## Lab on a Chip



## CORRECTION

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## Correction: Microfluidic devices powered by integrated elasto-magnetic pumps

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Correction for 'Microfluidic devices powered by integrated elasto-magnetic pumps' by Jacob L. Binsley et al., Lab Chip, 2020, 20, 4285-4295, DOI: 10.1039/D0LC00935K.

The authors regret that the following items are incorrect in the original article.

Firstly, the units of viscosity are incorrectly labelled throughout the paper (listed as kg ms<sup>-1</sup> as opposed to kg m<sup>-1</sup> s<sup>-1</sup>). This

Additionally, in section 2.6, a constant ratio between Q and  $v_{\rm peak}$  was found to be ~775/2104, which is in fact a value taken from an intermediate step, which was also miscalculated. The correct ratio between Q and  $v_{\rm peak}$  should be stated as  $\sim 0.430 \times 10^{-2}$ 10<sup>-6</sup>. Due to the miscalculation included, the flow rates represented in the abstract and Fig. 6 and 7 are, in fact, ~30.0% greater than originally stated. Since this scaling affects all flow rates proportionally, it does not change the shape of the plotted curves, and therefore does not alter the discussions or conclusions drawn from them.

Please find the corrected figures below.

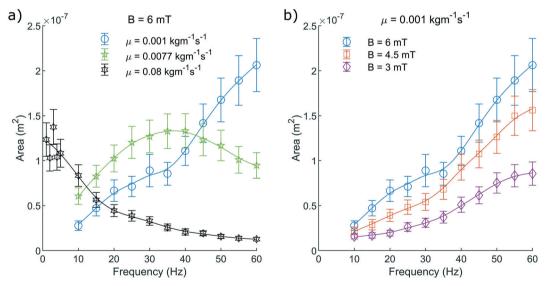


Fig. 5 The pump motion as a function of frequency. a) Depicts the dependence on fluid viscosity with a constant field amplitude of 6 mT and b) depicts how the motion depends on field amplitude with a constant dynamic viscosity of 0.001 kg m<sup>-1</sup> s<sup>-1</sup>. The blue curve is duplicated between both a) and b) for reference. The median area contained within the closed loop path traced by the non-reciprocal motion of the magnetic head of the pump, as suggested in Fig. 4, is shown. This is recorded as a function of driving frequency and repeated for a range of dynamic viscosities and driving field amplitudes. The plotted line is a simple smoothing spline between the data points to act as a visual guide.

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60

50

Correction

0

10

20

30

Frequency (Hz)

40

10<sup>-3</sup> a)  $\mu$  = 0.001 kgm<sup>-1</sup>s<sup>-1</sup>  $\times 10^{-3}$ B = 6 mT□ ▼ ▼  $\mu$  = 0.001 kgm<sup>-1</sup>s<sup>-1</sup> B = 6 mT3.5 3.5  $\mu$  = 0.0077 kgm<sup>-1</sup>s<sup>-1</sup>  $B = 4.5 \, mT$ 3 3 B = 3 mTVolume Displacement ( $\mu$ l/cycle) Volume Displacement ( $\mu$ l/cycle)  $\mu = 0.08 \text{ kgm}^{-1} \text{s}^{-1}$ 2.5 2.5 2 1.5 1.5 0.5 0 -0.5

Fig. 6 The net volume of fluid displaced per pump cycle. This consists of both the pump and recovery stroke. a) Depicts the displacement when varying the fluid viscosity at constant field amplitude of 6 mT. b) Depicts the displacement when varying the amplitude of the applied field at a constant fluid viscosity of 0.001 kg m $^{-1}$  s $^{-1}$ . This is measured as described in section 2.4. The plotted line is a simple smoothing spline between the data points to act as a visual guide.

60

50

-1.5

0

10

20

30

Frequency (Hz)

40

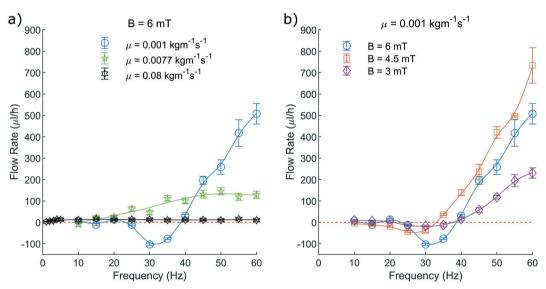


Fig. 7 The average volumetric flow rates produced by this pumping system. a) Shows the volumetric flow rate when varying the fluid viscosity at constant field amplitude of 6 mT. b) Shows the volumetric flow rate when varying the amplitude of the applied field at a constant fluid viscosity of 0.001 kg m $^{-1}$  s $^{-1}$ . The plotted line is a simple smoothing spline between the data points to act as a visual guide.

The Royal Society of Chemistry apologises for these errors and any consequent inconvenience to authors and readers.