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Three-dimensional strain engineering in epitaxial vertically aligned nanocomposite thin films with tunable magnetotransport properties†

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Three-dimensional (3D) frameworks have been successfully constructed by interlayering $\text{La}_{0.7}\text{Sr}_{0.3}\text{MnO}_3$ (LSMO)– CeO_2 based epitaxial vertically aligned nanocomposite (VAN) thin films with pure CeO_2 (or LSMO) layers. Such 3D interconnected CeO_2 scaffolds integrate the lateral film strain by the interlayers with the vertical strain in VAN layers, and thus achieve the maximized strain tuning in LSMO. More importantly, by varying the types of the interlayers (*i.e.*, CeO_2 or LSMO) and the number of interlayers from 1 to 3 layers, such 3D framework nanostructures effectively tune the electrical transport properties of LSMO, *e.g.*, from a 3D insulating CeO_2 framework with integrated magnetic tunnel junction structures, to a 3D conducting LSMO framework, where the magnetoresistance (MR) peak values have been tuned systematically to a record high of 66% at 56 K and enhanced MR properties at high temperatures above room temperature (~ 325 K). This new 3D framed design provides a novel approach in maximizing film strain, enhancing strain-driven functionalities, and manipulating the electrical transport properties effectively.

Conceptual insights

We present a novel concept that implements a three dimensional (3D) strain scheme in epitaxial thin films. This is achieved by combining 2-phase vertically aligned nanocomposite with thin interlayers to effectively couple vertical interface strain with the lateral interface strain. Different from conventional epitaxy thin films and the vertically aligned nanocomposite (VAN) thin films, the 3D strain scheme takes advantages of both architectures and promotes various strain-driven physical properties, *e.g.*, record high magnetoresistance values (MR%) as low field magnetoresistance properties have been demonstrated in the $\text{La}_{0.7}\text{Sr}_{0.3}\text{MnO}_3$ (LSMO)– CeO_2 interlayered with different numbers of CeO_2 interlayers. This work brings a new approach to achieve highly strained films beyond the critical thickness in epitaxy thin films and to demonstrate enhanced vertical strain coupling by the 3D strain scheme. This demonstration not only shows the power of 3D strain scheme in strain engineering, multifunctionality coupling, and flexibility in structural designs, but also fulfills the urgent demands of new material designs for future electronic devices.

Introduction

ABO_3 -Based perovskites have attracted substantial research interest and have been widely applied in various modern electronic devices, because of their versatile electrical and magnetic properties, such as superconductivity, colossal magnetoresistance (CMR), ferroelectricity, ferromagnet, and multiferroicity.^{1–8} The physical properties of perovskite oxides are mainly determined by their building blocks- BO_6 octahedral units. Constructed by the B-site transition metal cation coordinating with six oxygen ligands, BO_6 octahedral units interconnect with each other by sharing corners and forming a three-dimensional (3D) framework. Altering the

size, shape, and connectivity of those units can directly tune the B–O–B bonds, crystal structure, and other physical characteristics, such as magnetic anisotropy, transition temperature, electronic bandgaps, thermal conductivity, and magnetotransport properties.^{9–12} Strain engineering has been agreed on as one of the most effective approaches for such structural and property tuning.^{10–13}

Great effort has been devoted to exploring effective strain engineering. One of the most effective approaches is substrate strain control where various substrates with different lattice parameters are explored for in-plane strain control.^{14–16} The approach provides an effective lateral strain tuning in relatively thin films (within the critical thickness of a few nanometers) since the substrate strain is relieved with increasing film thickness.^{17,18} In parallel, implementing heteroepitaxial 2-phase nanocomposite thin films can incorporate additional interfacial strain into the matrix film through interface coupling between the two phases, such as zero-dimensional (0D) nanoparticles in matrix, two-dimensional (2D) multilayered films, and very recently, vertically aligned nanocomposite (VAN) thin films.^{18–29}

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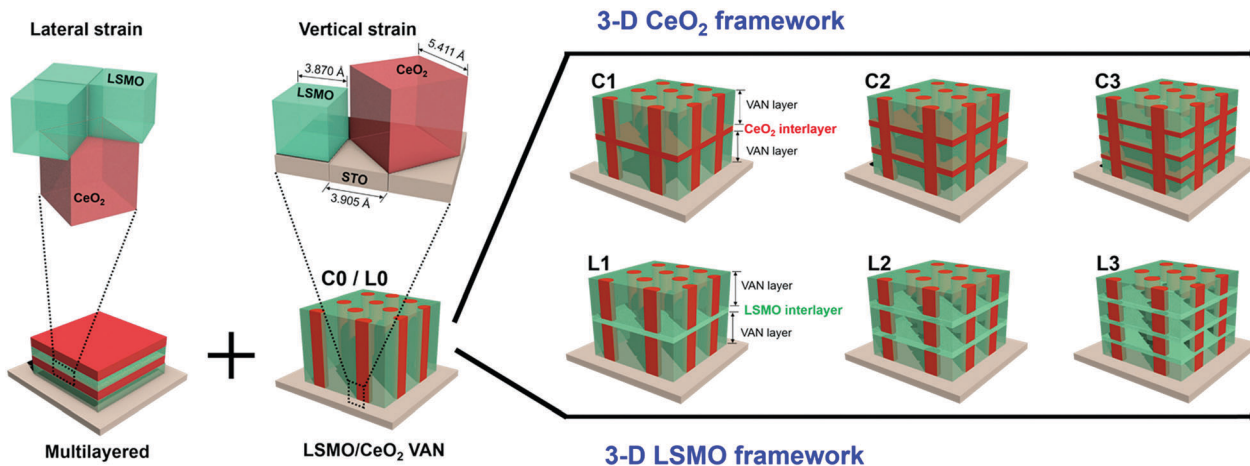


Fig. 1 Schematic illustration of 2-phase heterogeneous microstructure evolution of the thin films: from vertical aligned nanocomposite (VAN) C0/L0 to 3D CeO₂ framed thin films C1–C3 and 3D LSMO framed thin films L1–L3. The 3D framed microstructure is achieved by alternative growth of the single phase and the VANs in multilayered fashion. This design combines the lateral strain introduced from multilayered thin film and the vertical strain from interfacial coupling in VANs, creates 3D interconnected CeO₂ or LSMO framework microstructures within the thin films, and provides a versatile tool to achieve 3D strain tuning. The unit cells and phase of LSMO are in green, and the unit cells and phase of CeO₂ are in red.

In VANs, the lattice strain can be maintained in much thicker films because of the vertical interface coupling. In addition, the density of the secondary phase, column dimensions and morphologies are also considered as major factors in the strain tuning of VAN films. Using VANs, a broad range of multifunctionalities, such as multiferroicity, ferroelectricity, low field magnetoresistance (LFMR), and anisotropic electrical/ionic transport properties have been demonstrated.^{11,17,20,22,25,30}

3D nanostructured materials such as branched nanorods or nanoforests have attracted extensive research attentions because of their unique 3D nature. Taking full advantages of the vertical and horizontal dimensions, these 3D nanostructures exhibit many fascinating physical and chemical properties because of the highly enhanced interfacial area and stability, compared to the one-dimensional (1D) nanowire arrays.^{31–35} However, such 3D nanostructure designs in epitaxial thin film forms are scarce. To take advantages of the above strain control approaches and to explore the ultimate strain control in thin films, in this work, we propose a 3D strain architecture to combine the lateral strain introduced by the multilayered interfaces and the vertical strain from the vertical interface in VANs (as illustrated in Fig. 1). More specifically, this 3D strain control is achieved by the alternative growth of the single phase and the VANs in a multilayered fashion. La_{0.7}Sr_{0.3}MnO₃ (LSMO) is selected as the matrix for this 3D strain design as it has shown a strong CMR effect, magnetic anisotropy, spin-glass like behavior, and LFMR properties.^{11,22,36,37} Various secondary phases have been demonstrated for enhanced LFMR in LSMO VAN films.^{19,36–39} CeO₂ is selected as the insulating secondary phase embedded in the LSMO matrix, because of its good in-plane lattice match with LSMO and STO after a 45° in-plane rotation (Fig. 1), as well as its high thermal/mechanical stability.^{26,36,38} Furthermore, CeO₂ can serve as the insulating layer favoring spin-dependent tunneling, and is easier to explore the synergistic effects between strain tuning and the LFMR effect.

As illustrated in the left panel of Fig. 1, either CeO₂ or LSMO single layer is selected to construct the 3D CeO₂ framework or the 3D LSMO framework, respectively. More specifically, the single layer LSMO–CeO₂ (molar ratio of LSMO : CeO₂ = 1 : 1, also called L5C5) VAN thin films were prepared as control experiments and named as C0 or L0, without LSMO or CeO₂ as the interlayers. 3D CeO₂ interlayered thin films with 1, 2, and 3 interlayers inserted in VAN structures are named as samples C1, C2, and C3, respectively. Similarly, 3D LSMO interlayered thin films with 1, 2, and 3 interlayers inserted in VAN are named as sample L1, L2, and L3, respectively. To explore the power of 3D strain effects offered by the 3D framework built in the LSMO–CeO₂ VAN systems, the molar ratio of LSMO and CeO₂ is maintained at 1 : 1 in the VAN layers. Such ratio was selected based on the previous reports where effective tunneling effects from the secondary phase have been found.^{27,36,37,40} This set of interlayered samples are expected to combine the vertical strain control by the VAN structures and the lateral strain control by the interlayers to achieve 3D strain modulation. LFMR properties are measured and correlated with the strain in these 3D strained frameworks.

Results and discussion

Transmission electron microscopy (TEM) and scanning transmission electron microscopy (STEM) images (Fig. 2) confirm the microstructures of samples C0–C3 and L0–L3. The thickness of all the as-deposited films are around 100–120 nm. A columnar nanocomposite structure with the alternative columns of LSMO and CeO₂ can be clearly seen in the VAN thin film C0 from the cross-sectional TEM and the corresponding STEM images (Fig. 2a and b), respectively. It is obvious that the CeO₂ nanopillars with a large aspect ratio are vertically grown in the LSMO matrix as seen from the high resolution TEM (HRTEM) image in Fig. 2c.



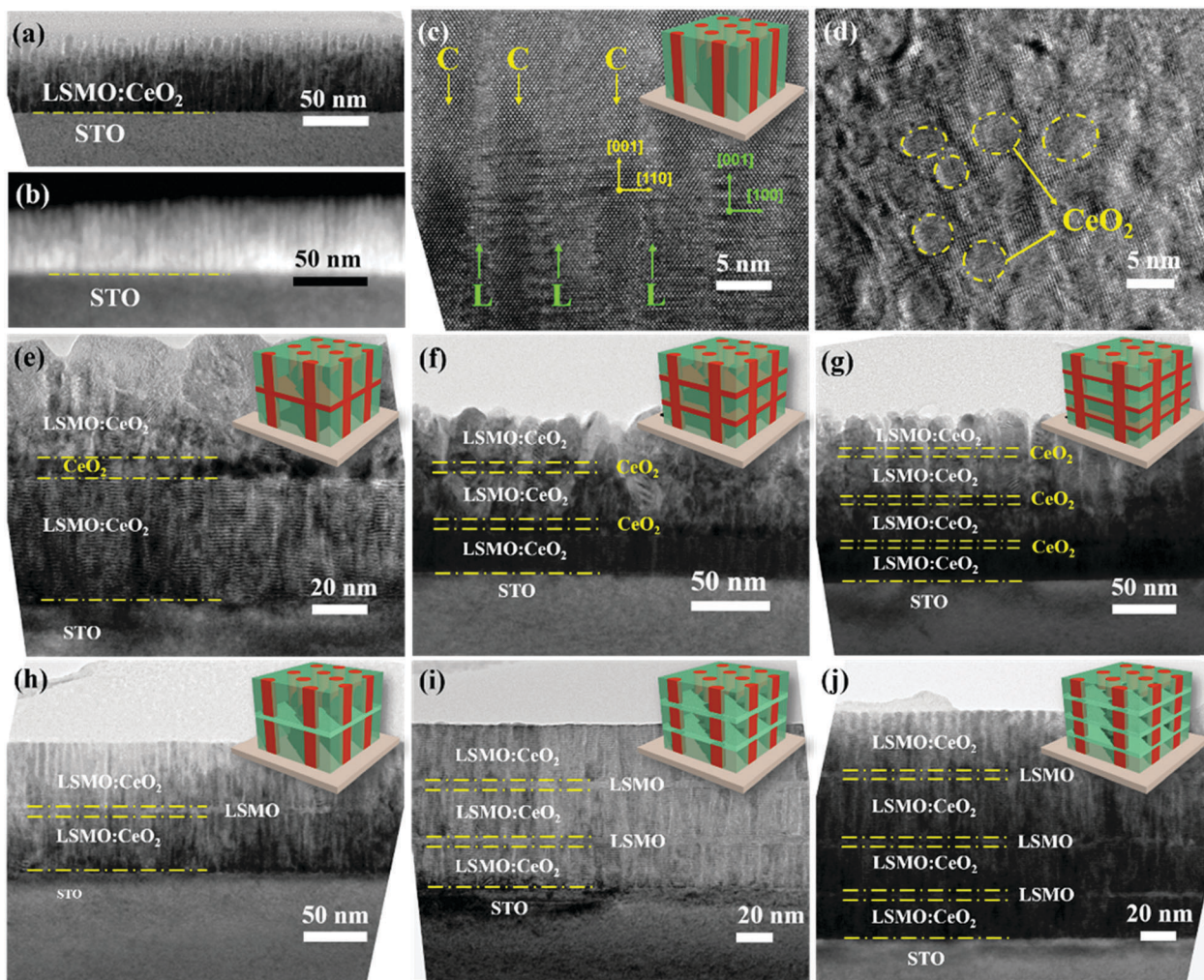


Fig. 2 (a) Cross-sectional TEM image of the VAN thin film C0 and (b) its corresponding STEM image at low magnification. (c) Cross-sectional and (d) plan-view HRTEM images of sample C0. In the HRTEM image of (c), "C" in yellow points out the CeO₂ nanopillars and "L" in green points out the LSMO matrix. Clearly, those CeO₂ nanopillars with a large aspect ratio are vertically aligned and well distributed in the LSMO matrix and the sharp phase boundaries suggest the well separated growth of the two phases. Cross-sectional TEM images of the thin films (e–g) C1–C3 and (h–j) L1–L3, showing the microstructures of 3D interconnected CeO₂ and LSMO frames embedded within the thin films respectively.

The uniform distribution of the CeO₂ nanopillars in-plane is confirmed by the plan-view TEM image of C0 (Fig. 2d and Fig. S1f, ESI†). These images present clear and sharp interfaces between the LSMO/CeO₂ phases with limited inter-diffusion. In addition, the diameter of the circular-shaped CeO₂ nanopillar domains is estimated to be 2–5 nm. Fig. 2e–g and h–j present the 3D framed structured samples C1–C3 and L1–L3, respectively. Overall the structures are all grown as the designed 3D framed structures, as shown in the inset. For example, in the 3D CeO₂ framed thin films C1–C3, each CeO₂ interlayer is around 5 nm thick, sandwiched between LSMO–CeO₂ VAN layers, and joined by vertical CeO₂ nanopillars in the VAN layers to form a 3D CeO₂ frame embedded in the thin films. Similarly, in the 3D LSMO framed thin films L1–L3, each LSMO interlayer is around 5 nm thick and sandwiched between the LSMO–CeO₂ VAN layers. It is noted that as the number of CeO₂ interlayers increases, the surface roughness increases gradually from C1 to C3. This might be related to the surface roughness

introduced by CeO₂ interlayers. In contrast, the incorporation of LSMO interlayers maintains relatively smooth film surfaces in L1–L3 without obvious porosity on the top surfaces (Fig. 2h–j). Instead, a well-defined 3D interconnected LSMO frame is clearly observed within the dense films. Overall these VAN thin films are grown with a high epitaxial quality despite the introduced interlayers. The film quality is comparable with previously reported LSMO-based nanocomposites.^{36,38}

XRD was employed to study the evolution of the out-of-plane strain in both CeO₂ and LSMO phases as a function of the interlayer structure. The full XRD 2θ - ω patterns of samples C0–C3 are present in Fig. 3. The (00 l) diffraction peaks for both are present which confirms that CeO₂ and LSMO have grown highly textured along the (00 l) direction on STO(001) substrates, despite the minor LSMO(111) texture in the films. To reveal the strain state of LSMO and CeO₂, the local scans of CeO₂(004) and LSMO(003) are plotted in Fig. 3b and c for all the C0–C3 samples. It is clear that, as the number of CeO₂ interlayer increases, the



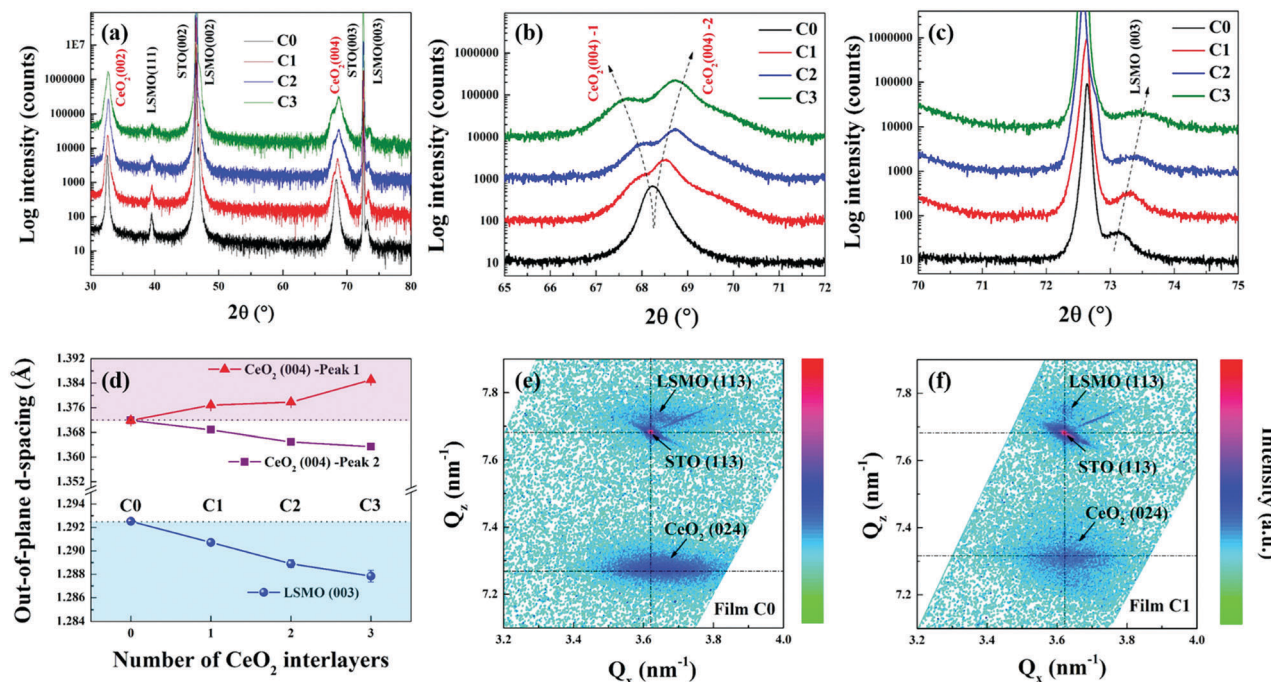


Fig. 3 (a) XRD 2θ - ω patterns of the VAN thin film C0 and the 3D CeO_2 framed thin films C1–C3. (b) Local $\text{CeO}_2(004)$ 2θ - ω scans of the VAN thin film C0 and the 3D CeO_2 framed thin films C1–C3. (c) Local LSMO(003) 2θ - ω scans of the VAN thin film C0 and the 3D CeO_2 framed thin films C1–C3. (d) Systematic tuning of the out-of-plane d -spacing of $\text{CeO}_2(004)$ and LSMO(003) by the 3D structure engineering in C0–C3 (the d -spacing values and error bars are listed in Table S3, ESI[†]). The red and purple lines belong to $\text{CeO}_2(004)$ Peak 1 and 2, respectively, while the blue line belongs to the LSMO(003) peak. The pink regime represents the tensile out-of-plane strain area of the CeO_2 phase and the blue regime represents the compressive out-of-plane strain area of the LSMO phase, compared to sample C0. Reciprocal space maps (RSMs) of (e) the VAN thin film C0 and (f) the 3D framed thin film C1 near STO(113). The spots of LSMO and CeO_2 in the RSM reveal the high quality epitaxy growth of the two phases on STO substrates.

$\text{CeO}_2(004)$ peak starts to split into two peaks, *i.e.*, Peak 1 and 2, which are getting further apart (Fig. 3b). This suggests the coexistence of two different strain states in the CeO_2 phase for the cases of C1–C3. To differentiate the contributions of the two CeO_2 peaks, the XRD data was carefully examined. As the number of the lateral CeO_2 interlayer increases, the intensity and sharpness of Peak 2 (on the right) increases, and Peak 1 (on the left) maintains its similar intensity. It suggests that Peak 2 is attributed to the CeO_2 lateral layers and Peak 1 is from the CeO_2 vertical nanopillars. The origins of the two $\text{CeO}_2(004)$ peaks are further confirmed by a strain mapping using geometric phase analysis (GPA) in Fig. 4, to be discussed later. Simultaneously, the LSMO(003) peak shifts to higher angles as the interlayer number increases (Fig. 3c). According to the XRD patterns and the Bragg's law, the $d_{(00l)}$ -spacing values of both CeO_2 and LSMO phases are calculated and plotted in Fig. 3d (also listed in Table S3, ESI[†]). In the VAN thin film C0, $d_{\text{CeO}_2(004)}$ is ~ 1.372 Å and $d_{\text{LSMO}(003)}$ is ~ 1.293 Å, which are marked with dashed lines, respectively. In Fig. 3d, the upper branch (CeO_2 Peak 1) of $d_{\text{CeO}_2(004)}$ representing the vertical CeO_2 columns gradually increases from 1.377 Å (C1) to 1.385 Å (C3) as the number of CeO_2 interlayers increases. The lower branch (CeO_2 Peak 2) marked in purple represents $d_{\text{CeO}_2(004)}$ of the lateral CeO_2 interlayers and gradually reduces from 1.369 Å (C1) to 1.363 Å (C3). The out-of-plane strain is calculated and listed in the (Table S4, ESI[†]). Compared to the single layer LSMO– CeO_2

VAN sample C0, the vertical CeO_2 nanopillars are in the tensile out-of-plane strain of 0.361%. The lateral CeO_2 layer is under the compressive out-of-plane strain of -0.224% in C1. With increasing lateral CeO_2 interlayers in C3, the out-of-plane strain in the 3D CeO_2 framework increases almost three times compared to that of C1. The vertical CeO_2 nanopillars of C3 are under 0.962% tensile strain out-of-plane and the lateral CeO_2 interlayers are under -0.618% compressive out-of-plane. In comparison, from C1 to C3, $d_{\text{LSMO}(003)}$ is reduced from 1.291 Å (C1) to 1.288 Å (C3), corresponding to a gradually enhanced compressive strain out-of-plane from -0.139% (C1) to -0.362% (C3). Overall, compared to the reference C0, the out-of-plane strain coupling between the CeO_2 vertical nanopillars and LSMO matrix in C1–C3 is obviously strengthened as the number of CeO_2 interlayer increases, indicating the effectiveness of the 3D strain framework. Fig. 3e and f compare the reciprocal space maps (RSMs) near the substrate STO(113) peak for C0 and C1, respectively. Again, the strain state evolution is further confirmed by the RSM data, *i.e.*, from C0 to C1, the LSMO(113) peak spot is shifted upwards similar to that in Fig. 3c and $\text{CeO}_2(024)$ is broadened along Q_z direction reflecting the peak splitting in Fig. 3b. In comparison, the 3D LSMO frameworks (L1–L3) reduce the out-of-plane strain coupling between the CeO_2 vertical nanopillars and LSMO matrix with the increasing number of lateral LSMO interlayers (Fig. S5 and Table S5, ESI[†]). For these cases, the strain tunability of the epitaxial thin films is mainly determined by the 3D interconnected LSMO frames.



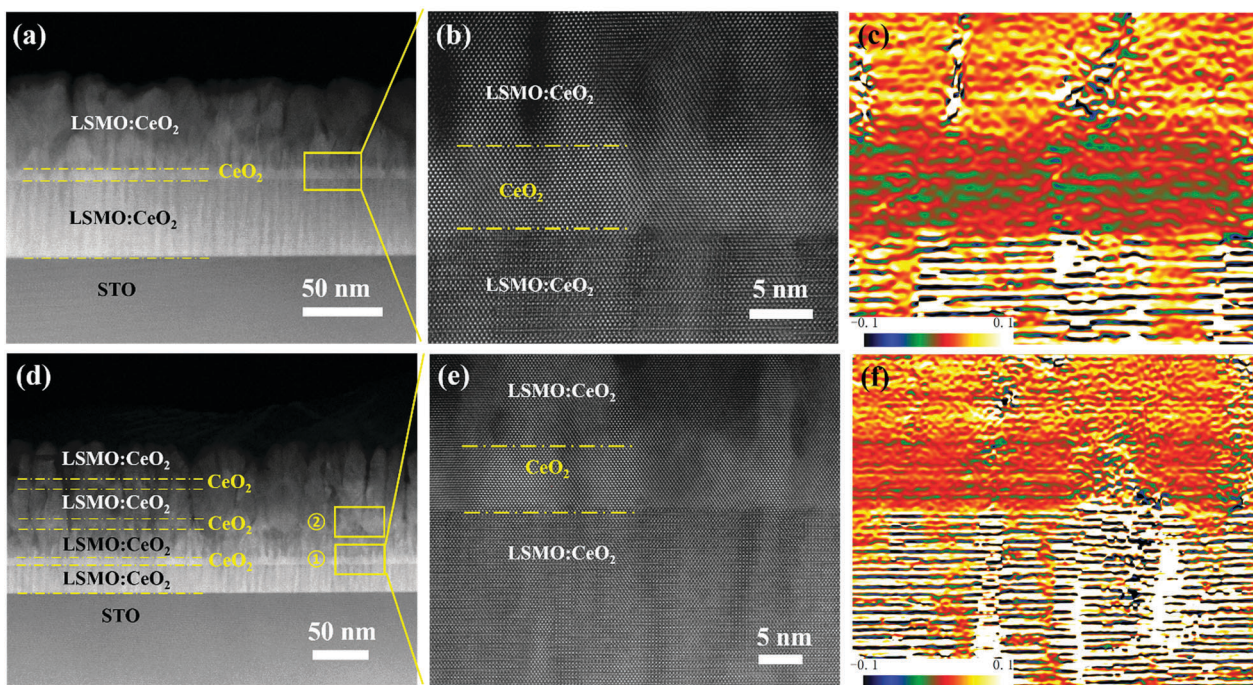


Fig. 4 (a) Cross-sectional STEM image of the 3D CeO₂ framed thin film C1, (b) its HRSTEM image at the lateral CeO₂ interlayer area (marked by a yellow rectangular in (a)), and (c) the corresponding GPA ϵ_{yy} (out-of-plane strain) map of the image shown in (b). (d) Cross-sectional STEM image of the 3D CeO₂ framed thin film C3, (e) its HRSTEM image at the first lateral CeO₂ interlayer area from bottom (marked by the yellow rectangular as 1), and (f) the corresponding GPA ϵ_{yy} (out-of-plane strain) map of the image shown in (e). Here the lateral CeO₂ interlayer area is selected as the reference in each GPA ϵ_{yy} map of (c) and (f), and thus exhibits a red–green color. The CeO₂ vertical nanopillars within VAN layers are shown in a bright yellow color, illustrating larger out-of-plane d -spacing in those vertical CeO₂ nanopillars compared to its reference of the lateral CeO₂ interlayer area.

Fig. 4a and b exhibit the STEM images of sample C1 under a high-angle-annular-dark-field (HAADF) mode in low magnification and high resolution, respectively. Consistent with the previous TEM results, the STEM images confirm the 3D interconnected CeO₂ frames embedded in the films. High resolution STEM images (Fig. 4b) show a very clear interface between CeO₂ and LSMO with a high epitaxial quality. A similar structure is observed at the first lateral CeO₂ interlayer of sample C3 (Fig. 4d and e). However, as the number of interlayer increases, a large surface roughness is seen. To clearly resolve the 3D strain state in the samples, geometric phase analysis (GPA) was conducted using the high resolution STEM images (Fig. 4b and e), and presented as the vertical strain (ϵ_{yy}) maps in Fig. 4c and f, respectively. Here the lateral CeO₂ interlayer area is selected as the reference in each GPA ϵ_{yy} mapping and is shown by a red–green color. The bright yellow color contrast of CeO₂ in the VAN part suggests that the vertical CeO₂ nanopillars have a larger out-of-plane d -spacing, *i.e.* a tensile strain out-of-plane compared to the lateral CeO₂ layer, which is consistent with our observation of the two split peaks in the XRD data (Fig. 3). A sharp change of ϵ_{yy} can be clearly seen across the lateral CeO₂ and VAN layers, indicating that the c -lattice parameter of CeO₂ varies abruptly in those layers. It is consistent with its filtered image (Fig. S3, ESI[†]), in which the lateral CeO₂ interlayer shows a smaller out-of-plane d -spacing and the CeO₂ in the VAN part presents a larger tensile strain out-of-plane. These observations confirm the distribution of the distinct d_{00r} -spacing within the homogeneous 3D interconnected CeO₂ frameworks, *i.e.*, the

d_{00r} -spacing of CeO₂ is much higher along the vertical nanopillars than that in the lateral CeO₂ layers. Such enhanced out-of-plane strain between CeO₂ and LSMO is caused by the effective 3D CeO₂ frames and the interfacial coupling between the CeO₂ nanopillars and the LSMO matrix. Such vertical strain could potentially lead to the variation of the length and angle of Mn³⁺–O–Mn⁴⁺ bonds and thus affect the overall magnetotransport properties, which has been previously reported.^{12,41,42} Overall the finding confirms our initial 3D strain design where a highly strained LSMO can be achieved using a 3D CeO₂ framework.

To resolve the transport properties in these 3D framed structures, the temperature dependent resistance (R - T) curves at zero-field are shown in Fig. 5a for samples C0–C3. Overall, reducing resistance with increasing temperature represents a typical semiconductor behavior in C0–C3, because of the large portion of CeO₂ introduced in the nanocomposites (CeO₂:LSMO \geq 1:1 in C0–C3). Fig. 5b plots the temperature dependence of the magnetoresistance (MR%) in the 3D framed nanocomposite films C0–C3, with clearly defined MR peaks located near 50 K. The MR% of films C0–C3 increases at first and then reduces as the temperature increases from low temperature to room temperature. The MR% peak value of the VAN thin film C0 is \sim 40%, which is higher than many other reported LSMO composite films.^{27,36,38,43–45} 3D CeO₂ frameworks further enhance the overall MR properties, where the MR peak value increases from 40% (C0) to 51% (C3), 57% (C2) and maximizes at 66% (C1). The enhancement can be explained by the 3D CeO₂



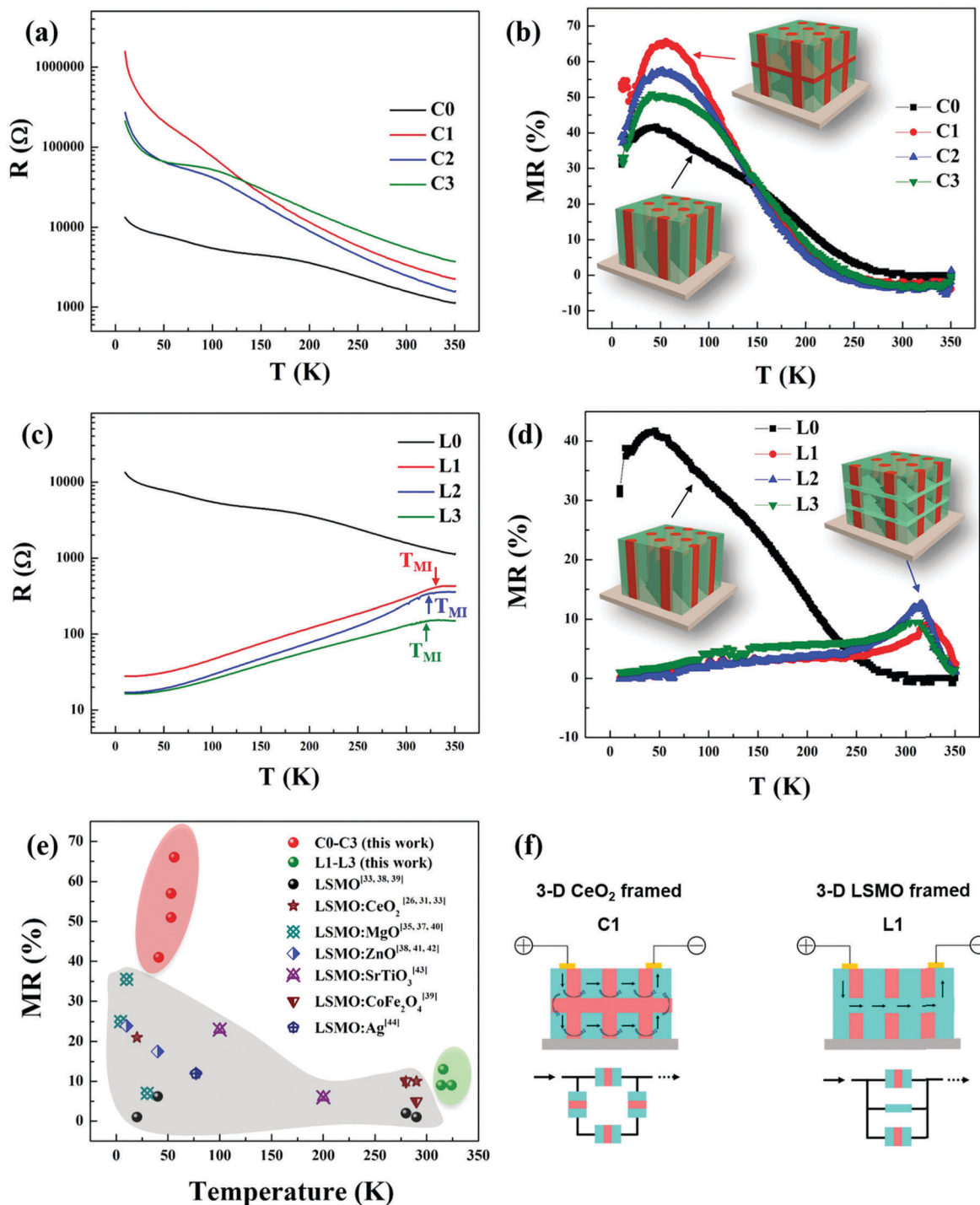


Fig. 5 (a) R - T plots of 3D CeO_2 framed nanocomposite thin films C0–C3. (b) The temperature dependence of MR for the nanocomposite thin films C0–C3. (c) R - T plots of 3D LSMO framed nanocomposite thin films L0–L3. The arrows point out the metal-to-insulator transition temperature T_{MI} of L1–L3. (d) The temperature dependence of MR for the nanocomposite thin films L0–L3 with the metal-to-insulator transition temperature T_{MI} marked for samples L1–L3. (e) Summary of the maximum LFMR values of LSMO-based composite thin films recently reported and their corresponding peak temperature.^{26,31,33,35,37–44} All the LFMR values listed here are measured under the same magnetic field of 1 T applied out-of-plane (perpendicular to the film plane). (f) Schematic illustrations of the circuit models for the 3D CeO_2 framed nanocomposite structure C1 and the 3D LSMO framed nanocomposite film structure L1.

framework as indicated in Fig. 5f. Such 3D CeO_2 framework not only tailors the out-of-plane strain of the LSMO phase, but also builds up the 3D tunneling framework for the electron transport. The synergistic effect between the strain tuning and

the tunneling effect in C1–C3 (red dots) highly promotes the MR properties and enables a record high MR% in LSMO nanocomposites (Fig. 5e).^{26,36,38,43,45–52} The relatively lower MR% in C2 and C3 compared to C1 is possibly related to the



surface roughness observed in both samples where the 3D insulating framework might not be effective in the top layers.

The L1–L3 samples with a 3D LSMO framework exhibit a metallic behavior in contrast to the C1–C3 samples (Fig. 5c), as their resistances gradually increase from 10 K to 350 K with a metal-to-insulator transition temperature T_{MI} at ~ 325 K. The metallic behavior is associated with the high composition of LSMO in L1–L3 and the 3D interconnected conductive LSMO frames built in the composite films L1–L3. Meanwhile, the resistance of the composite films L1–L3 decreases with inserting more lateral LSMO interlayers over the entire temperature regime. The LSMO interlayers interconnect with the vertical LSMO domains forming a conductive 3D frame in the film. Thus, the tunneling magnetoresistance effect is effectively reduced. But interestingly, such L1–L3 structures enable higher MR values at higher temperatures, *e.g.* 13% at 316 K in sample L2, which is a dramatic MR value improvement compared to C0–C3 and the previous reports at higher temperatures (*e.g.*, near room temperature).

Based on the above observations, it is clear that magnetic tunneling junctions (MTJ) of LSMO/CeO₂/LSMO and their geometrical arrangement in these composite films are very important for enhancing the LFMR properties. In C1–C3 samples, there are effective vertical and lateral MTJ structures integrated in the system by incorporating CeO₂ interlayers in the VAN system as indicated in Fig. 5f. Such 3D insulating frameworks effectively maximize the 3D magnetic tunneling effect and lead to a record high MR% in the LSMO based systems.

Most of the previous nanocompositing efforts focus on single layer VAN structures. For example, changing the dimension and density of MgO, Chen *et al.* altered the strain and magnetic properties of LSMO–MgO VAN systems and tripled the MR value to 40% at 20 K.¹¹ Similarly, the LFMR value of the LSMO–CeO₂ VAN structure was enhanced from 5% to 21% at 20 K by reducing the secondary phase domain size from ~ 7 nm to ~ 3 nm.³⁸ Fan *et al.* systematically shifted the transition temperature and promoted the LFMR up to $\sim 35\%$ at 20 K by tuning the shape and relative ratio of CeO₂ domains in the LSMO–CeO₂ VAN system.³⁶ This work with a 3D strain framework using both the lateral and vertical interlayers structures effectively maximizes the 3D strain state in the systems, manipulates the electron transport paths in these systems, and thus enables even larger tunabilities of the strain-enabled physical properties and the overall electrical transport phenomena. In addition, the 3D framed structure can be realized in other compositions of the VAN systems. As a demonstration, a multilayer stack of L7C3/CeO₂/L7C3 is constructed to demonstrate the feasibility of the 3D frame designs in other compositions. As shown in Fig. S7 (ESI[†]), the lateral CeO₂ interlayer interconnects with vertical aligned CeO₂ nanopillars in the VAN L7C3 layers and forms the 3D CeO₂ framed structure, very similar to the case of L5C5. Furthermore, XRD (Fig. S7e and f, ESI[†]) and the corresponding SAED patterns (Fig. S7c and d, ESI[†]) all demonstrate excellent epitaxial quality of the 3D stack and obvious strain tuning introduced by the CeO₂ interlayer. This further confirms the power and feasibility of 3D strain effects generated by this 3D framed microstructure in the epitaxial thin films.

Conclusions

The 3D framework thin films of LSMO–CeO₂ epitaxial VANs interlayered with either CeO₂ or LSMO are designed and processed to effectively control the strain state of the films as well as the electron transport phenomena. This 3D strained framework structures combine both the lateral strain by the layered structures and the vertical strain in the VAN and thus maximize the overall strain in the films. Under the synergistic effects of the 3D maximized strain tuning and the integrated vertical and lateral magnetic tunnel junction structures, the 3D CeO₂ interlayered samples show a record high MR% of 51–66%, while the 3D LSMO interlayered thin films boost the MR% peak in the relatively higher temperature regime (near room temperature). This 3D strain framework concept opens up a new avenue to maximize the film strain beyond the initial critical thickness and can be applied to many other material systems with strain-enabled functionalities beyond magneto-transport properties.

Experimental

Target preparation

The targets of pure LSMO, pure CeO₂, and composite LSMO–CeO₂ (molar ratio 1 : 1 of LSMO and CeO₂) were prepared *via* a conventional ceramic sintering process. A stoichiometric mixture of La₂O₃, MnO₂, and SrCO₃ powders were ground, pressed into a disk, and annealed at 1300 °C in air for 12 h to form a pure LSMO target. The same procedure was also employed to synthesize the CeO₂ target at 1200 °C for 6 h and the LSMO–CeO₂ target at 1300 °C for 12 h, respectively.

Thin film growth

The 3D LSMO–CeO₂ framed nanocomposite films were grown on SrTiO₃ (STO)(001) substrates *via* a pulsed laser deposition (PLD) approach with a KrF excimer laser ($\lambda = 248$ nm). Before deposition, the chamber was vacuumed to a base pressure of 1.0×10^{-6} Torr (1 Torr = 133.3 Pa) or better. During deposition, the substrates were maintained at 750 °C and the oxygen pressure was controlled at 200 mTorr with a laser frequency of 1 Hz. After deposition, the substrates were cooled down at a cooling rate of 10 °C min⁻¹ under an oxygen pressure of 200 Torr.

To synthesize the 3D framed nanocomposite films with distinct nanostructures, different numbers of deposition pulses were used and summarized in Tables S1 and S2 (ESI[†]), including the VAN thin films C0/L0, the 3D CeO₂ framed thin films C1–C3, and the 3D LSMO framed thin films L1–L3, respectively. Sample C0 has no lateral CeO₂ interlayer which is the typical LSMO–CeO₂ VAN structure. From sample C1 to C3, the CeO₂ interlayer number gradually increases from 1 to 3.

Characterization

The phase and orientation of the thin films were characterized by X-ray diffraction (XRD) (2θ – ω and ϕ scans with Cu K α radiation, PANalytical Empyrean system). The reciprocal space mapping was also conducted to analyze the strain and *d*-spacing variations of



the thin films. Transmission electron microscopy (TEM) images, and selected-area electron diffraction (SAED) patterns were collected on FEI TALOS F200X operated at 200 kV. The cross-sectional and plan-view samples for TEM analysis were prepared by a standard procedure, including manual grinding polishing, and a final precision ion polishing step (PIPS 691, Gatan, Inc.). The high-resolution scanning TEM (STEM) images were collected on an aberration-corrected FEI Titan microscope equipped with a high brightness Schottky-field emission electron source operated at 300 kV. A commercial program, a Digital Micrograph plug-in (DM 1.8.3 package, HRTEM Research Inc.), was used for geometric phase analysis (GPA). The GPA method provides the strain mapping of the entire area based on the atomic spacing variation calculated based on the original STEM images. The out-of-plane strain ϵ_{yy} is derived to illustrate the local lattice displacement from the reference lattice. The strain in GPA is the relative value and in this work the lateral CeO₂ interlayer area is chosen as the reference, which shows with red-green coloration. Due to $\epsilon_{yy} = (c^{\text{local}} - c^{\text{ref}})/c^{\text{ref}}$, the sign of ϵ_{yy} represents a tensile (“+”) or compressive (“-”) strain in the local lattice compared to the reference. GPA yields a strain map with color contours to illustrate the location of the relative strains. Since the lateral CeO₂ interlayer area is selected as the reference area, the GPA ϵ_{yy} maps in this work (Fig. 4c, f, and Fig. S4b, ESI†) are used to analyze the out-of-plane strain distribution of CeO₂ phase specifically. Magnetron sputtering and shadow masks were used to deposit Au contacts for the transport measurements. The magnetotransport properties of the thin films were systematically studied by the Physical Properties Measurement System (PPMS Model 6000, Quantum Design) in a four point probe configuration (in Van der Pauw geometry) with a 1 T magnetic field applied out-of-plane (perpendicular to the film plane) and the current applied in-plane. Each sample was first cooled from 350 K down to 10 K without the applied magnetic field, and then heated up to 350 K under a magnetic field of 1 T. Electrical resistance was recorded in the temperature range of 10–350 K with and without the applied magnetic field of 1 T. The corresponding magnetoresistance (MR) was calculated by the following equation:

$$\text{MR (\%)} = [(R_0 - R_H)/R_0] \times 100\% \quad (1)$$

where R_H and R_0 is the electrical resistance with and without the applied magnetic field of 1 T at the same temperature.

Author contributions

HW conceived and supervised the project. HW, JMD and XZ discussed the experimental design and project planning. XS deposited the 3D-framed LSMO–CeO₂ thin films, performed XRD analysis and strain calculation. JH assisted in film deposition and conducted PPMS measurements. JJ and PL conducted the TEM/STEM and HRTEM/HRSTEM analysis. XS, MF, Han W. carried out the reciprocal space mapping and analyses. XS and QL prepared the TEM samples and the schematics under

the supervision of XZ. HW, XS, XZ, and JMD drafted and revised the manuscript.

Conflicts of interest

There are no conflicts of interest to declare.

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