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Density functional theory methods applied to homogeneous and heterogeneous catalysis: a short review and a practical user guide

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The application of density functional theory (DFT) methods in catalysis has been growing fast in the last few decades thanks to both the availability of more powerful high computing resources and the development of new efficient approximations and approaches. DFT calculations allow for the understanding of crucial catalytic aspects that are difficult or even impossible to access by experiments, thus contributing to faster development of more efficient and selective catalysts. Depending on the catalytic system and properties under investigation, different approaches should be used. Moreover, the reliability of the obtained results deeply depends on the approximations involved in both the selected method and model. This review addresses chemists, physicists and materials scientists whose interest deals with the application of DFT-based computational tools in both homogeneous catalysis and heterogeneous catalysis. First, a brief introduction to DFT is presented. Then, the main approaches based on atomic centered basis sets and plane waves are discussed, underlining the main differences, advantages and limitations. Eventually, guidance towards the selection of the catalytic model is given, with a final focus on the evaluation of the energy barriers, which represents a crucial step in all catalytic processes. Overall, the review represents a rational and practical guide for both beginners and more experienced users involved in the wide field of catalysis.

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1. Introduction

Catalytic processes are fundamental to modern and sustainable chemistry. Catalysis refers to the process of enhancing the transformation rate of chemical compounds into other products in a selective manner. Therefore, a catalyst is a substance involved in the overall reaction mechanism and is capable of significantly lowering the activation energy of the “turnover-limiting step”, generally referred to as the rate-determining step. Furthermore, the structure of a catalyst can be designed to accelerate specific steps leading to target products, thus properly controlling the selectivity. Since the catalyst itself is recovered after the chemical reaction, becoming newly available for subsequent chemical transformations, the thermodynamic equilibrium of the reaction is unchanged. This allows for the conversion of large quantities of reactants using small amounts of catalyst under milder conditions than those required in the absence of the catalyst.

Catalysts are usually divided into two main categories: homogeneous and heterogeneous catalysts. In the former case, several organic and metal-coordination compounds have been proposed as homogenous catalysts. On the other hand, solid surfaces of bulk organic and inorganic nanoparticles and 2D materials are mainly involved in heterogeneous catalysis. Very recently, a new class of catalysts has emerged, which consists of anchoring an active homogeneous catalyst on a solid support, thus obtaining the so-called “hybrid catalyst”.^{1–3} A different strategy based on the same idea of bridging heterogeneous catalysis and homogeneous catalysis led to the development of single atom catalysts (SACs),^{4–6} in which metal atoms are anchored to the support and act as the active center for the catalytic reaction. The fundamental idea behind these combined systems is that they might benefit from the individual properties of their homogeneous and heterogeneous constituents. Indeed, while homogeneous catalysts typically exhibit a high tunability of activity, they lack high stability and good electron transport often found in heterogeneous catalyst systems.

Based on the energy source, catalytic reactions can be categorized into three main different types: thermocatalysis, photocatalysis, and electrocatalysis. However, new emerging strategies that combine two modalities have emerged leading

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to, for example, electrophotocatalysis and photothermal catalysis. Depending on the nature of the catalytic system, specific computational techniques need to be applied accordingly: for example, the investigation of the photocatalytic activity can be achieved by using time-dependent DFT (TD-DFT),⁷ which allows for the correct description of the excited states formed upon adsorption of the light photons, the determination of excited state barriers, conical intersections and absorption spectra. Another method includes the GW approximation,⁸ which yields good results for bandgaps, but requires exceptional computational cost and it does not yield thermodynamic properties.

On the other hand, various descriptors have been used in predicting the electrocatalytic activities of electrocatalysts. Among them, the d-band center proposed by Nørskov *et al.*^{9,10} has been proved as a promising descriptor for rationalizing the electrocatalytic activity. A detailed analysis of the computational tools used for studying the photo- and electrocatalytic activity goes beyond the scope of this review and it can be found elsewhere.^{9,11}

Computational modeling has been revealed to be a powerful tool for the mechanistic investigation of all kinds of catalytic systems through molecular and periodic simulations. The insights from computational studies are indeed used for the rational design of more catalytically active materials thus suggesting novel potential catalysts that can undergo subsequent experimental verification (see Fig. 1). Among the available computational methods, density functional theory (DFT)^{12,13} is the most commonly used due to the optimal compromise between accuracy and computational cost in comparison with the alternative semi-empirical methods (SEMs)^{14,15} and wavefunction-theory-based approaches (WFAs).^{16–18} Indeed, while SEMs are less accurate and robust but much faster, WFAs, such as coupled-cluster, are more accurate and robust but much slower. Furthermore, DFT can be employed in a “black-box” manner that does not require significant *a priori* knowledge of the system. Based on DFT results, a great deal of experimental phenomena can be elucidated at the atomic scale, thus allowing a wide range of catalytic features and properties to be tackled, such as

estimation of adsorption energies, activation energy barriers, and electronic structure information.

For example, according to the Brønsted–Evans–Polanyi (BEP) relation, the energy barriers of chemical reactions scale approximately linearly with the adsorption energies of the molecules.^{19,20} Therefore, the reliable prediction of adsorption energies is a key element for the search of new and more efficient catalysts.²¹ In this regard, accurate adsorption energies have been calculated by DFT methods and used as descriptors of the catalytic activity of a large number of systems.^{22–24} DFT studies have also addressed the computational screening of surface structures for the design of novel catalysts for a wide range of reactions, including methanation,²⁵ ammonia synthesis²⁶ and others.^{27,28}

DFT computations were used to formulate a novel charge modulated switchable CO₂ capture strategy (see Fig. 2) based on boron nitride (BN) nanosheets and nanotubes, whose CO₂ adsorption/desorption can be controlled and reversed by modifying the charge state of the BN nanomaterials.²⁹ Particularly, the authors demonstrated that CO₂ molecules weakly adsorb on neutral BN; however, when excess electrons are injected into the sorbent material, the adsorption of CO₂ molecules is dramatically enhanced. On the other hand, as the excess electrons are removed, the adsorbed CO₂ is easily released. The authors also demonstrated the high selectivity of charged BN nanomaterials in the separation of CO₂ from gas mixtures such as CO₂/CH₄ and CO₂/H₂. This work represents the first report supporting BN nanomaterials as effective capture/release CO₂ materials, whose processes occur spontaneously without any barriers once the charge is injected into, or dismissed from, BN nanostructures. Even though the authors state that the DFT suggested modification of the charge state of BN nanomaterials can be easily achieved experimentally using electrochemical methods, electrospray, electron beam, or by gate voltage control, the high band gap of BN poses a challenge on how effectively the material can be charged. To overcome this issue, by means of DFT investigations, Tan and collaborators³⁰ investigated borophene, a new type of two-dimensional (2D) boron sheet with a metallic behavior, and demonstrated that conductive borophene nanosheets are a highly promising candidate for charge modulated switchable CO₂ capture. Moreover, these negatively charged borophene nanosheets are highly selective for separating CO₂ from mixtures with CH₄, H₂, and/or N₂. These theoretical studies open up the exploration of novel charge-modulated sorbent materials with higher selectivity, CO₂ capture capacity, ideal thermodynamics and reversibility.

Therefore, in the light of the crucial contribution of DFT calculations to catalysis, the main objective of this review is to give extensive guidance towards the application of DFT methods in computational catalysis. Particularly, a brief introduction to DFT is discussed first, followed by a discussion on DFT approaches based on atomic centered basis sets and plane waves, underlining the main differences, advantages and limitations. In the third paragraph, critical guidance towards the selection of the catalytic model is given. Eventually, a final



Fig. 1 Schematic representation of the contribution of DFT approaches to the investigation of catalytic processes and the design of new catalysts.



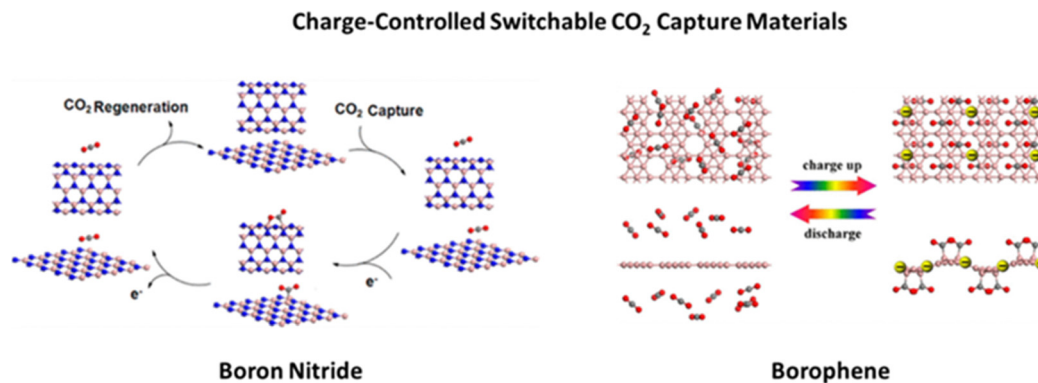


Fig. 2 Charge-controlled switchable CO₂ capture boron nitride and borophene materials proposed on the basis of DFT studies. Reproduced from ref. 29 and 30 with permission from American Chemical Society, copyright 2013 and 2017.

focus on the evaluation of the energy barriers, which is a crucial step in catalytic processes, is discussed.

2. A brief introduction to DFT

Density functional theory (DFT) has emerged as an accurate first-principles alternative to quantum mechanical molecular investigations. DFT is primarily a theory of electronic ground state structures based on the electron density, $\rho(r)$, as opposed to the many-electron wave function, $\Psi(r, r_2, \dots, r_N)$. Since the density $\rho(r)$ is a function of only three spatial coordinates (rather than the $3N$ coordinates of the wave function), density-functional theory is computationally feasible even for large systems. Moreover, contrary to the wavefunction, the electron density is a physical observable, and its integration over all space gives the total number of electrons N , as expressed in eqn (1):

$$N = \int \rho(r) dr = N \int \dots \int |\Psi(r, r_2, \dots, r_N)|^2 dr_2, \dots, dr_N \quad (1)$$

In the last l.h.s. of eqn (1), $\rho(r)$ is expressed as a function of the wave function and, for this reason, it is defined as a “functional”. Indeed, a functional is a function of a function. In DFT, the functional is the electron density which is a function of space and time. As it will be discussed below, the electron density of a system uniquely determines the ground state energy and properties of a system.

The electron density at a particular position in space, $\rho(r)$, can also be written in terms of the individual electron wave function as:

$$\rho(r) = 2 \sum_i \varphi_i^*(r) \varphi_i(r) \quad (2)$$

In eqn (2), the summation goes over all the individual electron wave functions, so the term inside the summation is the probability that an electron with individual wave function $\varphi_i(r)$ is located at position r . The factor 2 appears because electrons have spin and the Pauli exclusion principle states that each individual electron wave function can describe two different electrons with different spins.

The entire field of density functional theory rests on two fundamental mathematical theorems proved by Kohn and Hohenberg. The first theorem states: “the ground-state energy is a unique functional of the electron density” or “the ground-state electron density uniquely determines all properties, including energy and wave function, of the ground state”. Unfortunately, although the first Hohenberg–Kohn theorem rigorously proves that a functional of the electron density exists and can be used to solve the Schrödinger equation, the theorem says nothing about its exact form. The second Hohenberg–Kohn theorem defines an important property of the functional: “the electron density that minimizes the energy of the overall functional is the true electron density corresponding to the exact solution of the Schrödinger equation”. If the “true” functional form was known, then we could vary the electron density until the energy from the functional is minimized, giving us a prescription for finding the relevant electron density. This variational principle is used in practice to provide approximate forms of the functional. The functional described by the Hohenberg–Kohn theorem can be written in terms of the single-electron wave functions $\varphi_i(r)$ since these functions collectively define the electron density, $\rho(r)$, as seen in eqn (2). In other words, electrons interact both with the other electrons and with the ‘external potential’.

The discussion above has emphasized that the density determines the external potential, which determines the Hamiltonian, which determines the wave function. And, of course, with the Hamiltonian and wave function in hand, the energy can be computed. However, if one attempts to proceed in this direction, there is no simplification over MO theory, since the final step is still the solution of the Schrödinger equation, and this is prohibitively difficult in most cases. The difficulty derives from the impossibility to describe the electron–electron interaction term in the Hamiltonian. In a key breakthrough, Kohn and Sham realized that things would be considerably simpler if only the Hamiltonian operator for a non-interacting system of electrons is employed. The crucial bit of cleverness, then, is to take as a starting point a fictitious system of non-interacting electrons that have for their overall ground-state density the same density as some real systems of interest where



the electrons do interact. Next, we divide the energy functional into specific components to facilitate further analysis, in particular:

$$\begin{aligned} E[\rho(r)] &= T_{\text{ni}}[\rho(r)] + V_{\text{ne}}[\rho(r)] + V_{\text{ee}}[\rho(r)] \\ &\quad + \Delta T[\rho(r)] + \Delta V_{\text{ee}}[\rho(r)] \\ &= T_{\text{ni}}[\rho(r)] + V_{\text{ne}}[\rho(r)] + V_{\text{ee}}[\rho(r)] + E_{\text{XC}} \end{aligned} \quad (3)$$

where the terms on the r.h.s. refer, respectively, to the kinetic energy of the non-interacting electrons, the nuclear–electron interaction, the classical electron–electron repulsion, the correction to the kinetic energy deriving from the interacting nature of the electrons, and all non-classical corrections to the electron–electron repulsion energy. The ‘difficult to treat’ terms $\Delta T[\rho(r)]$ and $\Delta V_{\text{ee}}[\rho(r)]$ have been lumped together in the single term E_{XC} , which is usually referred to as the exchange–correlation energy (more details will be given in Section 3.6). This term includes not only the quantum mechanical exchange and correlation effects, but also the correction for the difference in kinetic energy between the fictitious non-interacting system and the real one and, to some extent, for the classical self-interaction energy (discussed below). It must also be pointed out that although exact DFT is variational, this is not true once approximations for E_{XC} are adopted.

2.1. Conceptual density functional theory

Conceptual density functional theory (CDFT) is a DFT-subfield developed by Parr,³¹ whose application covers various subdisciplines of chemistry, ranging from organic to inorganic chemistry, from polymer to materials chemistry, and from catalysis to nanotechnology.

Within CDFT relevant chemical concepts and principles can be extracted from the electron density to understand and predict the chemical behavior of a system.³² CDFT essentially relies on the fact that the ground state energy of an N -electron system as given by the Hohenberg–Kohn theorem can be considered to be depending on the number of electrons, N , and the external potential, $v(r)$, which are themselves determined uniquely using the density, $\rho(r)$. In this context, the responses of the system to changes of the number of its electrons and/or the external potential provide information about its reactivity. In other words, the partial derivatives of electron density and total energy, E , with respect to the number of electrons and external potentials allow for the determination of certain reactivity indices (or descriptors) from which it is possible to quantify the different chemical behaviours of a system. These reactivity indices can be divided into global reactivity indices including electronegativity (χ), chemical hardness (η), softness (S), electrophilicity (ω), chemical potential (μ), and polarizability (α), which elucidate the overall structure, reactivity, and bonding of molecular motifs, and local parameters such as local hardness ($\eta(r)$), local softness ($s(r)$), Fukui functions ($f(r)$), and local philicity ($\omega(r)$), that define the site-selectivity of a molecule.³³

3. Choice of the computational protocol

The accuracy of the DFT results deeply depends on the choice of the selected catalytic model and computational protocol, which in turn depends on the type of catalytic system.

In the following, the main differences in terms of computational approaches and models for homogeneous, heterogeneous and hybrid catalysts will be discussed. Moreover, we will briefly discuss the main limits related to the considered DFT methods.

3.1. Basis sets in molecular systems

While a finite relatively low number of atoms are involved in homogeneous systems, this number becomes ‘‘infinitely’’ large in heterogeneous catalysts. Consequently, one of the main differences in treating such different systems is the use of appropriate basis sets. For molecular systems, the basis set is a set of functions used to describe the shape of the orbitals in an atom. Molecular orbitals and entire wave functions are created by taking linear combinations of basis functions and angular functions, which means that the functions should go toward zero as the distance between the nucleus and the electron becomes large. For example, Pople basis sets^{34–41} are among the most commonly used sets for molecular systems since they are often not demanding, and widely available in commercial packages, such as licensed Gaussian,⁴² and open-source ORCA.^{43,44}

Their typical notation is n-mxG, which implies that each core orbital is described by a single contraction of n Gaussian Type Orbital primitive functions, while each valence shell orbital is described by two contractions, one with m primitives and the other with x primitive. More accurate results for the computed geometries and vibrational frequencies can be achieved by the inclusion of polarization functions. The addition of polarization functions⁴⁵ is indicated by * or **, where one single * means that d primitive functions are added to all the atoms but hydrogen, and ** includes also the addition of p primitives to hydrogen atoms. Referring to the above example, the notation will become n-mxG* or n-mxG**.

Omitting polarization functions on non-hydrogen atoms is a good strategy to significantly reduce the computational cost in systems where hydrogen does not take active part in the properties of interest. In this case, the error introduced by not including hydrogen polarization functions is often rather constant and, as the interest is usually in energy differences, tends to cancel out. On the other hand, when hydrogen atoms play a crucial role in the properties of interest, it is of course not a good idea to neglect polarization functions on hydrogen. Similarly, diffuse functions⁴⁶ can be added by including + or ++ for diffuse function on all atoms rather than hydrogen or including hydrogen as well (n-mx+G or n-mx++G). These diffuse functions are primitives with small exponents, thus describing the shape of the wave function far from the nucleus. Diffuse functions are used for anions, which have larger electron



density distributions. They are also used for describing interactions at long distances, such as van der Waals forces.

It is quite common to introduce mixed basis sets, in which more accurate basis sets are used for describing the “active” atoms that belong to the part of the molecule directly involved in the process under investigation, while the “spectator” atoms are instead described by less accurate basis sets. For example, in one of our works,⁴⁷ the standard 6-311G* basis sets have been employed for all non-metal atoms of the investigated complex, except C and H atoms of the marginal phenyl rings, which have no crucial role in the catalytic activity. For these atoms, the smaller 6-31G basis sets have been used. Similar approaches were used also in ref. 48 and 49. However, a proper balance between the accuracy of the basis set(s) and the computational cost needs to be always taken into account in order to avoid artifacts and/or meaningless results. Maseras and collaborators⁵⁰ investigated the effect of basis sets on a rhodium catalyst by using different sizes of basis sets for the ligand and the transition metal. The authors found that the use of a too small size of the ligand basis set in comparison to that of the transition metal reduces the accuracy of the structural parameters even in cases where the ligand has a marginal role in the catalytic mechanism. This interesting “ligand/TM basis set size relationship” and its impact on computational cost and accuracy add another level of complexity to calculations involving transition metal species.

Even though the literature offers a wide number of examples, it is always better to validate the chosen basis set(s) by comparing the accuracy of the obtained computational results with the available reported experimental data.

Another family of commonly used basis sets is known as basis sets of Ahlrichs and coworkers⁵¹ that, in Gaussian software,⁴² are indicated with the SV, SVP, TZV, and TZVP keywords, referring to the initial formations of the split valence and triple zeta basis sets from this group.^{52,53} Def2 basis sets represent the “newer” redefinitions of these basis sets,^{54,55} and they can be requested in Gaussian with the corresponding keywords: Def2SV, Def2SVP, Def2TZV, Def2TZVP, Def2QZV, Def2QZVP, and QZVP. The open-source ORCA^{43,44} also allows for the utilization of both older and newer Ahlrichs basis sets that can be combined with auxiliary basis sets for notably speeding up the calculations. However, the corresponding keywords are slightly different, and we direct the reader to consult the manual for detailed guidance.

Other classes of basis sets include the Dunning,⁵⁶ Jensen,^{57,58} Sapporo^{59,60} and the atomic natural orbitals (ANOs).⁶¹ A complete list of all available basis sets for electronic structure calculations goes beyond the scope of this short review. However, we want to emphasize that the choice of the most suitable basis set strongly depends on the system and the main property under investigation. On the other hand, the balance between the accuracy and the computational cost should also be considered. Even though small systems allow for the selection of larger and more accurate basis sets, similar choice becomes impracticable when larger systems are under investigation. As a rule of thumb, the basis sets of double zeta

quality with polarization might be suitable for getting accurate enough geometries, while more accurate energies can be obtained by performing single point (SP) calculations using more extended basis sets on the stationary point geometries. However, diffuse functions should always be included for systems containing anions. It is also worth mentioning that Ahlrichs basis sets are consistently available for a larger part of the periodic table and are also considered more efficient than Pople- and the Dunning-type sets for standard DFT treatments.^{62,63}

3.2. Effective core potentials

Differently from semiempirical methods, in which core electrons are completely neglected and minimal basis sets are used for valence electrons, in *ab initio* methods all the electrons are usually represented. However, including all core electrons and their basis functions for heavy atoms is computationally demanding. Indeed, due to the rapid oscillation of the electron wave functions in the proximity to the nuclei, a large number of rapidly oscillating functions (a large set of Gaussians functions for GTO-based calculations) are required to adequately describe the core region. Since core electrons are not always particularly important in defining chemical bonding and other physical properties, they can be efficiently replaced by potential functions in the Hamiltonian referred to as effective core potentials (ECPs). These terms include the electron–electron repulsion of the replaced core orbitals, which is crucial for properly describing the properties of valence electrons.

Moreover, for elements belonging to the lower half of the periodic table, scalar relativistic effects, such as relativistic mass defect and core orbital contraction spin coupling terms, become significant, and therefore they should not be neglected. The inclusions of these terms lead to the so-called relativistic effective core potentials (RECPs). Core potentials must be used along with a valence basis set that was created to accompany them. Some molecular properties may no longer be computed accurately if they are dependent on the electron density near the nucleus (*i.e.* NMR shielding). In such cases, the use of relativistic all electron calculations that include special Hamiltonians, such as X2C,^{64,65} ZORA,^{66,67} or DKH,⁶⁸ might be needed.

It is worth mentioning that the term ECP is mostly used among the chemical community, while the physics community tends to prefer the term pseudopotential (PP), which will be briefly introduced below. ECPs or PPs are usually developed by considering an isolated atom of one element. However, a crucial property of ECP/PPs is transferability, based on which reliable results should be obtained when the chemical environment of the atom is changed without further adjustment of the ECP. Current DFT codes typically provide a library of ECPs and PPs that includes an entry for each (or at least most) element in the periodic table. Calculations that do not include the use of ECPs are instead referred to as all-electron calculations.

Many of the most efficient homogeneous catalysts consist of transition metal complexes. For these systems, the utilization of ECPs for describing heavy atoms might have great



advantages in terms of cost/accuracy balance. When using ORCA, the utilization of ECPs is recommended when the system under investigation contains many heavy elements (heavier than Kr). In such cases, more accurate energies or property calculations can be obtained performing subsequent single-point calculations with an all-electron scalar relativistic approach. On the other hand, if only one heavy atom is present there is no significant advantage in introducing ECPs, while more accurate results, almost as fast, can be obtained using an all-electron relativistic approximation. Moreover, the use of ECPs is unadvised when the molecule does not contain elements heavier than Kr.

The relativistic compact Stuttgart/Dresden (SDD) effective core potential^{69–71} is largely used for precious metals, such as Ru¹⁹ and Pt,^{72,73} but it is also employed to describe the core electrons of non-precious transition metals, such as Zn^{74,75} and Ni,⁷⁶ and heavier halogens such as iodine atoms.^{77,78} Sousa and collaborators⁷⁹ found that use of SDD effective core potential has a very limited impact, in terms of accuracy, in the determination of metal–ligand bond lengths and angles in zinc-complexes, and it is a good and safe alternative to the use of an all-electron basis set. Another ECP widely employed in quantum chemistry is the Los Alamos National Laboratory (LANL2DZ) that was developed by Hay and Wadt.^{80–83} LANL2DZ basis sets are routinely employed to study transition metal compounds^{84–88} or clusters containing heavy elements.^{89–91}

3.3. Basis set superposition error

Interaction or binding energies between two species (atoms or molecules) A and B are usually calculated as:

$$E_{\text{int}} = E_{\text{AB}}(\text{AB}) - E_{\text{A}}(\text{A}) - E_{\text{B}}(\text{B}) \quad (4)$$

which leads to an overestimation of the computed interaction energy known as the basis set superposition error (BSSE). The BSSE occurs as a consequence of the variational principle, since a lower energy is obtained for the molecular system by using a bigger basis set. In eqn (4), the AB complex is described by a bigger basis set than each of the two A and B separate species. In fact, in AB the basis functions on one species play a role in describing the electron density of the other species, and therefore lower the energy of the dimer with respect to the sum of the individual monomer's energies. Extrapolation toward the complete basis set (CBS) limit minimizes the superposition error⁹² but it is often computationally prohibitive. The most suitable procedure for correcting for the BSSE is called counterpoise (CP) correction.⁹³ In typical CP methods, the description of the product complex is unchanged, while separate components are provided in the presence of the basis set associated with the other species. In equation form, this is given as:

$$E_{\text{int}} = E_{\text{AB}}(\text{AB}) - E_{\text{AB}}(\text{A}) - E_{\text{AB}}(\text{B}) \quad (5)$$

where the subscripts refer to the used basis functions and the letters in parentheses indicate the species included in each calculation. In detail, in eqn (5) the same basis set size is used for AB, A and B systems, by including so called “ghost orbitals” for the lack electrons of the separate A and B species. Since the

utilization of very large basis sets is prohibitive for many of the studied systems, the use of a counterpoise correction is highly recommended for the accurate computation of molecular interaction energies by *ab initio* methods.

A significant advantage of plane-wave basis sets discussed below is that they are independent of the nuclear positions. As a consequence, plane-wave based calculations are free of the basis set superposition error. In one of our works, we have compared the adsorption energy of one D-glucose molecule on a titanium dioxide (TiO₂) surface using a localized atomic orbital scheme *vs.* plane waves.⁹⁴ The results have underlined that, using localized atomic orbitals, the effect of the BSSE is a significant fraction of the interaction energy, and it should not be neglected. Indeed, the inclusion of BSSE leads to interaction energy values in perfect agreement with those obtained using PW-based calculations.

3.4. Basis sets in periodic systems

Methods based on plane-wave basis sets are suitable for the investigation of crystalline materials. For infinite systems, the molecular orbitals merge into bands, since the energy spacing between distinct levels vanishes. The electrons in a band can then be described by orbitals expanded in a basis set of plane waves (PW), which in three dimensions can be written as a complex function.

In a perfect crystal, which is invariant under direct lattice translations, the values of a function will be identical at equivalent points on the lattice. Therefore, the electron density and the external potential of the unperturbed system keep the crystal periodicity: $A(\vec{r}) = A(\vec{r} + \vec{r}_i)$ ($A = n, V_{\text{ext}}$), and also the wavefunction assumes the same values at equivalent points of the lattice. The inherent periodicity of crystals can be exploited by invoking Bloch's theorem to express the wave function as a product of a phase factor by a function $u_{\vec{k}}(\vec{r})$ having the crystal periodicity as:

$$\varphi_{\vec{k}}(\vec{r}) = e^{i\vec{k} \cdot \vec{r}} u_{\vec{k}}(\vec{r}) \quad (6)$$

where $u_{\vec{k}}(\vec{r})$ is periodic in space with the same periodicity of the supercell. The periodicity of $u_{\vec{k}}(\vec{r})$ means that it can be expanded in terms of a special set of PW. In other words, each orbital wavefunction is expressed as a linear combination of PW which differs by reciprocal lattice vectors:

$$u_{\vec{k}}(\vec{r}) = \sum_{\{\vec{G}\}} c_{\vec{G}} e^{i\vec{G} \cdot \vec{r}} \quad (7)$$

where the summation is over all vectors defined by $\vec{G} = m_1 \vec{b}_1 + m_2 \vec{b}_2 + m_3 \vec{b}_3$ with integer values for m_i ($i = 1, 2, 3$). These sets of vectors defined by \vec{G} in reciprocal space are defined so that for any real space lattice vector \vec{a}_i , $\vec{G} \cdot \vec{a}_i = 2\pi m_i$. The $\sum c_{\vec{G}}$ terms are the Fourier coefficients in the wavevector space. $\{\vec{G}\}$

Therefore, by replacing eqn (7) into (6) we get:

$$\varphi_{\vec{k}}(\vec{r}) = \sum_{\{\vec{G}\}} c_{\vec{G}} e^{i(\vec{k} + \vec{G}) \cdot \vec{r}} \quad (8)$$

It is worth considering that there are two main problems with



the practical use of eqn (8): first, for a macroscopic lattice there are indeed an infinite number of k points within the first Brillouin zone. Second, to obtain the solution at a single point in the k space, a summation over an infinite number of possible values of \vec{G} is necessary. Fortunately, the latter issue can be addressed by considering that the functions appearing in eqn (8) have a simple interpretation as solutions of the Schrödinger equation, with kinetic energy:

$$E = \frac{\hbar^2}{2m} |\vec{k} + \vec{G}|^2 \quad (9)$$

Hence, it is reasonable to expect that the solutions having lower energy values are more physically important than those with very high energy. As a result, it is usual to truncate the infinite sum above to include only solutions with kinetic energies less than some value: $\frac{\hbar^2}{2m} |\vec{k} + \vec{G}|^2 < E_{\text{cut}}$.

Therefore, the infinite sum then reduces to:

$$\varphi_{\vec{k}}(\vec{r}) = \sum_{\{\vec{G}\}: \frac{\hbar^2}{2m} |\vec{k} + \vec{G}|^2 \leq E_{\text{cut}}} c_{\vec{G}} e^{i(\vec{k} + \vec{G}) \cdot \vec{r}} \quad (10)$$

From the basic principles of Fourier analysis, the need for including wave vectors of increasing magnitude is connected to the smoothness of the function to be expanded: the smoother the function, the faster the expansion convergence. Functions that vary rapidly in space need a very large number of wave vectors to be described, when expanded in PW. The smoothly varying nature of Kohn–Sham states means that for insulators and semiconductors a well-converged sampling density can usually be achieved using a modest number of wavevectors. For metals, however, the abrupt change in the occupancy of each state with wavevector means that much denser grids are required.

E_{cut} is the maximum allowed kinetic energy of the plane waves involved in the truncated sum eqn (9) and is a crucial parameter. On one hand, the larger the E_{cut} , the better the quality of the basis set, which tends to a complete one. On the other hand, the smaller the E_{cut} , the smaller the number of Fourier coefficients to be calculated and stocked in the computer memory. As a consequence, E_{cut} is determined through a compromise between numerical accuracy and computational cost. In practice, E_{cut} is the only parameter that adjusts the quality of the PW basis set. The choice should be done by looking at the behavior of several quantities (total energy, structural parameters, electronic structure, *etc.*) as a function of E_{cut} . As soon as they converge reasonably, the optimal E_{cut} is determined.

On the other hand, the idea of considering an infinite number of vectors k is replaced in practice by sampling the Bloch functions on a discrete mesh of wavevectors often referred to as k -points. This is possible because the wavefunction at points which are close together in k space does not change significantly, and therefore it can be represented by a representative point. Obviously, the denser the set of k vectors,

the more accurate will be the result. One of the most known k sampling methods is the Monkhorst⁹⁵ and Gamma methods.

Ideally, one should ensure that the calculation converges both in terms of the number of wavevectors k and E_{cut} . This should be done by performing some preliminary convergence tests in which the number of k -points is gradually increased while keeping E_{cut} fixed with a large value. Similarly, a dense fixed k -point mesh is used to get the converged E_{cut} value. In many ways, the parameter E_{cut} is easier to define than the k -points, as most packages will apply sensible default settings if no other information is supplied by the user. Just as with the k -points, it is a good practice to report the cutoff energy used in the calculations to allow people to easily reproduce the obtained results.

In conclusion, the main advantage of using PW basis sets is that each Bloch state is expressed as a Fourier series, whose basis functions are computed efficiently and straightforwardly. Moreover, the basis set is orthonormal and its size (and therefore accuracy) is controlled by a single parameter, the cut-off energy E_{cut} or equivalently wavevector G_{cut} . The ground state energy is variational with respect to G_{cut} , allowing the accuracy to be systematically improved simply by increasing G_{cut} . On the other hand, one of the main drawbacks of the approach is the much larger number of basis functions required in comparison with the use of localized basis sets. This notably increases the computational cost, particularly for the evaluation of the Fock exchange term as required by hybrid exchange–correlation functionals (see below). The second difficulty is in the representation of sharp peaks in the Kohn–Sham states, for example those occurring in the core regions near nuclei, and therefore the need for using pseudopotentials as discussed in the next paragraph.

3.5. Pseudopotentials

In analogy to that observed for molecular systems, where the inclusion of all core electrons for heavy atoms requires a large set of atomic localized functions, the explicit inclusion of core electrons in PW-based calculations is rather expensive. Therefore, as already mentioned, due to the rapid oscillation of the electron wave functions in the proximity of the nuclei, describing the core region adequately requires a large number of rapidly oscillating functions, *i.e.* a PW basis with very large E_{cut} . In order to reduce the computational cost, pseudopotentials (PPs) are used for smearing the nuclear charge and modelling the core electrons. Each pseudopotential contains the minimum energy cutoff that might be used in the calculations, and they are typically characterized by a “core radius”, r_c (which may depend on the angular momentum of the valence orbitals). For distances smaller than r_c , the potential is described by a suitable analytical function, typically a polynomial or spherical Bessel function, and the pseudo-wave function and its first and second derivatives are required to match those of the reference wave function at r_c . As a consequence, pseudopotentials with small r_c , named “hard” PPs, need more PW basis functions and higher cutoff energies for describing the region beyond r_c , making the calculations computationally



more demanding. On the other hand, “soft” PPs are characterized by larger r_c , lower cutoff energies, and less PW basis functions. Even though soft PPs are less computationally demanding, a too large r_c may significantly decrease the quality of the calculated results.

One of the most widely used PPs is known as ultrasoft pseudopotentials (USPPs), developed by Vanderbilt.⁹⁶ These pseudopotentials include E_{cut} values significantly lower than those of alternative approaches, whose reduced accuracy is balanced by the introduction of a set of empirical parameters. This latter aspect might limit the transferability of these pseudopotentials. For this reason, DFT codes based on their use typically include multiple USPPs with varying degrees of softness for some elements.

Another frozen core approach that avoids some of the disadvantages of USPPs is the projector augmented-wave (PAW) method, introduced by Blöchl⁹⁷ and later adapted for plane-wave calculations by Kresse and Joubert.⁹⁸ Their work shows that well-constructed USPPs and the PAW method provide essentially identical results in many cases and, just as importantly, these results are in good agreement with those from all-electron calculations. In materials with strong magnetic moments or with atoms that have large differences in electronegativity, the PAW approach gives more reliable results than USPPs.

In one of our recent works,⁹⁹ we have applied the USPP method to pristine and doped/alloyed gallium nitride (GaN), proposed as an efficient photocatalyst for the CO₂ reduction to value-added products. USPPs were also used in studies dealing with 2D materials¹⁰⁰ and metal oxides¹⁰¹ underlying their applicability to describe a wide range of catalytic materials. Similarly, the PAW method has been widely applied to several classes of catalytic materials, ranging from the most studied TiO₂ metal oxide⁹⁴ to graphene¹⁰² and transition metal dichalcogenides (TMDC).¹⁰³

While there is essentially no basis set error when using plane waves for expanding the orbitals, significant accuracy limitation arises from the employment of the pseudopotential to describe the core region. As a consequence, all molecular properties that depend directly on the core electrons (as in X-ray photoelectron spectroscopy) or the electron density near the nucleus (as in NMR shielding and coupling constants) cannot be properly described. Moreover, both the USPPs and PAW method are built based on the local density approximation (LDA) and the generalized gradient approximation (GGA) to the exchange–correlation (ex) energy functional. Therefore, calculations performed with the more recently developed XC functionals use PPs built from LDA or PBE atomic calculation. Their utilization might lead to inconsistent results for both total-energy and band-structure.¹⁰⁴

3.6. Functionals

One of the most important differences between DFT calculations performed using spatially localized functions and periodic wave functions relies on the form of the exchange–correlation functional. DFT methods applied in computational

chemistry are based on the re-introduction of orbitals, whose main flaw is the improved complexity from 3 to 3*N* variables, the re-emerged electron correlation term, and the consequent poor representation of the kinetic energy. As mentioned above, Kohn and Sham partially overtook the kinetic-energy problem by splitting this term into two parts: one that can be calculated exactly, and one consisting in a small correction term. The former is calculated under the assumption of non-interacting electrons and, as in the Hartree–Fock (HF) formalism, represents the main contribution to the total kinetic energy. The remaining kinetic energy contribution, associated with the interacting electrons, is absorbed into an exchange–correlation term, which includes also the interacting electrostatic term. A general DFT energy expression can be written as in eqn (11):

$$E_{\text{DFT}}[\rho] = T_{\text{s}}[\rho] + E_{\text{ne}}[\rho] + J[\rho] + E_{\text{XC}}[\rho] \quad (11)$$

where $T_{\text{s}}[\rho]$ refers to the kinetic energy of the non-interacting electrons, and $E_{\text{ne}}[\rho]$ and $J[\rho]$ refer to the classical nuclei–electron interaction and electron–electron repulsion, respectively. The term exchange–correlation energy, E_{XC} , includes the difference in kinetic energy between the fictitious non-interacting system and the real one, along with the effects of quantum mechanical exchange and correlation, and all the correction for the classical self-interaction energy:

$$E_{\text{XC}}[\rho] = (T[\rho] - T_{\text{s}}[\rho]) + (E_{\text{ee}}[\rho] - J[\rho]) \quad (12)$$

In Kohn–Sham theory one major task is to derive approximations to the exchange–correlation energy functional, which is the only unknown term. As a consequence, the main difference between various DFT methods is the choice of the functional form for E_{XC} . Even though the exchange–correlation potential, whose existence is guaranteed by the Hohenberg–Kohn theorem, is a unique functional, valid for all systems, its true form is not known (except for special cases, such as the uniform electron gas discussed below). For this reason, several functionals have been developed in the last few decades. The simplest classification divides the functionals into two main categories: non-empirical and empirical functionals. The former has been constructed to satisfy certain constraints in order to make use of the known exact constraints on the true Kohn–Sham functional. On the other hand, empirical functionals make use of some parameters that are obtained by fitting experimental or *ab initio* data.

Perdew and co-workers¹⁰⁵ have defined the so-called Jacob’s ladder (see Fig. 3) based on which improved and more accurate functionals are placed at higher rungs, with the Schrödinger equation, solved without approximation, placed at the highest step. As anticipated above, the uniform electron gas represents the only case where the E_{XC} functional can be derived exactly. In this case, the electron density is constant at all points in space. Similarly, the local density approximation (LDA) assumes variations of the density to be slow and treats the local density as a uniform electron gas and represents the first rung of Jacob’s ladder. The second class of functional after the LDA includes information about the local electron density and the local



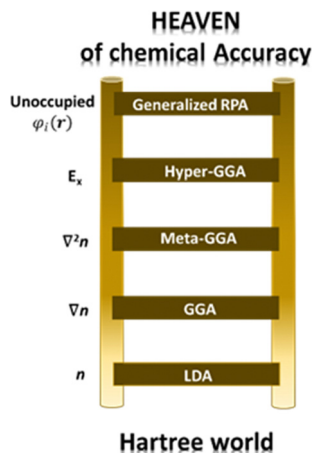


Fig. 3 Jacob's ladder of density functional theory going from the Hartree world of independent electrons (bottom) to the heaven of chemical accuracy (top). n stands for the density, E_x for the exact exchange, and $\varphi_i(r)$ for the orbitals.

gradient in the electron density, defining the so-called generalized gradient approximation (GGA). It is important to notice that the inclusion of more physical information in GGA in comparison with LDA leads, in principle, to more accurate functionals. However, their performance is not always better than LDA. In the third rung of Jacob's ladder are placed the *meta*-GGA functionals, which include the Laplacian (second derivative) of the density. Hybrid functionals (also known as hyper-GGAs) belong to the fourth rung of the ladder. These functionals combine some percent of the non-local, exact exchange-energy density with a GGA. Due to the numerical details associated with solving the Kohn–Sham equations in a plane-wave basis set, introducing the nonlocality of exact exchange greatly increases the numerical load of solving these equations, thus drastically limiting their usage in calculations based on plane waves. On the other hand, this issue is not so severe when localized basis sets are used, making hybrid functionals the most commonly used in quantum chemistry calculations with localized basis sets.

Two of the main drawbacks of DFT approximations are the self-interaction error (SIE) or delocalization error (DE) and the missing long-range correlation effects that will be discussed in more detail in the next paragraphs.

However, it is worth anticipating that the SIE is reduced in hybrid functionals where a fraction of approximate DFT exchange is replaced by Fock exchange. Another attempt to reduce the SIE is the utilization of range-separated functionals (RSs).^{106–108} In this approach, the exchange interaction is split into two components, a long-range (LR) coming from Hartree–Fock, and a short-range (SR) DFT component derived from local-density or generalized-gradient approximations (LDA or GGA). The range-separation parameter, ω , is then defined to set the distance at which the exchange term switches from HF to DFT. Based on the approach suggested by Kronik *et al.*,^{109–112} the optimal value of ω , which is found to be strongly system-dependent, can be tuned (giving the tuned range separated

functionals) to fulfill Koopmans' theory¹¹³ for the first ionization energy. Alternatively, it can be determined to reproduce experimental data.¹¹⁴ The Heyd–Scuseria–Ernzerhof (HSE)^{115,116} functional is based on this approach; it is built by starting with the PBE functional and mixing a portion of exact exchange into only the short-range portion of the problem. Other commonly used RS functionals are ω -B97XD¹¹⁷ and CAM-B3LYP¹¹⁸ RS functionals.

One of the most recent functionals is the Strongly Constrained and Appropriately Normed (SCAN) *meta*-GGA functional¹¹⁹ that satisfies all the 17 known constraints for *meta*-GGA functionals and is constructed to be almost exact for the noble gases and jellium surfaces. Carter and co-workers found that the utilization of the SCAN functional accurately describes the oxidation energetics of binary transition metal oxides (TMOs). However, in order to get oxidation enthalpies comparable to experiment the Hubbard term, U , on the TM centers has to be introduced leading to the SCAN+ U framework.¹²⁰

Based on this description, it is clear that there is not a unique functional that is suitable for all systems. Reliable results and computational cost dramatically rely on the functional's selection. Therefore, the understanding of the main similarities and differences between the various functionals that are in common use is crucial for selecting the most suitable functional.

Moreover, guidance in selecting the correct functional can be obtained by carefully checking the literature. It is also highly advisable to first perform some benchmark studies, in which several functionals are used and the results are compared to any available experimental parameters. However, it is important to note that the results obtained by DFT studies greatly vary depending on the used method which might lead to diverse conclusions. The use of the right functional is not trivial and is still highly discussed between researchers not only for complicated systems but also for transition metal surfaces and complexes.

Among the hybrid functional, the most widely used in quantum chemistry is the B3LYP^{121–123} that, together with other hybrid DFT methods, in general achieves excellent results for equilibrium geometries¹²⁴ across the periodic table. Vetere and collaborators¹²⁵ performed geometry optimizations and harmonic frequency calculations of heavy metals using the GGA PBE¹²⁶ and the corresponding hybrid PBE0.¹²⁷ Both the functionals give better results than B3LYP, with PBE0 performing better than PBE for the reproduction of geometrical features, while both give similar good agreement for frequencies. On the other hand, the GGA BLYP^{121,122} functional has been reported to perform satisfactorily on modeling chemical reactions in comparison with hybrid or *meta*-GGA functionals¹²⁸ for some oxides such as silica¹²⁹ and metal oxides.¹³⁰ The performance of B3LYP for both isomerization energies and heats of formation of organic molecules leads to an average error of about 3.0 kcal mol⁻¹, which is reduced to 2.4 and 2.2 for heats of formation and isomerization energies, respectively, when dispersion forces (see below) are taken into account.¹³¹ In one of our last works,⁷⁷ we found that the long range hybrid



ω -B97XD¹³² functional tends to overestimate the calculated energy barriers with respect to hyper-GGA B3PW91¹³³ and B3LYP for systems that involve organic molecules. Moreover, the adsorption energy of CO₂ on GaN surfaces calculated at the B3LYP level of theory has been found to be similar to that obtained using the more accurate double hybrid PBE0DH^{134,135} functional that combines exact HF exchange with an MP2-like correlation to a DFT calculation. Thus, hybrid DFT methods provide a quantitative means of investigating reactive chemistry in a large range of systems.^{78,89,136–138} Two of the most widely used GGA functionals in calculations involving solids are the Perdew–Wang functional (PW91)¹³⁹ and the Perdew–Burke–Ernzerhof functional (PBE).¹⁰³ Even though most of the works dealing with periodic boundary conditions and plane waves still use the GGA functional, thanks to the High Performance Computing improvement that was fast achieved in the last few decades, the number of studies that include the HF exchange is rapidly increasing.¹⁴⁰ Zaffran and Toroker¹⁴¹ have shown that standard DFT is sufficient to evaluate the geometry of the NiOOH material, but hybrid functionals are necessary to properly study the NiOOH electronic structure.

A bunch of approximations have been introduced to further overcome DFT limitations and they are currently widely available in different codes. Among these, inclusion of Hubbard terms and dispersion forces allow for very accurate results. These approximations will be shortly described in the following.

3.7. Self-interaction error

A systematic difficulty of DFT relies on the so-called SIE that results from an unphysical repulsive interaction of an electron with itself, which is due to the contribution of the electron to the total electron density. This error is not present in the HF method, since the spurious self-interaction energy is exactly cancelled out by the contributions to the energy from exchange. The same would happen in DFT if the exact Kohn–Sham functional was known. Since that is not the case, the incomplete cancellation of the self-interaction energy appears in any approximate DFT functional. One of the examples where the self-interaction error is significant is transition metal oxides. When these materials are modelled using DFT involving LDA and GGA approximations, exchange and correlation effects are not properly taken into account leading to not reliable results. A better description of metal oxide surfaces is provided by self-interaction correction (SIC)^{142–144} and GW approximations (GWA)^{145,146} but these methods are computationally very demanding and not appropriate for the large systems that are required for surface and cluster simulations. As mentioned above, the SIE is partially corrected in hybrid exchange functionals thanks to the inclusion of a percentage of the exact exchange energy in the E_{XC} term, and range-separated functionals.

A different approach, which has been proved particularly suitable for strongly correlated electron materials, is known as the DFT+ U method or Hubbard method,¹⁴⁷ which is of relatively computationally low cost and therefore applicable to

extended systems. In this method, the underestimated electronic interactions are corrected by simply adding the semi-empirically tuned numerical parameter “ U ”. The method is also based on a combination between HF and DFT. Specifically, it combines a HF-like approach that takes into account the on-site Coulombic repulsion among localized d electrons by incorporating an extra energetic penalty for delocalization, with DFT for “everything else”. Following this scheme, a correction for electron self-interaction to the DFT energy is added by introducing two numerical parameters, U and J , which involve different aspects of self-interaction.

García-Mota and collaborators have reported that the inclusion of the Hubbard- U term to DFT (DFT+ U) is necessary to reproduce the experimental trends observed in the oxygen evolution reaction (OER) activity of strongly correlated cobalt oxides.

Noteworthy, Barlocco *et al.*¹⁴⁸ have investigated the role of functionals in predicting the activity of single atom catalysts (SAC) in the hydrogen and oxygen evolution reactions (HER and OER). Based on their findings, the authors highly recommend the use of the PBE+ U approach to investigate systems that include transition metal (TM) atoms at the right of the first TM row, while the adoption of the standard PBE functional is found suitable for some 4d and 5d TM atoms.

3.8. Dispersion forces

Dispersion interactions, such as van der Waals interactions and London forces, are associated with interacting electrons that are spatially well separated. These attractive interactions are due to the dynamic correlations between fluctuating charge distributions. Since semi-local and hybrid functionals do not account for these interactions, they are not suitable for systems where these forces play an important role. In such cases, a correlation dispersion term should be added to the semi-local or hybrid functionals, leading to the resulting energy:

$$E_{\text{vdw}} = E_{\text{XC}}^{\text{sem/hyb}} + E_{\text{disp}} \quad (13)$$

One possible way to include dispersion forces in DFT calculations is to incorporate empirical potentials of the form $\frac{C_6}{R^6}$, where the C_6 coefficients are pairwise atomic parameters, along with a damped function, f_{damp} . This method, developed by Grimme,^{149,150} is known as the dispersion-corrected DFT or DFT-D method. The oldest version, known as DFT-D2,¹⁵¹ has the form:

$$E_{\text{disp}}^{\text{D2}} = -s_6 \sum_A \sum_{B < A} \left(\frac{C_{6,AB}}{R_{AB}^6} \right) f_{\text{damp}}^{\text{D2}}(R_{AB}) \quad (14)$$

An alternative to Grimme's DFT-D2 is the empirical dispersion correction of Chai and Head-Gordon,¹⁵² which uses the same form but with a slightly different damping function.

The newer versions of Grimme's D2 method are the D3¹⁵³ and D4^{154–156} corrections. The D3 version includes a similar



potential to that in D2 with the addition of C8 terms:

$$E_{\text{disp}}^{\text{D2}} = - \sum_A \sum_{B < A} \left[s_6 \left(\frac{C_{6,AB}}{R_{AB}^6} \right) f_{\text{damp},6}^{\text{D2}}(R_{AB}) + s_8 \left(\frac{C_{8,AB}}{R_{AB}^8} \right) f_{\text{damp},8}^{\text{D2}}(R_{AB}) \right] \quad (15)$$

The more recent Becke–Johnson-damping version¹⁵⁶ makes use of a different damping function, and it is usually referred to as DFT-D3(BJ).

Grimme and collaborators argued that the inclusion of dispersion correction is indispensable in any DFT treatment, and it should always be taken into account.¹⁵⁷

4. Choice and validation of the catalyst model

As already mentioned, one of the main differences between homogeneous and heterogeneous catalysts is their size. The former contains a finite and relatively low number of atoms that, instead, becomes “infinitely” large in the latter. Due to their finite size, the real structure of a homogeneous catalyst is, in principle, easier to be modeled. However, many homogeneous catalysts, such as complexes of transition metals, consist of bulky organic substituents which notably increase the computational cost. In some cases, these substituents are necessary only to stabilize the structure of the catalyst and do not take active part in the catalytic process. In such cases, a common practice is to replace these bulkier groups with smaller ones, thus saving computational time and resources without affecting the validity of the results. For instance, in one of our works, the β -diketiminato ligand of Mg and Ca complexes used as an efficient catalyst for the dehydrogenation of dimethylamine-borane (DMAB) was simplified by replacing the two *i*-Pr substituents of the *N*-aryl groups with H atoms.¹⁵⁸ Similarly, a simplified model of the $[\text{Rh}(\text{Ph}_2\text{P}(\text{CH}_2)_2\text{-PPh}_2)(\text{C}_6\text{H}_5\text{F})]^+$ complex, in which the phenyl rings of phosphine ligands have been replaced with less demanding methyl groups, has been used to explore the plausible reaction pathways of dehydrogenation/dehydrocoupling of amine-boranes.¹⁵⁹

As previously mentioned, the infinite number of atoms involved in heterogeneous catalysts is reduced when modeling these systems.^{160–163} Two main approaches are generally used: cluster approach (CA) and periodic boundary condition (PBC) calculations.

Both methods present advantages and disadvantages that are briefly described below.

The PBC approach allows for the investigation of extended surfaces and provides an accurate description of the structural properties of the surface and molecular adsorbates. Moreover, remarkably accurate solid-state properties such as equilibrium lattice constants, bulk moduli, cohesive energies, work functions, elastic and phonon properties, vacancy formation and surface energies can be achieved performing PBC calculations at the semilocal level of theory.^{164–168} However, as mentioned in previous paragraphs, these functionals fail in properly

describing the exchange and correlation effects, leading to an inaccurate description of the electronic band gaps.¹⁶⁹ Since more truthful exchange–correlation functionals are computationally expensive when used in PBC calculations, the most suitable alternative is the use of the DFT+*U* method described above. PBC calculations involving charged systems are problematic due to the spurious interactions between the charges in different periodic images that can affect the physical picture. Furthermore, the investigation of complex reaction mechanisms involving several stationary points is computationally more demanding with respect to CA. On the other hand, the CA allows for the use of hybrid functionals with lower computational cost, thus obtaining a more accurate description of the electronic properties. CAs are also more suitable for studying charged systems thanks to the possibility of adding/subtracting a charge carrier without suffering from interactions with similar charge carriers due to PBC.^{91,170} The reduced size of CA allows for the interception of all the stationary points, including the more complex transition states, at much lower computational cost. In some of our previous studies^{129,130,171} cluster models have been successfully used to investigate a wide range of catalytic reactions. It has to be pointed out that the selection of a cluster model is not trivial, and particular attention should be paid to the choice of the cluster size and the most suitable procedures to saturate the peripheral atoms.¹⁷⁰ Indeed, a cluster may undergo strong deformations with respect to its starting structure and the dangling bonds at the termination may introduce spurious states in the surface’s electronic structure, thus influencing its chemical reactivity. When such issues arise, two different strategies might be applied consisting in embedding the cluster (1) in a larger structure, which is treated with cheap empirical molecular mechanics methods¹⁷² or (2) in a network of polarizable Coulomb point charges, mimicking the long-range ionic network in a solid (electrostatic embedding).¹⁷³

Additional difficulties in modelling heterogeneous systems with both the approaches need to be considered for proper model selection. In cases where no experimental information about the most stable phases of the crystal is given, different facets of the surfaces need to be taken into account. It is worth mentioning that the physical and chemical properties of the surface deeply depend on the particular crystallographic plane where the cleavage is performed. An estimation of the thermodynamic stability of the different structures can be obtained by calculating the formation energy reported by Person *et al.*,¹⁷⁴ and defined as:

$$\mu_{i=1,\dots,n}^0 = G_{i=1,\dots,n}^0 - \sum_i^n \mu_i^{\text{ref}}, \quad (16)$$

where μ^0 is the chemical potential, G is the Gibbs free energy of the compound, and μ_i^{ref} is the chemical potential of element i .

Eqn (16) has been widely used to evaluate the stability of target catalysts from the theoretical predictions^{175,176} as long as to guide the design of new catalysts.¹⁷⁷

The number of atomic layers included in the slab should also be carefully assessed. Convergence tests should be



performed to evaluate the number of layers that has to be considered in the model, while the size of the surface area should be chosen in order to accommodate the adsorbed molecules involved in the catalytic process and to avoid spurious interactions between their images. Moreover, the stoichiometric composition within the slab model should be taken into account.

Vacancy formation is very likely to occur in heterogeneous catalysts, such as O vacancies in metal oxides and N vacancies in nitride materials. It has been proved that vacancies play a crucial role in the activity of many catalytic systems^{160–163} and therefore their formation and effect on catalytic processes should not be neglected. Nevertheless, due to the inevitable oversimplification of real systems, calculations of homogeneous and heterogeneous systems are always afflicted with methodological errors. For this reason, it is highly recommended to connect theory with as many spectroscopic experiments as one can possibly obtain.

In hybrid systems, due to the presence of the active or inactive solid support to which the homogeneous catalyst is anchored, calculations based on PBC and CA are adopted. For example, García-Melchor and collaborators³ have studied the stability and activity of a homogeneous dimeric Ir complex catalyst that is attached onto the surface of the IrO₂(110) heterogeneous catalyst. The authors have compared the activity of the hybrid catalyst to that of the corresponding homogeneous and heterogeneous constituents and found that there is not a significant loss of activity of the homogeneous catalysts after its anchoring to the oxide surfaces. To model the hybrid catalyst, the authors anchored this dimeric Ir complex on top of the IrO₂(110) surface with a 6 × 2 periodicity through two oxygen atoms to the coordinatively unsaturated sites (CUS) of the surface. As a result of the considerable size of the combined system, calculations for this catalyst were performed at the Γ -point.

Despite their apparent simplicity, SACs are challenging to model due to their boundary nature between homogeneous and heterogeneous catalysts. Similarly to homogeneous catalysts, SACs consist of individual atoms, whose chemical reactivity directly relates to their electron configuration and orbital diagram. On the other hand, as in heterogeneous catalysts, the strong interaction of the single atoms with the underlying support influences their charge spin state, and their overall chemical reactivity. Also in this case, approaches based on CA and PBC calculations are used to model these systems. A detailed discussion of pros and cons of both approaches can be found in references.^{178–180}

Based on these considerations, it appears clear how the reliability of any presented results strongly relies on the accuracy of the selected model. Therefore, the choice of the model together with that of the computational protocol should always be guided by balancing accuracy and computational cost.

5. Determination of accurate energy barriers

One main aspect of catalysis is the efficiency of the conversion process leading to the formation of the desired products.

Catalytic reactions proceed *via* several reaction steps in which reactants are converted into products by the involvement of intermediates and transition states (TSs), many of which are too unstable to be isolated experimentally. Therefore, while experimentally isolated species, which include the final products, do allow for the suggestion of plausible reaction mechanisms, they usually lack the possibility to picture all the subsequent reaction steps, thus limiting the detailed knowledge of the involved catalytic cycle. In this regard, DFT investigations have been proved to be of utmost importance since they allow for the interception of all relevant stationary points on the potential energy surfaces (PESs), thus representing a unique tool for identifying the missing structures and the related energy barriers. Moreover, different reaction paths leading to the same products can be hypothesized and explored by means of DFT calculations, and the most accessible pathway can be identified by determining the lowest activation barriers along with the corresponding involved rate determining states. This information is crucial for suggesting structural and electronic modification that leads to the design of new, more efficient catalysts. It should also be recalled that although local geometry optimization is a routine procedure in any DFT package, appropriate protocols are needed to identify the reaction pathways and the energy and geometry of the saddle point that connects two local minima in the potential energy surface of a given system. The availability, efficiency, and reliability of such protocols are clearly of uppermost importance when applying theoretical modeling to catalysis studies. Simm and collaborators¹⁸¹ have organized the plethora of strategies developed for the exploration of PESs into three classes: the first one includes methods in which, starting from a point on the PES, new TSs and intermediates are discovered by relying on local curvature information. This process is repeated until all relevant stationary points of the PESs are explored. In the class 2 methods, the starting point is a minimum energy structure from which new intermediates and TSs are obtained through the application of heuristics. Once a new intermediate is found, the minimum energy pathway (MEP) connecting it to the starting structure can be searched for. Eventually, the third class is based on the combination of chemical knowledge and intuition with ultrafast computer simulations in an interactive setting to efficiently explore intermediates and TSs of a PES. More details about all these methods can be found in references.^{181–183}

5.1. Transition state theory

A chemical reaction involves the rearrangement of nuclear configurations from the reactant state to the product state. For polyatomic molecules, an infinite number of possible rearrangement paths can, in principle, take place. Reactant molecules that have lots of energy could follow high energy paths, while low energy paths are involved in conversion of reactants with lower energy. Since a complete description of a chemical reaction including all these paths is challenging (because of the need to map out a multidimensional potential energy surface), a simplified approach, termed the transition



state theory, is commonly employed. This approach is based on the identification of a saddle point (transition state) on the PES that corresponds to a maximum along a MEP for a particular reaction coordinate. The latter is a concerted vibration, characterized by an imaginary frequency value, involving two or few atoms of the molecular system, whose variation follows bond-breaking or a bond-formation.

The most commonly applied algorithms for the transition state search can be divided into two main categories: methods based on the initial guess of the transition state (such as Quasi-Newton methods, Bery algorithms and Dimer methods), and those based on the optimized reactant and product structures (including the quadratic synchronous transit approach (QST), nudged elastic band (NEB) and climbing image NEB (CI-NEB)). The use of the former is highly recommended when the user has a clear idea of what the transition state structure should look like. Quasi-Newton methods require an initial estimate of the Hessian and implicitly assume that the potential energy surface has a quadratic shape. When the Bery algorithm is used the Hessian is computed incrementally, which further speeds up the calculation. On the other hand, the dimer method becomes advantageous if the product state on the MEP is not known. It has to be noticed that a poor initial guess can cause slow convergence or convergence to an incorrect structure or even failed to get a desired transition state. In such cases, the user can rely on double-ended interpolation techniques based on which the generation of the TS structure is performed by the algorithm starting from the known reactant and product. It has to be pointed out that these methods are more computationally demanding since they require the computation of additional calculations. For instance, when the NEB method is selected, the algorithm generates a number of images along the reaction path that are optimized by adding additional spring forces along the band between images. Each of these images finds the lowest energy while keeping equal spacing to the neighboring image.

Different to local optimization methods, double ended interpolation methods only converge to a close vicinity of the TS but do not precisely locate the TS. Therefore, these methods are usually combined with TS guess algorithms, such as the Bery optimization algorithm and dimer method mentioned above. The overall TS search is therefore divided into two steps: in the first one, the vicinity of a TS is located by a double ended interpolation method, while the second step refines the structure by a local TS optimization method.

Most common packages used in quantum chemistry and solid-state physics, such as Gaussian,⁴² ORCA,^{43,44} VASP^{184,185} and QuantumEspresso,¹⁸⁶ allow for the utilization of both the methods that are easily accessible by specifying the corresponding keywords.

5.2. Energetic span model

According to the energetic span model (ESM),¹⁸⁷ the turnover frequency (TOF) of a catalytic event can be derived from electronic-structure calculations by identifying the energetic span of the cycle, δE , which is defined as the energy difference

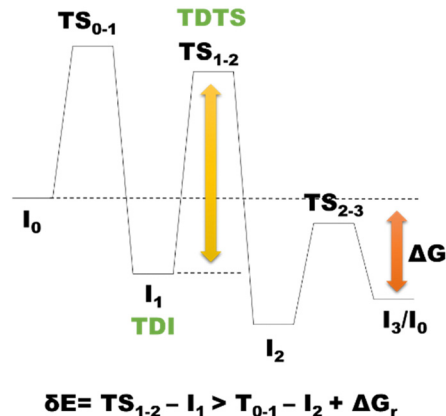


Fig. 4 Energy profile of a model catalytic cycle in which the highest value of δE is obtained by considering the energy difference between TS_{1-2} and I_1 that thus represent the TDTS and TDI, respectively.

between the points of the highest and the lowest energy along the reaction profile corresponding to the complete catalytic cycle. Kozuch and Shaik^{188–191} extended this model by including the ΔG_r of the reaction, and defining δE_{ij} as:

Therefore, if the j -th transition state lies after the i -th intermediate, then δE_{ij} is just the energy difference among them; if j -th transition state precedes the i -th intermediate, then δE_{ij} is their energy difference minus the ΔG_r . The highest value of δE_{ij} corresponds to the energy span of the cycle connecting the TOF-determining intermediate (TDI) and the TOF-determining transition state (TDTS) (see Fig. 4). The use of ESM is largely spreading.^{192–195} In some of our most recent works, ESM has been applied to determine the rate determining states involved in the catalytic formation of MeOH catalyzed by a homogeneous Ru complex¹⁹ and a heterogeneous catalyst based on GaN,¹⁷¹ along with the determination of the rate determining states involved in cyclic carbonate formation *via* CO₂ insertion into epoxide catalyzed by organic molecules.⁷⁷ The application of ESM to heterogeneous catalysis is hindered by several reasons,¹⁹⁶ including the utilization of simplified catalyst models, such as infinite perfect periodic single crystal surfaces to represent the more complicated real catalysts, and the higher difficulty in intercepting transition states involved in heterogeneous catalysis with respect to molecular systems. Moreover, the ESM cannot be used for precise modeling of the kinetics of reactions involving several active sites¹⁹⁷ such as in the case of heterogeneous catalysts, and last but not least, this model leads to the determination of the TOF, which is usually difficult measure in heterogeneous catalysis.

6. Conclusions and outlook

Thanks to the increasing computational power and improved computational methodologies, computational catalysis has become a powerful tool for studying, rationalizing, and even predicting the reactivity of a wide range of catalytic materials. Particularly, methods based on DFT has been proved crucial to get insights into the mechanistic details of catalytic reactions,



allowing for the identification of active catalytic species, intermediates and transition states that are challenging to study *via* experimental approaches due to their high instability. However, there are still several challenges that limit the accuracy of the computational methodology, and therefore, the reliability of the obtained results. These challenges are mostly related to the complex nature of catalytic cycles and the precise reproduction of the catalyst model and conditions. In this regard, DFT studies are usually performed post experimentally to support and help rationalize the observed chemical reactivity. However, thanks to the extraordinary fast progress that computational methodologies have been achieving, it is highly auspicious that new implemented computational tools can be used for the development of novel reactions, innovative synthetic concepts, and more efficient catalysts. In this context, this review offers a practical guide for scientists that can contribute to the application and the further improvement of computational catalysis.

Author contributions

The manuscript has been entirely written by Valeria Butera.

Conflicts of interest

There are no conflicts to declare.

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