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High throughput and multiplex localization of proteins and cells for in situ micropatterning using pneumatic microfluidics†

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Micropatterning technologies are emerging as an enabling tool for various microfluidics-based applications in life science. However, the high throughput and multiplex localization of multiple bio-components in a microfluidic device has not yet been well established. In this paper, we described a simple and in situ micropatterning method using an integrated microfluidic device with pneumatic microstructures (P μ Ss) for highly controllable immobilization of both proteins and cells in a high throughput, geometry-dynamic, and multi-patterning way. The precise Pluronic F127 passivation of microchamber surface except the P μ Ss-blocked regions was performed and characterized, and spatial dynamics and consistency of both the P μ Ss and protein/cell micropatterning were optically evaluated and quantitatively demonstrated too. Furthermore, a systematical investigation of P μ Ss-assisted micropatterning in microfluidics was carried out. The feature of high throughput and spatial control of micropatterning can be simply realized by using the well-designated P μ S arrays. Meanwhile, co-micropatterning of different proteins (bovine serum albumin and chicken egg albumin) and cells (human umbilical vein endothelial cells and human hepatocellular carcinoma cells) in a microfluidic device was successfully accomplished with the orderly serial manipulation of P μ S groups. We demonstrate that P μ Ss-assisted micropatterning can be applied as a convenient microfluidic component for large-scale and diversified protein/cell patterning and manipulation, which could be useful for cell-based tissue organization, high-throughput imaging, protein-related interactions and immunoassays.

Introduction

Micropatterning technology is always interesting in the application of biochemistry, cellular and molecular biology/immunology.^{1,2} This is because of its remarkable capability in precise manipulation of cells, biomolecules (e.g., proteins and nucleic acids), and signal-mediated communication and interaction at microscale.³⁻⁵ Selective arrangement of these biological substances on the designated surface of substrates has gained tremendous attention in fundamental cell research,^{2,6} and also open doors to experimental approaches in biomedical diagnostics, drug discovery, and tissue engineering.⁷⁻⁹ For example, recent progresses in cellular and biomolecular micropatterning have already proven invaluable in increasing our understanding of the structural and functional relationships of homo/heterotopically biological communities.¹⁰⁻¹² In the past decade, a wide variety of micropatterning strategies, such as photolithography,¹³ stencil patterning,¹⁴ microfluidic

patterning,¹⁵ microcontact printing,¹⁶ ink-jet printing¹⁷ and selective plasma etching,¹⁸ have been explored and proposed for the development and innovation of this microcontrol system in a high throughput and geometry-controllable manner. Nevertheless, the multifactor organization and serial manipulation of micropatterning for the dynamic purpose is still being explored, and it requires a systematic consideration of the bio-microenvironment construction.¹⁹⁻²²

Microfluidics is supposed to be a promising platform for life science due to its excellent performance in the spatiotemporal control of microfluidic perfusion and biological samples, in simulation of tissue-relevant context, as well as in the feasible sequential manipulation.²³⁻²⁶ Given the scales at which micropatterning operates, integration with microfluidics can broaden the range of biological applications.²⁷ However, integrating aforementioned micropatterning methods with microfluidic systems is not straightforward.^{28,29} The micropatterning surfaces are commonly incompatible with

1 microfluidic device assembly because of the harsh treatments
2 (i.e., thermal and plasma bonding) could alter the properties and
3 functionalities of the micropatterning surfaces, or even
4 compromise bioactivity of proteins and cells.³⁰ Therefore, the
5 development of in situ micropatterning within microfluidic
6 device is potentially of benefit. On the other hand, the
7 continuously increasing complexity of microfluidic systems
8 also requires the development of methods for the robust
9 fabrication and control of the functional surfaces.^{31,32} Currently,
10 several approaches like laminar flow micropatterning have been
11 demonstrated to successfully control the surface properties and
12 cell adhesion in microchannels.^{33,34} Furthermore, in situ
13 microfluidic protein capture has been developed with the
14 pressure-modulated microfluidic valves.^{35,36} However, either
15 the spatial control (e.g., geometry- and size-variable) and high
16 throughput, or the multiple bio-component localization (i.e.,
17 different types of proteins and cells) of micropatterning in
18 microfluidics remains largely out of reach.

19 To this end, we present an in situ micropatterning
20 development of both proteins and cells through the pneumatic
21 microstructures (P μ Ss) and P μ S-assisted surface passivation.
22 The localized proteins and cells with various quantities can be
23 arranged in the microchamber based on the adjustable actuation
24 of P μ Ss. Moreover, high-throughput and geometry-controlled
25 micropatterning of multiple biological components can be
26 realized in the device respectively using the specially designed
27 P μ S arrays. In addition, we demonstrated that this approach has
28 the ability to complete a co-micropatterning of different
29 proteins/cells with an organized localization simultaneously in
30 the same chamber through a successive manipulation of the
31 P μ Ss.

32 Experimental

33 Materials and reagents

34 RTV 615 poly(dimethylsiloxane) (PDMS) prepolymer and
35 curing agent were purchased from Momentive Performance
36 Materials (Waterford, NY, USA). Surface-oxidized silicon
37 wafers were obtained from Shanghai Xiangjing Electronic
38 Technology Ltd (Shanghai, China). The AZ 50XT photoresist
39 and developer were bought from AZ Electronic Materials
40 (Somerville, NJ, USA). The SU-8 2025 photoresist and
41 developer were purchased from Microchem (Newton, MA,
42 USA). Chicken egg albumin (CEA) was purchased from
43 Dingguo Biotechnology Ltd. (Beijing, China). Bovine serum
44 albumin (BSA) was obtained from Amresco (Solon, OH, USA).
45 The EZ-Label FITC Protein Labeling Kit was brought from
46 Pierce Biotechnology (Rockford, IL, USA). The Alexa
47 Fluro594 Protein Labeling Kit was from Molecular Probes
48 (Eugene, OR, USA). Collagen-I, fluorescein diacetate (FDA),
49 acridine orange (AO), propidium iodide (PI) and Pluronic F127
50 were bought from Sigma-Aldrich (MO, USA). Dulbecco's
51 modified Eagle's medium (DMEM), fetal bovine serum (FBS),
52 CellTracker Orange CMRA and CellTracker Green CMFDA
53 were obtained from Gibco Invitrogen Corporation (CA, USA).

All solutions and other chemicals were purchased from local
commercial suppliers and were of analytical reagent grade,
unless otherwise stated. All solutions were prepared using
ultrapurified water supplied by a Milli-Q system (Millipore[®]).

Device fabrication

The microfluidic device used in the present study was
fabricated through multilayer soft lithography.³⁷⁻³⁹ Two
different molds were first produced by photolithographic
processes to create the fluidic components and control
components. The components were embedded in corresponding
layer of the PDMS matrix. To prepare the mold for the
fabrication of the fluidic components, a 30 μ m-thick positive
photoresist (AZ 50XT) was spin-coated onto a silicon wafer.
After UV exposure, the fluidic components on the wafer were
developed using an AZ 400K developer. The mold of the
control channels, including the patterning P μ Ss, was made from
a 20 μ m-thick negative photoresist (SU8-2025) patterned on a
silicon wafer.

Both the fluidic and control molds were exposed to
trimethylchlorosilane vapor for 3 min before fabricating the
microfluidic device. A well-mixed PDMS prepolymer [RTV
615 A and B (8:1, w/w)] was poured onto the fluidic mold,
which was then placed in a Petri dish to obtain a 3 mm-thick
fluidic layer. The PDMS prepolymer [RTV 615 A and B (20:1,
w/w)] was spin-coated onto the control mold at 1,800 rpm for
60 s to obtain a thin control layer (about 41 μ m-thickness).
Both layers were cured at 80 °C for 30 min. After incubation,
the fluidic layer was peeled off the mold and holes were
introduced for sample access and waste exclusion. Then, the
fluidic layer was trimmed, cleaned, and manually aligned to the
control mold. After baking at 80 °C for 2 h, the assembled
layers were trimmed, and then peeled off the control mold, and
a set of holes were punched to enable access to the control
channel network. The punching process was performed using a
custom-made puncher with the assistance of TV monitor. The
assembled layers were then placed on a glass slide which was
spin-coated with a PDMS prepolymer [RTV 615 A and B
(10:1, w/w)] at 2,000 rpm for 60 s and cured at 80 °C for 10
min in an oven. The microfluidic device was ready for use after
baking at 80 °C for 72 h.

Cell culture

Human umbilical vein endothelial cells (HUVEC-C, a cell line
derived from primary human umbilical vein endothelial cells)
and human hepatocellular carcinoma cells (HepG2) were
obtained from the Chinese Academy of Sciences (Shanghai,
China). Two types of cells were routinely cultured in DMEM
supplemented with 10% FBS, 100 U/mL penicillin, and 100
 μ g/mL streptomycin in a humidified 5% CO₂ atmosphere at 37
°C. The cells were normally passaged at a ratio of 1:3 every 3
days to maintain them in the exponential growth phase. When
the cells reached confluence, they were harvested through
trypsinization with 0.25% trypsin in phosphate buffered
solution (PBS, 0.01 M, pH 7.4) at 37 °C. Trypsinization was
stopped by adding freshly supplemented DMEM. The cell

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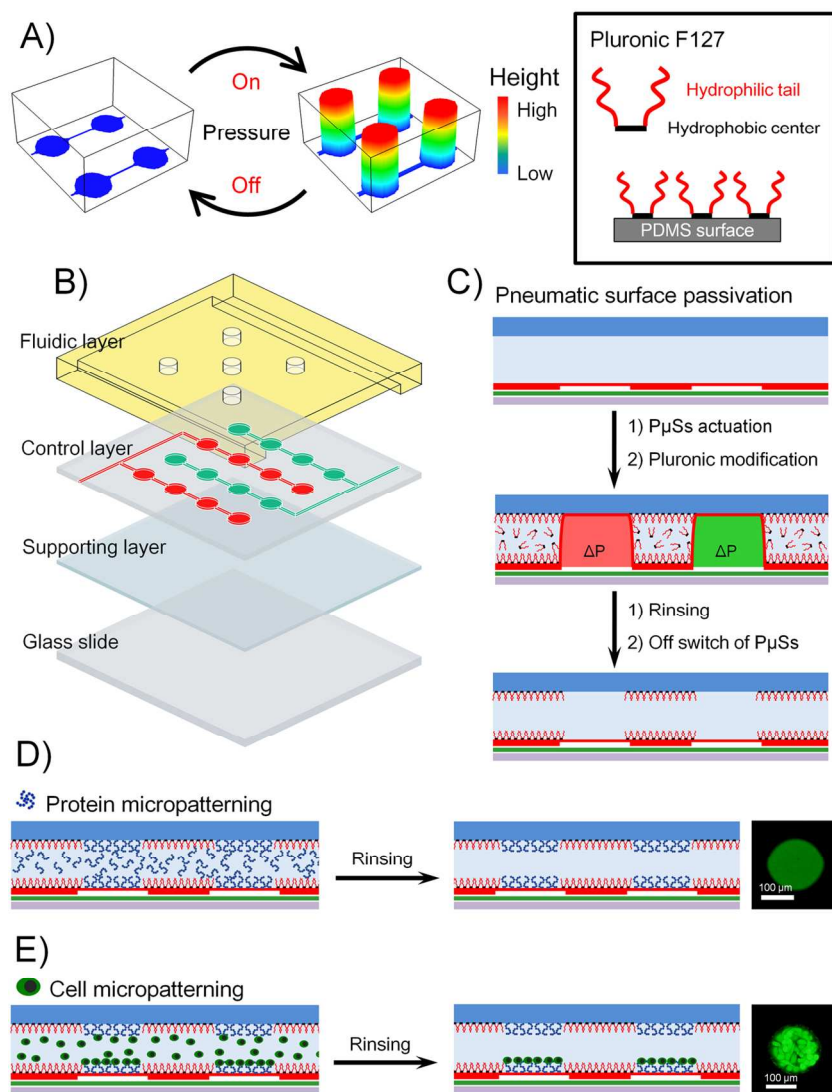


Fig. 1 Microfluidic device structure and micro patterning process. (A) Three dimensional views of PμSs with on/off switch by gas pressure. (B) Composition of the device (the four layers are sequentially shown from top to bottom, namely, the fluidic layer, control layer, supporting layer, and glass slide). (C) PμSs-assisted surface passivation by Pluronic F127, which just modify the non-blocked region in the chamber. (D) Protein micropatterning on the PμSs-blocked surface. The fluorescent image shows FITC-labelled BSA was immobilized on the round surface corresponding to the PμSs-blocked area. (E) Cell micropatterning on the PμSs-blocking and adhesive protein-pretreated surface. HUVEC-C cells presented a well-controlled adhesion on the surface corresponding to the PμSs-blocked region. The schematic image in the square on the top right presents the feature of Pluronic F127 which has both hydrophilic and hydrophobic groups, and shows its immobilization on the PDMS surface.

suspension was centrifuged at 1000 rpm for 5 min. The cells were then resuspended in supplemented DMEM for further use.

Controllable surface passivation

Sterilization of the device was performed at the beginning of surface passivation. Microfluidic device was first rinsed by flushing 70% alcohol, ultra pure water, and PBS one after another. Thereafter, the PμSs were activated by gas pressure to generate blocked regions on the surface of the microchamber in the device. Then, a solution of 1% w/w Pluronic F127 in PBS

were injected into the microfluidic device and allow to be adsorbed onto the PDMS surfaces of the microchamber. After incubation for 24 h at room temperature, the microfluidic device was washed with PBS thoroughly for at least three times and the PμSs were selectively deactivated to release the blocked regions for micropatterning.

The contact angles of PDMS surfaces before and after Pluronic coating were measured using Dropmeter 100 equipment (Maist Vision, Ningbo, China) via the sessile drop technique.⁴⁰ Each data point was based on 10 contact angle measurements at 5 different positions on the PDMS specimen.

Protein micropatterning in the microfluidic device

Preparation of different fluorophore-labeled proteins (BSA and CEA) was performed for significant visualization of protein localization before patterning process. BSA were labeled with FITC following the instructions of the EZ-label FITC protein labeling kit, and the CEA were labeled with A594 using the Alexa Fluoro594 protein labeling kit. The labeled proteins were protected from light by covering tubes in foil, and were stored at 4 °C until use. The final concentration of the labeled proteins was totally adjusted to 1 mg/mL in PBS.

For single type of protein micropatterning, all the PμSs were switched off and FITC-BSA solutions were introduced into the Pluronic passivated microfluidic device. After 1 h incubation at 37 °C, the microchannel was washed thrice with PBS. Furthermore, while doing multiple protein micropatterning, the PμSs corresponding to the specific block regions in the chamber were switched off and the other PμSs were switched on to block the rest designated regions. FITC-BSA solutions were then injected into the microfluidic device and were allowed to immobilize onto the exposed blocking regions for 1 h at 37 °C. Following by washing with PBS for three times to flush away unimmobilized FITC-BSA, the former actuated PμSs were switched off, and the rest blocked regions were presented to contact the injected solution of 1 mg/mL A594-CEA. After incubated for 1 h at 37 °C, the microchamber was rinsed with PBS and washed three times to flush away unimmobilized A594-CEA.

Cell micropatterning in the microfluidic device

1 Before cell micropatterning, 200 $\mu\text{g}/\text{mL}$ collagen-I solution was
2 first introduced into the microfluidic device for 2 h-incubation
3 at 37 $^{\circ}\text{C}$ followed by rinsing with PBS. For single type of cell
4 micropatterning, HUVEC-C cells at a density of 1×10^6
5 cells/mL or HepG2 cells at a density of 5×10^6 cells/mL were
6 loaded into microfluidic device and incubated under static
7 culture condition for 2 h at 37 $^{\circ}\text{C}$. Afterwards, the cell
8 suspension was replaced by fresh medium. For clearly
9 observation of micropatterning and viability assessment, the
10 cells in the microfluidic device were stained with FDA (10
11 $\mu\text{g}/\text{mL}$ in PBS), AO (10 $\mu\text{g}/\text{mL}$ in PBS) and PI (10 $\mu\text{g}/\text{mL}$ in
12 PBS). Briefly, after removing the growth medium and rinsing
13 with PBS, the FDA/PI or AO/PI staining solution flowed into
14 the chambers, and the staining process was performed for 5 min
15 at 37 $^{\circ}\text{C}$. Afterward, PBS was introduced for 5 min as a final
16 rinse.

17
18 For co-micropatterning, HUVEC-C and HepG2 cells were
19 prestained respectively using different CellTracker dyes (10
20 $\mu\text{mol}/\text{L}$ in fresh DMEM) before the seeding process according
21 to the manufacturer's instructions (Invitrogen). Same
22 manipulations to the multiple protein micropatterning, the
23 specific group of P μS s were actuated and the others were
24 switched off. HepG2 cells were then introduced into the
25 microfluidic device at a density of 5×10^6 cells/mL. After 2 h
26 incubation under static culture condition at 37 $^{\circ}\text{C}$, fresh
27 medium was introduced into microfluidic device to remove the
28 non-adhering cells. After another 4 h culture, the actuated P μS s
29 were switched off and the second type of cells (HUVEC-C) was
30 seeded into the microfluidic device at a density of 1×10^6
31 cells/mL. The non-adhered cells were removed by a fresh
32 medium rinsing after 2 h static culture condition. All the cell
33 culture steps were performed inside the incubator. The
34 information on the P μS control can be found in the
35 supplementary information.

36 37 **Microscopy and image analysis**

38 Bright-field and fluorescence images were acquired using an
39 inverted microscope (Olympus, CKX41) equipped with a
40 charge-coupled device camera (Olympus, DP72) and a mercury
41 lamp (Olympus, U-RFLT50). Data acquisition and
42 measurement were performed using Image-Pro Plus 6.0
43 software (Media Cybernetics Inc.). The size of the blocked P μS
44 region was determined by tracking the distinct edge of P μS and
45 was measured using image analysis software Image Pro Plus
46 6.0. All the experiments in the current study were repeated at
47 least five times. During each repetition at least 50 data were
48 collected for statistical analysis. The statistical analysis was
49 performed with software SPSS 12.0 (SPSS Inc.). The results
50 and error bars in the graphs were expressed as the mean \pm SD.
51 Tests of data significance were performed using one-way
52 ANOVA.

53 54 **Results and Discussion**

55 56 **Device design and fabrication**

To realize in situ micropatterning inside the microchamber, the
pneumatic manipulation is applied here for region-specific
functionalization. Generally, the operation of common
pneumatic microvalves depends on the fact that PDMS is an
elastomer, and is also based on the restriction of a fluidic
channel by the deformation of PDMS membrane under
pressure. In the past fourteen years, microvalves are particularly
important as components that have enabled the design and
examination of complicated microfluidic devices, and these
have opened up a number of areas of application in chemistry
and biology.^{41,42} The on/off switch of microvalves has been
used to complete various controllable microfluidic
manipulations like microflow orientation, bead and cell
trapping, and local protein/antibody immobilization.^{36,38,43,44} As
we known, the microvalves remain flat under 0 psi gas
pressure, and can also deflect upwards to the top surface of
microchannel while using an enough gas pressure actuation.
Both the top and the bottom surface areas corresponding to the
valves can be blocked and protected. This means that the spatial
control of surface functionalization can be performed. Along
with those excellent works aforementioned, we plan to improve
and demonstrate the precise micropatterning in the microfluidic
device by pneumatic component, and make its function (i.e.,
high throughput and shape-changeable) and application (i.e.,
proteins and mammalian cells) more diversified in this study.

Generally, the integrated microfluidic device in the present
study is composed of four layers (Fig. 1 and Fig. S1, ESI \dagger): the
fluidic layer, the control layer, the supporting layer, and a glass
slide. In detail (Fig. S2–Fig. S7, ESI \dagger), the fluidic layer, with
micrometer-scaled component, contained an individual
chamber for protein and cell staying. To prevent chamber
collapse during the experiment, a set of micropillar arrays was
specifically and optimally arranged in the chamber (Fig. S2–Fig.
S7, ESI \dagger). The inlet and outlet were set at the both ends of the
chamber respectively, and were used for liquid injection,
chamber purging, protein and cell loading and waste exclusion.
The control layer consisted of two sets of water-filled channel
networks incorporated pneumatic microstructures (P μS s) in
their middles or terminals. The P μS arrays were independently
controlled by external gas pressure (For the information on P μS
control, see the supplementary information, ESI \dagger). Different
from the common valves (i.e., size similar to the channel) in
microfluidic chips, the size of the P μS s here is much smaller
than the size of microchamber (For the detailed dimension of
all the devices used in the current study, see Fig. S2–Fig. S7,
ESI \dagger). When pressure is applied, the membrane of the P μS s
deflects upwards to the top surface of the fluidic chamber,
creating the blocked regions, which can be reversibly and real-
time controlled through on/off switch of pneumatic actuation
(Fig. 1A and Fig. S8, ESI \dagger). Finally, the supporting layer
coated on the glass slide was employed for irreversible seal of
the channel networks in the control layer.

57 58 **Surface passivation and micropatterning**

The hydrophobicity of PDMS tends to promote nonspecific
protein adsorption (biofouling).⁴⁵ For micropatterning of

biological substances, it is essential to create bio-inert regions on the microchamber surface except the P μ Ss-blocked surface before the biological substances deposit. Although the use of covalently grafted polymer to modify PDMS has been proposed to create robust coatings with tunable chemistry and precise local definition, the methods reported so far are relatively

complex to implement and difficult to integrate with microfluidic chips.^{46,47} Alternatively, physically adsorbed polymer coatings appear as an interesting approach to covalent ones since the coating process can be easily implemented inside a microfluidic device.⁴⁸ Among the possible candidates, a group of PEO-based triblock polymers (such as Pluronics) has been

proven to be especially suitable for the prevention of protein adsorption and cell attachment.⁴⁹⁻⁵¹ The mechanism contributing to this capability is generally attributed to its hydrophilicity, flexibility, chain mobility, and high steric exclusion volume in water.⁴⁹ Pluronics, with the general composition of (PEO)_m(PPO)_n(PEO)_m (for Pluronic F127, m = 100, n = 65, molecular weight = 12,600), has been widely used in many biotechnological applications because of its extremely low toxicity and immunogenic response.⁵¹ Thus, Pluronic was chosen as blocking agent to passivate the non-blocked regions in this study. This class of polymers have poly(propylene oxide) (PPO) centers with poly(ethylene oxide) (PEO) side chains (Fig. 1 and Fig. S9, ESI†). The PPO domain adsorbs quasi-irreversibly to hydrophobic surfaces, creating a surface coating of PEO chains. Fig. 1C schematically depicts the bio-inert modification of the non-blocked region using Pluronic F127. The P μ Ss were firstly actuated to protect the blocked spots and then the whole microchamber was incubated with the Pluronic solution. Since non-blocked regions could access liquid freely, Pluronic molecules could interact with the PDMS surface of these regions through hydrophobic interaction and then form a poly(ethylene oxide) (PEO) covered layer in the microchamber. Due to the difference in liquid access between non-blocked regions and blocked regions, the localized anti-adhesive domains can be easily created in non-blocked regions. Meanwhile, the wettability of Pluronic-treated surface was evaluated through contact angle, which was believed to play an important role in controlling surface hydrophilization. The result (Fig. S9, ESI†) showed that the contact angle decreased after coating with Pluronic. This indicates that the wettability of PDMS surface increased after coating. Although this increase of wettability is lower than the one obtained

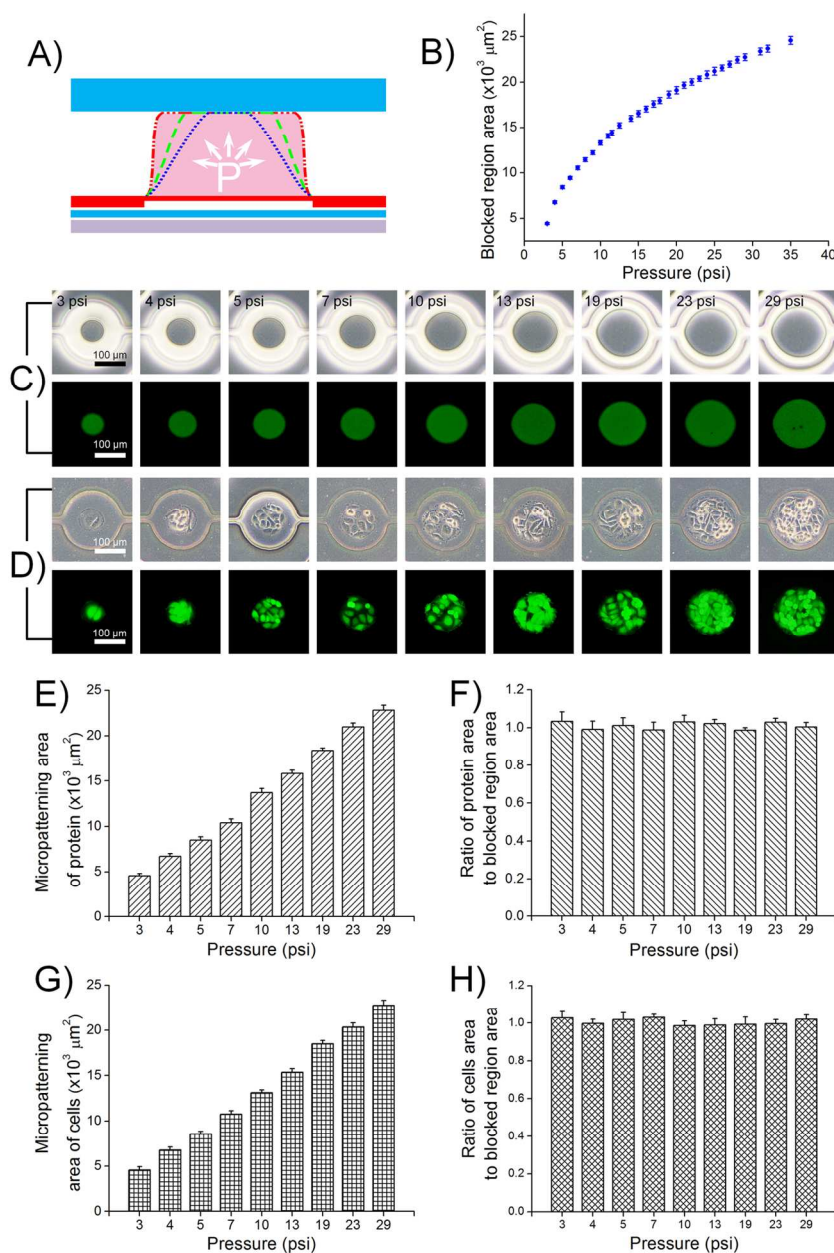


Fig. 2 Dynamic investigation of P μ S manipulation and micropatterning of proteins and cells at different gas pressures. (A) Sectional view of P μ S deformation dynamics by changing gas pressures. (B) Quantification of P μ S blocking dynamics at various gas pressures. The blocked area between the P μ S and the top surface of microchamber was applied for quantitative assessment. (C) The optical images of P μ S-blocked regions (top) and the fluorescent images of FITC-labelled BSA micropatterning (bottom) at various gas pressures. (D) The optical images of HUVEC-C cell micropatterning (top) and the fluorescent images of micropatterning of HUVEC-C cell stained by FDA/PI solution (bottom). (E) Micropatterning area of BSA at various gas pressures. (F) Ratio between the BSA patterned area and P μ S-blocked area. (G) Micropatterning area of HUVEC-C cells at various gas pressures. (H) Ratio between the HUVEC-C cell patterning area and P μ S-blocked area. The pressures used in (D) are corresponding to the pressures in (C).

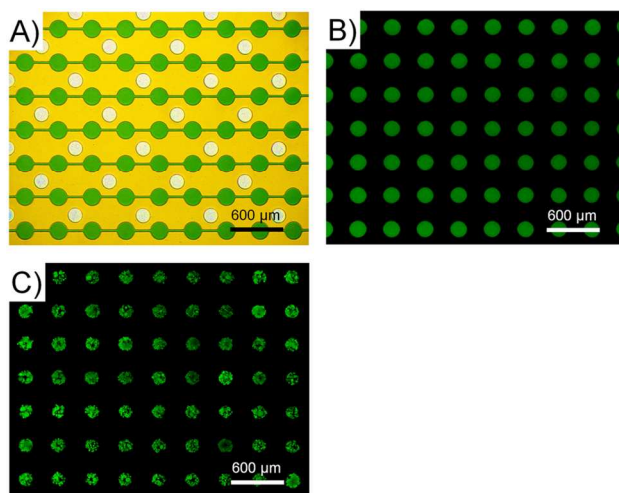


Fig. 3 High throughput micropatterning using the P μ S array. (A) The optical image of P μ S array. Microchannel network in the control layer was loaded with green food dye for visualization of the P μ Ss. (B) Array-like micropatterning of FITC-labeled BSA in the chamber. (C) Array-like micropatterning of HepG2 cells (AO/PI staining) in the chamber. These results suggest that both proteins and cells can be localized by using the P μ S array in a high throughput way.

after oxygen plasma or UV/O₃ treatment of PDMS,^{52,53} the results are in the typical range of the hydrophilization achieved after the surface treatment of hydrophobic surfaces using physisorbed polymers.^{54,55}

Further, the protein and cell loading/positioning tests were performed to investigate the effect of Pluronic treatment and the feasibility of pneumatic micropatterning in a wide range of biological applications. For protein micropatterning, FITC-labeled BSA was introduced into the microchamber. Albumin was used because of its abundance in human blood and its strong adhesion tendency. Fig. 1D showed that FITC-BSA selectively adsorbed to the areas of the blocked regions and non-staying on the Pluronic-treated surfaces. Meanwhile, the cell micropatterning also presented the similar results (Fig. 1E). After the loading and rinsing processes, the cells were spatially immobilized on the surface of the blocked region pretreated with the cell adhesive protein. Clearly, the adhered cells on the surface of the blocked regions formed a well-restricted micropatterning shape. The results suggest that the micropatterning method has the ability to position cells inside a microfluidic device with control over their spatial arrangement. Meanwhile, the effect of Pluronic in anti-protein absorption and anti-cell adhesion was demonstrated. These results demonstrated that the pneumatic micropatterning cooperated with Pluronic-assisted surface passivation works for the in situ localization of both protein molecules and mammalian cells in microfluidics.

The deformation of the PDMS membrane was affected by the applied pneumatic pressure, which could further affect the area of the blocked regions. Thus, the spatial appearance dynamics of the P μ Ss was first evaluated correspondingly by subjecting them to varied gas pressures (Fig. 2). In the current study, we tested a range of pneumatic actuation from 0 psi to 35

psi (a pressure range that could keep the device integrity and prevent leakage) for the systematic characterization of P μ S-assisted blocking dynamics. As expected, the PDMS membrane showed positive deformation along with the increase of gas pressure (Fig. 2B), which resulted in the enlargement of the blocked area on the surface of microchamber. These results implied that the size-modulated bio-micropattern could be realized in the microchamber through pressure control. Furthermore, a quantitative immobilization of FITC-BSA and HUVEC-C cells onto the blocked surface was performed respectively under various gas pressures. Fig. 2C and 2E showed that the protein micropatterning area was increased positively along with the change of the applied pressures, which was also consistent with the tendency of the deformation of PDMS membrane. Same to the tendency of protein micropatterning, the micropatterned cell area also increased with increasing pressure (Fig. 2D and 2G). The blocked regions were covered with the adhered cells varying from several cells to dozens of cells, which suggested that this type of P μ S-assisted micropatterning method could realize cell localization at single cell level. Meanwhile, the multi-quantity of cell micropatterning can be performed by using dynamically controlled P μ Ss in the device. Further, the assessment of geometrical consistency between the blocked regions and the protein/cell immobilized areas was performed, respectively. The area ratio between the blocked regions and protein/cell patterning regions was used for quantitative comparison. The results (Fig. 2F and 2H) showed that the areas of both

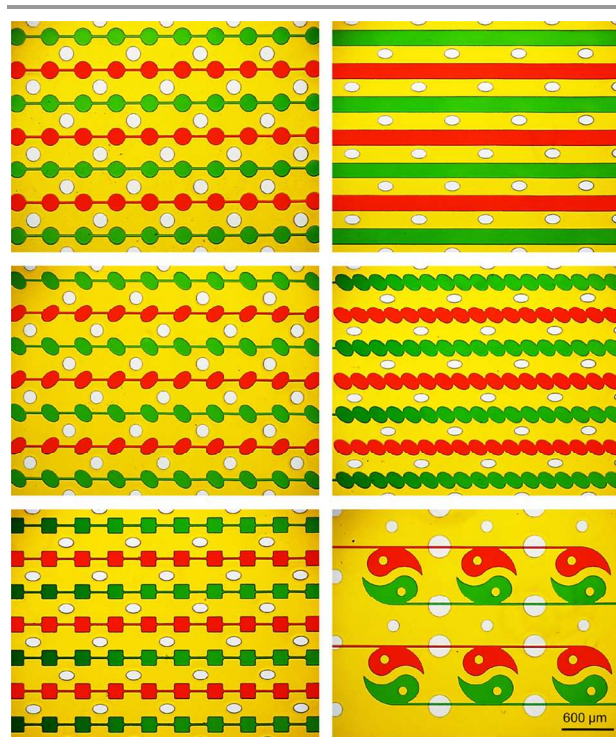


Fig. 4 The shape-diversified P μ Ss in the microfluidic devices. Totally, six types of P μ Ss were prepared in this study, such as round, strip, oval, wavy, square, and Taiji-shaped P μ Ss. Two sets of P μ Ss in the devices were marked respectively by green and red food dyes.

1 micropatterned proteins and cells presented well-defined
 2 geometry corresponding to the blocked regions. Totally, these
 3 results suggested that the size modulation of both protein and
 4 cell micropatterning could be carried out by pressure-regulated
 5 P μ Ss in the microfluidic device, and the generated protein/cell
 6 micropatterning on the surface of the chamber faithfully
 7 reproduced the geometric property of P μ S-blocked region.
 8

9 Protein/cell micropatterning in a high throughput and 10 geometric diversity way

11 Micropatterning has the feature of manipulating a large quantity
 12 of homotypic samples and controlling their spatial
 13 configuration. Therefore, further experimental investigation of
 14 pneumatic micropatterning in the device integrated with P μ S
 15 array (Fig. 3A) was performed to achieve a feasible control of
 16 bio-component (proteins and cells) localization in a high
 17 throughput and geometry-controlled manner. To perform
 18 protein micropatterning, the P μ S arrays were all switched off
 19 and kept at a non-actuated status to expose the blocked regions.
 20 The FITC-labeled BSA solution was then introduced into the
 21 Pluronic-pretreated chamber, and incubated for a while
 22 following by rinsing. The results showed that a large number of
 23 proteins arranged on the surface of the blocked areas, which
 24 formed a stable spotted array of proteins (Fig. 3B). The protein
 25 arrays are known as a good platform for high throughput study
 26 of various protein-related interactions, as well as different
 27 immunoassays.^{56,57} The P μ S array-based cell micropatterning
 28 was also performed in the microfluidic chamber. HepG2 cells
 29 were loaded into the device and selectively immobilized on the
 30 collagen-pretreated surface. The rinsing process removed the
 31 rest cells suspended in the chamber. As shown in Fig. 3C,
 32 HepG2 cells completely adhered on the surface of the collagen-
 33 treated spot array, and were organized as a shape-controlled cell
 34 population with high viability (no dead cells were observed
 35 during this test). This result demonstrated that the well-defined
 36 cell array was successfully accomplished by using the P μ Ss
 37 integrated in the microfluidic device, which would be much
 38 helpful for high throughput cell assay and analysis.
 39

40 Meanwhile, the exploration of geometric diversity of
 41 pneumatic micropatterning was carried out. For this purpose,
 42 we designed and fabricated six types of microfluidic devices
 43 with different shape of P μ Ss, including round, strip, square,
 44 oval, Taiji-shaped, and wavy (Fig. 4, and Figs. S2-S7, ESI \dagger).
 45 Based on the P μ Ss control and Pluronic modification, the
 46 protein (BSA) and cell (HUVEC-C and HepG2)
 47 micropatterning were performed respectively in these devices.
 48 Fig. 5A showed that FITC-labeled BSA exhibited uniformly
 49 fluorescent shape in the microchamber, almost corresponding
 50 to what the P μ Ss look like. Similarly, two types of cell
 51 populations also presented a controlled adhesion in the blocked
 52 regions with different shapes, corresponding to the type of
 53 P μ Ss geometry (Fig. 5B and 5C, and Fig. S10, ESI \dagger). These
 54 results suggested that the spatial appearance of both protein and
 55 cell micropatterning in the device could be precisely controlled
 56 by using the well-designated P μ Ss, and demonstrated that this
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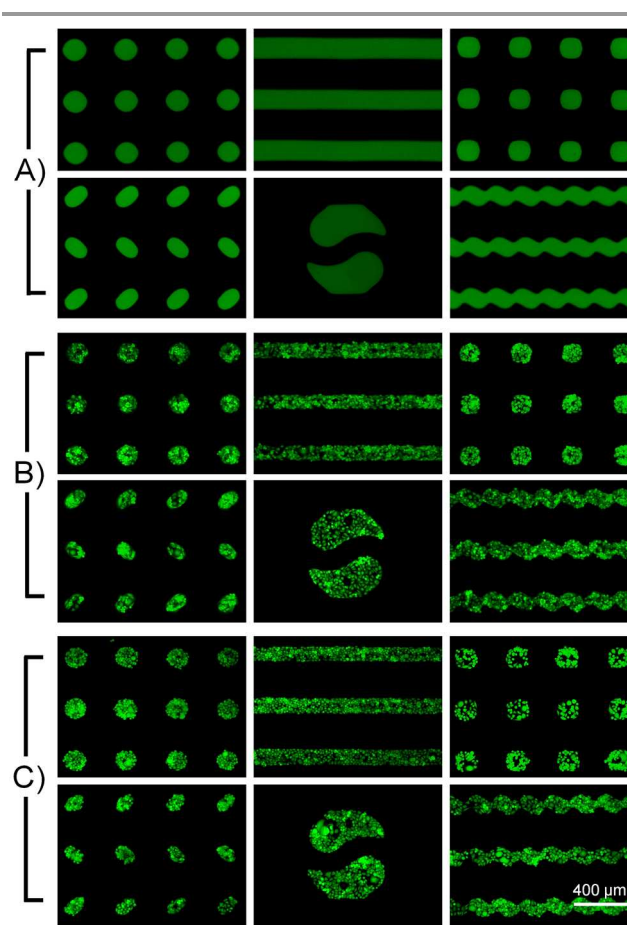


Fig. 5 Geometry-controlled micropatterning by different well-designed P μ Ss. (A) The fluorescent images of BSA micropatterning using different P μ Ss. (B) The fluorescent images of HUVEC-C cell micropatterning using different P μ Ss. (C) The fluorescent images of HepG2 cell micropatterning using different P μ Ss.

micropatterning method had the ability of producing a high quality of protein localization and cell organization.

P μ Ss-based protein/cell co-micropatterning

In this section, we demonstrated the applicability of this pneumatic method for in situ micropatterning multiple biological substances. The sequentially controllable manipulations of P μ Ss were applied to carry out the biological co-micropatterning in the device (Fig. S11, ESI \dagger). After bio-inert surface modification of the non-blocked regions in the microchamber, one set of P μ Ss was depressurized to expose the blocked regions for the bio-component solution accessing, and the other P μ Ss remained actuation to keep the rest of the blocked regions from liquid accessing. Thereafter, the first biological component was introduced into the microchamber and selectively immobilized onto the exposed blocking regions. Subsequently, the second bio-component micropatterning was obtained by the same process after off switch of another set of the P μ Ss. The in situ micropatterning of multiple biological components inside the microfluidic device can be performed through successively modulating the on/off switch of the P μ Ss

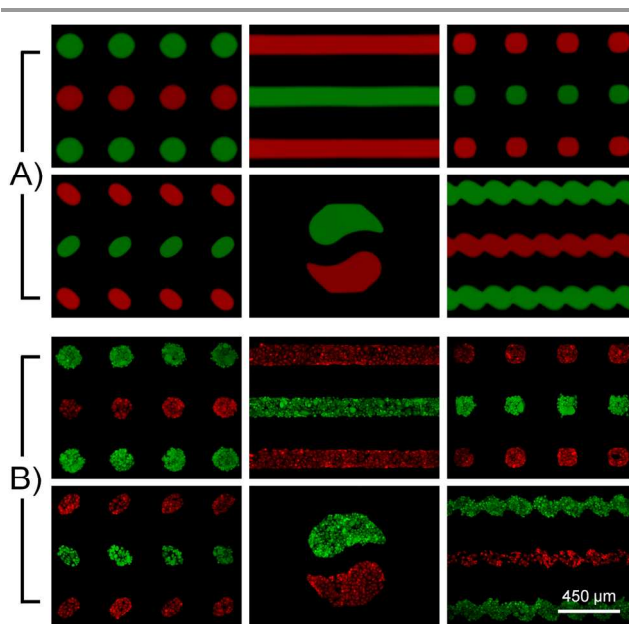


Fig. 6 Co-micropatterning of different proteins/cells using P μ Ss. (A) Immobilization of both FITC-labelled BSA and Alexa Fluoro594-labelled CEA with various shapes in the same chamber. (B) Localization of both HUVEC-C cells (red) and HepG2 cells (green) with various shapes in the same chamber.

without using external devices or complex fabrication process, which provides a simple and compatible method to achieve co-micropatterning inside the microfluidic device.

In the current study, the micropatterning of multiple proteins (BSA and CEA) and cells (HUVEC-C and HepG2) was respectively constructed by using this method. The results (Fig. 6A) showed that the multiple micropatterning of proteins with varied shapes were fabricated by successively operating the P μ Ss. The spatial micropatterning of multiple proteins inside the microchamber could potentially broaden the application of this microfluidic pneumatic method in the studies of protein interactions and immunoassays. Furthermore, the results presented the cell co-micropatterning can also be accomplished inside the microfluidic chamber (Fig. 6B and Fig. S12, ESI†). The micropatterned cell populations presented well-defined geometry with various shapes. HUVEC-C and HepG2 cells were respectively localized at the specifically defined regions without contamination between each other. This suggests that the P μ Ss-assisted method allows for the micropatterning of multiple cell types, with high control performance of the spatial arrangement of cells. The ability of engineering micropatterning of multiple types of living cells allowed implementation of complex microenvironment for quantitative biological assessment, which indicated that the potential use of the pneumatic micropatterning in many cellular studies such as wound healing, stem cell differentiation, and tumor metastasis.

Conclusions

In this study, we presented an in situ micropatterning approach for high throughput and multiplex localization of proteins and mammalian cells by using pneumatic switch and controllable

surface passivation in a microfluidic device. The pneumatic microstructures can conveniently realize the multi-quantity of protein/cell immobilization in the well-defined regions based on their precise-controlled dimensional dynamics. Meanwhile, the P μ Ss can accomplish the array-like micropatterning operation of multiple biological components in the device, which could be a new preparation for high-throughput biology. Further, the well-designed P μ Ss have the ability to simply realize the geometric diversity of protein/cell localization. More importantly, we demonstrated that multi-types of proteins and cells could be co-patterned with shape-regulated arrangement on the defined surfaces of microchamber in the microfluidic device, which would contribute to several multifactor-involved biological studies like protein interaction, cell coculture and communication, and tissue simulation. Additionally, the on-chip integration of P μ Ss-assisted micropatterning is potentially useful for the development of various microfluidic high-throughput screening, clinical diagnosis, and immunosensor.

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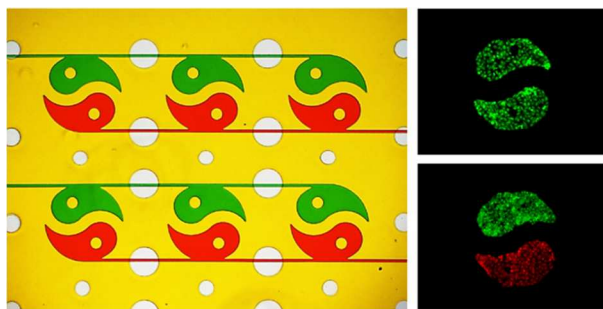
† Electronic Supplementary Information (ESI) available: P μ S control and supplementary Fig. S1–S12 about P μ Ss-assisted micropatterning of biological components in the microfluidic device. See DOI: 10.1039/b000000x/

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Graphical Abstract



We present a micropatterning method for protein/cell localization by using pneumatically controllable microstructures in an integrated microfluidic device.

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