MD) [14]. MD can provide specific information regarding
9 the interfacial behavior of demulsifiers without compromising the atomistic details.
10 However, the time scale and length scale accessible to classical MD is too short to
11 allow for observation the efficiency of demulsifiers in the crude oil-water emulsions.
12 Generally, oilfield emulsions have droplet sizes exceeding $0.1\mu\text{m}$ and may be larger
13 than $50\mu\text{m}$ [15]. It is obvious that the demulsification takes place at mesoscopic level.
14 However, by introducing dissipative force and the coup of friction coefficient and
15 noise amplitude, DPD is an excellent method for the simulation of coarse-grained
16 systems over considerable length and time scales up to the mesoscopic level [16].

17 DPD method is a powerful tool for investigating emulsion systems. Lin et al. [17]
18 used DPD method to study the microstructures of an emulsion using alternating
19 copolymers as the demulsifiers and also to study the kinetics of emulsion formation.
20 Subsequently, Fan and Striolo [18] reported the mechanism of coalescence of droplets
21 in Pickering emulsions. Fraaije et al. [19] made use of the DPD method to design the

1 microemulsion process and succeeded in proposing a dependable method of moments
2 for computational microemulsion analysis.

3 In this paper, demulsification efficiencies of several types of novel polyether
4 demulsifiers, in which the hydrophobic group PPO blocks were replaced by
5 polybutylene oxide (PBO) blocks and polytetrahydrofuran (PTF) blocks, were
6 investigated by dissipative particle dynamics (DPD). Moreover, the dynamics for the
7 demulsification process has been investigated and the demulsification kinetics discuss.
8 Finally, by introducing the root mean square end-to-end distance $\langle R \rangle$ and the radial
9 distribution function (RDF), the effect of different hydrophobic blocks on the
10 demulsification efficiency has also been studied. As a result, the coalescence process
11 in the presence of demulsifiers can be better understood.

12 2. Model and Methods

13 2.1 Dissipative Particle Dynamics (DPD) Simulation Technique

14 The DPD simulation was developed by Hoogerbrugge and Koelman and cast in the
15 present form by Español [16]. In DPD simulation, the aggregates of plurality of atoms
16 or molecules are defined as a bead. Every bead's motion equation accords with the
17 Newton's law.

$$18 \quad \frac{dr_i}{dt} = v_i, f_i = m \frac{dv_i}{dt} \quad (1)$$

19 Where r_i and v_i are denoted as the position vector and velocity of the i th bead.

$$20 \quad f_i = \sum_{i \neq j} (F_{ij}^C + F_{ij}^D + F_{ij}^R) + f_i^S \quad (2)$$

1 The term in brackets are three non-bonded forces acting between each pair of beads:
 2 conservative repulsive forces (F_{ij}^C), representing excluded volume; dissipative forces
 3 (F_{ij}^D), representing viscous drag; random forces (F_{ij}^R), representing stochastic impulse.
 4 The remaining terms are forces due to bonded interactions: springs force (f_i^S).

5 Here, conservative forces (F_{ij}^C), is usually soft repulsive of the form

$$6 \quad F_{ij}^C = \begin{cases} a_{ij}(1-r_{ij}) \hat{r}_{ij} & \text{if } |r_{ij}| < 1 \\ 0 & \text{if } |r_{ij}| \geq 1 \end{cases} \quad (3)$$

7 Where a_{ij} is a maximum repulsion between particles i and j , r_{ij} , $|r_{ij}|$ are the distance
 8 and relative distance between them, with the corresponding unit vector \hat{r}_{ij} which
 9 defined as $\hat{r}_{ij} = (\mathbf{r}_i - \mathbf{r}_j) / |r_{ij}|$.

10 The other two forces dissipative forces (F_{ij}^D), random forces (F_{ij}^R) are given by

$$11 \quad F_{ij}^D = \begin{cases} -\gamma\omega^D(r_{ij})(\hat{r}_{ij} \cdot \mathbf{v}_{ij})\hat{r}_{ij} & \text{if } |r_{ij}| < 1 \\ 0 & \text{if } |r_{ij}| \geq 1 \end{cases} \quad (4)$$

$$12 \quad F_{ij}^R = \begin{cases} \sigma\omega^D(r_{ij})\theta_{ij}\hat{r}_{ij} & \text{if } |r_{ij}| < 1 \\ 0 & \text{if } |r_{ij}| \geq 1 \end{cases} \quad (5)$$

13 Where \mathbf{v}_{ij} defined as $\mathbf{v}_{ij} = \mathbf{v}_i - \mathbf{v}_j$, \mathbf{v}_{ij} is the velocity difference for the two particles, and
 14 θ is a random number between 0 and 1, ω is the weight function. γ is the friction
 15 coefficient and σ is the noise amplitude. The combined effect of these two forces is a
 16 thermostat, which conserves momentum and, hence, gives the correct hydrodynamics
 17 at sufficient long time and length scales [20].

18 To obey the fluctuation-dissipation theorem, it must have $\omega^D = (\omega^R)^2$, and the system
 19 temperature will follow from the relation between γ and σ . $\sigma^2/\gamma = 2kT$. The same

1 integration algorithm, weight functions, and parameters as Groot and Warren are
 2 utilized throughout paper [16]:

$$3 \quad \omega(r) = \omega^C(r) = \omega^D(r) = \sqrt{\omega^R(r)} \quad (6)$$

4 Where

$$5 \quad \omega(r) = \begin{cases} 1 - \frac{r}{r_C} & \text{if } r < r_C \\ 0 & \text{if } r \geq r_C \end{cases} \quad (7)$$

6 Throughout this paper the reduced units are used and r_C is the unit of length, kT (the
 7 temperature of the thermostat) is the unit of energy, and the mass unit is the mass of a
 8 DPD bead. In these units, the dissipative parameter $\gamma=4.5$, the noise parameter $\sigma=3.0$
 9 [21].

10 All DPD beads belonging to the same molecule are connected by a loosely bounded
 11 spring. By means of this spring force, the molecule's stiffness can be controlled, and
 12 the particles can be interconnected to complex topologies. According to Groot's work,
 13 the spring force f_i^S on particle i can be calculated by equation with a spring force
 14 constant $K=4.0$ [22].

$$15 \quad f_{ij}^S = K \left(\frac{r_{ij}}{r_C} \right) \hat{r}_{ij} \quad (8)$$

16 This spring constant controls the stiffness of the molecule; however, the simulation
 17 results are not very sensitive to the stiffness of the molecule [22].

18 **2.2 Coarse-Graining Model**

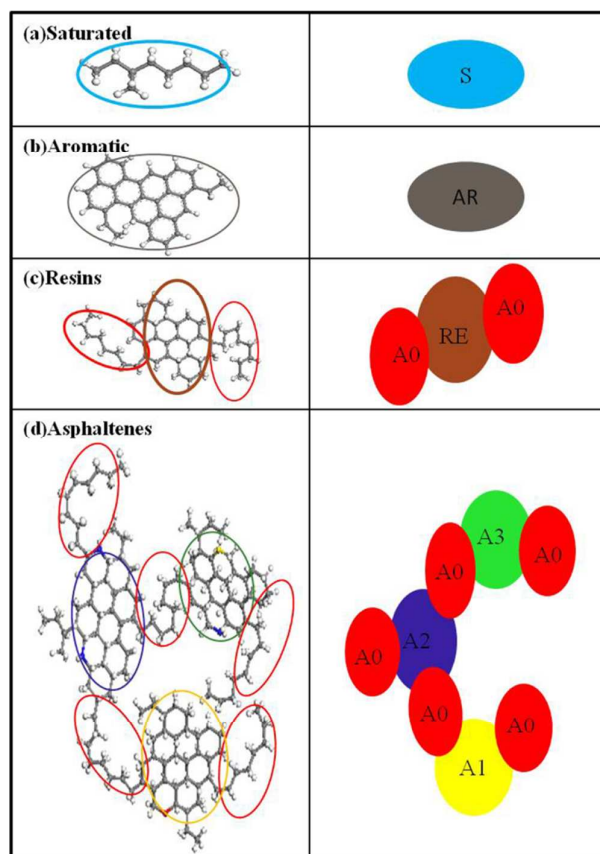
19 It is well-known that crude oil ingredients are extremely complex and multifold,
 20 and significant differences in physical properties differences exist in different oilfield

1 regions and different strata. Zhang et al. proposed a reliable method, in which crude
2 oil could be substituted by SARA, four-fractions which include saturates (S),
3 aromatics (AR), resins (RE), and asphaltenes (A) [23]. It is believed that these
4 representative fractions are endowed with unique physical and mechanical properties,
5 due to which, they interact chemically and physically with each other, giving crude
6 oils, having rich and complex behaviors [24]. It is also very convenient to adopt this
7 strategy when the characterization data of the oil sample is available. In this paper, the
8 ultra-heavy oil emulsions produced in Shengli Oilfield were chosen to carry out all the
9 entire simulations. As shown in **Table 1**, the contents of asphaltenes and resins in
10 Shengli oilfield reach up to 19.88% and 20.67% respectively. They are primary
11 interfacial active substances, which promote the formation of highly stable
12 water-in-oil emulsions.

13 **Table 1.** Property of the ultra-heavy crude oil in Shengli Oilfield[25].

Density(20°C) g•cm ⁻³	Viscosity(50°C) mPa•s	Asphaltenes %	Aromatics %	Resins %	Saturates %
1.0072	40960	19.88	39.28	20.67	20.17

14 In the present case, 18 water molecules were considered as a single bead. Saturates
15 or aromatics are denoted by one bead (see **Figure 1**). With two alkyl chains and an
16 alicyclic core, the resin is defined as three beads, as shown in **Figure 1c**, and the ratio
17 of number of hydrogen to carbon atoms and the average relative molecular weight are
18 1.68 and 603.076 g/mol, respectively.



1
2 **Figure 1.** Schematic representation of coarse-grained crude oil SARA models. Figure
3 (a) saturated, namely, 3-methyl-octane, Figure (b) aromatic, 8 condensed aromatic
4 rings in its structure, Figure (c) resins, two alicyclic groups and two alkyl chains in its
5 structure, Figure (d) asphaltenes, core consisting of three alicyclic groups and five
6 alkyl chains in the structure. Core 1 of asphaltenes contains one oxygen atom, core 2
7 contains two nitrogen atoms, and core 3 contains one nitrogen atom and one sulfur
8 atom.

9 Though, it is a well-known fact that asphaltenes are present inherently as condensed
10 aromatic rings in the core, connected to each other by alicyclic groups and alkyl
11 chains, the degree and the way in which the condensed aromatic rings of asphaltenes
12 are in dispute at present [26-27]. Regardless of the debates concerning the structures
13 of the constituents of the crude oil fractions like asphaltenes and resins, it was
14 common to take the idea that asphaltene molecules are continental architectures,
15 which have the shape of a hand, the aromatic rings appearing as the palm and the

1 alkyl side chains as the fingers (see **Figure 1d**). Another widely accepted model for
2 asphaltenes is an archipelago architecture, which were thought to be composed of
3 several small fused aromatic rings connected by bridge chains of small molecular
4 weights. Archipelago architecture model is more applicable to light crude oil rather
5 than to heavy or ultra-heavy oil. This paper chose continental architectures. Since the
6 topological structure of asphaltenes is extremely complex, constructing a favorable
7 coarse-grained model to investigate the demulsification process is still a challenge.
8 However, Fernando Alvarez et al. [28] proposed a simplified but useful asphaltene
9 model, although some dispute still exists. In this model, asphaltene cores as a
10 single bead by characteristic intra-molecular hydrogen bonding amongst its molecules
11 [29]. At the same time, the asphaltene molecules have one or more rigid planes [30].
12 Therefore, it has to be considered as a single molecular bead and one needs to
13 consider the individuality of the aromatic cores or the polarity effect of heteroatoms as
14 well as maintaining the rigid planes of asphaltenes. This type of coarse-graining
15 method to treat polycyclic aromatic compounds is consistent with the experimental
16 results and has also been reported [31-33].

17 Based on the structural and chemical properties of asphaltenes, three asphaltene
18 cores and five aliphatics are used to construct a molecule of asphaltene authentically.
19 An asphaltene molecule of $At_{3\text{cores}}-3N+S+O$ is shown in **Figure 1d**. In the present
20 work, connection rigidity in bound between the asphaltene and resin core beads and
21 their aliphatic connected beads connected with aliphatics is considered to be similar to

1 the rigidity of the interconnection between the polymer beads. Therefore, the spring
2 force constant K , associated with the strength of the string interaction between the
3 beads, is kept constant, with $K=4.0$ (in reduced units, $K_B T/R_C^2$) for all the connected
4 beads in the system [28]. For the simulation of asphaltene, the ratio of the hydrogen to
5 carbon atoms and average relative molecular weight is 1.5701 and 20001.589g/mol.

6 In a similar way, three types of triblock demulsifiers are stipulated, whose
7 structures follow the sequences (1) DPO, T-[PO]₂[EO]₁₂[PO]₁₂, (2) DTF,
8 T-[TF]₂[EO]₁₂[TF]₁₂, (3) DBO, T-[BO]₂[EO]₁₂[BO]₁₂. N, N-dimethyl ethanolamine
9 (T) is the demulsifier initiator and EO, PO, TF, BO are ethylene oxide, propylene
10 oxide, tetrahydrofuran, and butylene oxide, respectively. The mesoscale
11 representation of demulsifiers was carried out using a linear Gauss chain of [EO],
12 [PO], [TF], [BO]. Three types of demulsifiers having different hydrophobic blocks
13 were specially prepared. Depending on solubility parameters, the immiscibilities
14 between different hydrophobic blocks and water are $I_{PO/water} < I_{TE/water} < I_{BO/water}$ [34].

15 In this paper, a rather moderate coarse-grained model was constructed by grouping
16 18 water molecules into one DPD bead. The physical units could be derived from the
17 promissory coarse-graining level. The length scale R_c in angstroms and the time scale
18 τ in picoseconds can be evaluated, as $R_c = 3.107(\rho N_m)^{1/3}$ Å, $\tau = (1.41 \pm 0.1)N_m^{5/3}$ ps with
19 $N_m = 18$, $\rho = 3$ [35]. Actually, length and time scales in physical units are $R_c = 11.744$ Å,
20 and $\tau = 173.1$ ps. It is easy to know that the spatial and temporal range of the DPD
21 simulations could be in the range of nanometers and micrometers.

2.3 Parameters in DPD Simulation

The results of DPD simulations are usually determined by two parameters, namely, the mode for coarse-grained of molecules and the interactions of DPD particles [36]. There are various ways to calculate the conservative force parameter. In 1997, Groot and Warren established a relationship between the conservative force parameter a_{ij} and the Flory-Huggins χ_{ij} parameter [16]. Later, the function of Flory-Huggins χ_{ij} parameter as the cohesive energy density was proposed by Travis in 2004 [37]. Besides this, the Flory-Huggins χ_{ij} parameter can be evaluated from the solubility parameters which could be obtained through simulation of dynamics (MD) or experiments [38-39]. However, it is still a challenge to determine the conservative force parameters for the particles representing the extremely complex fused aromatic rings in heavy crude oil. Most of the conservative force parameters are determined in this work by the Blends method [24]. “Blends”, which is the module of Materials Studio from Accelrys Inc., provides a way to obtain χ by estimating the miscibility behavior of binary mixtures. It predicts the thermodynamics of mixing directly from the chemical structures of the different kinds of beads. Therefore, only their molecular structures and a force field are required as inputs [40]. Here, the COMPASS force field is adopted, and the interaction parameters can then be calculated by the χ - a_{ij} relation with $\rho=3$ [41]:

$$a_{ij} = \frac{\chi_{ij}}{3.06} + 25 \quad (9)$$

Here, χ_{ii} is set at 0, and, a_{ij} is 25 [42]. Based on this, the conservative force

1 parameters a_{ij} between beads at 363K are listed in **Table 2**.

2 **Table 2.** Parameters of conservative force at 363K.

Bead name	A0	A1	A2	A3	AR	RE	S	W	T	PO	EO	TF	BO
A0	25												
A1	92	25											
A2	45	39	25										
A3	26	28	38	25									
AR	36	31	26	27	25								
RE	103	44	32	46	32	25							
S	25	105	147	152	156	78	25						
W	73	197	185	180	205	188	67	25					
T	71	25	25	25	33	35	61	54	25				
PO	35	95	105	145	123	38	35	48	35	25			
EO	40	95	132	123	143	41	39	43	34	25	25		
TF	61	117	108	128	184	77	59	52	33	/	52	25	
BO	67	176	195	185	143	47	64	68	32	/	39	/	25

3 **2.4 Simulation Details**

4 The DPD simulations were carried out using the DPD module in Material Studio
 5 6.1. In this paper, all the simulations were accomplished in a cubic box with a size of
 6 $40 \times 40 \times 40 R_c$ with periodic boundary conditions at 363K. Hence, for $\rho=3$, the total
 7 number of beads is 1.92×10^5 . Firstly, the oil-water emulsions were prepared by filling
 8 each simulation cell with the following crude oil and water composition: 17.75%
 9 asphaltenes, 35.07% aromatics, 18.46% resins, 18.01% saturates, and 10.71% water.
 10 This composition gives the following ratios: aromatic/saturate=1.947 and
 11 resins/asphaltenes=1.0397. Moreover, the other three cells containing oil-water
 12 emulsions and three types of 1% demulsifiers respectively are built to simulate
 13 demulsification process, and the process of demulsification is completely recorded.

3 Results and Discussion

3.1 Dynamics of the Demulsification Process

3.1.1 Water-in-oil Emulsions Model

The typical water-in-oil emulsions were firstly simulated, as shown in **Figure 2**. There are water droplets of five sized in the cell, whose three-dimensional coordinates are (8.8, 16 and 9.2), (12.8, 12.4 and 2.8), (9.2, 7.6 and 8.4), (3.2, 5.6 and 2.0), (6.8, 16.4 and 7.2), respectively. As reported previously, the accumulation of asphaltenes at the oil/water interface would result in the formation of a rigid film which acts a barrier to droplet coalescence [43-44]. The simulations of the water-in-oil emulsions are in accordance with reported data. The size and number of water droplets keep unchanging after 2.3×10^4 time steps, and hence stable crude oil emulsions are formed. Based on the morphologies of the emulsified water droplets in systems, stable crude oil emulsions are obtained and prepared for further demulsification simulations. A typical DPD simulation of demulsification requires only about 5×10^4 steps to separate emulsions. In this work, each simulation takes at least 10×10^5 steps and the first (1-2) $\times 10^5$ steps are for equilibration.

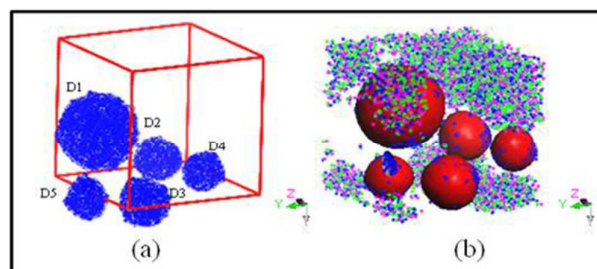


Figure 2. The morphology of oil-water emulsions. Figure (a) four representative

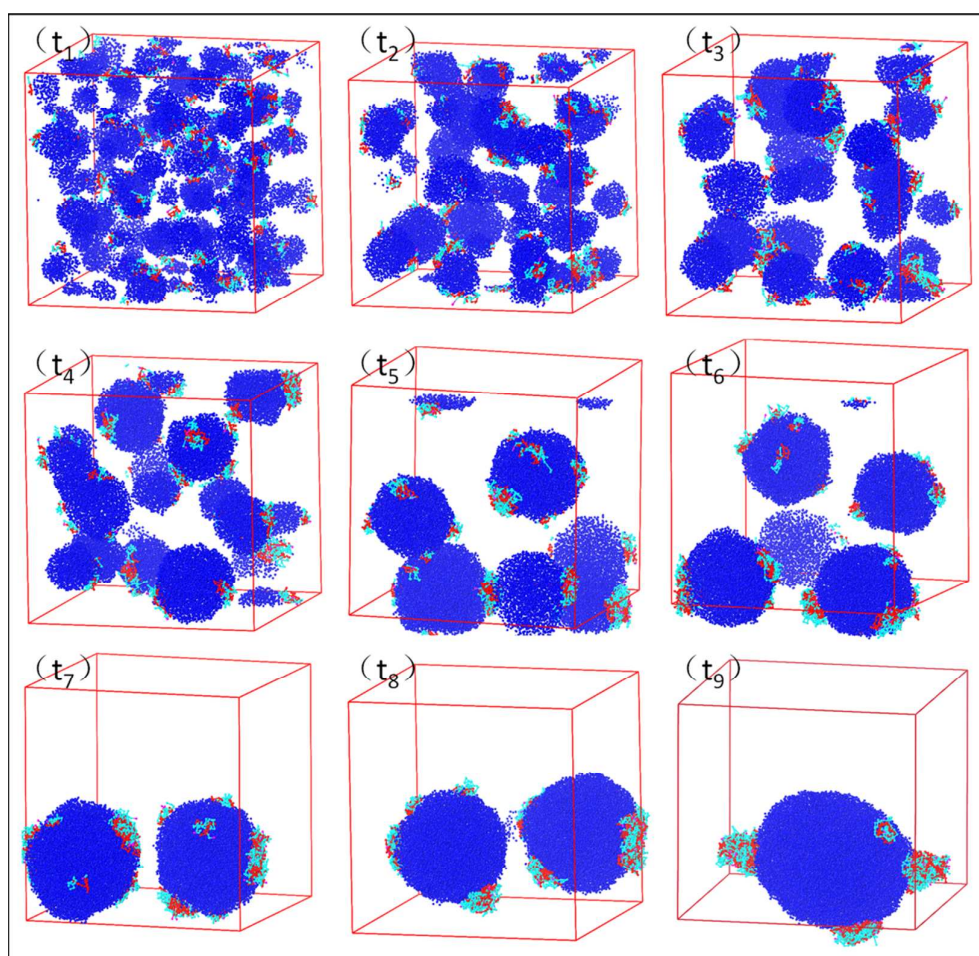
1 crude oil fractions are concealed, Figure (b) all the crude oil fractions are concealed
2 except asphaltenes.

3 **3.1.2 Demulsification Dynamics of Demulsifiers**

4 To the best of our knowledge, there is no discussion on the model of
5 demulsification of ultra-heavy crude oil at the mesoscale. **Figure 3** displays the
6 simulation results on the morphology of water droplets in oil-water emulsions, in
7 presence of each of 1% DPO demulsifiers. It is demonstrated that the increase in the
8 size of the droplets can be considered in two stages: preliminary swift stage due to
9 high dispersity of water and demulsifiers, secondary stage in which, the diameter
10 slowly increases due to the large distances between the droplets. Flocculation mainly
11 occurs in the initial growth stage. The similar morphology results for DTF and DBO
12 demulsifiers were displayed in Figure S1 and S2 of the Supporting Information.

13 In the flocculation stage, the droplets disperse uniformly and have short distances
14 between each other before 0.8×10^4 steps, as shown in **Figure 3a** (t_1 - t_5). In emulsion
15 systems, flocculation is a reversible process, in which two or more drops of the
16 disperse phase, cluster together as aggregates. Flocculation causes two effects which
17 are detrimental to emulsion stability: (i) an increase in the effective size of the
18 particles, thus enhancing the creaming rate and (ii) an increase in the probability of
19 coalescence, since flocculation precedes coalescence. In the secondary stage, major
20 coalescence of the droplets occurs, the size of the droplets are larger and have a longer
21 distances between each other, as shown in **Figure 3a** (t_6 - t_9). Once flocculation occurs,

1 the drops in close proximity with each other are separated by a thin asphaltenes film
2 of the continuous phase. Under the various forces acting on the film (kinetic or
3 gravitational), the films drain and rupture, resulting in the coalescence of the drops. In
4 brief, the continuous change in drop sizes in these systems results from the combined
5 processes of flocculation and coalescence. The change in the drop size can change the
6 stability of emulsions which results in separation of crude oil-water emulsions. The
7 similar feature of flocculation/demulsification stages for DTF and DBO demulsifiers
8 also can be found in Figure S1 and S2 of the Supporting Information.



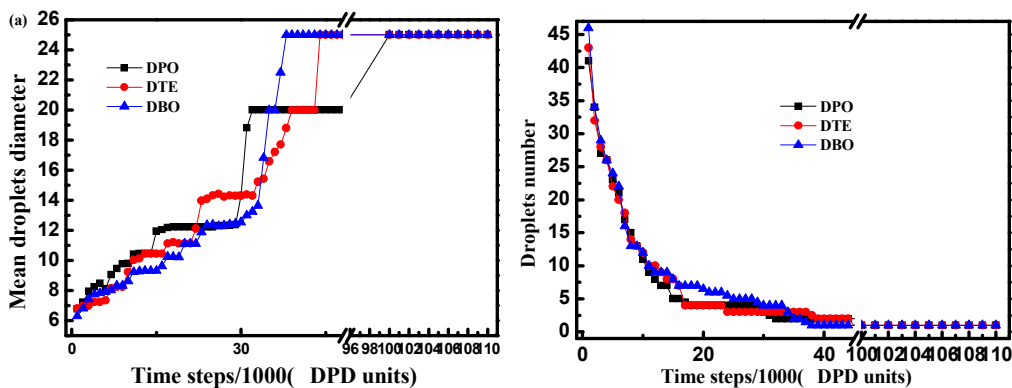
9
10 **Figure 3.** The snapshots of demulsification in presence of DPO demulsifiers during
11 simulation steps: t_1 , 0.1×10^4 time steps; t_2 , 0.3×10^4 time steps; t_3 , 0.5×10^4 time steps;

1 t_4 , 0.8×10^4 time steps; t_5 , 1.6×10^4 time steps; t_6 , 2.4×10^4 time steps; t_7 , 3.2×10^4 time
2 steps; t_8 , 4×10^4 time steps, t_9 , 10×10^4 time steps.

3 **3.2 The Comparison of Efficiency of Demulsifiers**

4 **3.2.1 The Variations in Diameter and Numbers of Water Droplets**

5 Attention was focused on the efficiency of demulsifiers having different structural
6 features in the hydrophobic blocks. As illustrated in **Figure 4**, generally the mean
7 diameter of the water droplets increases ladder-wise with time, whereas the number of
8 water droplets decreases with time. The mean diameter of the droplets and the number
9 of droplets are inversely correlated. Though the variation in the number of water
10 droplets with time is not quite obvious in simulation of different demulsifier systems
11 but the mean diameter of the water droplets changes a lot. Compared to DBO
12 demulsifiers, the mean diameter of the water droplets in crude oil emulsion system
13 with DPO and DTF demulsifiers is slightly larger before 3300 time steps. However,
14 finally the mean diameter of the water droplets in presence of DBO demulsifiers
15 abruptly becomes largest, and the time evolutions of diameters of water droplet also
16 can be visualized from the snapshots of demulsification. Number of water droplets in
17 presence of different demulsifiers sharply reduces at first and then reduces gradually
18 (see **Figure 4b**).



1
2 **Figure 4.** The time evolution of diameters of water droplets (a) and number (b).

3.2.2 The Variation of Dehydration Proportion

3
4 To obtain more information on the demulsification efficiency, the dehydration
5 proportion concept has been introduced. The dehydration proportion is the ratio of
6 dehydration or coalescence volume to the total volume of water. It is proportional to
7 the mean radius of droplets, whereas it is inversely proportional to the number of
8 droplets, as shown in the following equation

$$9 \quad \eta = \frac{\left(\frac{1}{n}\right)^{1/3} \frac{4}{3} \pi R^3}{\frac{4}{3} \pi R_{\max}^3} \quad (10)$$

10 Where n is the number of droplets in the cells, and the R is the mean radius of
11 droplets. In the above equation, $(1/n)^{1/3}$ is the number effect of droplets. R_{\max} is the
12 maximum radius of the droplets, when all the fragmented droplets integrate into a
13 single droplet.

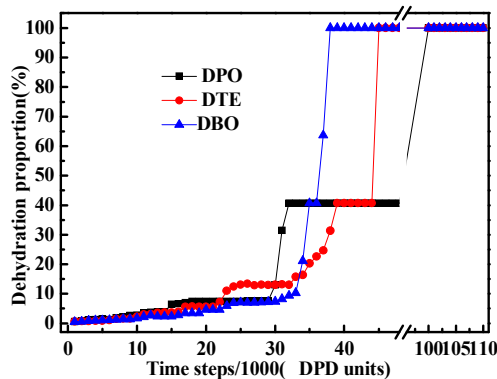


Figure 5. The time evolution of dehydration proportion.

The graph of dehydration ratio versus time is plotted from the calculations using equation (10), as shown in **Figure 5**. In general, the dehydration proportion with time in presence of different demulsifiers increases slightly initially and then increases sharply. The dehydration proportions show large differences in different demulsifiers, which is mainly by the result of variation of the mean diameter of the droplets. Though the dehydration proportion increases, which is related to the diameter of droplets growing larger and decreases with the number of droplets, it is evident that the dehydration proportion caused by DBO demulsifiers has an advantage over DTF demulsifiers and DPO demulsifiers. However, the dehydration rate of DPO is greater than that of DBO and DTF demulsifiers. Above conclusions could also be directly tested and verified by the above snapshots for demulsification.

3.3 The Kinetics of Demulsification

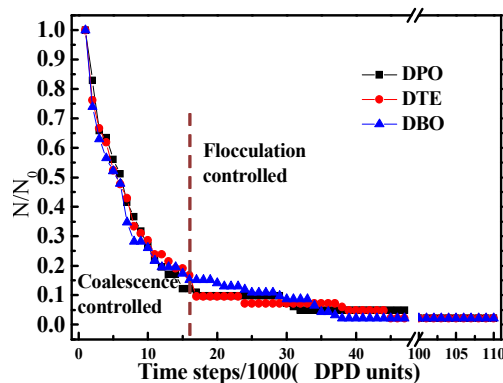
As we know, demulsification is a process which involves flocculation, coalescence, and separation of two immiscible liquids. Chemical demulsification usually results in enhancement of the rate of thinning of film and reduces the stability of the film. In

1 past decades, a number of models were developed to describe the rate of drainage of
2 emulsion films in relation to droplet-droplet coalescence phenomenon. With the
3 calculated data, N , at various time intervals, the flocculation (K) and coalescence rate
4 (α) constants can be calculated by fitting the data to the following kinetic equation
5 [45-46]

$$6 \quad \frac{N}{N_0} = e^{-G\lambda} \left[e^G + G \ln \lambda + \sum_{n=1}^{\infty} \frac{G^{n+1} (\lambda^n - 1)}{n \times n!} \right] \quad (11)$$

7 Where $G=K/\alpha N_0$ and $\lambda=1+\alpha N_0 t$, N_0 is the initial number of droplets in unit volume,
8 and t is time. As seen in **Figure 6**, the number of normalized droplets with time
9 decreases sharply before 16000 time steps, and then it declines slowly. Both the
10 demulsification snapshots and the variation in the number of normalized droplets
11 illustrate that the demulsification process is controlled by the combination of
12 flocculation and coalescence. In fact, as time progresses, the rate-controlling process
13 of demulsification changes from coalescence controlled to flocculation controlled. In
14 this paper, the transform time of rate-controlling process is 16000 time steps which
15 determined by the crossover point of tangents (see the Figure S3 of the Supporting
16 Information). This can be understood as follows: at the beginning of the process, due
17 to the large number of drops and the relatively high value flocculation rate is rapid,
18 the process is controlled by the rate of the coalescence step. As the process progresses,
19 the number of droplets decrease and the distance between droplets increases. As a
20 result, the rate of flocculation decreases and the process goes to completion. Thus,
21 there exists a change in the rate-controlling mechanism during the process. However,

1 the whole demulsification process is coalescence controlled, since $\alpha N_0/K \gg 1$ in our
 2 simulation systems [47].



3
 4 **Figure 6.** The time evolution of the number of normalized droplets.

5 The calculated coalescence rate constants depict the performance of the
 6 demulsifiers in the film-thinning process in demulsification. They also showed that
 7 high performance demulsifiers have higher coalescence rate constant [45]. According
 8 to the results, the flocculation (K) and coalescence rate (α) constants of
 9 demulsification process are listed in **Table 3**. It is seen that $K_{DBO} > K_{DTF} > K_{DPO}$ and
 10 $\alpha_{DBO} > \alpha_{DPO} > \alpha_{DTF}$ and all the rate constants comply with the demulsification
 11 performance.

12 **Table 3.** The flocculation (K) and coalescence rate (α) constants.

Demulsifiers	DPO	DTF	DBO
Flocculation rate constant (K)	5.5009×10^{-6}	5.5075×10^{-6}	5.7655×10^{-6}
Coalescence rate constant (α)	1.1908×10^{-4}	1.1912×10^{-4}	1.3013×10^{-4}

13 3.4 The Estimation of Demulsification Efficiency

14 Since polymer molecules may generally assume an enormous number of spatial
 15 arrangements, descriptions of chain configurations are generally provided in terms of

1 statistical (ensemble) averages of some characteristic property. In this case, two
2 parameters have been used to characterize average global configurations: the
3 moments and distribution of the root mean square end-to-end distance $\langle R \rangle$ and the
4 radial distribution function (RDF).

5 **3.4.1 Root mean square end-to-end distance $\langle R \rangle$**

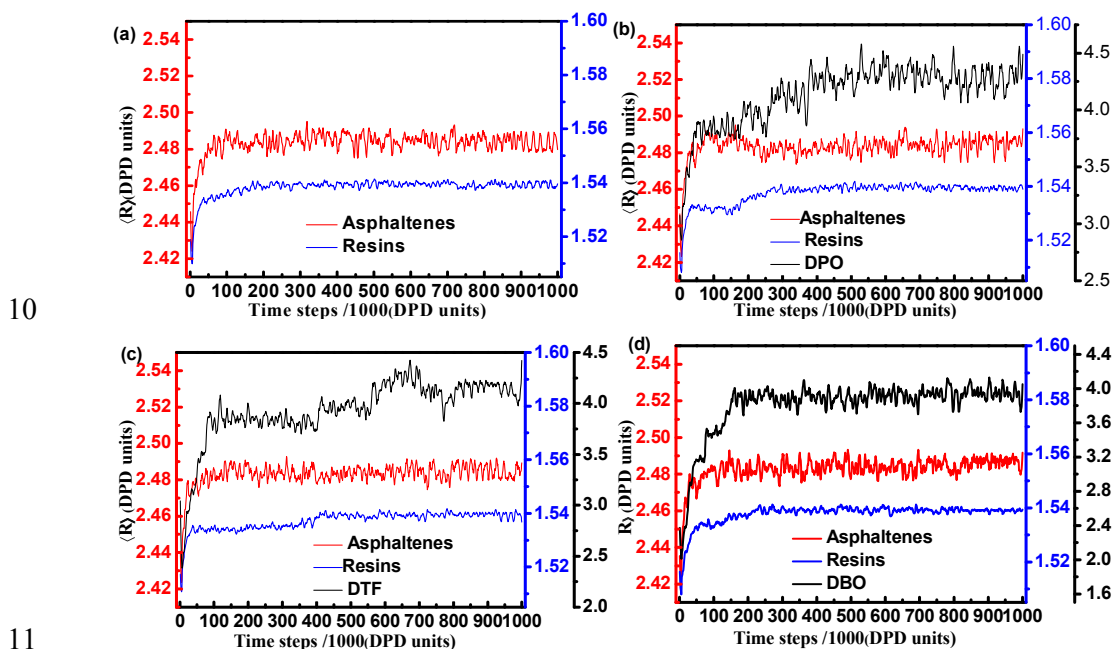
6 The root mean square end-to-end distance $\langle R \rangle$ shows the degree of stretching and
7 orderliness of orientation, and the arrangement of surface-active substances at the
8 oil/water interface. $\langle R \rangle$ is the average distance between two beads in each molecule. It
9 can be calculated using the following equation [17]

$$10 \quad \left(\langle h^2 \rangle^{1/2} \right) = \frac{1}{M} \sum_{i=1}^M (r_i - r_{cm})^2 \quad (12)$$

11 To analyze the feature of $\langle R \rangle$ in detail, four figures with identical scale of Y axis for
12 different systems but different scale of Y axis for different fractions are presented in
13 **Figure 7**. As the **Figure 7** illustrated, the $\langle R \rangle$ of asphaltenes and resins in different
14 systems swiftly reach the equilibrium after a transient increase. The change in the $\langle R \rangle$
15 for mesomolecules of asphaltenes and resins is not obvious because of the short chain
16 length of its mesomolecules. However, the $\langle R \rangle$ of demulsifiers trend to continue
17 growing with fluctuations. This indicates a larger area at the oil/water interface should
18 be provided for demulsifiers to cover.

19 Asphaltenes, resins and demulsifiers adsorb at the oil/water interface, with their
20 mixtures usually forming the composite Langmuir-Blodgett (LB) films at the interface

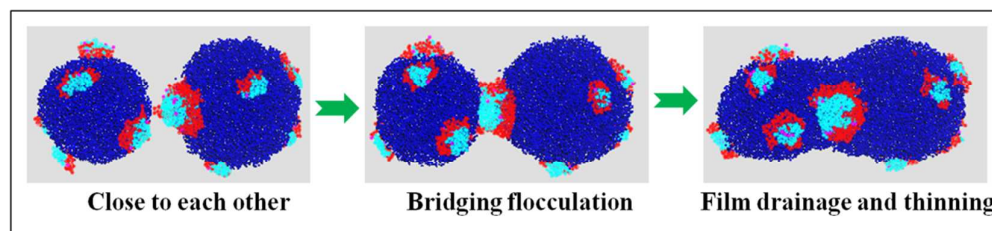
1 [48]. Mono-layers consisting of pure asphaltene fractions provide a rigid film,
 2 whereas the resins and demulsifiers build up a continuous open network. [49-50]. To
 3 obtain a more stretched and free configuration, the $\langle R \rangle$ of demulsifiers should become
 4 larger, thereby resulting in lowering of the $\langle R \rangle$ of asphaltenes surrounding the
 5 demulsifiers. The stretching configurations of demulsifiers show the mixed films of
 6 asphaltenes and demulsifiers leads to interface arraying towards an opening of the
 7 rigid asphaltene structure. Once the rigid asphaltene structure interface is replaced by
 8 continuous open network, the droplet-droplet coalescence becomes more likely, which
 9 can be seen from the demulsification process snapshots.



11
 12 **Figure 7.** The time evolution of root mean square end-to-end distance $\langle R \rangle$ for
 13 different fractions. Figure (a) corresponds to the crude oil-water emulsions; Figure (b),
 14 (c), (d) correspond to the crude oil/water/demulsifiers systems.

15 To understand the demulsification mechanisms, it is also very important to
 16 determine the demulsification efficiency. The interactions between two emulsion
 17 droplets are visualized by **Figure 8**. In this case, the water droplets adhere to each

1 other and stretch substantially before their final separation when pulled apart,
 2 indicating the presence of a strong force of adhesion between the water droplets,
 3 which often arise from gradient of interfacial tension [50]. Interestingly, such
 4 adsorption of demulsifiers leads to bridging flocculation or coalescence with the help
 5 their loops and tails, as illustrated in **Figure 8**. Moreover, it can also be seen that the
 6 demulsifiers could lead to partial displacement of original protecting interfacial films,
 7 with loosely bound demulsifiers containing loops and tails for flocculation, at the
 8 same time creating passages in the interfacial films for water to connect and hence
 9 coalesce [51]. All these simulation results are consistent with the reported
 10 demulsification phenomena [52].



11 **Figure 8.** Interactions of water droplets in presence of demulsifiers.
 12

13 3.4.2 Radial Distribution Function (RDF)

14 In order to further characterize the demulsification efficiency, the radial distribution
 15 function (RDF) has been introduced to express the configuration and ordered array of
 16 the molecular assemblage. RDF can be calculated using a reported formula [32]

$$17 \quad g_{ij}(r) = \frac{\{\Delta N_{ij}(r \rightarrow r + \Delta r)\}V}{4\pi \cdot r^2 \Delta r N_i N_j} \quad (13)$$

18 Where $\{\Delta N_{ij}(r \rightarrow r + \Delta r)\}$ is the ensemble averaged number of j around i within a shell
 19 from r to $r + \Delta r$, V is the system volume, N_i and N_j are number of i and j , respectively.

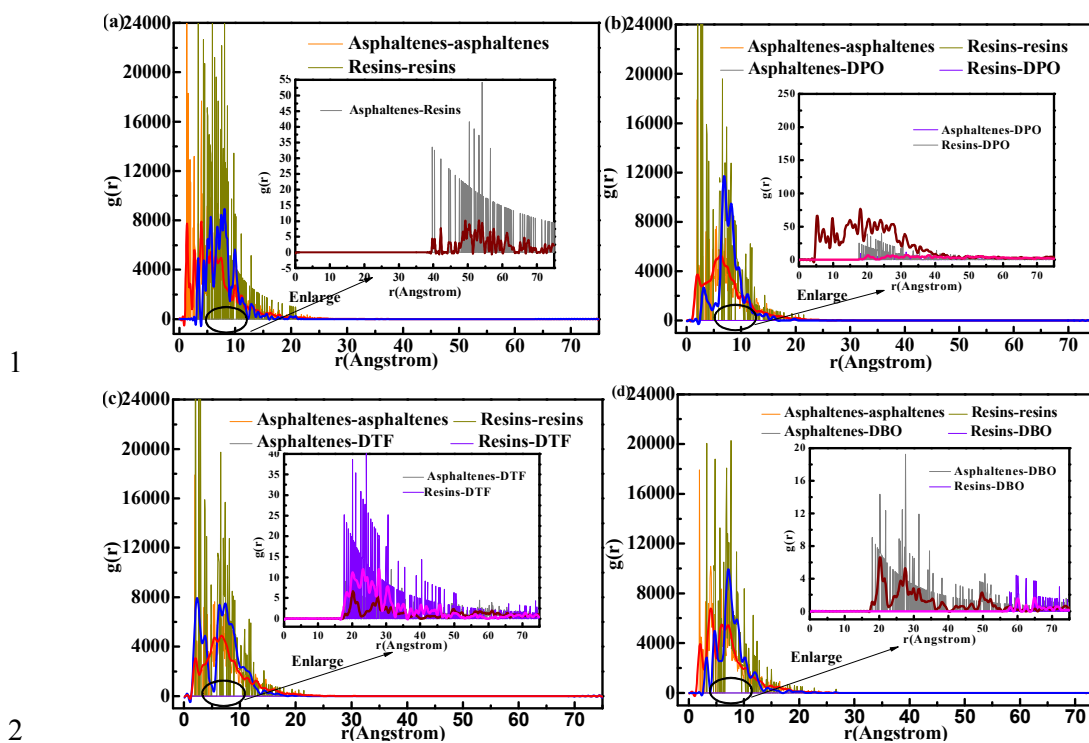


Figure 9. The $g(r)$ of the centroids of emulsion fractions. The vignettes of Figure (a) are enlarged to reflect the radial distribution functions between asphaltenes, resins in emulsions systems; and the vignettes of Figure (b), (c), (d), are enlarged to reflect the radial distribution functions between asphaltenes, resins and demulsifiers, particularly in presence of demulsifiers. Instantaneous pulling forces (dotted lines) and running averages (continuous lines) are shown.

The RDF in this case, calculated for a cut-off radius of 75 Å and an interval

distance of 1Å, is shown in **Figure 9**. In all the simulation systems the largest

contribution to RDF comes from asphaltenes-asphaltenes and resins-resins

respectively; therefore, asphaltenes are mainly surrounded by asphaltenes and in the

same way, typical resins are mainly surrounded mainly by resins, and same results

were also obtained by Fernando Alvarez et al. [28] In the case of the

asphaltene-asphaltenes, the highest peak is located at about 8.0 Å. This result is

consistent with the MD model and is also a good indication of the formation of

asphaltene aggregates [53]. The RDF for resins-resins exhibit well distinguished

1 peaks at about 4 Å and 6.5 Å, which are also consistent with the MD results [54]. All
2 these results prove that the DPD simulation model in this paper is reasonable. The
3 RDF of asphaltenes-demulsifiers and resins-demulsifiers are also provided. As shown
4 in the three vignettes of **Figure 9**, there is an indication of a rather strong and
5 remarkably structured interaction between asphaltenes and demulsifiers,
6 corresponding to the radial distribution range from 10 Å to 50 Å.

7 **4. Conclusions**

8 To the best of our knowledge, this is for the first time that DPD simulations are
9 used to investigate the demulsification efficiency with alternating hydrophobic blocks
10 of the polyether demulsifiers. Comparisons of demulsification efficiencies
11 demonstrate that DBO demulsifiers have an advantage over dehydration operation,
12 while the dehydration rate of DPO demulsifiers is superior to that of DBO and DTF
13 demulsifiers. The simulation results also prove that demulsification progress is
14 controlled by a combination of flocculation and coalescence. Based on the kinetic
15 equation, one can say that higher coalescence rate constants indicate the more
16 acceleration in the drainage process of the film and higher performance of
17 demulsifiers. In fact, as time progresses, the rate-controlling process of
18 demulsification changes from coalescence controlled to flocculation controlled.

19 The root mean square end-to-end distance $\langle R \rangle$ and the radial distribution function
20 (RDF) were introduced to characterize the demulsification efficiency. As $\langle R \rangle$ shows,

1 the configurations of the demulsifiers continue stretching which results in arraying of
2 interfaces. The demulsifiers absorbing at the interface lead to buildup of a continuous
3 open network and a high compressibility mixed film, such that the droplets aggregate
4 and coalesce. The variation of radial distribution function (RDF) indicates that there is
5 a rather strong and remarkably structured interaction between asphaltenes and
6 demulsifiers, corresponding to the radial distribution ranges from 10 Å to 50 Å. In
7 addition, all the results indicate that DPD method is a very powerful tool in the
8 investigation of efficiency of demulsification.

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