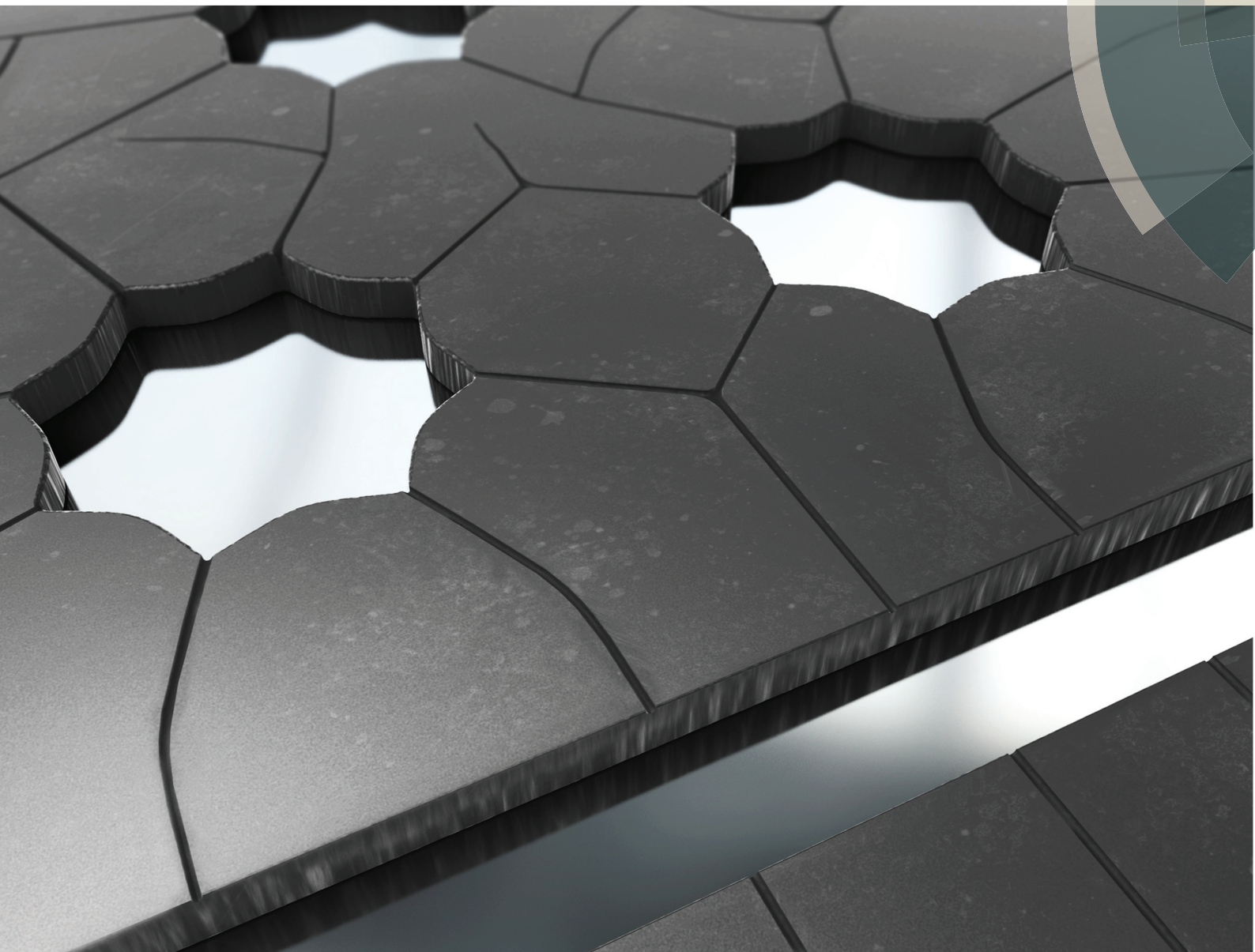


Nanoscale

www.rsc.org/nanoscale



ISSN 2040-3364



REVIEW ARTICLE
Taesung Kim *et al.*
Cracking-assisted fabrication of nanoscale patterns for
micro/nanotechnological applications





Cite this: *Nanoscale*, 2016, **8**, 9461

Cracking-assisted fabrication of nanoscale patterns for micro/nanotechnological applications

Minseok Kim,^a Dong-Joo Kim,^a Dogyeong Ha^a and Taesung Kim^{*a,b}

Cracks are frequently observed in daily life, but they are rarely welcome and are considered as a material failure mode. Interestingly, cracks cause critical problems in various micro/nanofabrication processes such as colloidal assembly, thin film deposition, and even standard photolithography because they are hard to avoid or control. However, increasing attention has been given recently to control and use cracks as a facile, low-cost strategy for producing highly ordered nanopatterns. Specifically, cracking is the breakage of molecular bonds and occurs simultaneously over a large area, enabling fabrication of nanoscale patterns at both high resolution and high throughput, which are difficult to obtain simultaneously using conventional nanofabrication techniques. In this review, we discuss various cracking-assisted nanofabrication techniques, referred to as crack lithography, and summarize the fabrication principles, procedures, and characteristics of the crack patterns such as their position, direction, and dimensions. First, we categorize crack lithography techniques into three technical development levels according to the directional freedom of the crack patterns: randomly oriented, unidirectional, or multidirectional. Then, we describe a wide range of novel practical devices fabricated by crack lithography, including bioassay platforms, nanofluidic devices, nanowire sensors, and even biomimetic mechanosensors.

Received 11th September 2015,
Accepted 7th December 2015

DOI: 10.1039/c5nr06266g

www.rsc.org/nanoscale

^aDepartment of Mechanical Engineering, Ulsan National Institute of Science and Technology (UNIST), 50 UNIST-gil, Eonyang-eup, Ulsan, 689-798, Republic of Korea. E-mail: tskim@unist.ac.kr; Fax: +82-52-217-2409; Tel: +82-52-217-2313

^bDepartment of Biomedical Engineering, Ulsan National Institute of Science and Technology (UNIST), 50 UNIST-gil, Eonyang-eup, Ulsan, 689-798, Republic of Korea

1. Introduction

Creating patterns and structures with dimensional sizes of 1–100 nm has played a crucial role in developing innovative nanotechnology that can precisely manipulate the motion and behavior of individual molecules.¹ Therefore, a facile but accu-



Minseok Kim

Minseok Kim received his B.S. (2010) in Mechanical Engineering from Chonnam National University, and his Ph.D. (2015) in Mechanical Engineering from Ulsan National Institute of Science and Technology, Korea. During his Ph.D. program, he focused on development of multi-scale micro/nanofluidic devices using unconventional nanofabrication techniques and materials including cracks, hydrogels, and nonporous membranes. Cur-

rently, he is a postdoctoral associate at the Research Laboratory of Electronics at Massachusetts Institute of Technology, where he is extending his research interests to analyze clinical biosamples such as patient blood, sputum, and urine to identify unknown pathogens in the samples.



Dong-Joo Kim

Dong-Joo Kim received his B.S., M.S., and Ph.D. degrees from the Department of Semiconductor Science and Technology, Chonbuk National University. He has developed a nanostructure based platform for separating specific target cells including circulating tumor cells (CTCs). He then joined Professor Taesung Kim's group at Ulsan National Institute of Science and Technology (UNIST) as a postdoctoral researcher. Currently, he is focus-

ing on the development of unconventional multi-scale fabrication techniques using crack-photolithography.



rate nanofabrication method provides a variety of applications in both science and engineering fields, encompassing nanomaterials,^{2,3} nanoelectronics,⁴ nanomechanics,⁵ nanobiotechnology,⁶ nanoenergy,⁷ and various nanodevices.⁸ To date, substantial efforts have been made to develop reliable nanofabrication techniques, which can be categorized into conventional and unconventional ones.

1.1. Conventional nanofabrication techniques

First, electron-beam lithography (EBL, Fig. 1A)^{9–11} is among the most precise methods of fabricating nanopatterns. EBL equipment emits high-voltage electrons (1–100 kV) to electron-sensitive or electron-resistive polymers (e.g. poly(methyl methacrylate)) to selectively remove unexposed or exposed resist. The patterning process of EBL is similar to that of photolithography; it consists of resist coating, exposure, and development processes but does not require masking structures during the exposure step because the EBL draws patterns directly using nanoscale e-beams with an automated scanning system. Similar to EBL, the focused ion beam (FIB)^{12–14} technique uses sequential exposure of nanoscale ion beam spots that can physically damage a substrate by ion bombardment. Because the power density of the ion beam ($\sim 10^9$ W cm⁻²)¹⁵ is much higher than that of an e-beam (10^7 W cm⁻²),¹⁶ it can directly generate nanoscale grooved patterns on a hard substrate without the use of masking structures and resist deposition. Although EBL and FIB lithography can create nanopatterns at a high resolution of up to a few nanometers,¹⁷ direct writing by nanoscale beams limits the fabrication throughput, making it costly and time-consuming to produce large-scale nano-

patterns. In addition, EBL and FIB lithography operate under high-vacuum conditions (typically 10^{-6} – 10^{-10} Torr); therefore, it costs somewhat more to set up and maintain facilities.⁹

Second, the throughput limitation can be partially resolved by using nanoimprint lithography (NIL, Fig. 1B),^{18–20} which replicates predefined nanopatterns on a rigid template by mechanically pressing conformal imprint resists. After the imprint resist is deformed, photoenergy or thermal energy is applied to harden the resist, and the master mold is released. In this manner, a number of nanopatterns can be duplicated repeatedly from an original master mold. Soft lithography²¹ is a similar duplication method in which silicone elastomeric precursor solutions are thermally cured. NIL and soft lithography enable high-throughput nanofabrication. However, they can be cost-ineffective when a template mold is usable for only a limited number of replications, and new master molds must be produced by other expensive nanofabrication techniques.

Third, another common approach to produce nanopatterns is top-down or bottom-up surface and bulk micromachining techniques such as silicon (Si) etching^{22,23} and thin film deposition^{24,25} in conjunction with selective patterning of photoresists as masking layers *via* photolithography²⁶ (Fig. 1C). Standard photolithography by Si etching is used for fabricating two-dimensional (2-D) nanopatterns that have nanoscale heights but microscale widths and lengths, resulting in a low aspect (width to height) ratio.^{27,28} The bulk Si material is usually eliminated by dry etching (e.g., reactive ion etching, RIE)²² or wet etching (e.g., using a potassium hydroxide solution).²⁹ Thus, the critical dimension for nanopatterns (height) is controllable by adjusting the etching rate of the Si substrate.



Dogyeong Ha

Dogyeong Ha received his B.S. (2013) from the Department of Mechanical Engineering, Ulsan National Institute of Science and Technology (UNIST), Korea. Currently, he is pursuing his M.S. and Ph.D. degree at the same Department of Mechanical Engineering at UNIST. His research interests include micro/nanofluidics, micro/nanofabrication, and microfluidic components such as micromixers and micropumps. Recently, he is

focusing on the development of unconventional, multi-scale micro/nanofabrication using crack-assisted lithography and inkjet printing. Also, he attempts to combine the crack-photolithography and soft-lithography so as to facilitate the development of various mixed-scale micro/nanofluidic devices in a convenient and high-throughput manner.



Taesung Kim

Taesung Kim is an associate professor in the Department of Mechanical Engineering, Ulsan National Institute of Science and Technology (UNIST). He received his B.S. and M.S. degrees from the Department of Mechanical Engineering, Seoul National University, and obtained his Ph.D. from the Department of Mechanical Engineering, University of Michigan at Ann Arbor. After being a post-doctoral research fellow at the University of Cali-

fornia at Berkeley and Lawrence Berkeley National Laboratory (JBEI), he started his independent research career at UNIST. His research interests include micro/nanofluidics, electrokinetics including numerical simulations, nanobiosensors, and inkjet printing based micro/nanofabrication. Currently, he is focusing on the development of unconventional multi-scale fabrication techniques using crack-photolithography and inkjet printing, and various microfluidic systems for bioreactors and high-throughput screening.



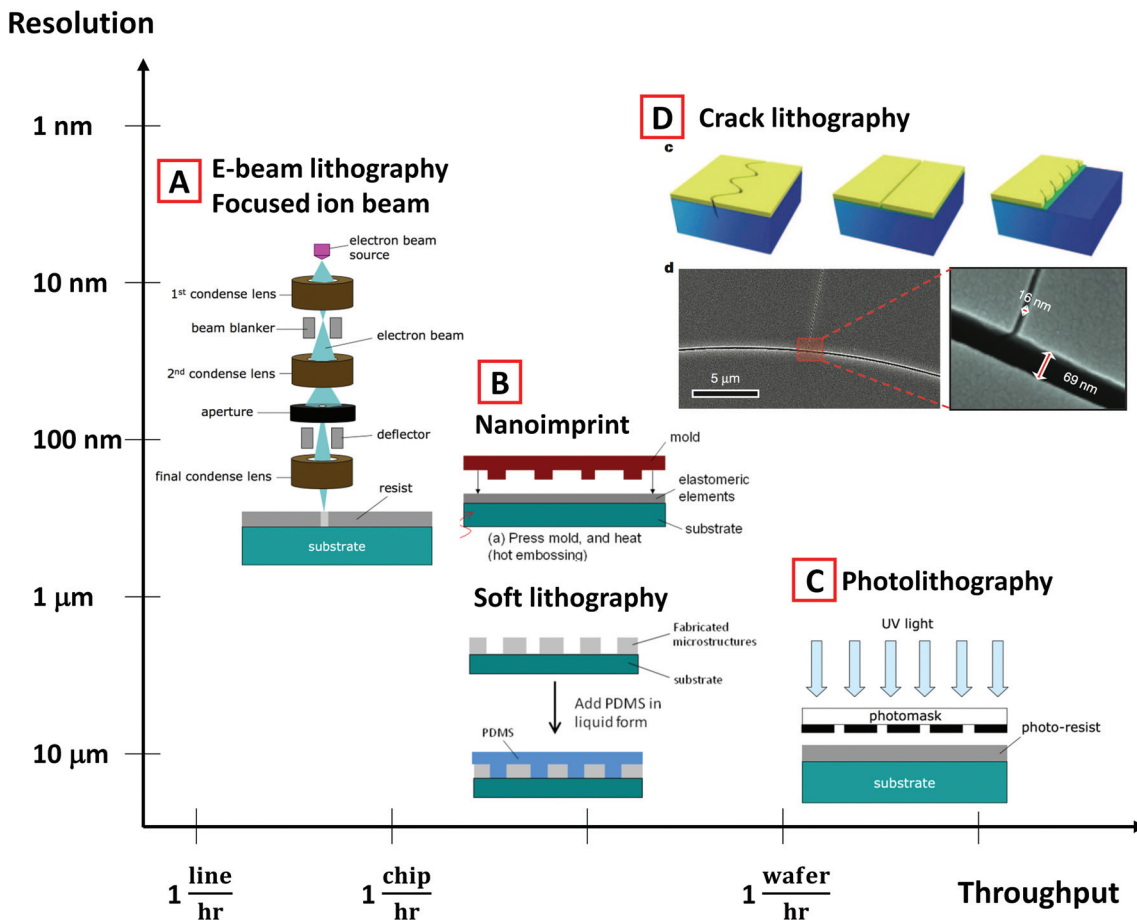


Fig. 1 Overview of conventional nanofabrication and unconventional crack lithography techniques. (A) Conventional nanolithography techniques such as EBL and FIB lithography show high patterning resolution, but the throughput is limited because these are direct writing methods. Reproduced with permission.²⁶ (B) Replica molding techniques such as nanoimprint and soft lithography exhibit intermediate levels of both resolution and throughput. Reproduced with permission.²⁶ (C) Photolithography exhibits high throughput because of batch processing, but the minimum feature sizes are usually limited to a few microns. Reproduced with permission.²⁶ (D) Crack lithography, a new nanopatterning concept using intentional cracking, generates nanopatterns over a large-scale film on a substrate. Theoretically, it can produce patterns at the single-molecule level over an entire material simultaneously, resulting in both high resolution and high throughput. Reproduced with permission.³⁵

Two-dimensional nanopatterns are also fabricated by surface nanomachining (thin film deposition) with photolithography-based photoresist patterning for the sacrificial layer process (SLP).^{28,30} The SLP is a representative bottom-up approach that uses sequential stacking of selectively patterned thin films. Photolithography by Si etching or thin film deposition is relatively simple and cost-efficient because it uses batch processing over a large-scale wafer, but the applications of the nanopatterns can be limited by their 2-D profile;²⁸ it is difficult to produce submicron line patterns, including one dimensional (1-D) nanowire and nanoscale spots, by photolithography-based micro-electro-mechanical system (MEMS) techniques.

1.2. Unconventional nanofabrication by cracking

As summarized in Fig. 1, conventional nanolithography methods such as EBL and FIB lithography have a superior resolution but an inferior fabrication throughput (Fig. 1A). Photolithography-based MEMS techniques, in contrast, show

limited patterning resolutions of up to a micron in line width, but simultaneously produce massively parallelized patterns by batch fabrication (Fig. 1C). On the other hand, NIL and soft lithography exhibit intermediate levels of both resolution and throughput; however, they are essentially replication methods that rely on other nanofabrication techniques to duplicate the original master molds (Fig. 1B). Thus, a nanofabrication technique that can produce patterns or structures with a high resolution and high throughput is urgently required.

Recently, designed material failures of thin films such as cracking,^{31–46} buckling (wrinkling),^{47–53} and folding^{54–56} have been introduced as time- and cost-efficient methods of creating nanopatterns. Although these morphological instabilities of thin films were considered as complex and chaotic phenomena, it was possible to generate well-organized nanopatterns by spatiotemporal engineering of the applied stresses and material properties. In particular, cracking-assisted nanofabrication, called crack lithography in this work, seems to be the



most promising alternative because it can simultaneously produce nanopatterns over a large-scale substrate (high throughput)^{3,35} and accurately control the feature size up to a few nanometers (high resolution).^{35,57} For instance, as shown in Fig. 1D, nanoscale cracking produces various propagating trajectories (patterns) such as oscillating, straight and stitch-like lines over a large-scale wafer at the same time. The cracks can either penetrate the substrates or be localized within thin films without a wide range of material choices, including popular semiconductor materials such as Si, SiO₂, and metals. In addition, cracking dimensions such as widths and depths seem to be comparable to the state-of-the-art resolution of conventional nanofabrication with dramatically reduced cost and time consumption without the use of complex and expensive facilities.

In 1998, the first comprehensive attempt was made to utilize the intentional generation of cracks as well-defined nanostructures by combinatorial material choices between thin films and substrates during chemical vapor deposition (CVD).⁵⁷ The next wave in cracking-assisted nanopatterns was in practical applications such as nanowires (2004),^{42,58} cellular patterning (2005),³³ and nanofluidic devices (2007).³⁶ Then, in 2012, crack lithography enabled high throughput nanofabrication at a wafer level by batch processing,³⁵ which was typically expensive and time consuming using conventional nanolithography techniques. In 2015, the throughput and controllability of crack lithography were fairly enhanced by controlling dimensions, directions, and propagating kinetics of nanoscale cracks with a spatiotemporal engineering of material properties and applied tensile stresses.^{38,59} Hence, crack lithography techniques became increasingly advanced in terms of not only their patterning capability such as resolution and throughput, but also extension of application fields.

In this review, we survey various crack lithography techniques for producing nanopatterns and categorize them into three technical development levels based on the controllability of the nanopatterning directions of the cracks: randomly oriented, unidirectional, or multidirectional. In addition, we review a wide range of applications of the nanopatterns produced by crack lithography, including biomolecular and cellular patterning, nanofluidic devices for mass-transport control, nanowire-integrated gas sensors, and even biomimetic multifunctional mechanosensors. Although several reviews on cracking-based patterning were reported previously, they considered only the fabrication of nanofluidic devices and biological applications.^{60,61} To the best of our knowledge, this review is the first to comprehensively investigate crack-assisted lithography techniques considering not only their nanopatterning capabilities but also a wide range of applications.

2. Fundamentals in cracking

In principle, cracking is the physical breakdown of the interaction (bonding) energy between adjacent atoms without complete separation of parts (fracture); it occurs when the applied tensile stress exceeds the ability of a material containing a

crack to resist fracture, called the fracture toughness (also called the critical stress intensity factor, K_c (Pa m^{0.5})).⁶² The stress intensity factor (K), which has the same physical unit as K_c (stress times the root of distance), is used for predicting how much a nominal tensile stress caused by external loads or residual effects is intensified near the tip of a crack. The magnitude of K is an extensive material property that depends on the size, position and shape of cracks, and the magnitude and applied rate of loads on the material. In theory, there are three pure fracture modes depending on the direction of the applied loads: Mode I – opening (tensile), Mode II – sliding (in-plane shear), and Mode III – tearing (out-of-plane shear). The linearly independent cracking modes often appear together resulting in complex cracking phenomena with different magnitudes of K_c and K according to the fracture modes. However, especially for thin film and substrate systems, pure Mode I is the most typical case, implying that the fracture toughness and stress intensity factor of Mode I (K_{Ic} and K_I) are the most important factors determining whether a crack begins to grow. That is, a crack propagates when $K_I \geq K_{Ic}$ and remains unchanged when $K_I < K_{Ic}$, which seems to be predictable and controllable by accurate engineering of loading and material conditions.

Fig. 2 shows imaginary cracking phenomena in a thin film, having a specific thickness (t_1), Young's modulus (E_1), and fracture toughness ($K_{c,1}$), on a rigid substrate to show the engineering parameters for crack control. For example, a thin film and substrate system can often be exposed to various external forces during fabrication and treatment of the film, including electrical,⁶³ optical,⁶⁴ thermal,⁶⁵ and even mechanical forces.⁶⁶ Because of the interaction between the materials

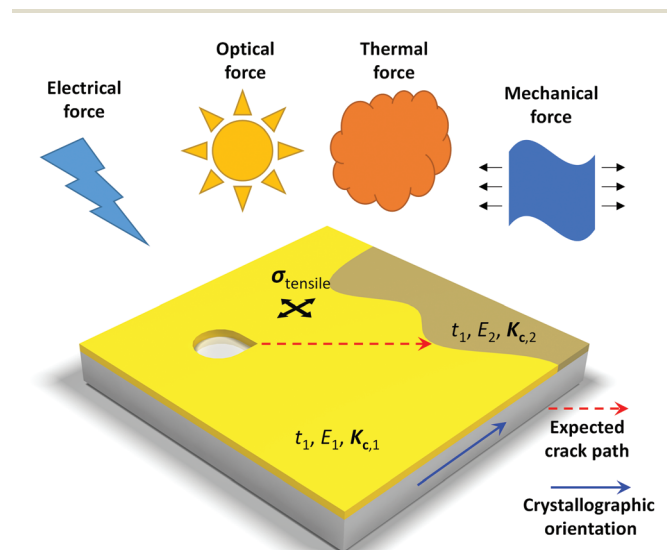


Fig. 2 Schematic showing a crack in a thin film on a substrate due to a tensile stress field (σ_{tensile}). An external force such as an electrical, optical, thermal, or mechanical force can apply tensile stress. The film has two regions with different material properties, for example, the film thickness (t_1 , t_2), Young's modulus (E_1 , E_2), and fracture toughness ($K_{c,1}$, $K_{c,2}$). In addition, the crack in the thin film on the substrate will be affected by the crystallographic orientation of the substrate.



(films and substrates) under the applied forces, an axial or isotropic tensile stress/strain can be induced in the film and amplified locally at sharp tip points such as notched microstructures. Because the nominal tensile stress field is concentrated around the notch, crack initiation at the notched position is favorable, and the crack then propagates along the maximal stress field. During propagation, the crack can encounter another region that has different material properties (t_2 , E_2 , and $K_{c,2}$). At the junction point, the crack can be terminated, redirected, or advanced with a different propagation velocity, depending on the local material properties of the new region. In addition, the crystallographic orientation of the substrate often affects the propagation direction of cracks, which can advance preferentially along the weakest bonding orientation. Consequently, these key factors, including the stress source, stress concentration effect, and material properties of the substrate and film, should be carefully engineered to control cracks so as to create nanopatterns at high resolution and high throughput.

3. Randomly oriented crack patterns

Fractal-like random structures created by cracking are observed frequently in various thin films and colloidal processes because high residual tensile stresses can be generated spontaneously by baking, drying, and deposition. In this section, we review randomly oriented crack patterns generated by solvent evaporation (drying) of self-assembled colloidal structures and by thin film CVD to understand the fundamental mechanisms of nanoscale cracking phenomena, which seems to be essential for advancing toward exquisitely controlled crack patterns.

3.1. Drying-mediated random cracks

Fig. 3A shows randomly oriented crack patterns in a self-assembled monolayer of uniformly sized polystyrene micro-

spheres ($d = 3.4 \mu\text{m}$).⁶⁷ For the cracking analysis, a close-packed, monolayered colloidal film was prepared with a relatively large grain size (10^5 – 10^6 spheres) by sandwiching the polystyrene microspheres between glass slabs, followed by a slow drying process. In the first step, localized defects such as vacancies and grain boundaries nucleated slowly without cracking because the stress concentration was insufficient to initiate cracks. After sharp tips formed at defective points, cracks were initiated and then propagated rapidly and linearly, as shown in both empirical (top images) and numerical (bottom images) results in the initial images in Fig. 3A. The rapid linear propagation was attributed to the stress concentration effects at the sharp tips of the defects. During propagation, some cracks merged with the adjacent cracks by changing their propagation directions or branched into multiple but smaller cracks. In the final stage, crack propagation slowed down and became nonlinear because the tensile stress caused by dehydration of the microspheres was non-uniform, resulting in the formation of complex fractal-like random cracks. After drying was complete, the average diameter of the polystyrene spheres was reduced from 3.4 to 2.7 μm (approximately 20%), and all the cracks were completely terminated.

Rao *et al.* reported similar randomly oriented crack patterns during a drying process (25 °C, 5 min) of spin-coated colloidal solutions containing acrylic nanoparticles ($d = 40$ – 80 nm) on a glass substrate.⁶⁸ The drying-mediated cracks showed different dimensions and densities according to the thickness of the coating layer.⁶⁹ For example, as the film thickness increased from 0.6 to 9 μm , the crack width increased gradually, but the number of cracks was reduced (Fig. 3B). In addition, the material properties of the contained colloidal particles, such as the size, shape, and Young's modulus, greatly affected the cracking phenomena.

The drying process can induce not only a tensile stress but also a twisting stress field, which creates a spiral cracking pathway (Fig. 3C).³² Leung *et al.* dried a dilute aqueous sus-

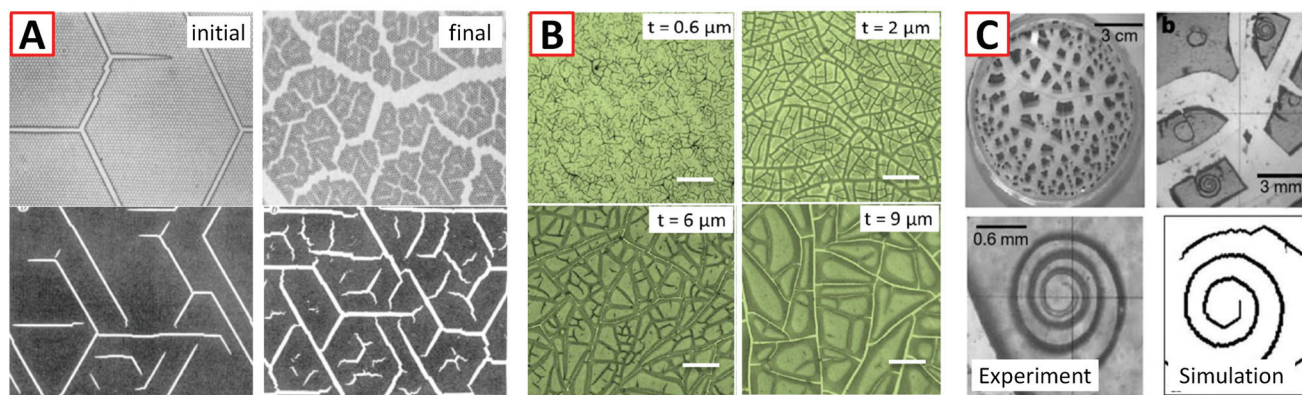


Fig. 3 Drying-mediated, randomly oriented crack patterns. (A) Straight linear cracks in a self-assembled polystyrene monolayer developed into fractal-like chaotic crack patterns during a continuous drying process. Top and bottom images show experimental and simulated results, respectively. Reproduced with permission.⁶⁷ (B) Drying-mediated cracks showed different cracking dimensions and densities according to the film thickness, which ranged from 0.6 to 9 μm . Reproduced with permission.⁶⁸ (C) Crack pattern with a spiral profile was observed in a dried nickel phosphate precipitate. Reproduced with permission.³²



pension of a precipitate such as nickel phosphate ($\text{Ni}_3(\text{PO}_4)_2$) in a Petri dish. As the suspension dried, it solidified and then divided into a number of small pieces. After it splintered, further continuous drying created a spiral crack in the precipitate fragment that gradually became detached from the Petri dish from the outside to the inside because of humidity gradients along not only the normal but also the radial direction. That is, drying proceeded from the top and lateral surfaces to the bottom and central part. This gradual and circular detachment of the precipitate fragment from the substrate induced a twisting stress field and created the spiral crack patterns; both experiments and numerical simulations revealed the same tendency (Fig. 3C). Interestingly, similar cracking phenomena occurred in other aqueous precipitates such as ferric ferrocyanide ($\text{Fe}_4[\text{Fe}(\text{CN})_6]_3$) and ferric hydroxide ($\text{Fe}(\text{OH})_3$), although the profile and size of the spiral cracks varied depending on the fragment size, solidified film thickness, and precipitate type.

3.2. CVD-based random cracks

Randomly oriented cracks were also found during various CVD processes, which can naturally give rise to residual tensile stresses originating primarily from the mismatch in thermal expansion coefficients between the substrate and deposited thin films. In contrast to the drying-mediated stress, the residual stresses were more uniform (isotropic and homogeneous) throughout a large-scale material, but the crystallinity of the foundation substrate (*e.g.*, a Si wafer) greatly affected the crack patterns. Gorokhov *et al.* first comprehensively investigated cracking phenomena in various CVD processes as a novel cracking-assisted nanofabrication concept.⁵⁷ For example, a glassy, brittle layer such as a Si oxide (SiO_2) or Si nitride (Si_3N_4) film was deposited on various substrates having different crystallographic orientations. As shown in Fig. 4A-i, a SiO_2 film was deposited on a

(111)-oriented substrate using low-pressure CVD (LPCVD) at a relatively low deposition temperature ($T_d = 100^\circ\text{C}$) and exhibited linear propagation of cracks that tended to be aligned in the $\langle 112 \rangle$ direction. Fig. 4A-ii shows periodically oscillating crack patterns produced by 600 nm CVD of a Si_3N_4 film on a (100)-oriented Si substrate at $T_d = 750^\circ\text{C}$. The propagation direction of the oscillating crack was determined by the formation of a plastic deformation zone in the substrate, which caused crack propagation oriented in the $\langle 110 \rangle$ direction. Interestingly, cracks in the Si_3N_4 thin film penetrated deep into a substrate when the residual stress was high enough to break the bonding energy of the substrate. This implies that the crack directions and dimensions can depend strongly on the substrate properties. For example, Fig. 4A-iii shows crack patterns in the surface of the (001)-oriented Si substrate after a Si_3N_4 film produced by 500 nm CVD at $T_d = 700^\circ\text{C}$ was peeled off. However, the effect of the crystallographic orientation of the substrate can be suppressed by positioning an amorphous interlayer as a damping layer between the thin film and substrate. The damping layer generally possesses higher elastic and ductile characteristics (high fracture toughness) than the brittle thin film, so elastic and/or plastic deformation of the damper layer consumes the shear energy originating from crack propagation in the thin film.^{35,57} Fig. 4A-iv shows orientation-free cracks in a SiO_2 film (450 nm thick, $T_d = 650^\circ\text{C}$) on a (111)-oriented germanium (Ge) substrate with a viscous interlayer of germanium oxide (GeO_2). Notably, the crack patterns were totally random without preferential propagation directions because the interlayer prevented the penetration of the cracks into the crystallized substrate. Thus, no plastic deformation zone was observed in the substrate, as confirmed by X-ray topography and transmission electron microscopy images.

Without employing an interlayer, Luke *et al.* and other researchers minimized the crystallographic effects by surrounding a cracking area with open trenches (etched

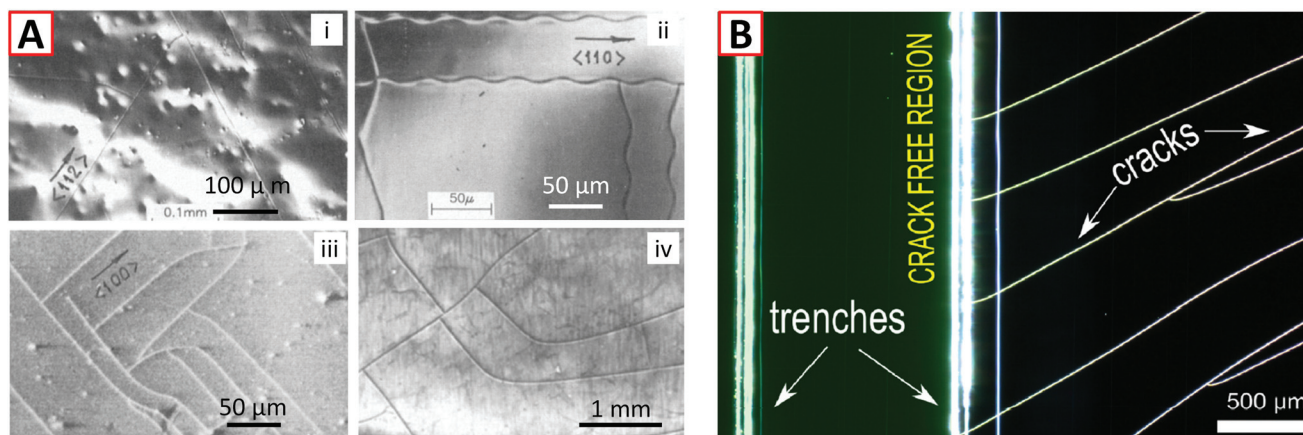


Fig. 4 Randomly oriented crack patterns observed in various CVD processes. (A) Crack patterns depended strongly on the CVD parameters: (i) crack patterns in a SiO_2 film on the (111)-oriented CdHgTe substrate, (ii) crack patterns in a Si_3N_4 film on the (100)-oriented Si substrate, (iii) crack patterns in the (001)-oriented Si substrate after a Si_3N_4 film was removed, and (iv) constraint-free crack patterns in a SiO_2 film on the (111)-oriented Ge substrate with a GeO_2 interlayered film as a damping structure. Reproduced with permission.⁵⁷ (B) Propagating cracks in a Si_3N_4 thin film, which also penetrated deep into the Si substrate, terminated at the crack-free region (trenches). Reproduced with permission.⁷⁰



Si patterns) in which crack propagation could not occur, as shown in Fig. 4B.^{70,71} Therefore, cracks initiated at random positions were terminated at the crack-free trenches, which kept the cracks from spreading or escaping to inside or outside of the crack-free regions. Cracks in the Si₃N₄ film typically penetrated the substrate owing to the high residual stress (Fig. 4A-iii); thus, a simple grooved trench was insufficient to stably block the propagating cracks. To increase the propagation resistance, Luke *et al.* fabricated multiple (up to five) trenches in series and successfully terminated the propagation of cracks at the crack-free trenches.

The substantial randomness of the cracks found in both colloidal drying and thin film CVD processes arises from complex interrelationships among the applied tensile stresses, the properties of the thin film (or colloid), the crystallographic orientation of the substrate, and even thermodynamic conditions such as temperature and humidity. In fact, randomly oriented cracks are not suitable for use directly as an accurate nanofabrication method; however, systematic characterization of the crack patterns introduced in this section provides several important suggestions regarding the fundamental principles of nanoscale cracking phenomena. First, randomly distributed sharp tips in initial defects caused crack initiation at random positions. Thus, the employment of pre-engineered sharp tips (notches) to concentrate the nominal tensile stresses would be advantageous for controlling crack initiation at the desired positions. Second, the crystallographic orientation of the substrate greatly influenced the crack patterns, so it can be applied to guide the propagation direction. In particular, the substrate choice in CVD was important because cracks in thin films often penetrate deep into the substrate. Third, locally engineered material properties of the thin films or substrates can be used to localize crack patterns in specific regions by preventing unwanted generation of cracks in other regions (crack-free regions). Finally, a tensile stress applied for cracking should be carefully controlled because crack patterns were directly affected by the direction, magnitude, and application rate of the tensile stress. Given a comprehensive under-

standing of cracking phenomena, we would advance one step toward controlling cracks for accurate nanofabrication.

4. Unidirectional crack patterns

Randomly oriented cracks are initiated everywhere and then propagate without any preference for alignment with particular directions. This is because the intensity and directionality of the applied tensile stresses could not be controlled at specific positions and toward specific directions. For this reason, applications of randomly oriented crack patterns focused primarily on simple modification of surface properties and functionalities by opening new surface areas.⁴¹ In this section and the following sections, we introduce unidirectional and multidirectional crack patterns that can be aligned with particular single or multiple directions by precise control of the applied tensile stresses to create crack patterns at predetermined positions with controllable geometries.

4.1. Control of crack position by notched microstructure

The residual tensile stress generated during CVD of thin films (e.g., SiO₂ and Si₃N₄) is essentially homogeneous and isotropic, so a mechanism to locally amplify the nominal tensile stress was necessary to control the cracking positions and directions. For this purpose, many researchers employed stress-concentrating microstructures such as notches and intentional defects, and created unidirectional crack patterns at predetermined positions.^{40,72} For example, Mani and Saif reported unidirectional crack patterns in a deposited SiO₂ thin film using a prefabricated deep, narrow microscale trench structure (Fig. 5A).⁷² The trench structure was patterned by deep reactive ion etching (DRIE) on a Si substrate, followed by plasma-enhanced CVD (PECVD; 4 μm thick, T_d = 250 °C) of an oxide layer for non-conformal coverage of the top surface of the trenches. That is, the top surface of the trench was covered perfectly by the oxide layer. The inside of the trench, however, had unfilled voids with triangular cross-sectional profiles,

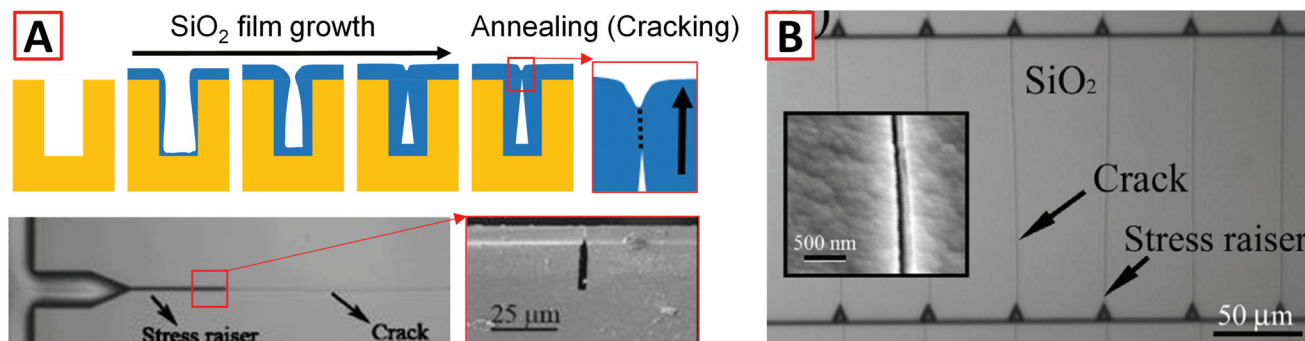


Fig. 5 CVD-based unidirectional crack patterns. (A) Schematic diagram showing a straight crack that was guided by a sharp triangular void structure (stress raiser) formed inside the SiO₂ film. Stress-concentrating void structures were fabricated using a deep micropatterned trench on a Si wafer, which induced non-conformal deposition. Bottom pictures are top and cross-sectional SEM images. Reproduced with permission.⁷² (B) Unidirectional crack arrays in a SiO₂ film were initiated at triangular notch structures (stress raisers) and terminated at the line patterns (stress releasers). Inset shows a magnified SEM image of the crack pattern. Reproduced with permission.⁴⁰



because the SiO₂ deposition rate was maximum on the top surface and gradually decreased along the penetration depth of the trench. After an annealing process, a residual tensile stress was applied by a condensation reaction that caused volumetric shrinkage of the thin film, which was locally amplified at the sharp tip of the void.⁷³ In this way, a unidirectional crack pattern was created at the predetermined slender void and then propagated vertically as straight cracks, as shown in the scanning electron microscopy (SEM) images in Fig. 5A.

Similarly, Alaca *et al.* and other researchers developed other unidirectional crack patterns using prefabricated triangular notch structures for local concentration of the normal tensile stress at the sharp tip.^{40,41,74} In fact, the stress-concentrating effects at sharp triangular notches were well-known in classical fracture mechanics^{75,76} but were rarely applied in microfabrication processes to control cracking phenomena until reported. Fig. 5B shows crack patterns in a deposited SiO₂ layer on a Si substrate; cracks were initiated at the notched positions and terminated at the open boundaries.^{41,74} To demonstrate the high-throughput capability of crack lithography, Alaca *et al.* prefabricated massively parallelized arrays of notches with a uniform spacing (50 μm), and line patterns using a 10 μm DRIE process. After the stress-modulating structures in the Si substrate were patterned, a 5–10 μm-thick SiO₂ film was deposited on the substrate using PECVD; then a heat treatment (400 °C for 20 min) was applied under a nitrogen atmosphere. The heat treatment was applied to generate residual tensile stress using thermal coefficient mismatch of the Si substrate and SiO₂ film, which is also the same principle used for the CVD-based cracks described above.

Consequently, the sharp tips at the triangular notches controlled the positions of crack initiation by locally concentrating the nominal tensile stress, and the initiated cracks propagated linearly because of the homogeneity of the tensile stress and thin film. A high power density was used for the DRIE process to fabricate the sharp corners at the notches and open bound-

aries,^{41,77} which was important for successfully controlling crack initiation and termination. In addition, Xia *et al.* evaluated the crack patterns in different notch-to-notch spaces because two approaching parallel cracks were attracted to each other, resulting in failures in the production of straight linear cracks.^{78,79} A minimum notch-to-notch space of 30 μm was chosen to guarantee linear crack propagation, although the specific value seems to depend on the CVD conditions.

4.2. Directional control by uniaxial tensile stress/strain

In contrast to spontaneous generation of residual tensile stress, uniaxial tensile stresses were directly applied using temperature gradients³⁷ and mechanical strains.^{33,43,80} For example, Yuse and Sano fabricated unidirectional crack patterns on a quenched glass specimen along the maximal temperature stress field by placing the sample between hot and cold reservoirs (Fig. 6A).³⁷ First of all, a small notch was prefabricated in the center and bottom of the long glass specimen to induce crack initiation at the predetermined notch point. Next, the glass specimen was heated for a few minutes to reach an equilibrium temperature with the hot reservoir and then gradually dipped into the cold reservoir using a linear motor holding the glass plate. Interestingly, the crack patterns were aligned in the temperature gradient direction and had various propagation profiles such as straight, oscillating, and nonlinear, depending on the intensity of the thermal stress. That is, the temperature difference between the hot and cold reservoirs (spatial gradient) and the temperature descending speed (temporal gradient) determined the intensity of the thermal stress.

In detail, unidirectional straight crack patterns were created at temperature differences between 50 and 100 °C with a 50 mm s⁻¹ sample descent speed (Fig. 6A-i), whereas nonlinear, randomly bifurcated cracks were generated at temperature differences greater than 250 °C with the same descent speed (Fig. 6A-iii). Under intermediate conditions, the crack

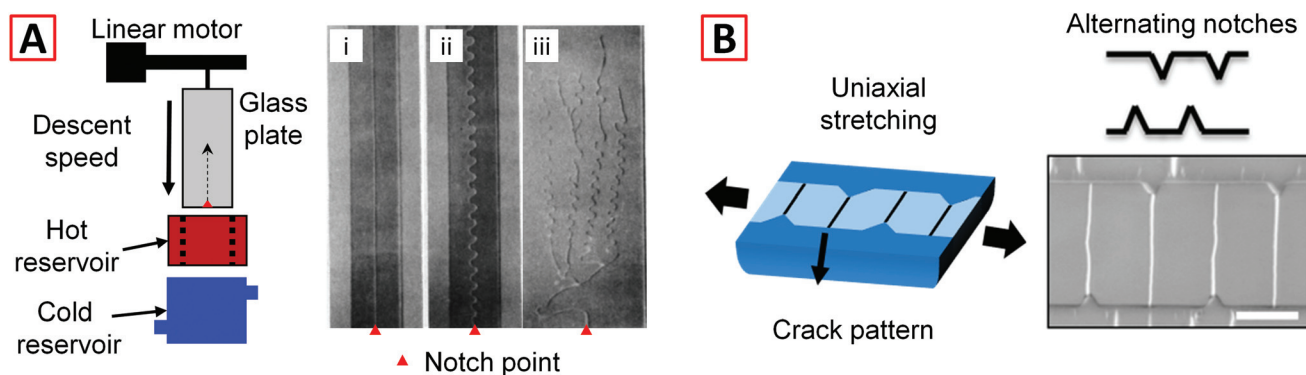


Fig. 6 Unidirectional crack patterns obtained by controlling axial stresses or strains. (A) Various unidirectional crack patterns, such as (i) linear, (ii) oscillating, and (iii) nonlinear profiles, were induced on glass substrates (sample size 24 × 64 × 0.13 mm³) by uniaxial thermal stress. The uniaxial thermal stress was controlled by varying the temperature differences between hot and cold reservoirs with different descent speeds (quenching rates). Reproduced with permission.³⁷ (B) Strain-controlled unidirectional crack patterns fabricated in a brittle thin film (*i.e.*, metal or oxidized PDMS layer) on an elastomer substrate (PDMS). Alternating notch pairs showed a high production yield for creating linear cracks. Reproduced with permission.⁴³



patterns became quasilinear (unidirectional with oscillating curves, Fig. 6A-ii). The wavelength and amplitude of the oscillating curves were also controllable by adjusting the temperature difference and descent speed, which directly determined the spatiotemporal temperature gradient. Oscillating curves were generated because extra energy was generated at higher temperature differences and slower descent speeds than those that created linear cracks. In other words, the extra propagation energy and time gave the crack tip sufficient opportunity to communicate with the lateral boundaries of the glass specimen, so the crack patterns developed gradually from linear to mildly sinusoidal and then saturated oscillating, eventually becoming totally nonlinear, with increasing temperature difference. In addition, the critical transition conditions of the crack patterns were also influenced by the thicknesses and width of the glass plate.

A relatively simple but high-throughput mechanism for applying uniaxial tensile stress was demonstrated by controlling the strain rates of a thin brittle film deposited on an elastomeric polydimethylsiloxane (PDMS) substrate.^{33,36,43} For example, Zhu *et al.* produced unidirectional crack patterns in a thin film by mechanically stretching a PDMS substrate using a high-precision jig.³³ The strain rate was applied using mechanical stretching, which can induce elastic deformation of the PDMS underlayer but create permanent deformation (cracks) in the brittle film on top. That is, the elastomer substrate has a higher fracture energy ($460 \pm 50 \text{ J m}^{-2}$ for PDMS)⁸¹ than the brittle film because of its ductile, rubbery nature. Subsequently, a number of unidirectional crack patterns were fabricated in the thin film layer aligned perpendicular to the axial tensile strain direction.^{33,36} In addition, the dimensions and density of the unidirectional crack patterns were regulated by adjusting the magnitude and application rate of the strain.

More recently, the same group upgraded the strain-controlled cracking mechanism by combining it with triangular notch structures to more accurately control the crack position and density.⁴³ Fig. 6B shows the notch-guided unidirectional cracks patterns in an oxidized layer on the PDMS surface. The cracks in the oxide-PDMS system were controlled by adjusting the strain rate, deposited film thickness, and notch configuration. In particular, the design of the prefabricated notches greatly influenced the quality (yield rate) of the crack patterns; three notch structure configurations were tested: paired, unpaired, and alternating notches. When paired notches were used, the counter-facing cracks that were initiated individually at each notched point were occasionally misaligned. The unpaired notches also exhibited misalignment issues because the cracks were occasionally initiated from the open boundary without notches and merged with a counter-crack extending from the notched side. In contrast, the alternating notches showed far fewer alignment issues, producing linear crack arrays with a high production yield (Fig. 6B). One of the greatest advantages of the strain-controlled cracking mechanism is the simple fabrication process (stretching) using inexpensive equipment such as a strain-controlling element (*e.g.*, a linear motor). In addition, the mechanism can be applicable to

various thin film materials including metals,^{43,82} polymers,⁸¹ and even monolayered biomolecules³³ or nanoparticles,⁸³ as long as the films can be uniformly coated on the flexible substrate.

5. Multidirectional crack patterns

5.1. Strain-controlled bidirectional cracks

Uniaxial strain-controlled cracks can be directly expanded to multidirectional ones by adding a strain-control unit for additional directions, although the directional freedom for cracking seems to be limited to a few directions owing to the complexity of the equipment required for large numbers of strain directions. Kim *et al.* deposited a relatively brittle, hard-PDMS (h-PDMS)^{84,85} thin film on a regular PDMS substrate and applied biaxial strains to the h-PDMS and PDMS composites to fabricate bidirectional crack patterns.⁴⁴ As shown in Fig. 7, bidirectional crack patterns appeared in the h-PDMS film throughout all the rows and columns, guided by a diamond-shaped notch structure having four sharp tips. Interestingly, the cracks in the h-PDMS film could not penetrate the PDMS substrate and stopped at the interface between h-PDMS and PDMS. This result was attributed to the fact that h-PDMS and PDMS have comparable Young's modulus (9.2 and 3.7

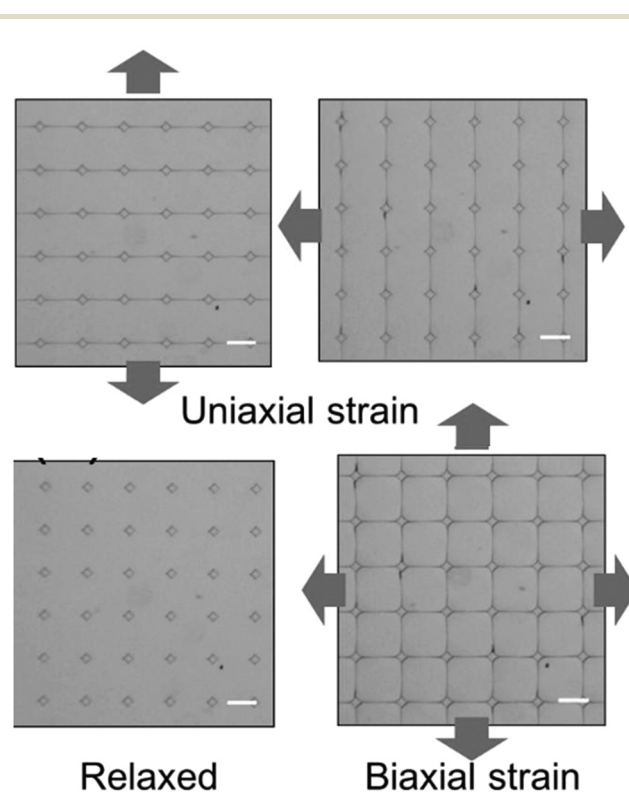


Fig. 7 Strain-controlled bidirectional crack patterns. Biaxial strain created microscale crack patterns in an h-PDMS layer on a PDMS substrate, guided by diamond-shaped notch structures for local stress concentration. Microscale cracks were recovered to nanoscale crack patterns by eliminating the biaxial strain. Reproduced with permission.⁴⁴



MPa, respectively) but very different fracture energies (12.9 and 460 J m⁻², respectively).⁸⁴ Thus, the height of the cracks can be controlled accurately by simply regulating the spin-coating parameters that determine the h-PDMS thickness. Generally, the thickness of previous thin films, such as oxidized PDMS or metal layers, on the PDMS substrate were unable to produce crack patterns larger than a micron, but h-PDMS is fabricated using a spin-coating method that can produce h-PDMS layers up to the microscale. Therefore, the crack patterns in the h-PDMS were relatively large, but their dimensions were recovered to the nanoscale by eliminating the applied strain because of the elasticity of the PDMS substrate.

5.2. CVD-based multidirectional cracks

CVD-based fabrication of uniaxial crack patterns can also be expanded to multidirectional cracks. Nam *et al.* fabricated various crack patterns in a Si₃N₄ film by LPCVD, requiring high temperatures ($T_d = 800$ °C),³⁵ which can cause high residual stresses owing to the large thermal expansion mismatch between the film and substrate materials.^{73,74} As in the CVD-based cracking mechanism described above, they pre-fabricated stress-modulating microstructures such as notches and open boundaries in a Si wafer using the DRIE process to control crack initiation and termination at the desired positions. The cracks in a Si₃N₄ film exhibited linear oscillating propagation with a tendency to be aligned in the <110> direction (Fig. 8A-i), and the oscillation curve was suppressed by inserting a SiO₂ interlayer that prevented penetration of the cracks into the Si substrate (Fig. 8A-ii), which is consistent with the results in Fig. 4A. Typically, it was not easy to terminate the propagating cracks in a Si₃N₄ layer using simple single-layered trench structures (open boundaries) because the

cracks in the Si₃N₄ film penetrated deep into the substrates owing to high residual stresses (Fig. 8A-iii). To terminate the cracks at the predetermined positions, they fabricated stair-like multilevel micropatterns that can gradually release the propagation energy (Fig. 8A-iv). Subsequently, the concentrated tensile stress for crack propagation was fully relaxed at the multilevel terminating position, and the cracks were terminated successfully at the desired positions even under strong residual stresses. However, the propagation directions seem to be constrained to specific orientations because the cracks in the Si₃N₄ film penetrated deep into the crystallized Si substrate, resulting in limited multidirectional crack patterns or requiring additional steps for inserting an amorphous damper layer.

The effect of penetration depth on cracking in the Si₃N₄ film was addressed simply by changing the film material to SiO₂, which has lower residual stresses (Fig. 8B).⁵⁸ Using a CVD-based cracking mechanism similar to that described above, Alaca *et al.* employed a sharp notch and open boundary trench to locally regulate the nominal tensile stress and control crack initiation and termination at predetermined positions. Stress-modulating microstructures were fabricated by RIE of the Si substrate to a 10 μm depth, and then a 5 μm-thick SiO₂ layer was deposited on top of the prefabricated Si wafer using PECVD. During annealing at 525 °C, crack patterns were generated from the sharp tip because of the residual tensile stress caused by condensation and volumetric shrinkage of the film. Because the residual stress of the SiO₂ film was much lower than that of the Si₃N₄ film,⁸⁶ the cracks were localized only in the SiO₂ thin film without penetration into the Si substrate, resulting in perfect multidirectional crack patterns without any interference with the substrate (Fig. 8B).

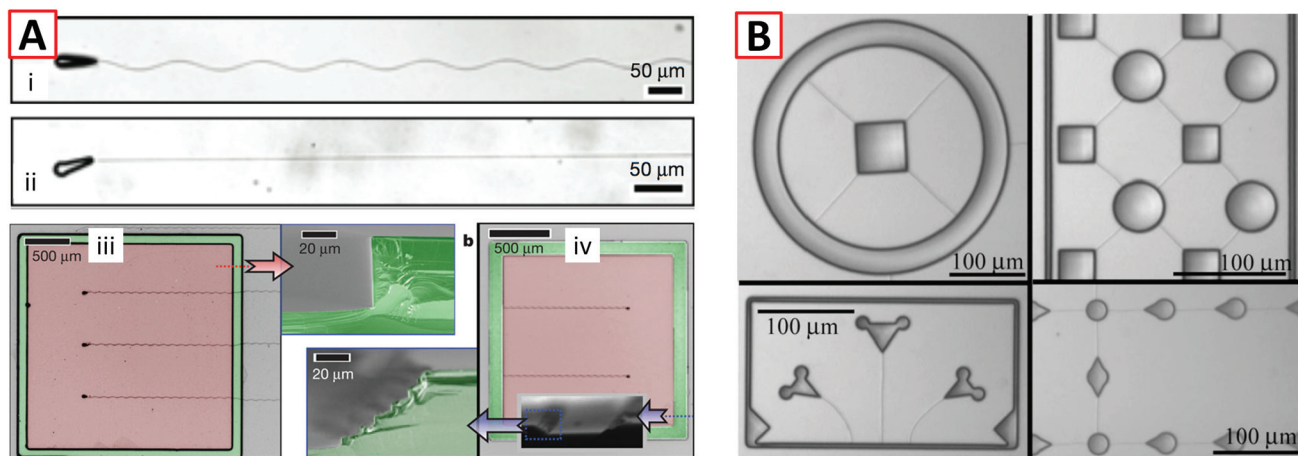


Fig. 8 CVD-based multidirectional crack patterns. (A) Microscopic images show crack propagation and termination in a Si₃N₄ film. Cracks in the Si₃N₄ film penetrated deep into the Si substrate, resulting in (i) oscillating (without the SiO₂ interlayer) or (ii) linear (with the SiO₂ interlayer) crack patterns. Propagating cracks were difficult to terminate (iii) at the simple trench structure because of crack penetration into the substrate, but they were successfully terminated (iv) at the multilevel stair-like microstructures. Interestingly, the crack patterns in the Si₃N₄ film were multidirectional, but the directional freedom can be constrained by adjusting the crystallographic orientation of the Si substrate. Reproduced with permission.³⁵ (B) Various multidirectional crack patterns created in a SiO₂ layer on a prefabricated Si substrate. Notched microstructures in the Si wafer controlled the crack patterns. Notably, the cracks in the SiO₂ thin films did not penetrate the substrate, showing constraint-free multidirectional crack patterns. Reproduced with permission.⁵⁸



However, it seems difficult to obtain CVD-based crack patterns without multiple, complex fabrication processes, including Si etching and thin film deposition. Moreover, the crack patterns were quite susceptible to unwanted cracking because every sharp tip, including molecular level defects and impurities, may initiate cracks.

5.3. Crack-photolithography technique for constraint-free multidirectional cracks

Most recently, Kim *et al.* developed an innovative cracking-assisted nanofabrication method, so-called crack-photolithography, that can produce multidirectional and arbitrarily shaped crack patterns at both the micro- and nano-scale using only the standard photolithography process (Fig. 9).³⁸ First, a photomask with triangular and round microstructures was used for selectively UV-exposing a 10 μm -thick SU-8 film coated on a Si wafer. Then the SU-8 pattern was immersed in an SU-8 developer solution to simultaneously fabricate micro-patterns and nanoscale crack patterns (Fig. 9A). To apply the necessary tensile stress for cracking during the development process, they produced crosslinking gradients in the SU-8 patterns along the normal direction to the substrate by simply eliminating the i-line UV filters. This novel process formed a relatively stiff SU-8 cluster (elastic layer) on top of a coarsely cured SU-8 underlayer (viscoelastic layer),⁸⁷ which enabled accurate crack control in the stiff top layer regulated by the underlayer creep.^{88,89} That is, the top and bottom layers

consisted of a monolithic material with an inhomogeneous crosslinking density along the normal direction to the substrate. Consequently, an isotropic tensile stress was naturally applied during the development process for micropatterning, because the coarsely crosslinked underlayer expanded more than the top brittle layer owing to the mismatch in the swelling coefficients according to the crosslinking density.⁹⁰ This isotropic tensile stress was concentrated at the sharp tip points for crack initiation, and then the cracks were simultaneously propagated in every direction without bias toward a specific direction within the elastic layer (Fig. 9B). In addition, they adopted a double-photomask process to locally control the material properties of the SU-8, such as the fracture toughness, and perfectly prevented unwanted cracking even when sharp notches were present. Thus, crack patterns were selectively produced only in the single-exposure region because the double-exposure regions can be further strengthened by the second exposure.⁹¹ Fig. 9C summarizes the controllability of the crack-photolithography technique: (1) no crack patterns were obtained using a round-round combination; (2) a straight crack pattern was obtained using a notch-round one; (3) a straight crack pattern was obtained by merging two counter-propagating cracks using a notch-notch one; and (4) no crack patterns appeared regardless of the microstructure shapes when the double-exposure process was used. By varying the crack control factors, Kim *et al.* fabricated various mixed-scale micro/nanopatterns using the single- (Fig. 9D) or double-

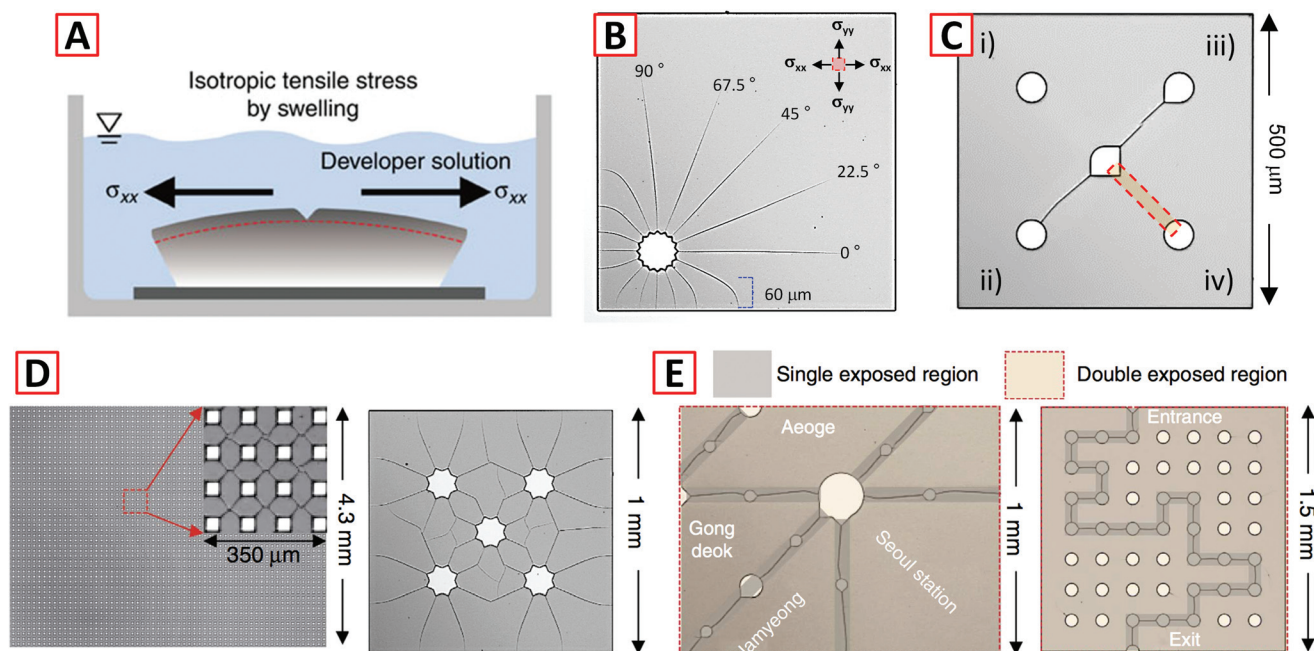


Fig. 9 Constraint-free multidirectional crack patterns during photolithography-based microfabrication. (A) Isotropic and controllable tensile stress was spontaneously applied during development of the photoresist (SU-8). (B) Isotropic nature of the tensile stress and SU-8 films enabled generation of perfect multidirectional crack patterns. (C) The crack photolithography technique controlled not only the local stress fields but also the local material strength by using additional photomasks, as shown in the four cracking cases (i, ii, iii, and iv). Various multidirectional crack patterns were produced by the (D) single- or (E) double-photomask process. Notably, crack patterns were localized in the single-exposure region, but no unwanted cracks were generated in the double-exposure region even when sharp tips were present. Reproduced with permission.³⁸



exposure process (Fig. 9E). For example, the Seoul metro map was replicated by crack patterns (nanopatterns) that were selectively produced only along the single-exposure regions to connect micropatterned metro stations.

Notably, crack photolithography enabled remarkable advances in crack control compared to previous crack lithography techniques. First, an isotropic, controllable tensile stress was spontaneously applied to an amorphous, homogeneous, and monolithic photoresist (*e.g.*, SU-8) by swelling during the development process. This allowed comprehensive control of the crack directions and dimensions during crack-photolithography, which resulted in fabrication of well-organized, size-controllable, constraint-free, and multidirectional crack patterns. Second, the crack patterns were selectively produced only in predetermined single-exposure regions by blocking any unwanted cracks. In fact, unwanted crack generation was the biggest challenge and should be addressed to increase the production yield and reproducibility of previous crack lithography techniques. Crack-photolithography, however, fully resolved the critical issues by spatiotemporally adjusting the fracture toughness of the SU-8 film, thereby improving the quality and reliability of the micro/nanoscale crack patterns and their applications. Third, crack-photolithography requires no additional fabrication processes or equipment to produce nanoscale crack patterns over a large-scale wafer except for the standard microfabrication process (photolithography), and hence multiscale micro/nanopatterns can be easily fabricated in a cost- and time-effective manner.

6. Applications of the crack patterns

Crack lithography techniques have demonstrated their ability to produce micro/nanopatterns at high resolution over a large-

scale substrate using facile fabrication procedures and simple, inexpensive facilities compared to conventional methods such as EBL, FIB lithography, and MEMS-based techniques. In particular, cracking can open new surfaces having characteristics unlike those of the existing surfaces and/or increase the surface area in a confined volume, so there is high potential to use cracks for developing new functional materials and devices. In this section, we review recent advances in novel applications of crack lithography techniques in various research fields, including biological assays, micro/nanofluidic devices, nanowire-integrated devices, and sensory systems.

6.1. Cellular and biomolecular patterning platform

First of all, unidirectional crack lithography techniques based on thin film and elastomer systems can pattern cellular adhesive molecules (*i.e.*, an extracellular matrix, ECM) by stretching and cracking a uniformly coated surfactant layer (Pluronic F108).³³ Because the surfactant can prevent attachment of ECMs to a PDMS substrate, the unidirectional crack patterns allowed selective coating of ECMs by opening fresh and surfactant-free PDMS surfaces, which eventually enabled selective patterning of C2C12 myoblasts only along the ECM areas (Fig. 10A and B). In addition, the cellular morphology of the attached C2C12 cells was aligned along the crack patterns by repeated stretching and relaxation cycles of the strain because the cells can sense micro/nanoscale topographical features (Fig. 10C). Reconfigurable cellular patterning and manipulation were considered essential techniques to investigate cellular responses in dynamic environments during cell growth and differentiation. Typically, however, their use was limited by the complex fabrication steps required to prepare the selective cellular adhesive substrates. Therefore, micro/nanopatterns based on crack lithography seem to be quite

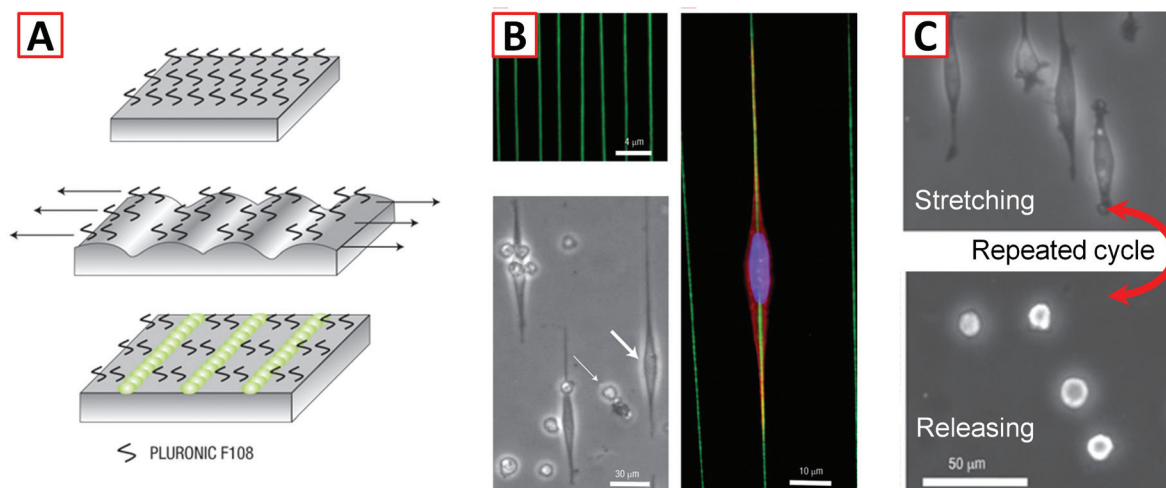


Fig. 10 Application of crack patterns for biomolecular/cellular patterning and analysis. (A) Surfactant layer (Pluronic F108) was uniformly coated on a PDMS substrate, followed by stretching (cracking) process to create a surfactant-free PDMS surface for selective coating with cellular adhesive molecules. (B) Microscopic images show the patterned fluorescent biomolecules and C2C12 myoblast cells. (C) Repeated stretch and release cycles were periodically applied to characterize morphological features of the cells in a dynamic cellular environment. Reproduced with permission.³³



effective for conducting rapid, low-cost biological assays because the crack patterns can be readily converted to micro/nanoscale cellular and/or biomolecular patterns over large areas (more than several centimeters squared) using simple procedures and inexpensive equipment. Given these advantages, crack-lithography-based bioassay platforms would provide scientists with significant insights into the fundamental relationships between cells and their environments, including cellular viability, proliferation, migration, and signal transduction.^{92,93}

6.2. Integrated micro/nanofluidic device

Another important application of crack lithography is nanofluidic devices, the characteristic channel dimensions of which are comparable to those of small biomolecules and ions, including proteins and deoxyribonucleic acid (DNA). Typically, it has been challenging to integrate nanochannels with microfluidic devices on the same surface using conventional techniques because microfabrication and nanofabrication were performed in series with low compatibility (e.g., photolithography and EBL). For this reason, the multiscale micro/nanopatterns produced by crack lithography techniques have been highlighted as the most appropriate alternative for fabricating integrated micro/nanofluidic devices. Here, we introduce two types of integrated micro/nanofluidic devices that were developed using different crack lithography techniques.

First, Huh *et al.* generated unidirectional nanoscale crack patterns on an oxidized PDMS substrate and integrated the patterns with another PDMS layer having microchannels.³⁶ The oxide layer on the PDMS substrate was stretched sufficiently to produce many unidirectional cracks that were perpendicularly aligned with the applied tensile strain, which is essentially the procedure demonstrated in Fig. 10. Then the nanoscale crack patterns were replicated using a UV-curable epoxy that was again used as a master for soft lithography to fabricate PDMS-based nanochannels. After the soft lithography, the PDMS nanopatterns were bonded with another microfabricated PDMS layer (microchannels) to form a liquid-tight, size-tunable micro/nanochannel network to be applied for linearization (stretching) of coiled DNA. Although they established a new paradigm for fabricating integrated micro/nanofluidic devices using crack lithography, it seems to be difficult to accurately control the nanochannel position and number owing to the lack of stress-modulating microstructures. In addition, the nanochannels and microchannels were prepared separately in different PDMS layers, so additional alignment steps were essential. Moreover, there seem to be potential compatibility issues with complex micro/nanofluidic channel designs.

Second, recently Kim and Kim developed an advanced technique for fabricating integrated micro/nanofluidic devices by adopting crack photolithography, which can simultaneously generate multiscale micro/nanopatterns on the same surface (Fig. 11).⁵⁹ Because the micropatterns and nanopatterns (cracks) were fabricated on the same surface using a single

photolithography process, they can be automatically aligned and integrated from the early design stage (Fig. 11A). In addition, the dimensions, position, and number of the cracks were accurately controlled by employing stress-modulating microstructures and adjusting the process parameters of crack photolithography (Fig. 11B), which enabled manipulation of the transport of small molecules in microchannels at will (Fig. 11C). Therefore, a microfluidic channel network can be readily integrated with nanochannel arrays that can function as diffusion-controlling but convection-suppressing nanostructures in microfluidic devices with highly robust, accurate, and expandable diffusion control. As an application of such micro/nanofluidic devices, they characterized the cell-to-cell communication of synthetic bacterial cells and found that the cells can chemically communicate with each other by extracellular diffusive microenvironments that were completely engineered using the nanochannel array (Fig. 11D). Hence, crack photolithography would facilitate the development of unprecedented micro/nanofluidic devices for a wide range of nanofluidic and biological applications.

6.3. Nanowire-integrated gas sensor

Crack lithography was also widely used to fabricate nanowire-integrated devices to detect and monitor gaseous environments.^{94,95} One-dimensional nanowires have generally been intensively studied because of their ultrahigh surface-area-to-volume ratio, which enables detection of a few gas molecules with a faster response time, lower power consumption, and greater portability than conventional sensors based on 2-D thin films.⁹⁶ However, current fabrication approaches still rely on conventional bottom-up^{97,98} or top-down^{99,100} techniques. Therefore, crack lithography techniques for nanoscale patterning have high potential to replace the current top-down or bottom-up approaches because they not only produce multiscale micro/nanopatterns on the same surface but also accurately control the dimensions and directions of the nanowires up to a few tens of nanometers.^{35,38}

For instance, Jebri *et al.* fabricated a bow-tie-like micropattern in a photoresist film on a Si wafer to create a nanoscale crack pattern in the middle, weakest point of the photoresist by thermal cycling to induce a tensile stress.^{42,94,95} As shown in Fig. 12A and B, the nanocrack micropattern served as a masking structure during deposition of a metallic nanowire material (zinc oxide, ZnO) by sputtering, followed by a lift-off process to remove the excess metal on the photoresist mask. Because the micropatterns and nanowires (cracks) were produced on the same surface, the nanowires were automatically aligned and connected to microelectrodes for signal transduction (Fig. 12C). The ZnO nanowires were used to detect oxygen (O₂) gas at partial pressures from 0.2 to 1000 mbar. Under UV illumination, the O₂ gas was changed to reactive O₂ species such as O²⁻, O₂⁻, and O⁻, which were easily adsorbed into the ZnO nanowire surface to form O₂ vacancies in the nanowires even at room temperature.¹⁰¹ Thus, the resistivity of the nanowires can be sensitively and selectively changed according to the O₂ partial pressure.^{95,101,102} Increasing the O₂ partial



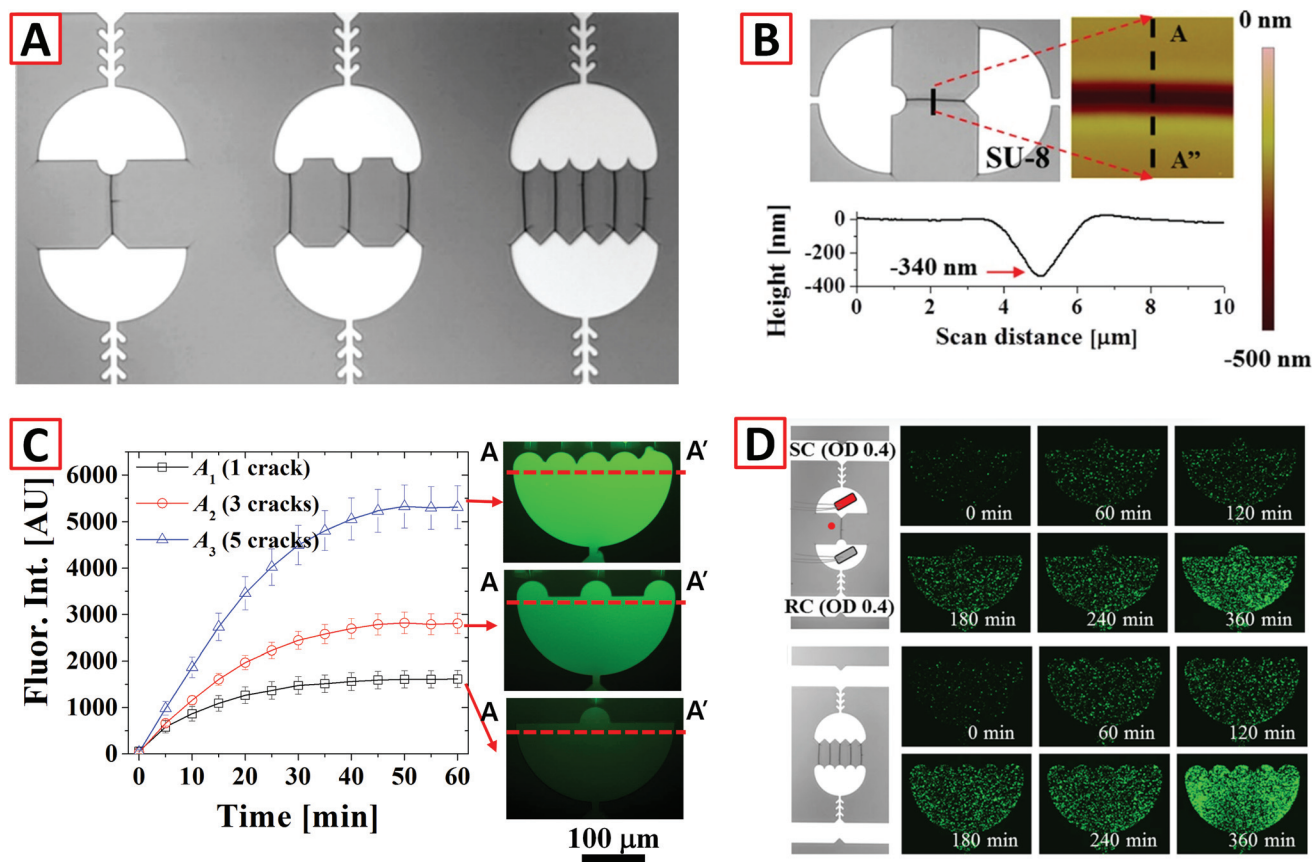


Fig. 11 Integrated micro/nanofluidic devices for controlling diffusion transport of biomolecules. (A) Microscopic image showing SU-8 micropatterns and nanoscale crack arrays fabricated on the same surface. (B) Microscopy and atomic force microscopy images showing the crack dimensions, which are nanoscale in height but microscale in width. (C) Diffusion rate of a fluorescent molecule was linearly controlled according to the nanochannel (crack) numbers. (D) Diffusion-controlled micro/nanofluidic device enabled characterization of the genetic induction and cell-to-cell signaling of synthetically engineered bacterial cells. Notably, the expression of the green fluorescent protein was accurately engineered by varying the length and number of nanochannels. Reproduced with permission.⁵⁹

pressure decreased the current passing through the nanowires, as shown in Fig. 12D. The principal sensor characteristics, such as the sensitivity, selectivity, and dynamic range, were superior to those of a control nanowire-integrated device fabricated by a conventional expensive nanofabrication technique (EBL).⁹⁴ Therefore, the crack lithography technique made it successful to fabricate nanowire-integrated microchips in a high-throughput and facile manner by batch processing. Because the produced gas sensors enabled quantitative detection of a few gas molecules, crack lithography techniques could be applied to fabricate other types of nanowires⁹⁵ by using various substrates, including flexible films.^{103,104}

6.4. Multi-functional mechanosensor

Increasing attention has been given to the development of multifunctional mechanosensors that can detect human motions, including moving, typing, talking, breathing, and even the heart beating, by being attached to the skin or clothes.^{105,106} However, it has been difficult for state-of-the-art vibration/strain sensors based on thin films to fully satisfy the technical demands such as ultrahigh mechanosensitivity with

both high flexibility and high durability in repeated bending and/or stretching cycles. Recently, Kang *et al.* reported crack-lithography-based multifunctional mechanosensors inspired by the spider sensory system (Fig. 13A).³⁹ The mechanosensors used reversible disconnection and reconnection processes based on zip-like nanoscale crack junctions that can transduce small mechanical changes (*i.e.*, strain) into large electrical signals (*i.e.*, resistivity). To fabricate the nanoscale crack sensor, a platinum (Pt) thin layer was deposited on a flexible polyurethane acrylate (PUA) layer on a polyethylene terephthalate (PET) film by sputtering. Both the PUA and PET polymers were flexible enough to bend or stretch without cracking, but the brittle Pt layer cracked under even a small tensile stain, so a number of unidirectional crack patterns formed in the metallic layer (Fig. 13B).

Similar to the case of cracks in a brittle film on an elastomeric substrate presented above, the crack density and dimensions were controlled by varying the bending radius of curvature, which determines the applied tensile stress. After the crack patterns were created, the nanoscale crack sensor was connected to metal electrodes to transduce the resistivity



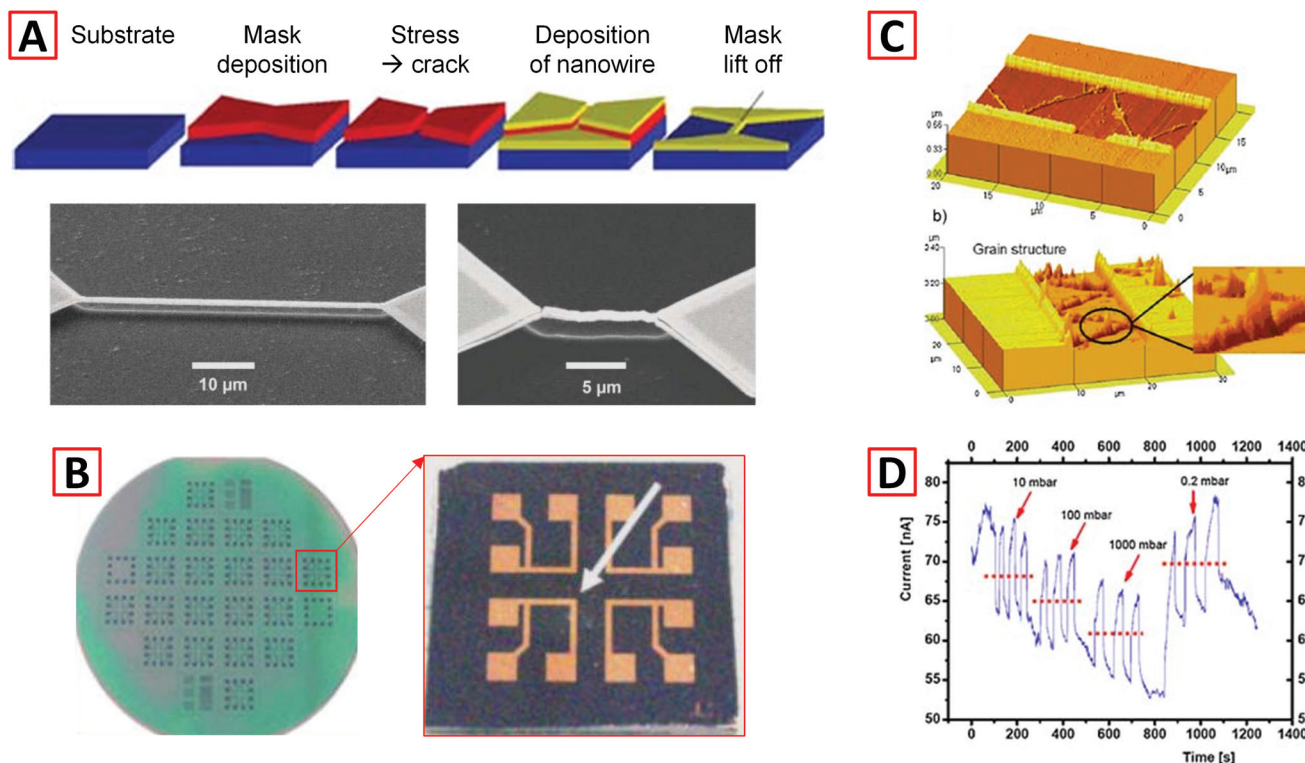


Fig. 12 Nanowire-integrated microchips for detecting gas molecules. (A) Schematic showing fabrication procedures for the nanowires using crack lithography. SEM images at the bottom show a fabricated metal nanowire that connects micropatterned metal pads. (B) Multiple nanowire-integrated devices on a wafer scale obtained using batch fabrication by crack lithography. (C) Atomic force microscopy images showing zigzag oriented Ti nanowires between two micropatterns. (D) Current signals detected by ZnO nanowires under different partial pressures of O₂ gas. Reproduced with permission.^{94,95}

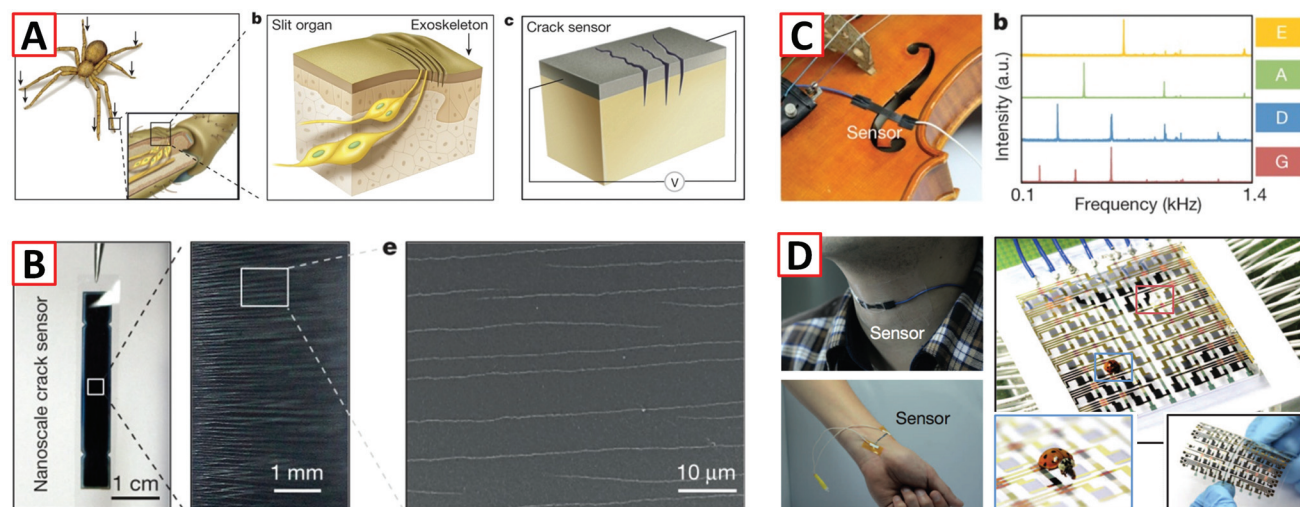


Fig. 13 Multifunctional nanocrack-based mechanosensors inspired by the spider. (A) Schematic showing the similarity between the spider's sensory system and the nanocrack sensors. (B) Nanocracks were fabricated by bending Pt thin films on a PUA substrate attached to a PET film. Inset SEM image shows a number of unidirectional nanocracks produced in the Pt layer. (C) Nanocrack sensor was attached to the curved surface of a violin to measure sound waves from the violin strings. (D) Nanocrack sensor detected various mechanical signals such as pressure and vibration signals while being attached to human skin or curved surfaces because of its flexibility. Reproduced with permission.³⁹



changes into current signals during motion detection. Interestingly, the nanoscale crack sensor was unprecedentedly sensitive to axial elongation and compression, because the resistivity of the cracked film was dramatically increased or decreased according to disconnection or reconnection events at the cracked surfaces. Thus, the sensitivity of the nanoscale crack sensor was highly enhanced by the disconnection–reconnection events, whereas the metallic film without crack patterns, which is the same as that in conventional strain gages, was not as sensitive as the nanoscale crack sensor owing to the absence of disconnection–reconnection events. The nanoscale crack sensor, which had a radius of curvature of 1 mm during crack generation, exhibited 450-fold higher sensitivity than the normal sensor without crack patterns at 0.5% strain. Furthermore, the nanoscale crack sensor showed high reproducibility and durability even for 5000 cyclic fatigue tests because the brittle film was already cracked, and the other polymeric layers were quite flexible; an inflexible and uncracked sensor is typically susceptible to fatigue cracks.

As an application of mechanosensors based on nanoscale cracks, a 5 cm × 5 cm sensing network consisting of 8 × 8 arrays, the individual sensing units of which are 2 mm × 2 mm in size, was fabricated and attached to a violin for real-time monitoring of sound waves. As shown in Fig. 13C, the mechanosensors accurately distinguished the vibration from the G, D, A, and E strings, which showed different vibrational amplitudes and frequencies. Based on the calibration of the basic

sound waves, the sensor successfully converted the mechanical vibration during a performance of Elgar's *Salut d'Amour* into digital signals by time sequential and *in situ* monitoring of the sound waves. Additionally, Kang *et al.* demonstrated that multifunctional crack sensors can detect various mechanical signals from a small insect, speech patterns, and even heart-beat rates (Fig. 13D). Therefore, crack lithography has high potential for application to various mechanosensors or piezo-resistive actuators, including health-care devices, thin film actuators, and real-time environmental monitoring devices with high mechanosensitivity, controllability, and durability.¹⁰⁷

7. Conclusions

Over the last few decades, a number of experimental and theoretical approaches have been attempted to understand and manipulate nanoscale cracks in order to produce well-defined small patterns with greatly reduced cost and time consumption compared to conventional nanofabrication. To provide a brief overview of the developmental history of crack lithography techniques, Table 1 summarizes representative crack lithography techniques and their features. Notably, the crack patterns depend strongly on the cracking mechanism, stress source, material properties of the thin films and substrates, and fabrication process and equipment. In addition, it

Table 1 Summary of representative crack lithography techniques

Ref.	Drying-mediated cracks ⁶⁷	Strain-controlled cracks ³⁶	CVD-based cracks ³⁵	Photolithography-based cracks ³⁸
Crack patterns	Randomly oriented	Unidirectional	Constrained multidirectional	Constraint-free multidirectional
Generation mechanism	Volume shrinkage of wetted particle during drying process	Mismatch of elastic modulus between thin film and substrate layer	Mismatch of thermal expansion between thin film and substrate layers	Mismatch of swelling volume in differently cross-linked photoresist
Material	Polystyrene monolayer on Si substrate	Oxide film on PDMS substrate	Si ₃ N ₄ film on Si substrate	SU-8 film on Si substrate
Stress source	Drying (isotropic tensile stress)	Mechanical stretching (uniaxial tensile stress)	Residual film stress (isotropic tensile stress)	Swelling (isotropic tensile stress)
Crack initiation	Global control (random position)	Global control (random position)	Local control (notched position)	Local control (notched position)
Crack propagation	Random (depending on the drying condition)	Anisotropic depending on the direction of applied uniaxial stress	Anisotropic depending on crystallographic orientation of substrate	Isotropic without dependency on substrate
Crack termination	Uncontrollable	Uncontrollable	Spatial control (stair-like microstructure)	Spatiotemporal control (exposure energy and development time)
Dimension of crack	W = several microns H = several microns (uncontrollable)	W = 500–2000 nm H = ~100 nm (globally controllable by strain rate)	W = ~100 nm H = ~1000 nm (uncontrollable)	W = 300–3000 nm H = 30–300 nm (locally controllable by exposure energy)
Fabrication process	(1) Monolayer coating (2) Drying process	(1) Preparation of PDMS slab (2) Oxide layer deposition (3) Applying mechanical stress	(1) Photolithography (2) SiO ₂ deposition (3) SiO ₂ reactive ion etching (RIE) (4) Si deep-RIE (5) Si ₃ N ₄ deposition	(1) Photolithography
Required equipment	Desiccator	Mask aligner, O ₂ plasma, stretching jig	Mask aligner, RIE-etcher, DRIE etcher, LPCVD	Mask aligner
Application	Functional surface, sensor	Functional surface, nanofluidic device, nanowire, sensor, actuator		



is important to control the dimensions and directionality of cracks during their initiation, propagation, and termination. Consequently, these factors determine applications of the cracks.

Initially, most research focused on investigation of cracking phenomena occurring in various microfabrication processes to identify the underlying fundamentals of nanoscale cracks. Skjeltorp and Meakin observed randomly oriented cracks in a self-assembled polystyrene monolayer and found that cracking was due to volume shrinkage of individual polystyrene spheres during a continuous drying process.⁶⁷ Such drying-mediated random cracks were widely used for producing functional surfaces or enhancing surface characteristics because they can create new surface areas.⁶⁸

Huh *et al.* and other researchers applied uniaxial strain/stress to impose a directional alignment on the randomly oriented cracks.³⁶ The strain-controlled cracks were fabricated by simple uniaxial stretching or bending without expensive micro/nanofabrication equipment. In addition, unidirectional cracks can produce a number of nanoscale straight lines with controllable density and dimensions. Thus, the crack patterns were used for biological patterning platforms, nanofluidic devices, nanowire-integrated devices, and even multifunctional mechanosensors. However, control of the axial strain or stress was limited to a few directions, and hence various mechanisms for applying isotropic stresses were developed to further increase the directional controllability.

Next, Nam *et al.* and other researchers used the residual film stress generated in various CVD processes, including those of widely used dielectric thin films such as SiO₂ and Si₃N₄.³⁵ The residual film stress, which is isotropic and homogeneous, was induced by the mismatch in thermal expansion between the thin films and substrates, and the nominal stress was locally concentrated or released by stress-modulating microstructures. That is, stress modulators such as notches and open boundaries played an important role in initiating and terminating cracks at predetermined positions. Furthermore, multidirectional crack patterns were fabricated by batch fabrication so that a number of nanopatterns (cracks) can be simultaneously created over a large-scale wafer, enabling high-throughput, cost-efficient nanofabrication. However, the cracking process involves expensive equipment and multiple complex fabrication processes, including photolithography, SiO₂/Si₃N₄ CVD, RIE, and even DRIE. Moreover, the directional freedom can be limited by the substrate constraints when the cracks in the thin films penetrated deep into a substrate having a crystallographic orientation.

Subsequently, to overcome these limitations, a constraint-free, single-photolithography-based cracking mechanism was developed by Kim *et al.*³⁸ In particular, the stress was applied using spontaneous isotropic swelling phenomena during photoresist development; therefore, no additional nanofabrication processes were required, except for the standard microfabrication (photolithography) process. In addition, the crack dimensions and pathways were completely engineered by adjusting the UV exposure energy, the intensity of which can

be spatiotemporally controlled using additional photomasks with a resolution of several microns. Therefore, constraint-free multidirectional crack patterns with locally controllable dimensions and directions can be facilely produced throughout a large-scale wafer. Owing to the high crack controllability, multidirectional crack patterns can cover all possible applications of unidirectional cracks with increased patterning directions and density.

In conclusion, state-of-the-art crack lithography techniques enabled us to fabricate nanoscale patterns with both high resolution and high throughput, which have been difficult to achieve simultaneously using conventional nanofabrication techniques. In particular, crack lithography techniques have accelerated the use of nanotechnology in individual laboratories even where expensive facilities and particular fabrication skills were unavailable, resulting in the development of novel and specific applications. However, further efforts should be made to expand the applicable materials, because the cracking mechanism seems to differ substantially, depending on the specifications of the material (*i.e.*, for ceramics, metals, polymers, and elastomers). In addition, downsizing the nanoscale cracks toward a single-molecule-level disassembly will open new opportunities not only for the development of advanced metamaterials and novel nanodevices but also for use as an accurate experimental platform to study the fundamental physics and mechanics of material fractures in the near future.

Acknowledgements

This work was supported by the National Research Foundation of Korea (NRF) grant funded by the Korea government (MSIP) (NRF-2014R1A2A1A10050431).

References

- 1 C. D. O'Connell, M. J. Higgins, S. E. Moulton and G. G. Wallace, *J. Mater. Chem. C*, 2015, **3**, 6431–6444.
- 2 S. S. Yao and Y. Zhu, *Adv. Mater.*, 2015, **27**, 1480–1511.
- 3 K. Kim, J. Guo, X. Xu and D. L. Fan, *Small*, 2015, **11**, 4037–4057.
- 4 B. Z. Tian, X. L. Zheng, T. J. Kempa, Y. Fang, N. F. Yu, G. H. Yu, J. L. Huang and C. M. Lieber, *Nature*, 2007, **449**, 885–889.
- 5 A. Rinaldi, P. Peralta, C. Friesen, D. Nahar, S. Licoccia, E. Traversa and K. Sieradzki, *Small*, 2010, **6**, 528–536.
- 6 M. Schwartzman, M. Palma, J. Sable, J. Abramson, X. A. Hu, M. P. Sheetz and S. J. Wind, *Nano Lett.*, 2011, **11**, 1306–1312.
- 7 L. M. Dai, D. W. Chang, J. B. Baek and W. Lu, *Small*, 2012, **8**, 1130–1166.
- 8 Z. Y. Wang and Z. H. Dai, *Nanoscale*, 2015, **7**, 6420–6431.
- 9 M. Altissimo, *Biomicrofluidics*, 2010, **4**, 026503.
- 10 A. A. Tseng, K. Chen, C. D. Chen and K. J. Ma, *IEEE Trans. Electron Packag.*, 2003, **26**, 141–149.



- 11 H. He, J. C. She, Y. F. Huang, S. Z. Deng and N. S. Xu, *Nanoscale*, 2012, **4**, 2101–2108.
- 12 R. Thakar, A. E. Weber, C. A. Morris and L. A. Baker, *Analyst*, 2013, **138**, 5973–5982.
- 13 Z. M. Han, M. Vehkamäki, M. Leskela and M. Ritala, *Nanotechnology*, 2014, **25**, 115302.
- 14 J. Kim, Y. U. Lee, B. Kang, J. H. Woo, E. Y. Choi, E. S. Kim, M. Gwon, D. W. Kim and J. W. Wu, *Nanotechnology*, 2013, **24**, 015306.
- 15 P. D. Yang, Z. J. Zhang, J. T. Hu and C. M. Lieber, *Mater. Res. Soc. Symp. Proc.*, 1997, **438**, 593–598.
- 16 C. L. Shen, Y. Peng, K. H. Wang and Q. Zhou, *Radiat. Phys. Chem.*, 2013, **83**, 8–14.
- 17 V. R. Manfrinato, L. H. Zhang, D. Su, H. G. Duan, R. G. Hobbs, E. A. Stach and K. K. Berggren, *Nano Lett.*, 2013, **13**, 1555–1558.
- 18 L. J. Guo, *Adv. Mater.*, 2007, **19**, 495–513.
- 19 C. Peroz, S. Dhuey, M. Cornet, M. Vogler, D. Olynick and S. Cabrini, *Nanotechnology*, 2012, **23**, 015305.
- 20 L. J. Guo, *J. Phys. D: Appl. Phys.*, 2004, **37**, R123–R141.
- 21 P. D. Yang, G. Wirnsberger, H. C. Huang, S. R. Cordero, M. D. McGehee, B. Scott, T. Deng, G. M. Whitesides, B. F. Chmelka, S. K. Buratto and G. D. Stucky, *Science*, 2000, **287**, 465–467.
- 22 Y. C. Wang and J. Y. Han, *Lab Chip*, 2008, **8**, 392–394.
- 23 C. H. Duan and A. Majumdar, *Nat. Nanotechnol.*, 2010, **5**, 848–852.
- 24 R. Karnik, R. Fan, M. Yue, D. Y. Li, P. D. Yang and A. Majumdar, *Nano Lett.*, 2005, **5**, 943–948.
- 25 H. J. Zeng, Z. L. Wang and A. D. Feinerman, *Nanotechnology*, 2006, **17**, 3183–3188.
- 26 A. Pimpin and W. Srituravanich, *Eng. J.*, 2011, 37–55.
- 27 J. Haneveld, H. Jansen, E. Berenschot, N. Tas and M. Elwenspoek, *J. Micromech. Microeng.*, 2003, **13**, S62–S66.
- 28 C. H. Duan, W. Wang and Q. Xie, *Biomicrofluidics*, 2013, **7**, 026501.
- 29 P. Mao and J. Y. Han, *Lab Chip*, 2005, **5**, 837–844.
- 30 M. B. Stern, M. W. Geis and J. E. Curtin, *J. Vac. Sci. Technol., B*, 1997, **15**, 2887–2891.
- 31 D. J. Green, R. Tandon and V. M. Sglavo, *Science*, 1999, **283**, 1295–1297.
- 32 K. T. Leung, L. Jozsa, M. Ravasz and Z. Neda, *Nature*, 2001, **410**, 166–166.
- 33 X. Y. Zhu, K. L. Mills, P. R. Peters, J. H. Bahng, E. H. Liu, J. Shim, K. Naruse, M. E. Csete, M. D. Thouless and S. Takayama, *Nat. Mater.*, 2005, **4**, 403–406.
- 34 M. P. Rao, A. J. Sanchez-Herencia, G. E. Beltz, R. M. McMeeking and F. F. Lange, *Science*, 1999, **286**, 102–105.
- 35 K. H. Nam, I. H. Park and S. H. Ko, *Nature*, 2012, **485**, 221–224.
- 36 D. Huh, K. L. Mills, X. Y. Zhu, M. A. Burns, M. D. Thouless and S. Takayama, *Nat. Mater.*, 2007, **6**, 424–428.
- 37 A. Yuse and M. Sano, *Nature*, 1993, **362**, 329–331.
- 38 M. Kim, D. Ha and T. Kim, *Nat. Commun.*, 2015, **6**, 6247.
- 39 D. Kang, P. V. Pikhitsa, Y. W. Choi, C. Lee, S. S. Shin, L. F. Piao, B. Park, K. Y. Suh, T. I. Kim and M. Choi, *Nature*, 2014, **516**, 222–226.
- 40 B. E. Alaca, C. Ozcan and G. Anlas, *Nanotechnology*, 2010, **21**, 055301.
- 41 O. Sardan, A. D. Yalcinkaya and B. E. Alaca, *Nanotechnology*, 2006, **17**, 2227–2233.
- 42 R. Adelung, O. C. Aktas, J. Franc, A. Biswas, R. Kunz, M. Elbahri, J. Kanzow, U. Schurmann and F. Faupel, *Nat. Mater.*, 2004, **3**, 375–379.
- 43 B. C. Kim, T. Matsuoka, C. Moraes, J. X. Huang, M. D. Thouless and S. Takayama, *Sci. Rep.*, 2013, **3**, 3027.
- 44 B. C. Kim, C. Moraes, J. X. Huang, T. Matsuoka, M. D. Thouless and S. Takayama, *Small*, 2014, **10**, 4020–4029.
- 45 J. Marthelot, B. Roman, J. Bico, J. Teisseire, D. Dalmas and F. Melo, *Phys. Rev. Lett.*, 2014, **113**, 085502.
- 46 A. Nakahara and Y. Matsuo, *Phys. Rev. E: Stat. Phys., Plasmas, Fluids, Relat. Interdiscip. Top.*, 2006, **74**, 045102.
- 47 W. H. Koo, S. M. Jeong, F. Araoka, K. Ishikawa, S. Nishimura, T. Toyooka and H. Takezoe, *Nat. Photonics*, 2010, **4**, 222–226.
- 48 N. Bowden, S. Brittain, A. G. Evans, J. W. Hutchinson and G. M. Whitesides, *Nature*, 1998, **393**, 146–149.
- 49 H. Q. Jiang, D. Y. Khang, J. Z. Song, Y. G. Sun, Y. G. Huang and J. A. Rogers, *Proc. Natl. Acad. Sci. U. S. A.*, 2007, **104**, 15607–15612.
- 50 C. M. Stafford, C. Harrison, K. L. Beers, A. Karim, E. J. Amis, M. R. Vanlandingham, H. C. Kim, W. Volksen, R. D. Miller and E. E. Simonyi, *Nat. Mater.*, 2004, **3**, 545–550.
- 51 X. Chen and J. Yin, *Soft Matter*, 2010, **6**, 5667–5680.
- 52 S. Chung, J. H. Lee, M. W. Moon, J. Han and R. D. Kamm, *Adv. Mater.*, 2008, **20**, 3011–3016.
- 53 K. Efimenko, M. Rackaitis, E. Manias, A. Vaziri, L. Mahadevan and J. Genzer, *Nat. Mater.*, 2005, **4**, 293–297.
- 54 P. Kim, M. Abkarian and H. A. Stone, *Nat. Mater.*, 2011, **10**, 952–957.
- 55 J. B. Kim, P. Kim, N. C. Pegard, S. J. Oh, C. R. Kagan, J. W. Fleischer, H. A. Stone and Y. L. Loo, *Nat. Photonics*, 2012, **6**, 327–332.
- 56 B. Li, Y. P. Cao, X. Q. Feng and H. J. Gao, *Soft Matter*, 2012, **8**, 5728–5745.
- 57 E. B. Gorokhov, V. Y. Prinz, A. G. Noskov and T. A. Gavrilova, *J. Electrochem. Soc.*, 1998, **145**, 2120–2131.
- 58 B. E. Alaca, H. Sehitoglu and T. Saif, *Appl. Phys. Lett.*, 2004, **84**, 4669–4671.
- 59 M. Kim and T. Kim, *Anal. Chem.*, 2015, **87**, 11215–11223.
- 60 R. Chantiwas, S. Park, S. A. Soper, B. C. Kim, S. Takayama, V. Sunkara, H. Hwang and Y. K. Cho, *Chem. Soc. Rev.*, 2011, **40**, 3677–3702.
- 61 B. C. Kim, C. Moraes, J. X. Huang, M. D. Thouless and S. Takayama, *Biomater. Sci.*, 2014, **2**, 288–296.
- 62 D. M. Robertson, D. Robertson and C. R. Barrett, *J. Biomech.*, 1978, **11**, 359–364.



- 63 T. Khatun, T. Dutta and S. Tarafdar, *Appl. Clay Sci.*, 2013, **86**, 125–128.
- 64 M. Mirkhalaf, A. K. Dastjerdi and F. Barthelat, *Nat. Commun.*, 2014, **5**, 3166.
- 65 R. Khandelwal and J. M. C. Kishen, *Int. J. Solids Struct.*, 2008, **45**, 6157–6176.
- 66 N. Vandenberghe, R. Vermorel and E. Villermaux, *Phys. Rev. Lett.*, 2013, **110**, 174302.
- 67 A. T. Skjeltorp and P. Meakin, *Nature*, 1988, **335**, 424–426.
- 68 K. D. M. Rao, R. Gupta and G. U. Kulkarni, *Adv. Mater. Interfaces*, 2014, **1**, 1400090.
- 69 J. C. Li, X. Gong, D. Wang and D. C. Ba, *Appl. Phys. A: Mater. Sci. Process.*, 2013, **111**, 645–651.
- 70 K. Luke, A. Dutt, C. B. Poitras and M. Lipson, *Opt. Express*, 2013, **21**, 22829–22833.
- 71 G. C. Hill, J. I. Padovani, J. C. Doll, B. W. Chui, D. Rugar, H. J. Mamin, N. Harjee and B. L. Pruitt, *J. Micromech. Microeng.*, 2011, **21**, 087001.
- 72 S. Mani and T. M. Saif, *Appl. Phys. Lett.*, 2005, **86**, 201903.
- 73 S. Mani and T. Saif, *Thin Solid Films*, 2007, **515**, 3120–3125.
- 74 O. Sardan, B. E. Alaca, A. D. Yalcinkaya, P. Boggild, P. T. Tang and O. Hansen, *Nanotechnology*, 2007, **18**, 375501.
- 75 X. H. Liu, Z. Suo, Q. Ma and H. Fujimoto, *Eng. Fract. Mech.*, 2000, **66**, 387–402.
- 76 A. C. Orifici, P. Wongwichit and N. Wiwatanawongsa, *Composites, Part A*, 2014, **66**, 218–226.
- 77 X. Zhang, K. S. Chen and S. M. Spearing, *Sens. Actuators, A*, 2003, **103**, 263–270.
- 78 Z. C. Xia and J. W. Hutchinson, *J. Mech. Phys. Solids*, 2000, **48**, 1107–1131.
- 79 D. Salac and W. Lu, *Comput. Mater. Sci.*, 2007, **39**, 849–856.
- 80 J. X. Huang, B. C. Kim, S. Takayama and M. D. Thouless, *J. Mater. Sci.*, 2014, **49**, 255–268.
- 81 K. L. Mills, X. Y. Zhu, S. C. Takayama and M. D. Thouless, *J. Mater. Res.*, 2008, **23**, 37–48.
- 82 H. Vandeparre, Q. H. Liu, I. R. Mineev, Z. G. Suo and S. P. Lacour, *Adv. Mater.*, 2013, **25**, 3117–3121.
- 83 Q. Zhuang, S. C. Warren, B. Baytekin, A. F. Demirors, P. P. Pillai, B. Kowalczyk, H. T. Baytekin and B. Grzybowski, *Adv. Mater.*, 2014, **26**, 3667–3672.
- 84 H. Schmid and B. Michel, *Macromolecules*, 2000, **33**, 3042–3049.
- 85 T. W. Odom, J. C. Love, D. B. Wolfe, K. E. Paul and G. M. Whitesides, *Langmuir*, 2002, **18**, 5314–5320.
- 86 O. Zohni, G. Buckner, T. Kim, A. Kingon, J. Maranchi and R. Siergiej, *J. Micromech. Microeng.*, 2007, **17**, 1042–1051.
- 87 M. Jamal, A. M. Zarafshar and D. H. Gracias, *Nat. Commun.*, 2011, **2**, 527.
- 88 J. Liang, R. Huang, J. H. Prevost and Z. Suo, *Exp. Mech.*, 2003, **43**, 269–279.
- 89 R. Huang, J. H. Prevost and Z. Suo, *Acta Mater.*, 2002, **50**, 4137–4148.
- 90 Z. Zhou, Q. A. Huang, W. H. Li, W. Lu, Z. Zhu and M. Feng, *IEEE Sens. J.*, 2007, 325–328, DOI: 10.1109/Icsens.2007.4388402.
- 91 S. Keller, G. Blagoi, M. Lillemose, D. Haefliger and A. Boisen, *J. Micromech. Microeng.*, 2008, **18**, 125020.
- 92 C. S. Chen, M. Mrksich, S. Huang, G. M. Whitesides and D. E. Ingber, *Science*, 1997, **276**, 1425–1428.
- 93 M. Thery, A. Jimenez-Dalmaroni, V. Racine, M. Bornens and F. Julicher, *Nature*, 2007, **447**, 493–496.
- 94 S. Jebril, M. Elbahri, G. Titazu, K. Subannajui, S. Essa, F. Niebelschutz, C. C. Rohlig, V. Cimalla, O. Ambacher, B. Schmidt, D. Kabiraj, D. Avasti and R. Adelung, *Small*, 2008, **4**, 2214–2221.
- 95 D. Gedamu, S. Jebril, A. Schuchardt, M. Elbahri, S. Wille, Y. K. Mishra and R. Adelung, *Phys. Status Solidi B*, 2010, **247**, 2571–2580.
- 96 F. Patolsky, G. Zheng and C. M. Lieber, *Nanomedicine*, 2006, **1**, 51–65.
- 97 A. Nerowski, J. Opitz, L. Baraban and G. Cuniberti, *Nano Res.*, 2013, **6**, 303–311.
- 98 C. O'Dwyer, M. Szachowicz, G. Visimberga, V. Lavayen, S. B. Newcomb and C. M. S. Torres, *Nat. Nanotechnol.*, 2009, **4**, 239–244.
- 99 Y. G. Sun, R. A. Graff, M. S. Strano and J. A. Rogers, *Small*, 2005, **1**, 1052–1057.
- 100 X. Yu, Y. C. Wang, H. Zhou, Y. X. Liu, Y. Wang, T. Li and Y. L. Wang, *Small*, 2013, **9**, 525–530.
- 101 N. M. Kiasari and P. Servati, *IEEE Electron Device Lett.*, 2011, **32**, 982–984.
- 102 M. Takata, D. Tsubone and H. Yanagida, *J. Am. Ceram. Soc.*, 1976, **59**, 4–8.
- 103 A. R. Madaria, A. Kumar, F. N. Ishikawa and C. W. Zhou, *Nano Res.*, 2010, **3**, 564–573.
- 104 C. H. Liu and X. Yu, *Nanoscale Res. Lett.*, 2011, **6**, 75.
- 105 S. P. Sane, A. Dieudonne, M. A. Willis and T. L. Daniel, *Science*, 2007, **315**, 863–866.
- 106 D. Son, J. Lee, S. Qiao, R. Ghaffari, J. Kim, J. E. Lee, C. Song, S. J. Kim, D. J. Lee, S. W. Jun, S. Yang, M. Park, J. Shin, K. Do, M. Lee, K. Kang, C. S. Hwang, N. S. Lu, T. Hyeon and D. H. Kim, *Nat. Nanotechnol.*, 2014, **9**, 397–404.
- 107 M. Kaltenbrunner, T. Sekitani, J. Reeder, T. Yokota, K. Kuribara, T. Tokuhara, M. Drack, R. Schwodiauer, I. Graz, S. Bauer-Gogonea, S. Bauer and T. Someya, *Nature*, 2013, **499**, 458–463.

