Independent responsive behaviour and communication in hydrogel objects†

Ross W. Jaggers and Stefan A. F. Bon†*

In this work, we show the fabrication of soft hydrogel alginate-based objects, namely fibres and beads, that have an individually programmed time delay in their response to a shared environmental stimulus. We utilize the enzyme urease to programme a self-regulated change in pH, which in turn activates the designed response of gel fibre disintegration or a change in gel bead colour. This design allows for independent response behaviour of a collection of bodies in a single closed system, as well as inter-material communication on shorter length scales. The incorporation of responsive time control directly into soft matter objects demonstrates an advance in the field of autonomous materials.

Living organisms can exhibit autonomy in their response to an external stimulus, a concept that drives both biological function and independent behaviour.1–3 Some form of intelligence is required to act in this way, and it is this principle that underpins the design of artificial life.4,5 For example, neural networks model the human brain and robotic devices can perform complex tasks.6,7

A key question in material design is “can this complex concept be stripped down to its essence without loss of autonomy?”.

A multitude of materials translate environmental stimuli into direct material responses. Examples include the catalytically driven actuation of colloidal particles,8–10 light-triggered inversion of emulsions11 and triggered change in capsule permeability.12–15 Though simple stimuli-response pathways can generate sophisticated behaviour, control is often dominated by the environmental cues, not the material itself.16

Alternatively, materials that moderate their own behaviour over time and selectively respond to their environments display autonomy and more closely resemble those found in nature.17,18 For example, the oscillatory Belousov–Zhabotinsky reaction has been used as an internal driver and communication tool,19,20 kinetic control has been used to trap supramolecular self-assemblies in metastable states,21–23 and homeostatic control has been demonstrated.24–26 Furthermore, enzymes have been used to programme the time-domain, as in the case of pH-responsive self-assemblies that utilize an internal feedback system.27–29

Here we show the fabrication of soft hydrogel objects, namely fibres and beads, that have an individually programmed time delay in their response to a shared environmental stimulus. We utilize the enzyme urease to programme a self-regulated change in pH, which in turn activates the designed response of gel disintegration. This design allows for independent response behaviour of a collection of bodies in a single closed system, as well as inter-material communication on shorter length scales. The incorporation of responsive time control directly into soft matter objects demonstrates an advance in the field of autonomous materials.

Conceptual insights

Autonomous response mechanisms are vital to the survival of living organisms and play a key role in both biological function and independent behaviour. The design of artificial life, such as neural networks that model the human brain and robotic devices that can perform complex tasks, relies on programmed intelligence so that responses to stimuli are possible. Responsive synthetic materials can translate environmental stimuli into a direct material response, for example thermoresponsive shape change in polymer gels or light-triggered drug release from capsules. Materials that have the ability to moderate their own behaviour over time and selectively respond to their environment, however, display autonomy and more closely resemble those found in nature. In this communication, we present soft hydrogel objects that possess an individually programmed time delay in their response to a shared environmental stimulus. We utilize the enzyme urease to programme a self-regulated change in pH, which in turn activates the designed response of gel disintegration. This design allows for independent response behaviour of a collection of bodies in a single closed system, as well as inter-material communication on shorter length scales. The incorporation of responsive time control directly into soft matter objects demonstrates an advance in the field of autonomous materials.
Aqueous solutions of sodium alginate (1 wt% for fibres, 5 wt% for beads, at pH 7) were used as the base material to construct hydrogels. Calcium chloride hexahydrate was used as a source for calcium ions to establish ionic cross-linking. Once formed using fluidic devices, these Ca\(^{2+}\) cross-linked hydrogels are stable when dispersed in water over a wide pH range.\(^{30}\)

![Fig. 1](image_url)  
**Fig. 1** Synthesis and action of composite fibres. Left (i): Formation of calcium ion cross-linked sodium alginate fibres using a microfluidic synthesis. A fluid stream of sodium alginate solution (1 wt%) containing oil droplets meets a bulk solution containing calcium ions (0.1 mol dm\(^{-3}\)), upon which an ionically cross-linked gel fibre forms. (ii) The gel network, cross-linked by calcium ions, entraps both the enzyme urease and oil droplets. Right: (a) Following a course of programmed behaviour, the fibre converts urea, the fuel, to ammonia, due to the inclusion of urease in its structure. (b) After a defined time period, the fibre generates a local increase in pH. This time-programming is afforded due to the bell-shaped activity curve of urease, where the relative enzyme rate, \(v' = (1 + 2 \times 10^{-9}[H^+]) + [H^+] / 5 \times 10^{-6}\), graph reproduced from ref. 33. (c) Within the low pH (3.50) bulk environment, partially protonated ethylenediaminetetraacetic acid (EDTA) can be found. As the pH of fibre increases locally, EDTA is deprotonated locally and chelates calcium ions. (d) This results in a loss of cross-linking and the release of oil droplets.

![Fig. 2](image_url)  
**Fig. 2** Fibre disassembly. The release of 41 entrapped oil droplets from fibres with different enzyme loadings, 10 (■), 8 (▲), 6 (▲), 5 (▼) and 4 g L\(^{-1}\) (▲), is tracked. As enzyme concentration within the fibre decreases, release follows after an increasingly longer dormancy period. The pH change of a fibre containing 10 g L\(^{-1}\) of urease is followed using the indicating dye bromothymol blue (BMB). As the pH locally increases, a change from yellow to blue is observed. By taking an RGB histogram and converting to HSV, the change in hue angle, and by extension, colour, is monitored (▲) and compared to disassembly of the 10 g L\(^{-1}\) fibre (■). Onset of fibre disassembly corresponds to a hue angle of 92 degrees, equal to a pH of 6.3 (see calibration in extended data).
Alginate-based hydrogels are widely used in food, personal care, and pharmaceutical applications due to their biologically friendly nature and ionic cross-linking capabilities, making them an excellent tool for the design of soft materials.\textsuperscript{31}

For fibres, we employed a flow focussing device which allows for coloured oil droplets to be embed along the length. Panels (i) and (ii) of Fig. 1 depict the formation of composite fibres by this method. Oil droplets (red) are formed in a continuous flow of 1 wt\% sodium alginate that meets a 0.1 mol dm\textsuperscript{-3} aqueous solution of calcium chloride hexahydrate, upon which the solution is ionically cross-linked by calcium ions. The oil droplets were used to distinguish fibres from one another as well as a way to track their disassembly. The sodium alginate solution contained varying amounts of the enzyme urease, which together with the oil droplets becomes entrapped upon crosslinking into the hydrogel matrix.\textsuperscript{32} The enzyme is introduced to indirectly control pH over time within the fibre. It does this by converting urea, added to the liquid environment in which the gels are placed, into ammonia and carbon dioxide. Importantly, the activity of urease is pH dependent, with a bell-shaped activity curve (see panel b material time programming and legend for its mathematical fit, Fig. 1).\textsuperscript{33}

When we place one of our hydrogel fibres (10 g L\textsuperscript{-1} urease) into acidic water of pH 4 in the presence of urea (0.09 mol dm\textsuperscript{-3}) and bromothymol blue as pH colorimetric indicator, it becomes evident that the local pH rises from within the fibre as a direct result of enzyme activity (see Movie 1, ESI,\textsuperscript{†} and Fig. 2).

Our first goal in autonomous hydrogel material design is to demonstrate programmed time delay in the disintegration of the fibres and thus release of the oil droplets.

The sodium salt of ethylenediaminetetraacetic acid (EDTA) is added to the bulk aqueous solution as a chelating agent for calcium ions, acting as a dormant Ca\textsuperscript{2+}-sink. The initial pH of the aqueous medium containing both EDTA and urea in which the fibres are placed is set at a value of 3.50. EDTA has a maximum binding affinity for Ca\textsuperscript{2+} at high pH, when all 6 of its donor groups (4 carboxylic acid groups and 2 nitrogens) are ionized. At pH 7.5, only a fraction of the EDTA will be in this

![Fig. 3](image_url) The independent action of fibres of different compositions in a closed system. Three populations of fibres can be seen: 10 g L\textsuperscript{-1} (red), 8 g L\textsuperscript{-1} (blue) and 4 g L\textsuperscript{-1} (orange). Fibres of a higher enzyme concentration start to disassemble before those of a lower concentration. At the beginning, all fibres are intact. After 78 seconds, only the red fibres have released their oil droplets. After 614 seconds, the blue fibres have released their droplets and after 1030 seconds, the orange fibres have released theirs. Scale bar = 1 cm.
communication between gels. Sodium alginate gel beads containing 0.008 g L\(^{-1}\) of urease and the indicating dye bromothymol blue (BMB) are placed in a bath of urea at pH 3.50 (the yellow beads at 30 seconds). A gel bead containing 10 g L\(^{-1}\) (the blue bead at 30 seconds) of urease is temporarily introduced, touching only one of the two 0.008 g L\(^{-1}\) urease beads (\(\square\)). This higher concentration bead has already been exposed to a urea solution and produces ammonia locally, and can be seen 'infecting' the bead it touches (\(t = 240\) and 450 seconds). As a result, the infected bead transitions from a low to high pH at a faster rate than its uninfected partner (\(\bigtriangledown\)), as indicated by BMB. Scale bar = 0.5 cm. By taking an RGB histogram and converting to HSV, the change in hue angle, and by extension, colour, of the three gel beads is tracked over the course of the experiment.

![Communication between gels. Sodium alginate gel beads containing 0.008 g L\(^{-1}\) of urease and the indicating dye bromothymol blue (BMB) are placed in a bath of urea at pH 3.50 (the yellow beads at 30 seconds). A gel bead containing 10 g L\(^{-1}\) (the blue bead at 30 seconds) of urease is temporarily introduced, touching only one of the two 0.008 g L\(^{-1}\) urease beads (\(\square\)). This higher concentration bead has already been exposed to a urea solution and produces ammonia locally, and can be seen 'infecting' the bead it touches (\(t = 240\) and 450 seconds). As a result, the infected bead transitions from a low to high pH at a faster rate than its uninfected partner (\(\bigtriangledown\)), as indicated by BMB. Scale bar = 0.5 cm. By taking an RGB histogram and converting to HSV, the change in hue angle, and by extension, colour, of the three gel beads is tracked over the course of the experiment.](https://zenodo.org/record/3261194/files/Commu1018.pdf)
such that the fibres disintegrate in a pre-defined order, as shown in Fig. 3 and Movie 2 (ESI†). The corresponding dormancy time periods were in approximate agreement with the results presented in Fig. 2.

At first glance, self-regulating behaviour means that disintegration of one fibre should not affect the others. Upon closer inspection of the video footage, however, it appears that the disintegration of the red fibre at the top influences that of its lower urease concentration, a blue one. This observation prompted us to look at how the gels might communicate with one another, and in turn, the effect this has on their programmed behaviour. For this we designed an experiment (lasting approximately 1000 seconds, see Fig. 4) in which a gel bead of high enzyme concentration (10.0 g L⁻¹) already at high pH, as indicated by its blue colour originating from bromothymol blue, makes temporary contact (240 seconds) with one of two yellow beads of lower urease concentration (0.008 g L⁻¹) in a pH 3.50 urea solution. Contact with the blue bead “infests” the yellow bead and it transitions faster to blue (exceeding a pH of 7.6 as indicated by the presence of bromothymol blue) than its unaffected counterpart. A plausible explanation is that the transient pH increase generated by the first bead drives the lower concentration bead up its bell-shaped pH activity curve due to the diffusion of locally generated base. This push decreases the pre-programmed dormancy period and allows the infected gel bead to reach a higher pH in a shorter time period. We quantify this change in colour as before by measuring the hue angle. The two 0.008 g L⁻¹ beads start with a hue angle of ca. 50°, corresponding to a yellow colour. The 10 g L⁻¹ bead has an angle of ca. 230°, typical of a deep blue colour. Over the course of the experiment the triggered bead reaches this maximum hue angle whilst the un-triggered bead does not. This is due to an increased dormancy period and a slower rate of change.

Conclusions

To conclude, our studies show that it is possible to design and fabricate hydrogel objects that can react with time control in response to a trigger originating from their environment. This provides a level of autonomy and ultimately shifts control from the environment to the material itself. Additionally, communication between nearby hydrogel objects was demonstrated. We believe that the combination of uniquely programmed response behaviour and communication opens up exciting opportunities in the design of soft robotic materials that are capable of signal transduction. As an example, soft robotic objects have to rely on the ability to send signals and act upon them often in complex environments. A chemical signalling pathway is an obvious choice. A collection of synthetic ‘tissues’ or ‘organs’ may receive a shared stimulus, and need to act differently and independently. The ability to build soft systems with independent function operating in the same physical space brings us closer to this biologically inspired design.

References

5 R. O. Doyle, Free will: it’s a normal biological property, not a gift or a mystery, Nature, 2009, 459, 1052.


