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# Ensemble hybrid machine learning to simulate dye/divalent salt fractionation using a loose nanofiltration membrane

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The escalating quantity of wastewater from multiple sources has raised concerns about both water reuse and environmental preservation. Therefore, there is a pressing need for intelligent tools that can aid in comprehending the intricate process of removing dyes and salts from wastewater beyond membrane technology. This study introduces novel standalone hybrid models that integrate an improved nonlinear ensemble approach to model the fractionation of dye and salt rejection (RJDS) (%) based on established experimental data. Using linear sensitivity analysis, two model combinations were identified based on different input variables: M1 ( $R = 52\%$ ,  $T = 50\%$ , and  $P = 61\%$ ) and M2 ( $R = 52\%$ ,  $T = 50\%$ ,  $P = 61\%$ ,  $F = 71\%$ , and  $RJ = 83\%$ ). These combinations were incorporated into hybrid neuro-fuzzy (NF) and least square support vector machine (LSSVM) models. The standalone and improved ensemble models were evaluated using several performance criteria, such as MSE, MAE, MAPE, RMSE, and PBAIS. The predictive outcomes demonstrated that NF-M2 outperformed all other models, with an MAE of 0.0002 and an RMSE of 0.0003. Similarly, the ensemble results indicated a significant improvement over the individual models. The study's findings demonstrate the reliability of intelligent tools for modelling RJDS (%) and serving as decision-making performance analysis tools. The proposed approach offers a novel, efficient and reliable technique for understanding and predicting dye and salt rejection in wastewater.

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## Environmental significance

Integrating experimental and novel machine learning-based modelling of dye and divalent salt rejection from fractionation using loose nanofiltration membranes in wastewater (WW) experiments has significant environmental implications. High levels of dyes and divalent salts in WW can lead to contamination of water bodies, soil, and plants, negatively impacting aquatic life and human health. The effective removal of dyes and divalent salts from WW is crucial for mitigating the potentially harmful effects of these substances on the environment. By developing accurate and reliable models for predicting dye and divalent salt rejection from WW using loose nanofiltration membranes, researchers can optimize treatment processes and reduce the environmental impact of WW discharge. This study's findings provide an innovative approach to WW treatment and highlight the importance of developing effective strategies for reducing pollutants in WW to safeguard environmental health.

## 1. Introduction

Recently, loose NF membranes have received significant attention in the fractionation of dyes/salts<sup>1</sup> and resource recovery.<sup>2</sup> The production and utilization of various dyes are continuously increasing due to their high requirement in critical and highly demanding societal, industrial products, which include plastics, paper, leather tanning packaging, pharmaceuticals, rubber, and textiles. Several conventional methods have been adopted to treat dyes, which include ozonation, sedimentation,

adsorption, floatation, and photocatalytic oxidation.<sup>3</sup> For instance, wastewater streams with hypersaline have shown resistance to biological treatment.<sup>4</sup> These kinds of streams poison the biological treatment systems, which can significantly impact dye degradation by microbes. However, the membrane-based separation process carries certain advantages of requiring no additives, allowing physical separation, being less energy intensive, and having excellent chances of scalability.<sup>5</sup> Loose NF membranes emerged as a powerful separation tool to fractionate dyes and salts compared to other tight NF membranes.

Membrane technology, while valuable, is often limited by its fixed design and lack of adaptability.<sup>6</sup> Membranes struggle with complex feed compositions and varying conditions, leading to suboptimal separation efficiency. Additionally, fouling and

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scaling can reduce the membrane lifespan and performance, necessitating frequent replacement. The one-size-fits-all approach of traditional membranes overlooks the intricacies of different applications, hindering optimal results.<sup>7,8</sup> To address these limitations, the integration of AI-based models can offer real-time monitoring, adaptive control, and predictive capabilities, revolutionizing membrane processes by optimizing the performance, extending the lifespan, and accommodating diverse operational scenarios.<sup>9</sup> Hence, integrating AI with membrane processes, this innovation ensures precision, adaptability, and improved resource utilization, marking a pivotal advancement in separation technology.<sup>10</sup>

Artificial intelligence (AI) is rapidly growing in several areas and helping significantly in the advancement and understanding of various challenges, including pattern recognition, smart cities, big data, intelligent search, pattern recognition, and healthcare.<sup>11</sup> Artificial intelligence has become a popular debate in the mainstream media, and researchers in almost every field are rapidly adopting it to consider it an opportunity to go beyond the human intellect.<sup>12</sup> It has been reported that some AI-based systems have blown the whistle by defeating the world champions in their domains of expertise, including the quiz game, Go and chess.<sup>13</sup> Machine learning and artificial intelligence are already making a mark in our daily lives. Still, how it would impact physical sciences and how it would be advantageous out of speculation now are big concerns for scientists. The near future would decide how it would be beneficial for solving tedious problems and long-awaited question marks in various research fields.<sup>14</sup>

In materials science, artificial intelligence is overgrowing and bringing astonishing results and predictions. For instance,<sup>15</sup> machine-learning techniques were used for large-scale MOF screening. It was found that the MOF properties are predictable through machine learning methods. Artificial intelligence and machine learning were also used to explore the possibilities of designing high-power-density membranes for pressure retarded osmosis. It has been found that the water permeability coefficient, thickness, and membrane types are the major contributors to improving the water flux, and operation conditions also play a critical role.<sup>16</sup> Viet and Jang developed various models based on artificial intelligence to predict filtration performance and membrane fouling in the osmotic membrane bioreactor.<sup>17</sup> The artificial intelligence method was employed to predict the engineering factors for the forward osmosis membrane.<sup>18</sup> Similarly, machine learning and artificial intelligence have been used for other membranes, including fuel cell alkaline anion exchange membranes<sup>9</sup> and proton exchange membrane electrolyzers.<sup>19</sup> Thus, artificial intelligence and machine learning can play a critical role in optimizing the membrane fabrication process<sup>20</sup> and membrane design and even can successfully predict discoveries in membrane science.<sup>21</sup> However, the utilization of artificial intelligence in membrane science is in the stage of infancy, specifically for loose nanofiltration membranes.

During the last decade, several machine learning (ML) techniques have been explored in various fields of desalination and membrane science and engineering.<sup>22–28</sup> Based on the

mentioned literature, AI-based techniques can be applied to designing and optimizing nano-filtration membrane systems. Machine learning algorithms, for instance, are used to predict membrane performance based on its physical and chemical characteristics.<sup>29</sup> This can help researchers and engineers to identify the most promising membrane materials and design parameters for a given application. Additionally, AI-based control systems can be used to monitor and adjust the operating conditions of a nanofiltration system in real-time, which can help to improve the efficiency and longevity of the membrane. It is worth noting that several surveys highlighted the limited use of AI-based models, specifically hybrid models, in wastewater dye and salt rejection. The rapid advancement of ML may offer new solutions to address the limitations of current membrane processes. Besides, conventional methods have their limitations, and AI-based models have had a significant impact on various industries. It is considered the fourth paradigm of science, alongside data-driven science, as shown in Fig. 1.

ML, a crucial component of AI, offers various advantages over traditional experimental and computational techniques.<sup>30</sup> One major benefit is its ability to quickly analyze large material databases, unlike the resource-intensive multi-physics simulations.<sup>31</sup> This leads to cost savings and more efficient material discovery.<sup>32</sup> However, a significant challenge in the field of membranes, particularly loose nanofiltration is obtaining sufficient experimental data. To address this, techniques such as selecting important features, increasing data, and processing them can be crucial in improving predictions and reducing training time. These methods can identify the relationship between features and parameters within large sets of data. This study was inspired by an established experimental laboratory using a loose NF membrane and loose layer surface functionalization of ultrafiltration (UF) membranes with nano-silver-immobilized polydopamine. The objective of the study was devoted to AI-based feasibility in modelling and simulation of rejection of dye/salt (RJDS). For this purpose, stand-alone models, namely neuro-fuzzy (NF) model and least square support vector machine (LSSVM), were employed. Subsequently, two different ensemble techniques *viz.* simple averaging ensemble (SAE) and nonlinear NF ensemble were proposed to improve the prediction accuracy of less accurate models.

## 2. Experimental methodology

The complete procedure of the preparation of the support and the membrane for the fractionation of the EBT/salt is reported in previously reported experimental work.<sup>33</sup> The polysulfone support was prepared on the polyethylene terephthalate support. For the support preparation, a solution of 18% polysulfone was made using dimethylacetamide. The moisture was removed by placing the polysulfone pellets at 50 °C under vacuum. An 18% homogeneous polysulfone solution was prepared by continuously stirring the dried polysulfone pellets overnight in dimethylacetamide. After the polysulfone pellets were completely dissolved, the solution was degassed for half an



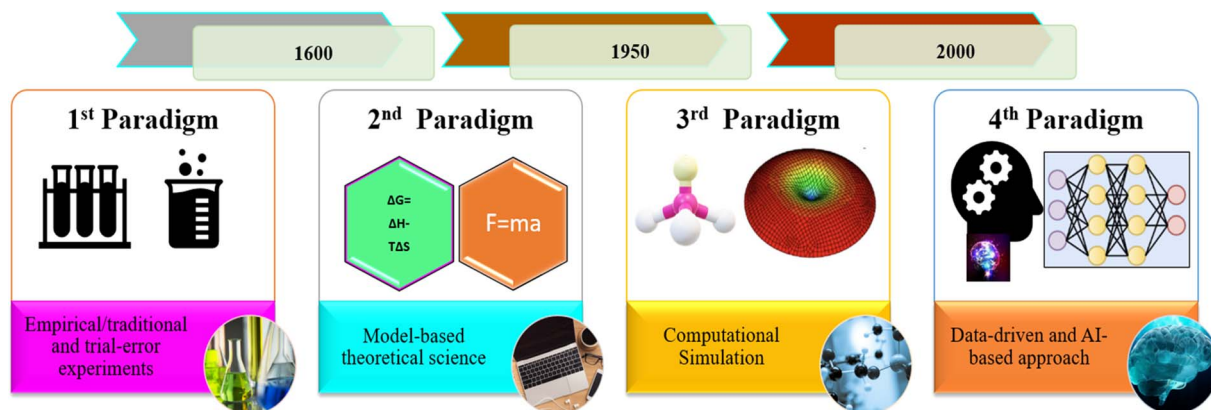


Fig. 1 The generation paradigms of science and engineering.

hour by placing it in a sonicator to remove the trapped bubbles produced during the dissolution of polysulfone. A thin film of the PS was made with the help of the doctor's blade on the surface of the polyethylene terephthalate support. After casting, the thin film was immediately immersed in a coagulation bath to solidify the support. After solidification for completion of the

phase inversion process, the PS membranes were placed in deionized water for a time span of 24 hours. The PS membranes were named M-0.

Different separating layers develop on the surface of the PS membranes by controlling the polymerization time. The membranes M-1 and M-2, abbreviated as D-6 and D-12, were

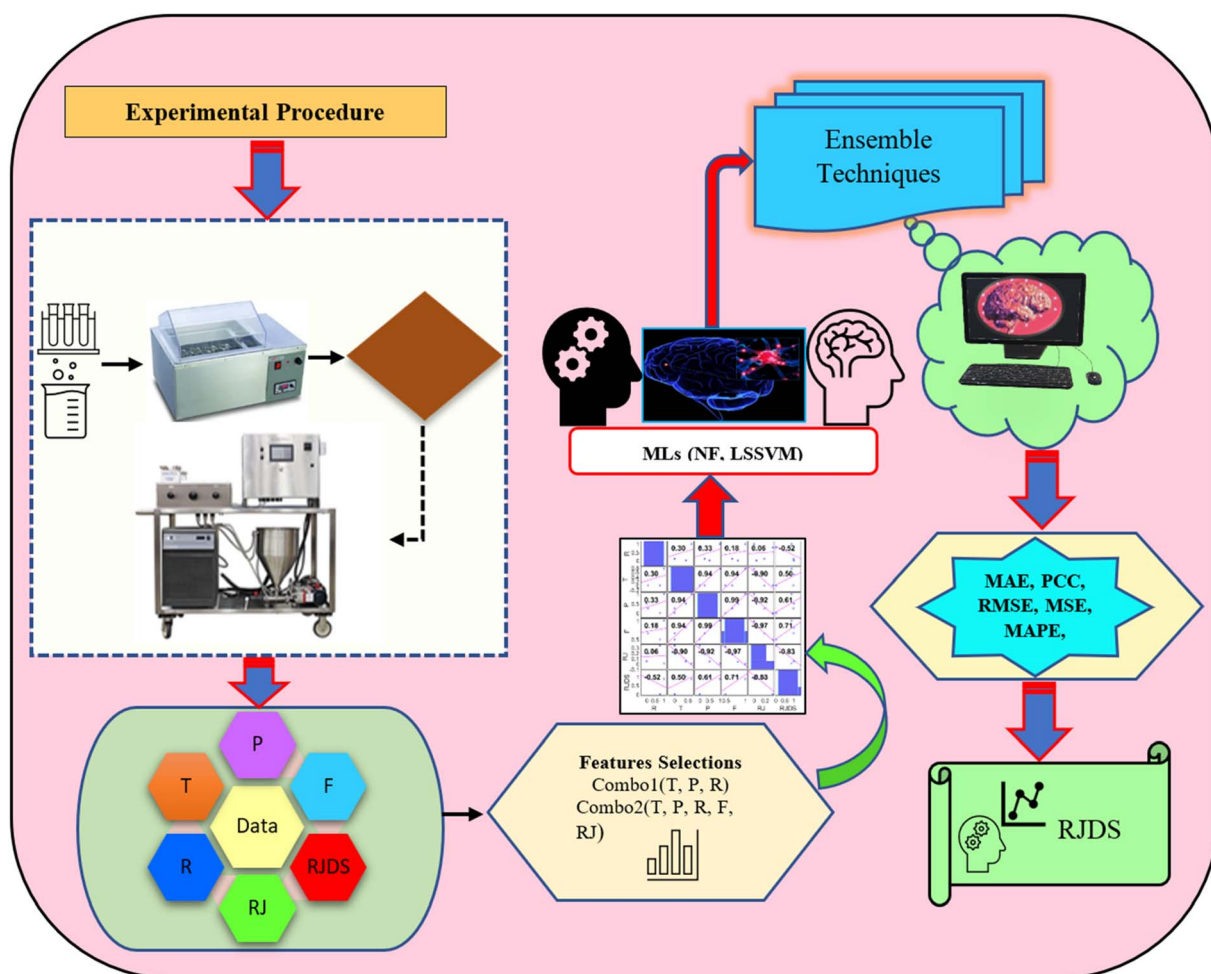


Fig. 2 The proposed modelling schema of this study.



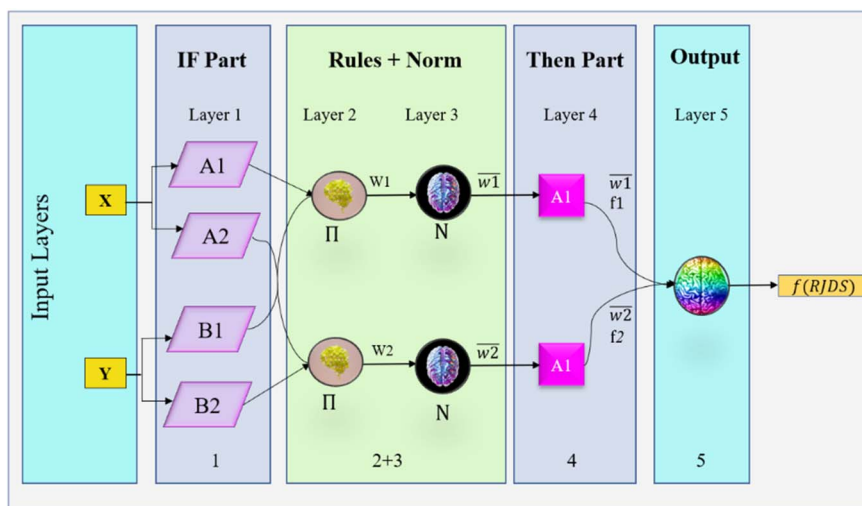


Fig. 3 Schematic diagram shows the structure of the NF model.

designed by keeping the PS membranes in a dopamine solution that is controlled at pH 8.5 for 6 hours and 12 hours, respectively. The membranes M-3 (AD6) and M-4 (AD12) were synthesized similarly for the period of 6 and 12 hours, except after the 20 minutes of polydopamine polymerization, the  $\text{AgNO}_3$  solution was added to reach 0.001 M concentration. Then EBT with 25 ppm and  $\text{MgSO}_4$  with 2000 ppm concentrations were prepared in deionized (DI) water and used as the feed solution. All these membranes were evaluated using the Sterlitech crossflow setup, which consists of 3 filtration cells.

## 2.1 Proposed AI-based methodology

The simulation of nanofiltration membrane performance was proposed using the hybrid neuro-fuzzy (NF) model and Least square support vector machine (LSSVM); afterwards the modelling accuracy was improved using simple averaging and nonlinear averaging techniques. It is worth mentioning that one of the advantages of using soft computing in nanofiltration

membrane desalination is the ability to optimize the process by analyzing and learning from large amounts of data. This can lead to improved performance, such as higher salt rejection rates and a longer membrane lifespan. Moreover, computational learning can be used to identify and predict potential issues with the membrane, allowing for proactive maintenance and preventing costly downtime. For this experiment, we used normalized data that were split into calibration and validation sets to simulate the rejection of dye/divalent salts. The experimental data which include roughness ( $R$ ), pressure ( $P$ ), flux ( $F$ ), rejection ( $RJ$ ), and rejection based on dye/salt ( $RJDS$ ) were pre-processed prior to the modelling schema. For the development of models, sensitivity analysis was used to generate two input combinations. The overall modelling schema is presented in Fig. 2.

Besides the sensitivity analysis, normalization (eqn (1)) and cross-validation were conducted to scale-up the data and assess the performance of a model by evaluating its ability to predict

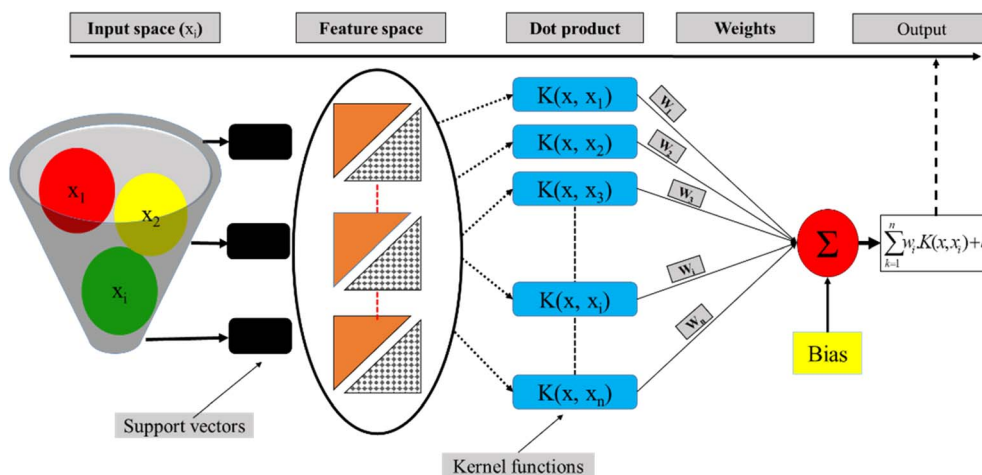


Fig. 4 Schematic view of the LSSVM model functioning process.





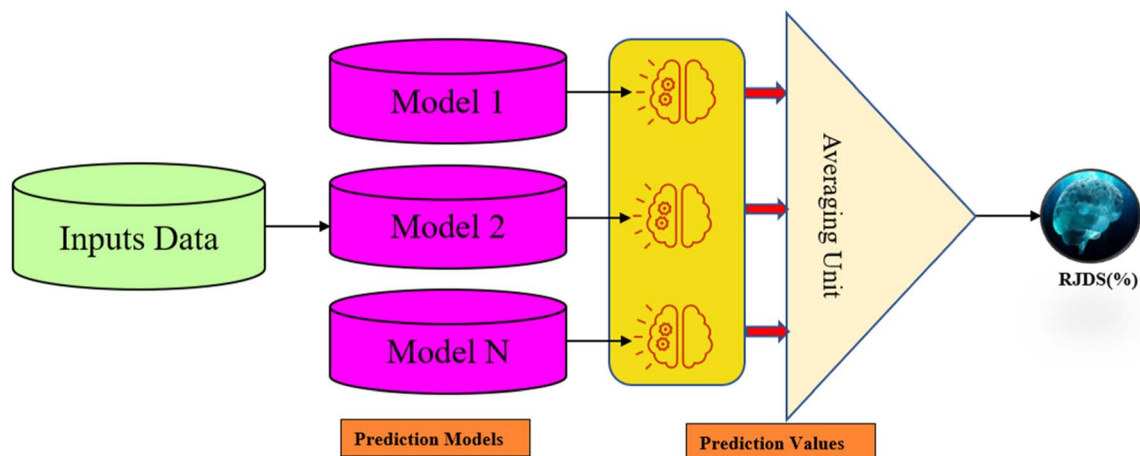


Fig. 5 Schematic diagram of the simple averaging ensemble method.

outcomes in new, unseen data. Cross-validation is used to avoid overfitting, which happens when a model is too closely fitted to the training data and performs poorly on raw, untainted

data.<sup>34–36</sup> Although there are various cross-validation techniques, the most well-known one is  $k$ -fold cross-validation, which involves splitting the data into  $k$  subsets, and training

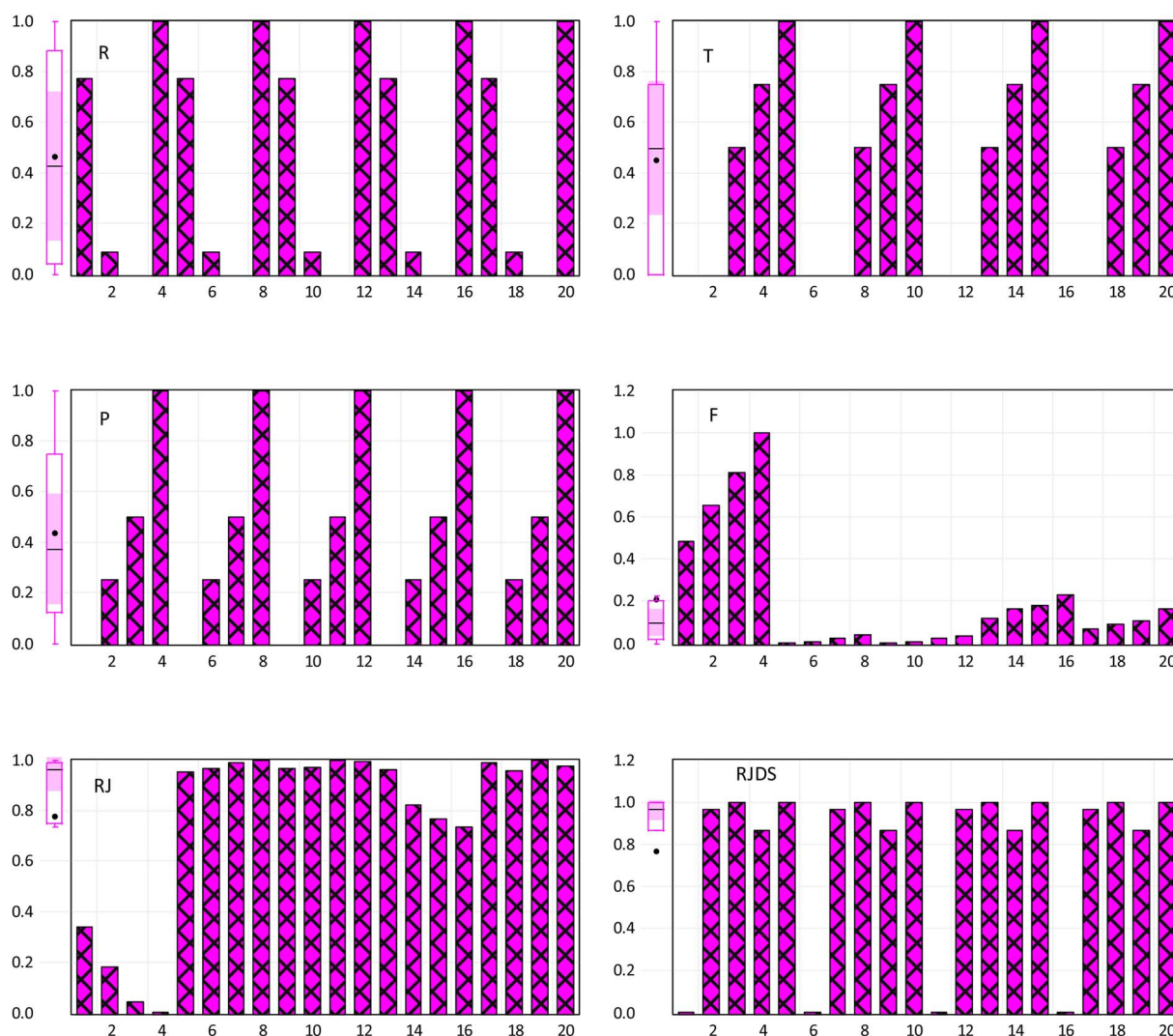


Fig. 6 Normalized visualization of raw input-output variables.



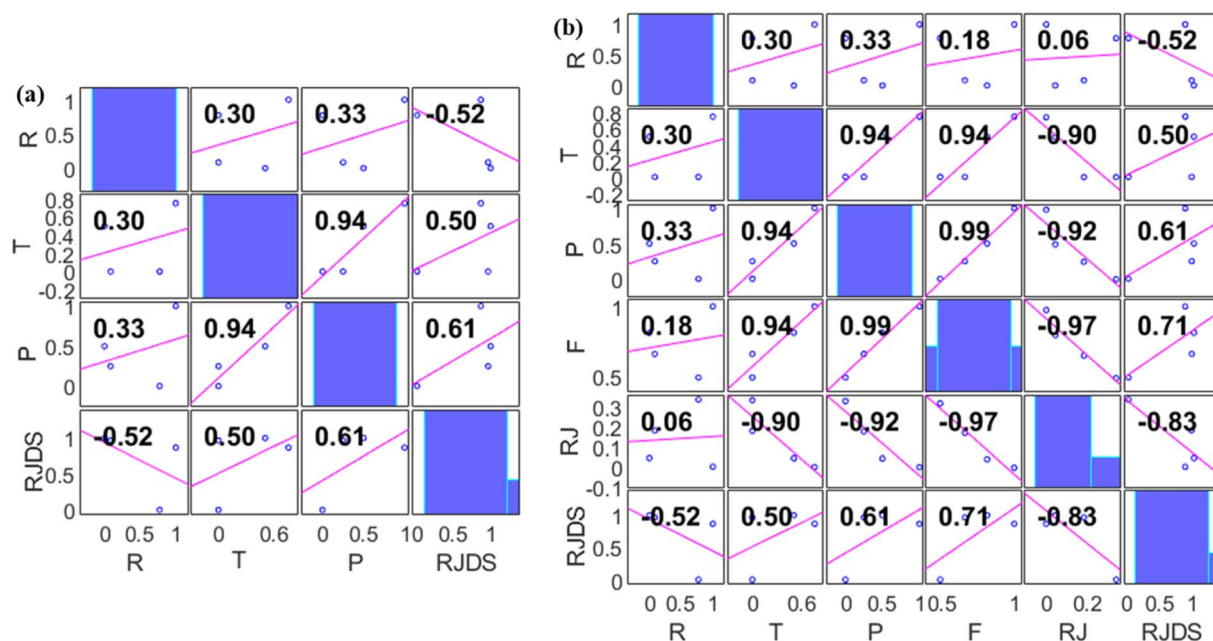


Fig. 7 Dependency analysis results of (a) combination 1 and (b) combination 2.

Table 1 Validation results for single and ensemble models

Models	Validation phase				
	MSE	RMSE	MAE	PCC	PBAIS
NF-M1	0.0950	0.3082	0.2196	0.6026	-0.0005
NF-M2	0.0000	0.0003	0.0002	1.0000	0.0000
LSSVM-M1	0.1039	0.3223	0.2534	0.5511	0.0000
LSSVM-M2	0.0663	0.2574	0.1946	0.7455	0.0001
SAE-NL-M1	0.0974	0.3121	0.2365	0.7891	-0.0003
SAE-NL-M2	0.0166	0.1288	0.0974	0.9427	0.0000
LSSVM-NF	0.0296	0.1719	0.0908	0.8955	-0.0003

and evaluating the model  $k$  times, each time using a different subset as the test set and the remaining  $k - 1$  subsets as the training set.<sup>37</sup> This allows the model to be evaluated on a variety of different data, giving a more accurate estimate of its performance on unseen data. Cross-validation is particularly useful for small datasets where it is important to maximize the amount of data used for training while still having enough data for validation. This is crucial for evaluating the performance of a model and fine-tuning its hyperparameters before it is deployed in a real-world setting.<sup>38,39</sup> The models were evaluated using several performance criteria such as RMSE (root mean square error), MSE (mean square error), MAE (mean absolute error),  $R^2$  (determination coefficient), percent bias (PBAIS) and

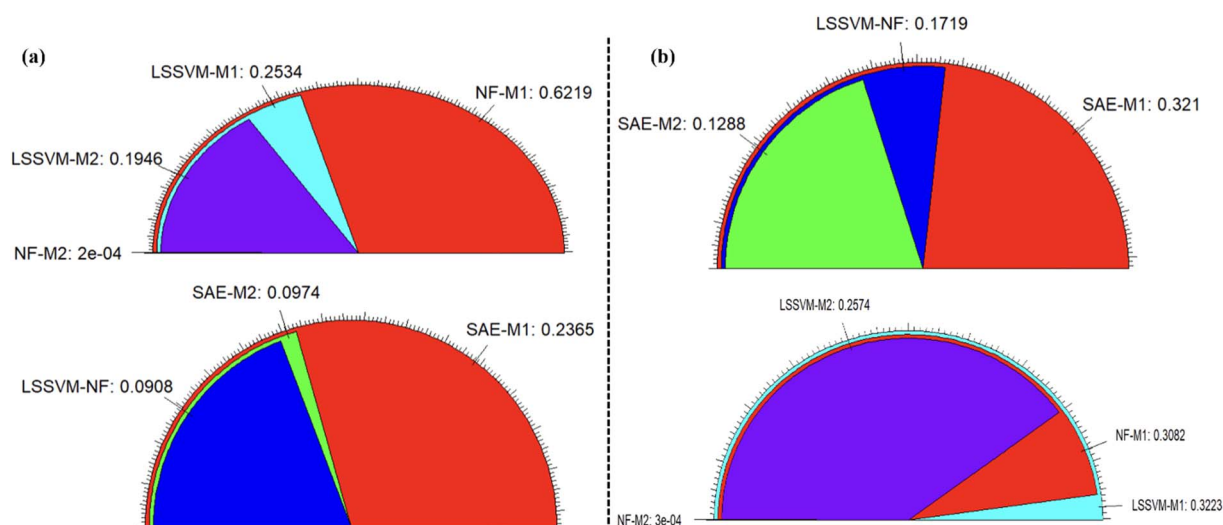


Fig. 8 Error fan plot for (a) MAE and (b) RMSE between the observed and predicted values.



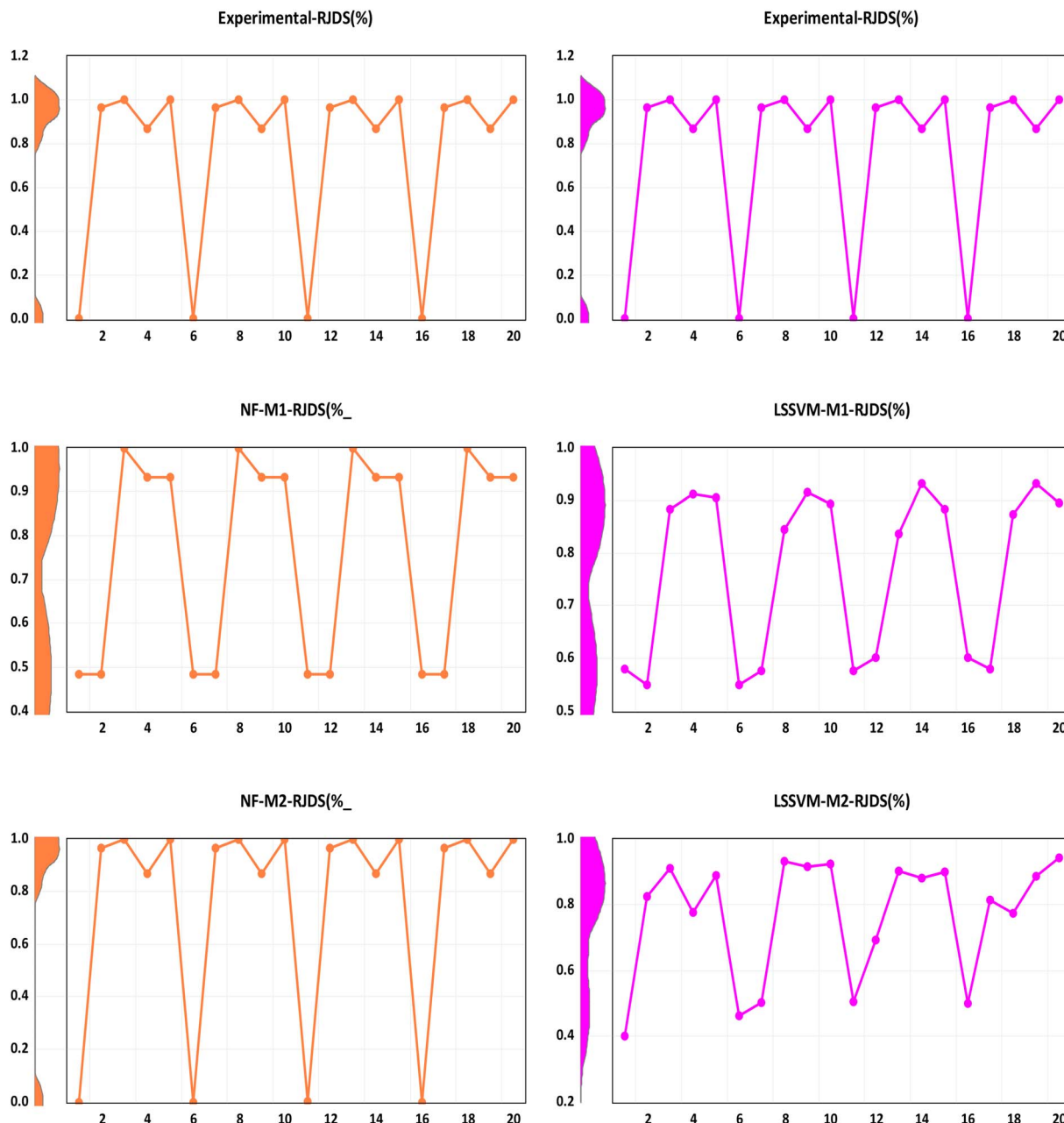


Fig. 9 Response plot between the experimental and simulated RJDS (%) for single models.

PCC (Pearson correlation coefficient), as shown in eqn (2)–(7), respectively.

$$y = 0.05 + \left( 0.95 \left( \frac{x - \bar{x}}{x_{\max} - x_{\min}} \right) \right) \quad (1)$$

where the normalised data are represented as  $y$ , the measured data as  $x$ , the mean data are calculated as  $\bar{x}$ ,  $x_{\max}$  is the maximum value of the data, and  $x_{\min}$  is the minimum value.

$$\text{RMSE} = \sqrt{\frac{1}{N} \sum_{i=1}^N (Y_{(p)} - Y_{(o)})^2} \quad (2)$$

$$\text{MSE} = \frac{1}{N} \sum_{i=1}^N (Y_{(p)} - Y_{(o)})^2 \quad (3)$$

$$\text{MAE} = \frac{\sum_{i=1}^N |Y_{(p)} - Y_{(o)}|}{N} \quad (4)$$

$$\text{PCC} = \frac{\sum_{i=1}^N [Y_{(p)} - \bar{Y}_{(o)}] [\hat{Y}_{(p)} - \hat{Y}_{(o)}]}{\sqrt{\sum_{i=1}^N [Y_{(p),i} - Y_{(p)}]^2 [\hat{Y}_{(p)} - \hat{Y}_{(o)}]^2}} \quad (5)$$



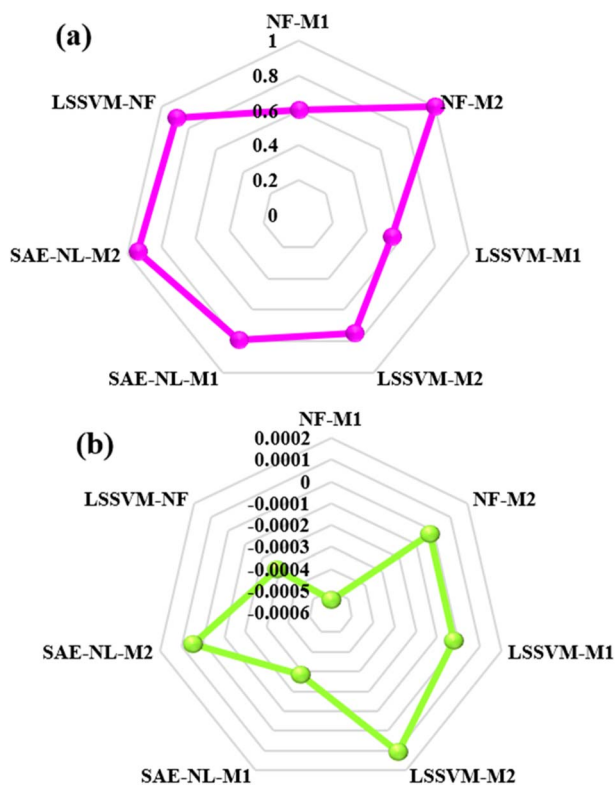


Fig. 10 Overall comparison using the radar plot for (a) PCC and (b) PBAIS.

$$\text{PBIAS} = \frac{\sum_{i=1}^N (Y_{(o)} - Y_{(p)})}{\sum_{i=1}^N Y_{(p)}} \quad (6)$$

## 2.2 Neuro-fuzzy model

The fuzzy inference system (FIS) and artificial neural network (ANN) are combined into a single intelligence technique known as neuro-fuzzy (NF) or adaptive neuro-fuzzy. To address scientific and technical issues, the NF model combines the best features of the two models. As a result of its usefulness in transforming existing bodies of data into constraint sets, FIS has gained widespread acclaim.<sup>40</sup> Optimizing the search space is a viable application for the generated sets, which can be used at the level of the network's topology. To further automate the process of tuning the parameters of a fuzzy controller, NF combines FIS with neural networks with backpropagation (BP).<sup>41</sup> Similarly, ANFIS possesses the requisite capabilities for network monotonic tuning using Takagi-Sugeno (TS). Such estimating ability is anticipated in cases where several membership functions were investigated in relation to the datasets, in addition to differentiable T-norm rules.<sup>42</sup>

Learning techniques are typically implemented in NF using a mechanism consisting of two stages.<sup>43,44</sup> The conceptual diagram of the basic NF architecture for TS-FIS is illustrated in Fig. 3. This diagram demonstrates that NF requires just two

inputs and a single output. A total of five layers of perceptrons or neurons make up the TS-FIS structure. They are the fuzzy layer, implication layer, normalizing layer, defuzzifying layer, and combining layer. Perceptrons and neurons within a single layer are functionally equivalent and share the same characteristics.<sup>44</sup>

## 2.3 Least square support vector machine (LSSVM)

LSSVM as a type of Support Vector Machine (SVM) is an established classification method that accurately groups data, has no issue with the number of dimensions of data, and only requires a short training sample.<sup>45</sup> By making slight adjustments, this technique was used by researchers for regression analysis.<sup>46</sup> The structural risk diminishing inductive concept was applied to SVM to obtain good generalization on a small set of learning patterns (Fig. 4). To reduce the risk described, researchers have been conducting simultaneous tests to decrease both the empirical risk and the dimension.

In the last three decades, researchers have made significant advances toward an enhanced VC, and their work has resulted in a theory that characterizes the qualities of learning machines and allows them to effectively generalize hidden data. Generally, support vector machines come in two primary types: SVC and SVR. A revised version of support vector for use in regression analysis has been developed by ref. 47. They developed a  $\epsilon$ -insensitive loss function, and then proceeded on to SVMs to address regression issues. In order to minimize  $\|\omega\|^2$  and hence reduce the model's complexity, researchers have applied a limit tolerance (epsilon) to SVM (eqn (7)).

$$\text{Minimize } \frac{1}{2} \|\omega\|^2 + C \sum_{i=1}^m (\epsilon_i + \epsilon_i^*) \quad (7)$$

where  $C$  and  $\epsilon_i$  are the factor employed for the empirical risk and the factor to modify the convergence speed, respectively, where  $m$  represents the computation of the data.

## 3. Ensemble learning concept

It is clear that when comparing the performance of different intelligent techniques on a specific dataset, one technique may perform better than the others. However, when using different datasets, the results can be quite different.<sup>48,49</sup> To take advantage of the strengths of all techniques and maintain a level of generalizability, an ensemble model can be created that combines the outputs of each technique, assigning different levels of importance to each output with the help of an arbitrator to achieve the desired outcome.<sup>50</sup> The performance of ML models will be improved using ensemble learning thereby combining the results of different predictors. It was proved that an ensemble of models provided more accurate results than a single model alone. There are many areas of research where ensemble techniques have been successfully implemented, including regression modeling, classification, web ranking, clustering, and time series. To enhance the effectiveness of a particular model, this research employed two linear and one





non-linear ensemble methods: simple average ensemble and neuro-ensemble non-linear average techniques.<sup>51</sup>

### 3.1 Simple averaging ensemble (SAE)

The simple averaging ensemble (SAE) is a popular method that is commonly the first option in application due to its flexibility and efficiency. It involves directly averaging the result of the individual model to provide the final outputs.<sup>52</sup> The simple averaging ensemble technique (SAE) is achieved through two steps: in the first step, each model is trained and tested separately,<sup>53,54</sup> and in the second step, the average of the model output was tested and compared with the observed tested values as illustrated in Fig. 5. The standard equation for SAE is as follows:

$$\rho_{(t)} = \frac{1}{N} \sum_{i=1}^N \rho_i(t) \quad (9)$$

where  $N$  is the number of models in the ensemble, and  $\rho_i$  represents the output of the single model at the time ( $t$ ).

### 3.2 Nonlinear averaging methods

The nonlinear averaging technique is achieved through training of another neural network. Each model's output is connected to a neuron in the input layer of the neural ensemble model.<sup>55,56</sup> When training a nonlinear ensemble model, such as a single NF or ANN using the activation function of the output and hidden layers, any algorithm can be trained by the network, and the epoch number and best structure of the ensemble network can be established *via* the trial and error technique.<sup>57</sup> In this study we used hybrid NF as the ensemble algorithm, although other non-linear kernels such as BPNN might also be utilized as such, a nonlinear ensemble, NF, was used in this research because it is the combination of the neural network and fuzzy logic.

## 4. Results and discussion

### 4.1 Pre-analysis analysis

The incorporation of an AI-based approach for experimental analysis can help reduce the time spent carrying out experiment and multiple redundant experiments which thus promotes the efficiency route as well as fabrication processes.<sup>58</sup> This will help in tackling the challenges of digitalization, transdisciplinary of research playing a crucial role of discovering a new system with high performance and accelerated optimization. This section explains the result of pre-processing, statistical visualization. Fig. 6 shows the normalized visualization of raw inputs-output variables on the basic statistical parameters, including the skewness, quartile range, bar chart, *etc.*, feature selection and core prediction of F, RJ, and RJDS based on experimental laboratory data. As stated above, this study is aimed at predicting parametric variables (RJDS) based on fractionation of dye/salt experiments. The predictive outcomes of RJDS were evaluated using RMSE which gives more weight to larger errors and are commonly used for regression problems, MAE gives equal weight to all errors, regardless of their magnitude, MAPE is

the average of the absolute differences between predicted and actual values, expressed as a percentage of the actual values, and MSE is the mean of the squared differences between predicted and actual values. MSE gives more weight to larger errors, and the bias of a model, which is the difference between the expected predictions of the model and the true values of the data. A low bias indicates that the model is making predictions that are close to the true values.

There is no doubt that this research is greatly devoted to crediting the seasoned ML algorithms; in this context, pre-processes such as dependency analysis and data stability were performed prior to the ML developments. The use of this type of pre-analysis process was recently reported in many studies.<sup>45,59</sup> Irrespective of making use of the whole input combination in the analysis, it was found that feeding the ML with too much input variables will result in increasing the computational burden as well as delays the time of simulation. Thus, Fig. 7 shows two different proposed combinations (combination 1 (M1) and combination 2 (M2)) for individual target variables using a dependency approach. From the computation analysis, RJDS ((combo-1 =  $R + T + P$ ) (see Fig. 7a) and (combo-2 =  $R + T + P + RJ + F$ ) (see Fig. 7b)) is based on a dimensional positive and negative relationship between the input and targets parameters. Despite the linearity of the dependency approach, it still proves to have good performance. Therefore, to achieve reliable results, this study further performed ML algorithm analysis to select the preferable input parameters using this approach.<sup>60</sup> The dependency results depicted that the absolute relationship with the target variables (RJDS) is associated with  $P$  (61%),  $R$  (52%),  $T$  (50%),  $F$  (71%), and  $RJ$  (83%). The numerical quantification shows that  $R$  and  $RJ$  are inversely proportional to RJDS, while  $P$  and  $T$  are directly related to the output variables. Although  $F$  and  $RJ$  can be output in some scenarios, it is worth mentioning that the objective of the modeling is to understand the complex nonlinear RJDS and ML feasibility for detecting them.

### 4.2 AI-based and ensemble results

This section deals with predictive results of single models (NF, LSSVM) using several performance evaluation criteria. In order to enhance the precision of our predictions, we introduced two distinct and innovative ensemble approaches (SAE-NL and LSSVM-NF). These groundbreaking methodologies were incorporated to elevate the accuracy of our predictive models. Both the ML and ensemble models were developed using MATLAB 2022b meanwhile for graphs, pre- and post-processing of data EViews 11.0 software and XLSTAT were employed. Furthermore, training as well as validation of the models was developed using the modelling schema. To achieve good generalisation of models, there is a need to determine the optimal model structure. For this purpose, several trial-and-error methods were used to generate the fuzzy inference system (FIS) for the NF model based on grid partition and sub-clustering. The hybrid optimum method was utilized with an error tolerance of 0.0005, triangular membership functions (MFs), and 100 epoch iterations. Similarly, optimum input combination for LSSVM was



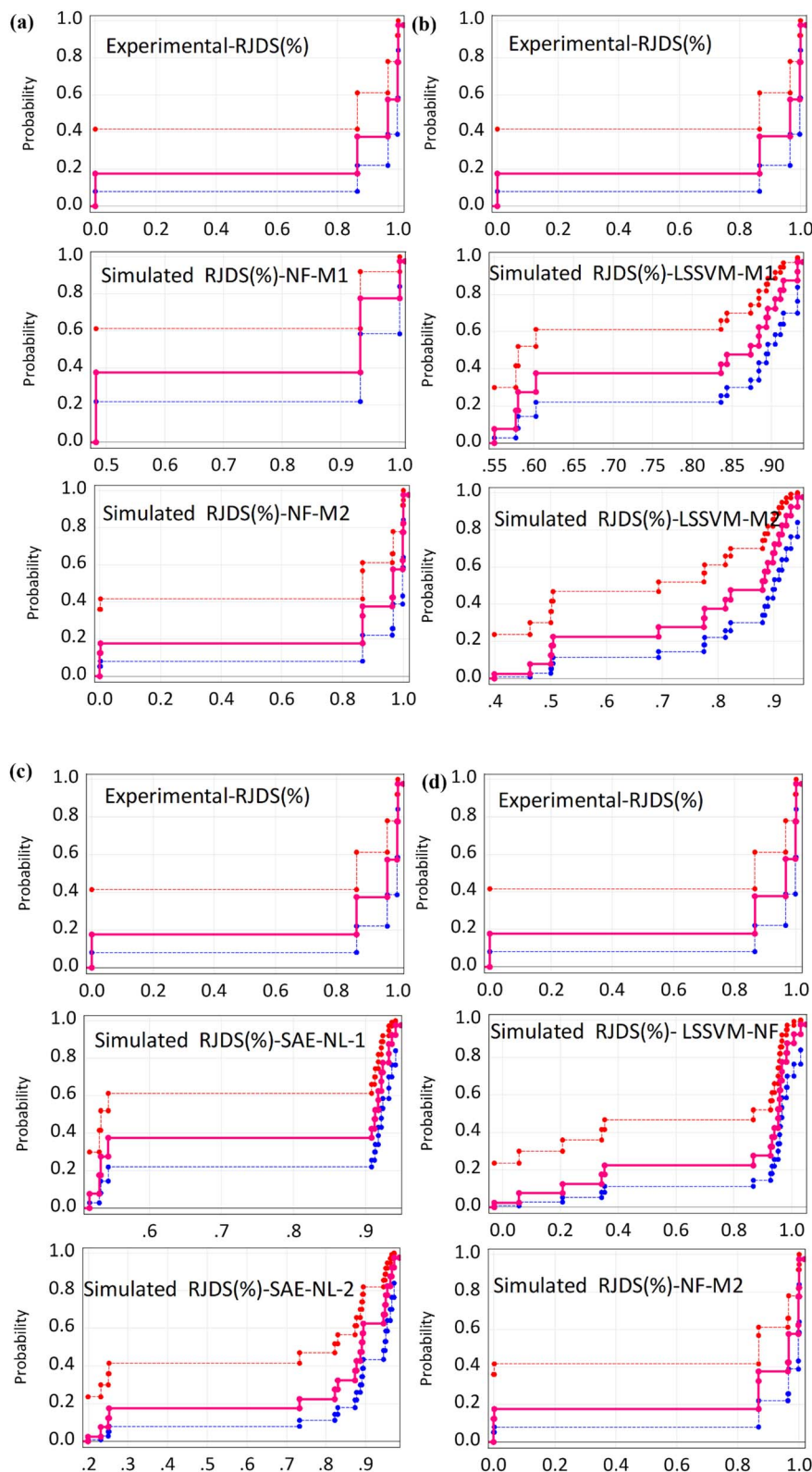


Fig. 11 Probability distribution function between the observed and simulated RDJ (%) (a) NF, (b) LSSVM, (c) SAE and (d) comparison of the best models.

essential as the  $C$  and  $g$  parameters were determined using a grid search algorithm with 1000 iterations. Table 1 presents the validation results for single and ensemble models.

According to the single predictive outcomes, NF-M2 emerged as the best model with satisfactory and reliable low error values for modelling RJDS. According to the validation phase's RMSE



values, the performance of a single model is in the following order: NF-M2 (0.0003) > NF-M1 (0.3082) > LSSVM-M2 (0.2574) > LSSVM-M1 (0.3223). However, for the ensemble model the error was hierarchically depicted as follows: SAE-NL-M2 (0.1288) > LSSVM-NF (0.1719) > SAE-NL-M1 (0.3121). It is worth mentioning that hybrid NF proved superior to all the models including improved ensembles. This is strange but not surprising owing to the powerful nature of NF models recorded in several science and engineering technical literature studies.<sup>34,61–65</sup> The error performance in terms of MAE and RMSE is presented in Fig. 8.

Recently, different studies in the literature have shown that ML techniques can be utilized to forecast models for a variety of membrane technology applications and processes.<sup>66</sup> MLs were used to investigate the correlation between operating conditions and membrane structural parameters with water/salt selectivity. They used the zeta potential and pore radius properties of the developed polyamide NF membrane and then two working parameters (feed concentration and pressure) to do the correlation studies regarding the water/salt selectivity. The results showed that membrane structure parameters have a greater importance in water/salt selectivity than operating conditions, and are associated with the variable influence for different salt types, with symmetric salts being mainly determined by size screening, while asymmetric salts are influenced by Donnan exclusion. The comparison of the single models is presented in Fig. 9.

Further investigation of the predictive models can be performed using goodness-fitting values of the models based on the radar chart plot as depicted in Fig. 10. The radar plots are used to appraise the relative multivariate observation with subjective numbers of the variables. Considering the multi-dimensional radar diagrams presented in Fig. 10, it can be noticed that the NF-M2, SAE-NL-M2 and LSSVM-NF models proved to be good and reliable approaches. In general, the achieved dependability performance of the models showed accuracy for the optimal evaluation. The research outcomes could impact the productivity of desalination and sustainable management from an environmental point of view, as addressed and recommended by ref. 67.

It is essential to understand that most of the combinations ( $P$ ,  $T$ , and  $R$ ) produced marginal accuracy in modelling the RJDS with the predictive accuracy ranging from 55–60% in terms of PCC. The simple strategy indicated that these accuracies were improved to 78% which is still not to the level of decision makers. This paper concluded that using the hybrid NF-M2 and SAE-NL-M2 approaches the required accuracy was attained. The quantitative comparison indicated that NF-M2 outperformed the other models by approximately 40% on average. The present work was numerically compared with that of ref. 22 which proposed an efficient and novel approach for finding a transmembrane pressure using Deep Reinforcement Learning (DRL) to predict different pressure adjustment levels, and the adjustment leads to a salt rejection (SR) of 99% for a desired water flux. This is to confirm that ML models can fit in to solve many problems across almost all fields. Going further,<sup>27</sup> experimental literature data on

machine learning were used to form prediction models of salt rejection rate and water permeability for thin film nanocomposite membranes. The variables such as size, loading, and pore size of the nanoparticles and other membrane properties were learned using the gradient boosting tree model. The results from the prediction show that porous nanoparticles, size, loading and wettability of the membranes are the key factors that influence the overall performance of the membrane. This was achieved with the help of the gradient boosting tree machine learning model.

Although all the performance criteria indicated that hybrid nonlinear and ensemble models are capable of predicting the target RJDS variables. The outcomes still suggest the use of other models with the integration of other process variables in order to understand the deep experimental process and reach the optimum decision making. Additional comparison of performance evaluation was based on PBAIS which is often not used in most of the technical problems. The PBAIS indicated how well the proposed model fits the calibration dataset. The validation table shows the bias of the models: NF-M1 (−0.0005), NF-M2 (0.0000), LSSVM-M1 (0.0000), and LSSVM-M2 (0.0001). Similarly, for the ensemble models the PBAIS is numerically indicated as: SAE-NL-M1 (−0.0003), SAE-NL-M2 (0.0000), and LSSVM-NF (−0.0003) which indicated that most of the models match the data training set. The overall trend of the data was captured by NF-M2 and SAE-NL-M2. Moreover, an additional comparison was conducted by ref. 68 that used ML in evaluating the performance optimization of the forward-osmosis membrane system for treatment of wastewater from the textile industry using the ML technique. They used the ML models in predicting the amount of reverse pure water flux and salt rejection of the membranes and they found that the models produce results with good precision. It is essential to visualize the overall outcomes using the empirical cumulative probability distribution function as presented in Fig. 11. These models have several advantages: they are easy to interpret, provide information about the distribution, allow for easy comparison of distributions, and can be used to model the probability distribution of a random variable. This can help to predict future outcomes and make decisions based on those predictions, as in the case of this study (RDJ).

Likewise,<sup>69</sup> machine learning models were used to quantitatively describe the non-linear ultrafiltration membrane fouling behaviors from process analysis, existing data process models and predictive models of unknown data prediction as well as feature analysis. The outcomes revealed a strong rejection impact on the ultrafiltration membrane when it is in contact with a polluted environment hence leading to an inconsistent self-pollution coefficient and swift fouling. The proposed prediction techniques showed outstanding dependability of the ML tools with a reasonable degree of accuracy, especially hybrid NF. As a result, it's possible to integrate these proposed predictive models with sensors, digital-twins technology or online monitoring systems for sustainable dye and salt experimental monitoring. It's worth mentioning a few limitations of the current study, such as the limited amount of data, testing only a few membranes, and



the need for validation through other dye/salt fractionation experiments to gain a comprehensive understanding at a regional level. Nevertheless, the same or other issues can be solved by utilizing more powerful predictive models., such as hybrid metaheuristic learning, objective optimization, and kernel functions. Going forward, it's important to use a vast amount of data to overcome data-related challenges of machine learning.

## 5. Conclusion

Generally, water serves as an integral part of sustainable development, including human needs and socio-economic growth. Regardless of its essential nature, Saudi Arabia as an arid region is facing serious concerns and challenges owing to the unsustainable practice of water resources. Recently, treated wastewater has been used to mitigate some percentage of water scarcity problems in the Kingdom due to the target Saudi Vision 2030 for clean and renewable water resources. It is believed that intelligent applications of wastewater, such as removing dye/salt using NF and other feasible membranes, would lead to achieving sustainable development goals, especially SDG 6. This study was aimed at providing insight into an AI-based tool for understanding the wastewater simulation of dye/salt (RJDS) rejection based on the experimental laboratory using a loose NF membrane. For this purpose, hybrid NF, LSSVM, and ensemble approaches were used to predict the rate of rejection of dye/salt. It is important to note that the correct research was based on real experimental work. The evaluation benchmarks such as MSE, MAE, MAPE, PCC, and PBAIS were statistically analyzed. The outcomes of the modelling schema indicated that corresponding linear sensitivity analysis was conducted and two model combinations were generated with absolute values of M1 ( $R = 52\%$ ,  $T = 50\%$ , and  $P = 61\%$ ) and M2 ( $R = 52\%$ ,  $T = 50\%$ ,  $P = 61\%$ ,  $F = 71\%$ , and  $RJ = 83\%$ ). The results of feature selection indicated that  $RJ$  and  $R$  were inversely correlated with the output while  $T$ ,  $R$ ,  $F$ , and  $P$  were directly correlated with the RJDS. The combination with M1 produces marginal to good performance while addition of  $F$  and  $RJ$  significantly improved the prediction outcomes. Similarly, the NF-M2 outperformed all the models with peak prediction accuracy and zero error followed by an ensemble approach which was affected by some weak models during the process. The LSSVM model generally is not reliable but its performance increased substantially during the nonlinear ensemble approach by almost 89% accuracy. The study proposed relies much more on experimental analysis to get more huge data instances, as the data-driven approach needs huge data to have reliable judgment. However, this served as one of the limitations of this study. With regards to future work, the study proposed the implementation of several types of membranes to capture the significant profile of produced water and the desalination process. New technology such as digital twins and the Internet of Things should be considered for integration with the experimental process of membrane dye/salt removal to keep records of the data and track the system automatically.

## Author contributions

Conceptualization, N. B and S. I. Abba; methodology and validation, N. B and S. I. Abba and J. U.; data curation, J. U. and M. B; writing—original draft preparation, N. B and S. I. Abba and J. U.; writing—review and editing, N. B and S. I. Abba and J. U.; supervision, I. H. A. and M. B.; funding acquisition and resources, N. B. All authors have read and agreed to the published version of the manuscript.

## Conflicts of interest

The authors declare no competing financial interests for all submitted manuscripts.

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