



Cite this: *Chem. Soc. Rev.*, 2016, 45, 6118

Man-made molecular machines: membrane bound

Matthew A. Watson and Scott L. Cockroft*

Nature's molecular machines are a constant source of inspiration to the chemist. Many of these molecular machines function within lipid membranes, allowing them to exploit potential gradients between spatially close, but chemically distinct environments to fuel their work cycle. Indeed, the realisation of such principles in synthetic transmembrane systems remains a tantalising goal. This tutorial review opens by highlighting seminal examples of synthetic molecular machines. We illustrate the importance of surfaces for facilitating the extraction of work from molecular switches and motors. We chart the development of man-made transmembrane systems; from passive to machine-like stimuli-responsive channels, to fully autonomous transmembrane molecular machines. Finally, we highlight higher-order compartmentalised systems that exhibit emergent properties. We suggest that such higher-order architectures could serve as platforms for sophisticated devices that co-ordinate the activity of numerous transmembrane molecular machines.

Received 25th November 2015

DOI: 10.1039/c5cs00874c

www.rsc.org/chemsocrev

Key learning points

- (1) Illustrative examples of natural transmembrane molecular machines.
- (2) The conceptual basis of molecular machines, categorisation of machine behaviour.
- (3) The state of the art of synthetic molecular machines operating in solution and at interfaces.
- (4) The progress towards and the future of man-made transmembrane molecular machines.

1. Introduction

Life depends upon the interplay of countless molecular machines.¹ These natural molecular machines operate at length-scales where the dominant energetic factors are random thermal fluctuations. Indeed, proteins have been described as 'kicking, screaming, stochastic molecules'.² Membrane-spanning biological molecular machines such as adenosine triphosphate (ATP) synthase³ and the bacterial flagellar motor⁴ offer proven strategies for overcoming the constant buffeting of Brownian motion to perform work that facilitates the existence of life.^{5,6} Many biologically inspired mechanically interlocked and light-responsive molecules have been synthesised,^{7–9} some of which are capable of performing macroscopic work when arrayed on surfaces.^{10–14} While the importance of synthetic nanotechnology continues to be highlighted,^{5,15} significant advances have also been made using molecules of biological origin such as DNA.¹⁶ The characteristics of many man-made transmembrane systems¹⁷ are somewhat limited compared to the exquisite functionalities displayed by biological transmembrane machines.¹⁸ Nonetheless, the bleeding-edge is starting to deliver man-made nanomechanical transmembrane

assemblies that integrate lessons from both evolved and designed systems to operate as true molecular machines under non-equilibrium conditions. Such advances offer great promise for the realisation of man-made transmembrane molecular machines that perform useful work.¹⁹

Anchoring motor proteins within two-dimensional lipid membranes provides a means of countering the thermal forces that dominate behaviour at the molecular scale. One of the most studied class of biological transmembrane molecular machine are the ATP (synth)ase rotary motors (Fig. 1a).^{3,20} ATP (synth)ases have a rotaxane-like architecture²¹ in which a spindle (blue) is threaded through both an F_0 motor in the membrane (green) and an F_1 motor in the cytosol (red and grey). In addition, the motors are held in close association by a stator (orange and pink). This assembly operates in two reciprocal modes. In the ATP synthesis mode, the reaction between ADP (adenosine diphosphate) and P_i (phosphate) is catalysed at the active sites of the F_1 motor. The catalytic cycle couples unidirectional rotation (driven by the flow of cations through the F_0 motor down a transmembrane gradient) to a cycle of conformational changes in the F_1 motor that involve sequential substrate binding, reaction, and ATP-dissociation.²⁰ Conversely, in the reciprocal mode, a transmembrane cation gradient is generated by the hydrolysis of ATP.³

EaStCHEM School of Chemistry, University of Edinburgh, Joseph Black Building, David Brewster Road, Edinburgh, EH9 3FJ, UK. E-mail: scott.cockroft@ed.ac.uk



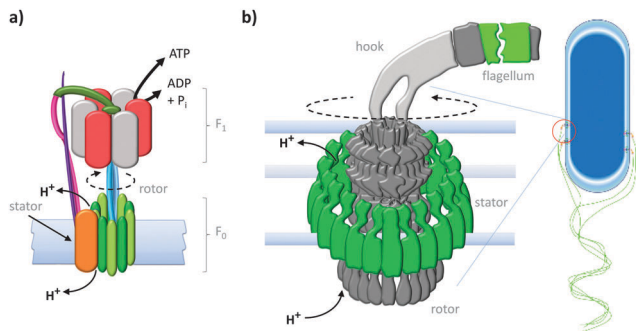


Fig. 1 Natural transmembrane molecular machines. (a) Archetypal F_1F_0 rotary ATP (synth)ase.^{3,20} (b) Bacterial flagellar motor complex.²²

The equally impressive bacterial flagella motor (Fig. 1b)²² also possesses a transmembrane rotaxane-like architecture and shares other mechanistic characteristics with ATP synthases. Flagellar motors utilise a ratchet mechanism to convert a transmembrane cation gradient into unidirectional motion that drives bacterial motility.²² The flow of cations through the stator (green) transiently changes the electrostatic interaction between the stator and the rotor to generate a torque that drives unidirectional rotation of the flagellum.²²

2. Man-made molecular machines; in solution and at interfaces

Natural molecular machines exploit the principles of molecular self-assembly, and thereby provide lessons for the construction of synthetic molecular machines. The underlying operating principles of molecular machines have been thoroughly discussed.^{5,15} However, the categorisation of a candidate system as a machine can be contentious due to differing interpretations of what constitutes “work” (particularly when energy is partitioned subjectively between different components of a system). Nonetheless, we have suggested one means of categorisation

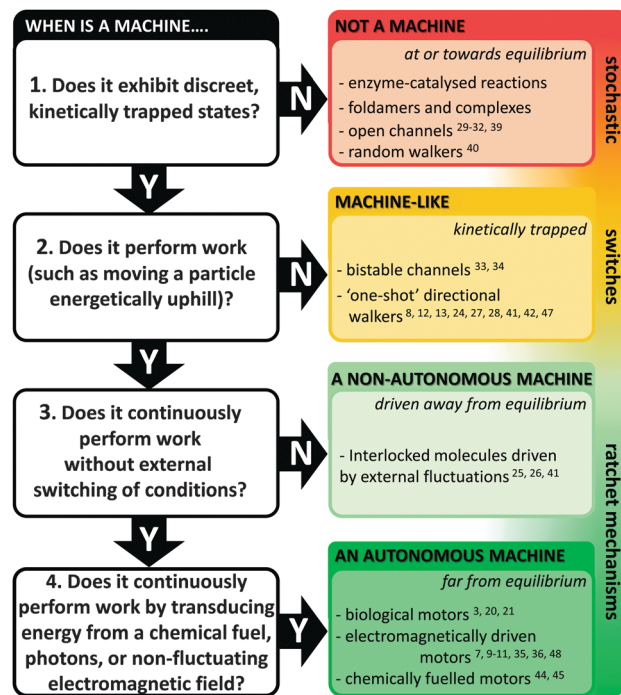


Fig. 2 Flow chart for categorising machine and machine-like systems. Superscript numbers indicate examples cited in this review.

in Fig. 2. Briefly, molecular shuttles flip between multiple states under thermodynamic control as a result of Brownian motion. The result is a time-averaged Boltzmann distribution between the states at equilibrium, with the position of the equilibrium being governed by the relative free energies of those states under differing conditions. A switch differs from a stochastic shuttle and can be defined as having machine-like properties due to the possession of at least two kinetically trapped states that can only be interconverted by the application of a specific stimulus. Work can be extracted from such a system when switching allows the return from a kinetically trapped state to a



Matthew A. Watson

Matthew Watson obtained his Chemistry MSci degree at the University of Glasgow. In 2010 he joined the University of Edinburgh to undertake a PhD in bionanotechnology followed by a further period of postdoctoral research. During his time in the Cockroft group he has developed synthetic transmembrane molecular machines that operate far-from-equilibrium. He is interested in applying the principles of molecular machine operation to

the construction of functional nanomaterials to address the challenges of our age.



Scott L. Cockroft

Scott Cockroft is a senior lecturer at the University of Edinburgh. He conducted PhD and postdoctoral work under the supervision of Prof. Christopher Hunter FRS (Sheffield, UK) and Prof. M. Reza Ghadiri (The Scripps Research Institute, California), respectively. The Cockroft group are researching molecular recognition in synthetic model systems, while seeking to harness these principles in the construction of molecular machines built from synthetic and biological

components. In his spare time Scott enjoys sitting on stone walls contemplating life, while proudly displaying the Yorkshire rose on his chest.



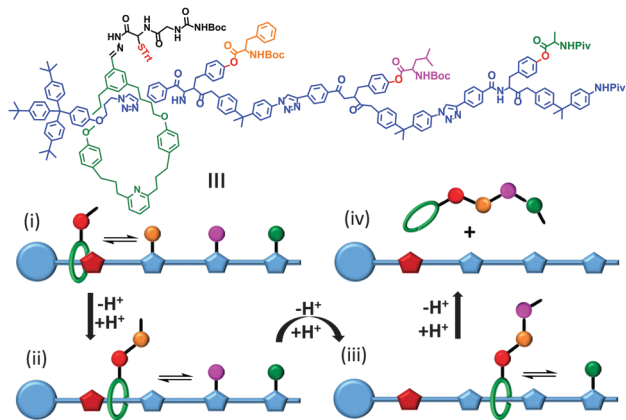


Fig. 3 A rotaxane-based peptide synthesiser.⁸ Trt = CPh₃, Boc = CO₂t-Bu and Piv = OCOt-Bu.

lower energy equilibrium state. In contrast, a true molecular machine can repetitively and asymmetrically cycle through different nanomechanical states by transducing potential energy into work.^{5,15} Notably, the changes between distinct states must not simply be the reverse of each other (as they are in a switch). Further distinctions can be drawn between autonomous and non-autonomous molecular machines. Non-autonomous machines rely on externally fluctuating conditions to ratchet asymmetrical cycles of work, while autonomous systems turn over chemical fuel, photons or other potential gradients to perform work continuously. In doing so, autonomous molecular machines generate a locally fluctuating potential, often manifested *via* ratcheted cycles of conformational change. The ratchet mechanisms that operate in both autonomous and non-autonomous machines can involve information²³ or energy.²⁴ Autonomous operation far from equilibrium is a defining characteristic of life exhibited by all biological molecular machines.¹⁹ Indeed, achieving comparable autonomous operation in synthetic systems remains a goal of utmost importance.

A. Mechanically interlocked architectures

Synthetic mechanically interlocked structures such as rotaxanes (that share the same topology as ATP synthases and bacterial flagellar motors) have been designed that exhibit impressive and diverse machine-like behaviours. One recent example mimics the function of the ribosome (or perhaps more closely, biogenic non-ribosomal peptide synthesis).⁸ The system shown in Fig. 3 was based on a rotaxane in which a linear 'track' molecule (blue) was threaded through a macrocyclic host (green). The macrocycle could shuttle back and forth at random between the stoppered end of the track and the site of the first pendant amino acid group on the thread (orange) (Fig. 3i). The macrocycle was covalently linked to a peptide chain, the first residue of which was a cysteine protected by a trityl group (red, STrt). Following deprotection, the thiolate group of the cysteine residue underwent transacylation with the first amino-acid blocking group (orange), removing it from the track. A subsequent reaction between the terminal amine of the peptide chain on the macrocycle extended the peptide chain and regenerated the



Fig. 4 An artificial molecular pump driven by external switching of redox conditions.²⁵

thiolate group (Fig. 3ii). This process was repeated until the final blocking amino acid was transferred to the growing peptide chain and the macrocycle dissociated from the track (Fig. 3iii and iv). Finally, the complete oligopeptide was cleaved from the macrocycle and the remaining protecting groups removed.

A topologically interlocked molecule has recently been employed as a rudimentary molecular pump (Fig. 4).²⁵ The system was composed of a molecular axle that could accept up to two macrocycles (blue). When the positively charged viologen units on both the macrocycle and the axle were reduced to radical forms (purple) the repulsion between the macrocycle and the axle was decreased. The macrocycle was then able to thread onto the partially reduced viologen station on the axle. Following threading, the viologen units on the macrocycle and axle were re-oxidised using NOPF₆. The electrostatic repulsion between the macrocycle and the positively charged end of the axle was sufficient to overcome the steric barrier presented by the isopropylphenyl group (green) such that the macrocycle became trapped on the stoppered alkyl chain. Repetition of the cycle of reduction, oxidation and reduction allowed a second macrocycle to be 'pumped' onto the alkyl chain in an overall energetically uphill process.

A key attribute of biological molecular machines is autonomous nanomechanical operation in repetitive cycles that dissipate energy supplied by a chemical or electromagnetic potential. One recent synthetic example that accomplished such dynamism is shown in Fig. 5.⁷ The system is composed of a 2,3-dinaphtho[24]crown-8 ether macrocycle (purple) and a molecular axle containing a photoisomerisable azobenzene moiety (*E* green, *Z* red), a cationic ammonium recognition site (blue) and a cyclopentyl terminus (grey). Under constant UV irradiation, the threading and dethreading proceeded with a directional bias (clockwise in Fig. 5). The macrocycle axle binding equilibria for both the *E* and the *Z* axle





Fig. 5 Light-driven autonomous cycle of unidirectional supramolecular assembly/disassembly.⁷

isomers lay towards the complex, but binding to the *E*-isomer was more favourable. Control experiments performed with double-stoppered compounds revealed that the barrier to macrocycle threading presented by the *E*-azobenzene moiety was lower than of the cyclopentyl group, while macrocycle unthreading over the *Z*-azobenzene moiety was less favoured compared to unthreading over the cyclopentyl group. Moreover, the *E*-complex was more sensitive to *E/Z*-photoisomerisation than the free *E*-axle, while the lifetime of the *Z*-complex was long enough that dethreading preferentially occurred over the cyclopentyl unit. The net result of the differing energetic barriers to threading/unthreading and the differing rates of isomer interconversion meant that threading and dethreading proceeded with a directional bias under constant photoirradiation (clockwise in Fig. 5). Although the system operated autonomously in a cyclical manner with molecular-level directionality, this directionality was lost when summed over the random orientations of the freely tumbling assemblies in solution. However, if it were possible to directionally orientate such a system across a lipid membrane then this would constitute a man-made molecular pump.

The challenge of extracting work from the controlled motion of mechanically interlocked species has been addressed by attaching them to surfaces. This reduces the degrees of freedom such that changes in the nanomechanical states of a large number of individual molecules may be manifested as a coherent change in the macroscopic properties of the surface. One demonstration of the extraction of macroscopic work from the collective nanomechanical movements of rotaxanes anchored to a surface is shown in Fig. 6.¹³ A bistable [3]rotaxane was prepared using two macrocycles (blue) that each featured a disulfide anchor (gold) threaded onto a stoppered thread containing two naphthalene stations (red) and two electroactive tetrathiofulvalene stations (green). The [3]rotaxanes formed a self-assembled monolayer on a gold cantilever *via* the disulfide anchors on the macrocycles. Oxidation of the tetrathiofulvalene



Fig. 6 Cantilever actuation driven by redox switching of surface-bound rotaxane shuttles.¹³

stations to their cationic form (purple) using $\text{Fe}(\text{ClO}_4)_3$ resulted in electrostatic repulsion between the cationic tetrathiofulvalene stations and macrocycles. Lateral displacement of the cantilever beam of 35 nm was measured due to the force imparted by the collective contractions of the self-assembled monolayer.

B. Synthetic rotary motors

In contrast to switches, rotary motors operate by cycling through a number of distinct states in response to energetic stimulation or the availability of a suitable fuel. Such behaviour has been demonstrated in a fully synthetic catenated architecture (Fig. 7).²⁶ The system was composed of two identical macrocycles (blue and purple) that were both threaded on a larger macrocycle containing four distinct binding sites (A to D). Each binding site exhibited different association constants for the threaded macrocycles due to their differing H-bonding abilities. Photoirradiation at 350 nm converted station A from the *E* to the *Z* isomer (1), while photoirradiation at 254 nm converted station B from the *E* to the *Z* isomer (2). Both stations A and B could be re-isomerised from *Z* to *E* (3) by heating to 100 °C for 24 hours, or by treatment with ethylenediamine at 50 °C for 48 hours or Br_2 under ambient light at -78 °C for 10 minutes. Repeated, sequential application of stimuli (1), (2) then (3), resulted in the net unidirectional rotational movement of both small macrocycles with respect to the larger macrocycle. Although the system can be defined as performing local work, no work can be extracted as the rotors are freely tumbling in solution.

Synthetic rotary motors have also been developed that can be driven by light (Fig. 8).⁹ These systems exploit repeated cycles of *E/Z* photoisomerisation of the central double bond and subsequent helicity inversion by thermal relaxation to convert between conformational states. Upon irradiation at 355 nm the central double bond photoisomerises from the most stable *cis* conformer (i) to a higher energy *trans* conformer (ii). Next, favourable helicity inversion facilitated by thermal fluctuations gives the stable *trans* conformer (iii). A second photo-excitation converts the compound to a higher energy *cis* conformer (iv) that undergoes



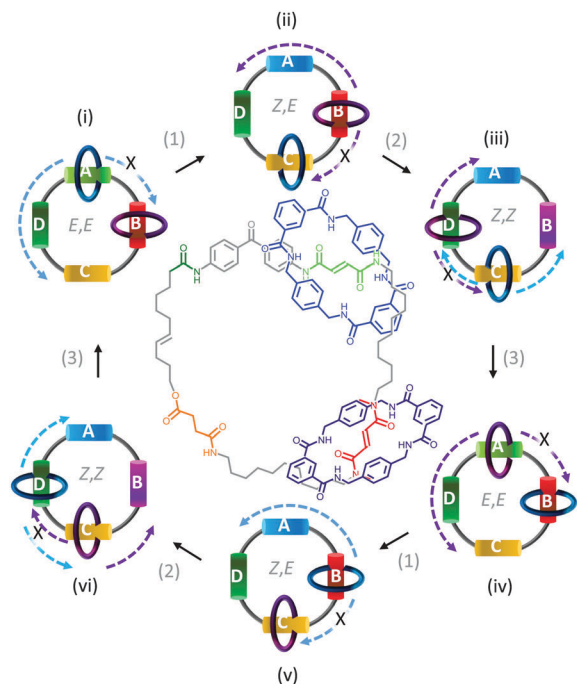


Fig. 7 Unidirectional rotation of catenated rings driven by switching of external light and chemical conditions.²⁶

thermal helicity inversion to return the system to the initial conformational state. Hence, under constant irradiation these motors rotate unidirectionally. Due to the diastereomeric relationship between each half of the molecule, retrograde motion does not occur because of the substantially higher barrier to re-isomerisation from the unstable state ($\Delta^\ddagger G_2^o$) compared to the barrier height for helix inversion ($\Delta^\ddagger G_1^o$). Variation of the X, Y and R groups has yielded motors that rotate autonomously under constant irradiation at remarkable rates of up to 3 MHz.⁹ Although each motor molecule generates a local torque, work cannot be extracted from an ensemble of freely tumbling, randomly orientated molecules in solution. Once again, the key to the extraction of work from these molecular rotors was

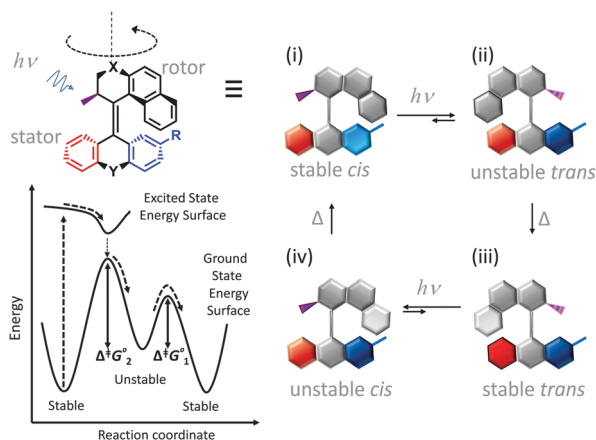


Fig. 8 Light-driven unidirectional intramolecular rotation of a synthetic molecular motor.⁹

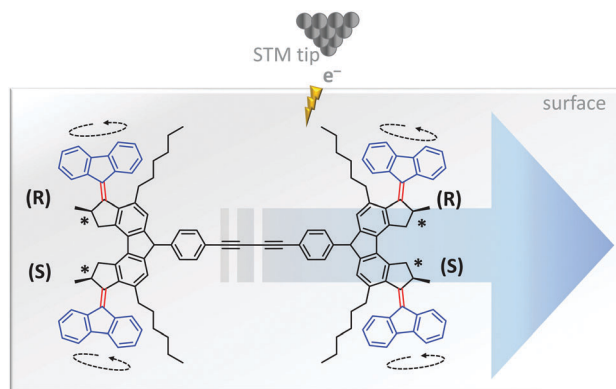


Fig. 9 Unidirectional linear translocation of a molecule containing bisarylidene rotors.¹¹

the involvement of a surface. In one study such motors were used as dopants in a chiral liquid-crystal film which caused the unidirectional rotation of microscale objects when photoirradiated.¹⁰

The unidirectional rotation of bisarylidene rotors has also been transduced into directional linear motion (Fig. 9).¹¹ When a car-like molecule containing four bisarylidene rotors was stimulated with electrons from an STM tip, the concerted motion of the rotors caused it to move along the surface. The net movement of each molecule was determined by the relative stereochemistries of the four rotors. The *R,R,S,S meso*-isomer shown in Fig. 9 gave unidirectional translation, as did the *S,S,R,R* configuration. The *R,R,R,R* and *S,S,S,S* isomers moved randomly while *R,S,R,S* and *S,R,S,R* did not move due to the cancellation of directionally opposed motions.

C. DNA-based molecular machines

Nature's molecular machines certainly exceed our own in terms of elegance, modularity and functionality. Bionanotechnological research has sought to exploit the principles of molecular recognition to repurpose biomolecules such as DNA and proteins as machine elements.¹⁶ Many of the achievements of wholly synthetic molecular machines, including programmable walkers²⁷ and molecular synthesizers²⁸ have also been accomplished by synthetic molecular machines based on DNA (sometimes years previously). Such DNA nanomachines exploit the programmable hydrogen-bonding interactions of canonical base pairing. One of the most impressive demonstrations of a DNA-based molecular machine is a peptide synthesiser based on a DNA walker (Fig. 10).²⁸ The system operated in a stepwise fashion reminiscent of the naturally occurring ribosome. The DNA track (black) and the strands bearing the amino acid monomers (blue, red and green) were first assembled in solution, and the walker (purple) subsequently added. Next, the walker could hybridise to the first DNA foothold (blue) bringing the free amine on the walker and the succinyl ester of the first foothold into close enough proximity to initiate an acylation reaction. The reaction caused the walker to fully migrate onto the blue foothold to reduce strain in the system. In this configuration, a DNAzyme region of the walker (purple) was able to catalytically cleave an RNA linker sequence (black dot). Since the first foothold (blue)



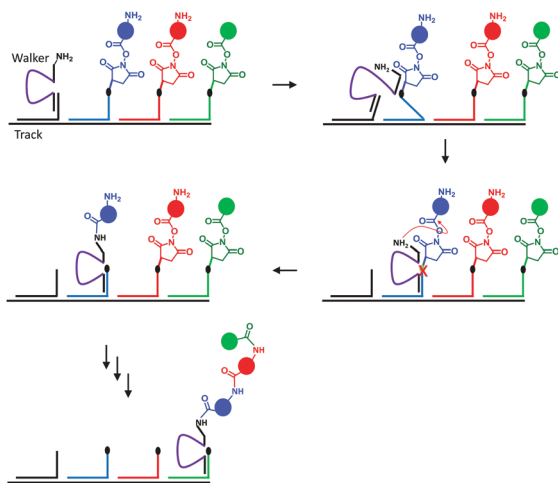


Fig. 10 A peptide synthesised based on a DNA walker.²⁸

had now been shortened by cleavage, binding to the subsequent (red) foothold was favoured. Repetition of this sequence of events facilitated the autonomous synthesis of a tripeptide. Overall, the system compares favourably to the more recent fully synthetic peptide synthesiser introduced in Fig. 3; it is easily constructed and operates under isothermal conditions. However, in common with the synthetic peptide synthesiser (and unlike the biogenic ribosome) processivity is limited because the effective molarity of the reacting groups decreases with each amino-acid addition step. Furthermore, the fidelities of the man-made systems are limited by the increased flexibility of longer chains, which might allow monomers to be added in an unintended order.

3. Man-made transmembrane molecular machines

In biology, lipid bilayers provide a route to system complexity. Self-assembly facilitates the spatial organisation of discrete entities with specific orientations within a membrane. This includes selective, stimuli-responsive channels that operate at equilibrium, as well as active transmembrane pumps that operate far from equilibrium to transduce energy into useful work. Efforts to mimic the functionality of natural transmembrane systems have mirrored this progression in complexity; from passive (Section 3A) to selective channels (Section 3B), to light-driven (Section 3C) and nanomechanical transmembrane assemblies that can operate far from equilibrium (Section 3D).

A. Artificial transmembrane channels

Lipid membranes provide an attractive platform for the construction of man-made molecular machines; bilayers are easily prepared and they are inherently biocompatible. Furthermore, they permit the spatial organisation of self-assembling biological and synthetic components in the realisation of man-made transmembrane devices. For example, both cyclic peptides (Fig. 11, left)²⁹ and DNA (Fig. 11, right)³⁰ have been used to create stable artificial nanopores across lipid bilayers. Both of

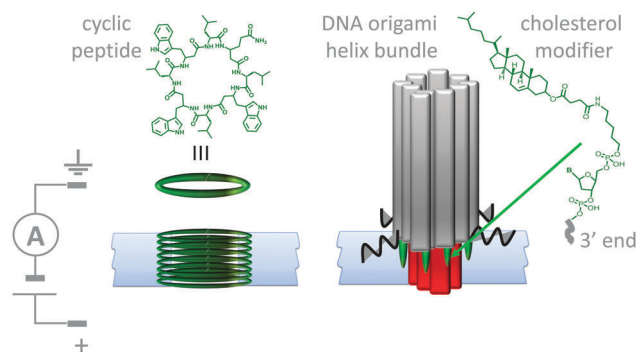


Fig. 11 Artificial nanopores in lipid bilayer membranes made using cyclic peptides (left)²⁹ and DNA origami (right).³⁰

these assemblies have dimensions close to those of natural protein channels and permit the passage of ions down a transmembrane potential or concentration gradient. The cyclic peptides (green) self-assemble into membrane-spanning tubes as they partition into the membrane. The assembly process was reasoned to occur by the stacking of aromatic side chains within the hydrophobic membrane interior, while the inside of the tubes present the polar amide backbone to the solvent. Similarly, the DNA origami nanopore was designed such that it was anchored into the bilayer *via* cholesterol-modified helix bundles (grey and red). The machine-like, voltage-sensitive gating (opening and closing) of the DNA-origami channels was also investigated. A channel variant bearing a strand that could readily adopt a channel-blocking conformation in response to high transmembrane potentials was observed to gate more than the original channel. Similarly, DNA origami tiles have been designed that modulate the flow of ions and biomolecules across channels at the ends of glass capillaries.³¹ Given the maturity of DNA nanotechnology,^{16,27} it can be envisioned that such approaches will soon develop beyond switchable channels to yield true transmembrane molecular machines capable of performing work (such as active transport).

B. Ligand-responsive transmembrane channels

Biological nanopores have also inspired the development of systems in which micro- to nano-scale apertures in solid-state wafers separate fluid-filled compartments. These artificial apertures can be functionalised to give tuneable systems that respond to stimuli such as voltage, pH, temperature, light, and even specific ions and enantiomers.¹⁸ Furthermore, selective transport across a partition can be achieved by exploiting the interactions between an analyte and the molecules used to functionalise the aperture. Although this machine-like behaviour mimics cellular function, most approaches developed to date act as simple gates or switches that are incapable of performing work such as establishing a chemical gradient.

The most sophisticated systems employing this top-down approach facilitate the simultaneous translocation and analysis of macromolecules. One such system mimics the nuclear pore complex (Fig. 12)³² and consisted of a nanopore formed in a polycarbonate wafer (grey) coated with gold and further modified



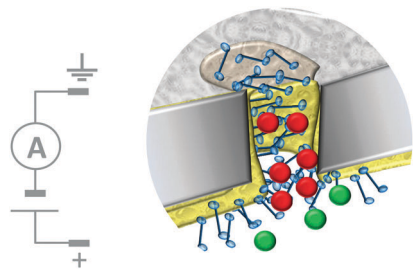


Fig. 12 Artificial nanopore system that mimics the nuclear pore complex.³²

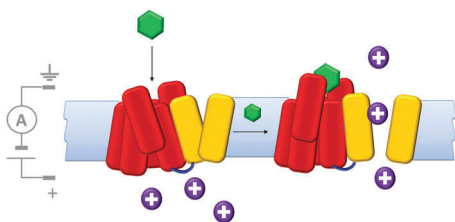


Fig. 13 A man-made ligand-gated transmembrane ion channel formed from the chimera of a K^+ ion channel (yellow) and G-protein-coupled receptor (red).³³

with phenylalanine-glycine-nucleoporin proteins (blue). The membrane-like wafer acted as a selective filter that facilitated the diffusion of specific, free and cargo-bound transport factors (red) through the pore *via* favourable non-covalent interactions with the nucleoporins. In contrast, passive transmembrane diffusion of similarly sized molecules (green) that were not recognised by the nucleoporins was hindered. One obvious difference between many solid-state and biological channels is their size. This difference arises from the difficulty in reproducibly obtaining nanometre-scale features using top-down engineering techniques. Channel size is important because the interactions between an aperture and an analyte become more pronounced when they have similar dimensions, and hence the likelihood of departure from simple diffusive behaviour increases.

Molecularly reproducible membrane-spanning devices can be obtained by repurposing biological pore proteins and modifying them as needed. For example, a protein chimera (Fig. 13) that combined a K^+ channel protein (yellow) with a G-protein-coupled receptor (red) has been engineered.³³ Analysis of ion currents flowing through the chimeric protein channels indicated that the ion channel opened upon binding of a known ligand (green) to the G-coupled-receptor. Thereby, artificial transmembrane signal transduction was achieved from a chemical signal without the molecule itself crossing the membrane.

C. Light-driven transmembrane devices

A number of devices that use light either as an external stimulus or as an energy source to drive transmembrane processes have been demonstrated. Synthetic photoactive functionalities that undergo conformational changes have been used in conjunction with biological channel proteins to facilitate optical control over membrane transport. One example of this approach involved engineering the mechanosensitive channel of large conduction

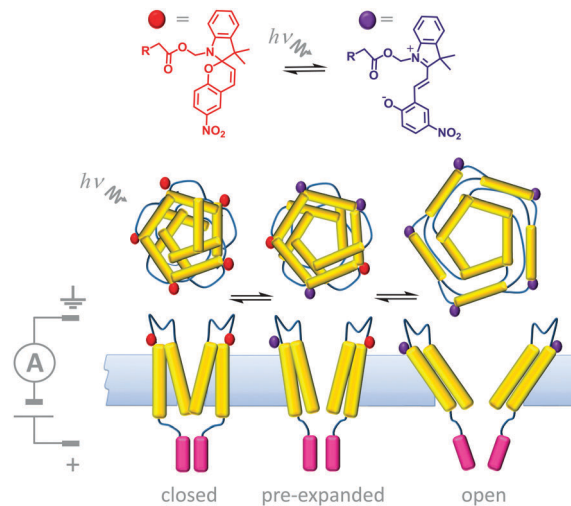


Fig. 14 Semi-synthetic light-gated ion channel prepared from a chemically modified mechanosensitive channel protein.³⁴

(MscL) from *E. coli* (Fig. 14).³⁴ The protein (yellow) was modified to have one cysteine residue per monomer allowing the incorporation of a photo-responsive cyanine group that could be reversibly switched between a neutral spiropyran form (red) and a charged zwitterionic merocyanine form (purple). When 366 nm UV light was shone on a membrane containing the chemically modified channels, a large-scale conformational change caused the channel to open, and permitting the flow of ions across the membrane under an applied transmembrane potential. The conformational change was fully reversed by ambient light at wavelengths >460 nm. Hence, light-actuated gating could be performed repeatedly by turning the UV light on and off.

ATP synthase has also been used as a component in a variety of artificially assembled devices. The key to achieving non-equilibrium properties in the example shown in Fig. 15 was the addition of a diphenyl quinone (Q_s) and a photoactive caroteneporphyrin-naphthoquinone (C-P-Q) (Fig. 15).³⁶ The synthetically functionalised membrane was shown to generate a transmembrane proton gradient in response to visible light, which could be exploited to drive the rotation of ATP synthase and the associated synthesis of ATP (as explained in Fig. 1a).

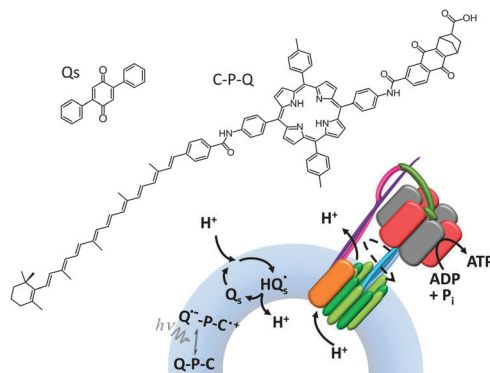


Fig. 15 An artificial photosynthetic vesicle.³⁶



target DNA complex (yellow and purple) that was present on one side of the bilayer. Complexation to the arm increased both the negative charge density and the effective molarity in the vicinity of the pore compared to the free target. The combination of these two effects meant that the barrier to DNA translocation could be overcome at an applied voltage of +50 mV. Next, complexation of streptavidin (green circle) to the biotin group on the target sequence trapped the translocated DNA on that side of the membrane. A DNA strand (pink) was then able to displace the cargoes into solution *via* a strand displacement process. The free DNA arm was then able to diffuse back through the pore, allowing further cycles to occur. This system has several characteristics of a machine; it operates autonomously, cycling directionally through multiple nanomechanical states *via* an information ratchet mechanism,²³ while also consuming a strand-displacing DNA fuel. Although DNA transport proceeded at a voltage that would normally be too low to overcome the energy barrier to translocation, DNA transport occurred in the same direction as the applied field (down the potential energy landscape). Thus, the translocation of DNA by this mechanism does not constitute work performed by the nanomechanical cycle (Qn. 2 in Fig. 2). Hence, the system can be considered as a catalytic translocase that lowers the activation barrier to a thermodynamically downhill process, rather than being an active transporter, pump or motor.

Indeed, motor proteins such as DNA polymerases have been employed in conjunction with biological pores to create transmembrane nanomechanical devices with machine-like properties. For example, the replication of DNA hairpins by $\phi 29$ DNA polymerase has been monitored at the single-molecule level using nanopores (Fig. 20).⁴² In this approach, a DNA-hairpin (black) was captured in an α -HL channel (blue) under an applied potential. The turn-over of dNTP fuel during extension of the self-primed hairpin by the polymerase (yellow) resulted in the captured DNA being ratcheted out of the pore against the applied transmembrane potential. The DNA hairpin contained an abasic region (red) that allowed the relative position of the strand in the pore to be determined from changes in the ion current flowing through a single channel.

A similar approach has been used to study the ratcheting of a protein through an α -HL nanopore by the motor protein AAA+ unfoldase (ClpX in Fig. 21).⁴³ The protein Smt3 (purple) was modified with a charged polypeptide tail (green) terminating in an ssrA recognition sequence (yellow). This modified protein

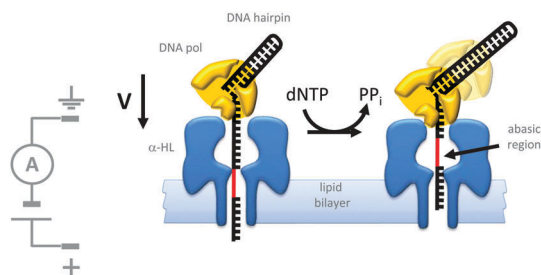


Fig. 20 Polymerase-catalysed replication of DNA monitored at the single-molecule level using a nanopore.⁴²

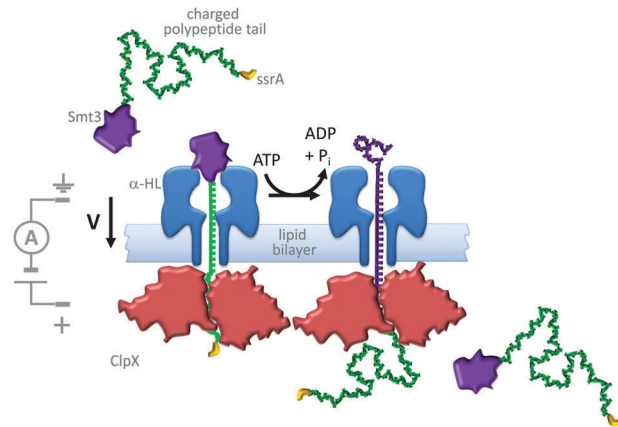


Fig. 21 ATP-coupled transmembrane protein translocation through α -HL.⁴³

was threaded through and captured within an α -HL nanopore by an applied transmembrane potential. The ssrA sequence was then recognised by the unfoldase (red) that was present on the opposite side of the lipid bilayer. Cycles of conformational change in the unfoldase driven by the turn-over of ATP allowed the captured protein to be unfolded and pulled through the pore (green to purple). The unfolding process was monitored *via* ratcheted changes in the ion current flowing through the pore under an applied potential.

Further efforts to create synthetic transmembrane molecular machines have employed protein chimeras. A recent, impressive example appended loops of the cochaperonin protein GroES (green) onto the α -HL nanopore (blue) (Fig. 22).⁴⁴ Natively, GroES forms a complex with GroEL to yield a catalytically active chaperonin that turns over ATP to drive a series of conformational changes that mediate the folding of proteins (yellow) within the internal cavity of the GroES–GroEL complex. Since both the GroES–GroEL complex and the α -HL share a seven-fold symmetry, the α -HL–GroES chimera was able to template the assembly of an active GroEL heptamer (pink). The ATP-driven chaperonin function of this engineered transmembrane assembly was characterised using gel-shift experiments in the bulk, while dynamic activity was monitored at the single-molecule level using transmembrane ion currents.

The assemblies described in Fig. 20–22 were used to monitor the machine behaviour of known motor proteins; a further

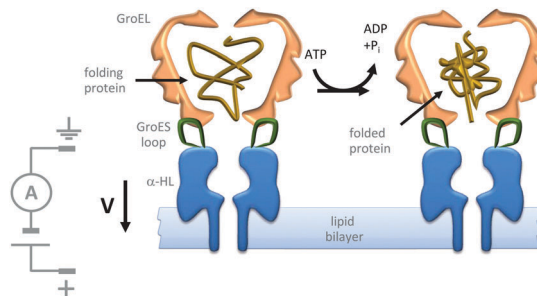


Fig. 22 Single-molecule observation of the ATP-fuelled folding of a protein using an engineered transmembrane co-chaperonin.⁴⁴



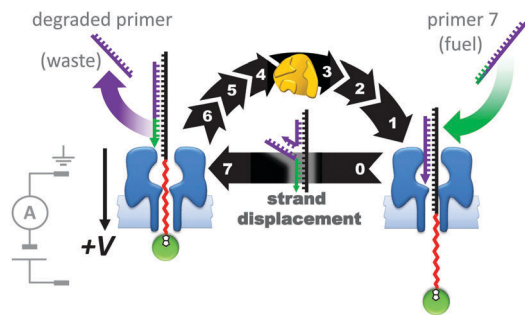


Fig. 23 A transmembrane reciprocating nanoactuator that operates with a temporally asymmetric nanomechanical cycle.⁴⁵

milestone has been the realisation of systems in which machine behaviour is an emergent quality possessed by the entire assembly. This goal was recently attained in the form of a transmembrane nanoactuator that turned over DNA molecules to fuel cycles of autonomous reciprocating (back-and-forth) nanomechanical motion (Fig. 23).⁴⁵ The approach built on the precedent set by a nanopore-based system capable of monitoring DNA polymerase activity with single-nucleotide resolution.^{46,47}

The device was assembled by threading a DNA-PEG copolymer (black-red) capped with a streptavidin-biotin stopper (green circle) through an α -HL nanopore under an applied potential. The captured co-polymer was then trapped in place by hybridisation to a fully complementary DNA primer (purple-green) to form a rotaxane-like transmembrane architecture. In the presence of DNA polymerase, pyrovanadate, Mn^{2+} and DNA fuel molecules, ion-current recordings revealed asymmetric saw-tooth patterns. These patterns corresponded to an emergent cycle of back and forth movement in the threaded co-polymer at rates of up to one cycle per minute. Stepwise 'downwards' movement of the threaded co-polymer (left to right in Fig. 23) arose due to DNA polymerase-catalysed degradation of the primer fuel, while displacement of the degraded primer by the invasion of a full-length primer pulled the threaded co-polymer 'upwards' in a single step (against the applied potential). The asymmetric conformational cycle was co-ordinated *via* an information ratchet mechanism since strand displacement could only occur once the primer had been sufficiently degraded.

E. Multi-compartment transmembrane devices

Contrasting with the isolated devices described above, higher-order living organisms are hierarchically organised into multiple chemically distinct environments by lipid bilayers. This partitioning allows the generation of transmembrane potentials by molecular machines working in different compartments, giving rise to emergent collective properties. Artificial systems have been developed that mimic the multi-compartmental nature of living organisms. For example, aqueous droplets can be submerged in oil and arranged into networks in which bilayers form at the interfaces between the drops (Fig. 24). The addition of proteins that insert into the bilayers connecting these droplet allows ions and analytes to pass between the droplets in a designed manner. In addition, the approach allows these

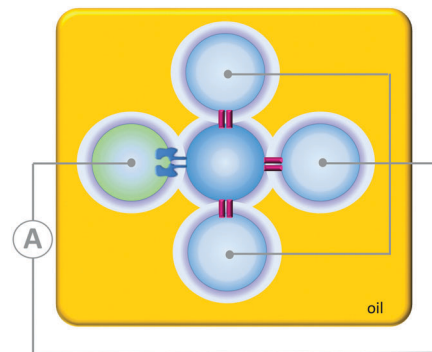


Fig. 24 A simple circuit constructed from a droplet interface bilayer network connected by an α -haemolysin pore and bacteriorhodopsin.⁴⁸

processes to be monitored by both electrical and optical methods. Applications have included a rudimentary light sensor that mimics optical, to chemical, to electrical signal transduction in animal sight (Fig. 24).⁴⁸ The sensor consisted of three droplets containing bacteriorhodopsin that were each connected to a common electrode. These three droplets were interfaced with a central drop containing only buffer. A fifth drop containing α -HL (green) was also interfaced with the central drop and connected to a counter electrode. The bacteriorhodopsin and the α -HL were then able to insert into the bilayer interfaces with the central droplet. Photoirradiation caused the bacteriorhodopsin to pump protons across the bilayer, leading to a measurable electrical current arising from the flow of ions through the droplet circuit.

The droplet network approach has been further expanded by the generation of higher-order 'multisomes' that can operate in aqueous environments rather than in oil baths (Fig. 25).⁴⁹ The assemblies were formed from multiple aqueous compartments that were organised, but not completely encapsulated within a larger droplet of oil. The aqueous droplets had distinct internal compositions (indicated by the different colours in Fig. 25) enabling distinct functionalities to be presented to the surrounding environment. In this manner, different droplets could respond to different

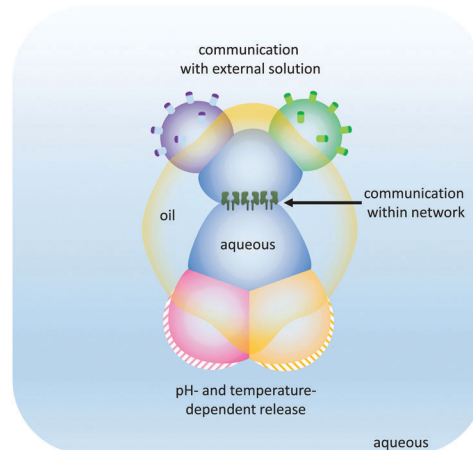


Fig. 25 Droplet multisomes that operate in aqueous environments.⁴⁹



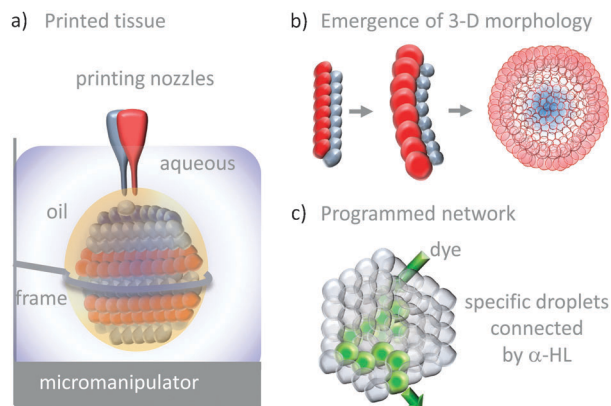


Fig. 26 Tissue-like 3-D printed droplet networks.⁵⁰

stimuli in distinct ways. In addition, the aqueous droplets could be connected at their internal interfaces by the inclusion of transmembrane pores such as α -HL. Thus, these multisomes were able to engage with their environment by sensing, processing and responding.

The droplet bilayer approach has been combined with 3D-printing technology to produce heterogeneous droplet networks that mimic some of the properties of living tissues (Fig. 26).⁵⁰ Sub-microlitre droplets were 'printed' in three dimensions within an oil droplet submerged in water (Fig. 26a). The resulting jelly-like material was held in place by a metal frame. Heterogeneous multi-compartment tissues could be printed that contained different concentrations (red and blue in Fig. 26a and b). The osmotic movement of water between droplets containing different salt concentrations in one- and two-dimensional tissues gave rise to assemblies with emergent three-dimensional morphologies (Fig. 26b). Furthermore, the inclusion of α -HL in specific droplets enabled the path of solute diffusion to be programmed in three dimensions (Fig. 26c). While these droplet-based systems do not constitute transmembrane molecular machines in their own right, they might serve as hosts for collectively operating transmembrane molecular machines in the future, paving the way to sophisticated multi-compartment devices with emergent properties.

4. Conclusions and future directions

Many avenues are being pursued in the design of molecular machines. Biology has not only inspired the development of man-made molecular machines, but also provided insights into the mechanisms of energy transduction on the molecular level. Implementation of fundamental mechanisms such as ratcheting^{23,24} have led to the construction of minimal synthetic designs that are free of the molecular 'baggage' acquired over billions of years of biological evolution.^{5,15} Despite the simplicity and elegance of many synthetic systems,^{7,9,25,26} no macroscopic work can be extracted from freely tumbling, randomly oriented molecules.² This fundamental Brownian limitation has been overcome by interfacing synthetic molecular machines with surfaces.^{10,11,13} In biology, similar entropic

constraints are afforded to molecular machines that work along one-dimensional biopolymers or across two-dimensional membranes. Indeed, it is hard to imagine life without the nucleic acid polymerases,^{42,46,47} transmembrane photosynthesis,³⁵ or ATP synthase.³ Substantial progress has been made since the first transmembrane channels were prepared,²⁹ including the realisation of stimuli-responsive channels that mimic some biological functions.^{30–32} However, few artificial transmembrane systems are as robust or reproducible as their biological counterparts, or display the autonomous operation ubiquitous to the machinery of life. Thus, many researchers have repurposed biological molecules such as stable pore proteins^{33,34,41} and DNA³⁰ to construct artificial transmembrane devices. Some of the most effective demonstrations of transmembrane machine behaviour have utilised motor proteins to attain assemblies that operate with autonomous nanomechanical cycles.^{44,45} While lessons continue to be learned from biology, principles from synthetic nanotechnology¹⁵ must be better integrated into the next generation of transmembrane architectures. Looking further ahead, multi-compartment devices^{49,50} might deliver hybrid synthetic/biological systems that coordinate the functions of numerous transmembrane machines to operate far from equilibrium,¹⁹ blurring the lines between life and the artificial.

Acknowledgements

We thank the Engineering and Physical Sciences Research Council (EP/H021620-1) and ERC Starting Grant No. 336935, 'Transmembrane molecular machines' for financial support.

Notes and references

- M. Schliwa and G. Woehlke, *Nature*, 2003, **422**, 759–765.
- R. D. Astumian, *Phys. Chem. Chem. Phys.*, 2007, **9**, 5067.
- S. Arai, S. Saijo, K. Suzuki, K. Mizutani, Y. Kakinuma, Y. Ishizuka-Katsura, N. Ohsawa, T. Terada, M. Shirouzu, S. Yokoyama, S. Iwata, I. Yamato and T. Murata, *Nature*, 2013, **493**, 703–707.
- X. Zhao, K. Zhang, T. Boquoi, B. Hu, M. A. Motaleb, K. A. Miller, M. E. James, N. W. Charon, M. D. Manson, S. J. Norris, C. Li and J. Liu, *Proc. Natl. Acad. Sci. U. S. A.*, 2013, **110**, 14390–14395.
- E. R. Kay, D. A. Leigh and F. Zerbetto, *Angew. Chem., Int. Ed.*, 2007, **46**, 72–191.
- A. Coskun, M. Banaszak, R. D. Astumian, J. F. Stoddart and B. A. Grzybowski, *Chem. Soc. Rev.*, 2012, **41**, 19–30.
- G. Ragazzon, M. Baroncini, S. Silvi, M. Venturi and A. Credi, *Nat. Nanotechnol.*, 2014, **10**, 70–75.
- B. Lewandowski, G. De Bo, J. W. Ward, M. Pappmeyer, S. Kuschel, M. J. Aldegunde, P. M. E. Gramlich, D. Heckmann, S. M. Goldup, D. M. D'Souza, A. E. Fernandes and D. A. Leigh, *Science*, 2013, **339**, 189–193.
- M. Klok, N. Boyle, M. T. Pryce, A. Meetsma, W. R. Browne and B. L. Feringa, *J. Am. Chem. Soc.*, 2008, **130**, 10484–10485.



- 10 R. Eelkema, M. M. Pollard, J. Vicario, N. Katsonis, B. S. Ramon, C. W. M. Bastiaansen, D. J. Broer and B. L. Feringa, *Nature*, 2006, **440**, 163.
- 11 T. Kudernac, N. Ruangsupapichat, M. Parschau, B. Macia, N. Katsonis, S. R. Harutyunyan, K.-H. Ernst and B. L. Feringa, *Nature*, 2011, **479**, 208–211.
- 12 J. Berna, D. A. Leigh, M. Lubomska, S. M. Mendoza, E. M. Perez, P. Rudolf, G. Teobaldi and F. Zerbetto, *Nat. Mater.*, 2005, **4**, 704–710.
- 13 T. J. Huang, B. Brough, C.-M. Ho, Y. Liu, A. H. Flood, P. A. Bonvallet, H.-R. Tseng, J. F. Stoddart, M. Baller and S. Magonov, *Appl. Phys. Lett.*, 2004, **85**, 5391–5393.
- 14 V. Balzani, A. Credi and M. Venturi, *ChemPhysChem*, 2008, **9**, 202–220.
- 15 S. Erbas-Cakmak, D. A. Leigh, C. T. McTernan and A. L. Nussbaumer, *Chem. Rev.*, 2015, **115**, 10081–10206.
- 16 J. Bath and A. J. Turberfield, *Nat. Nanotechnol.*, 2007, **2**, 275–284.
- 17 S. Matile, A. Vargas Jentzsch, J. Montenegro and A. Fin, *Chem. Soc. Rev.*, 2011, **40**, 2453–2474.
- 18 X. Hou, W. Guo and L. Jiang, *Chem. Soc. Rev.*, 2011, **40**, 2385–2401.
- 19 E. Mattia and S. Otto, *Nat. Nanotechnol.*, 2015, **10**, 111–119.
- 20 J. Weber, *Nat. Chem. Biol.*, 2010, **6**, 794–795.
- 21 C. A. Schalley, K. Beizai and F. Vögtle, *Acc. Chem. Res.*, 2001, **34**, 465–476.
- 22 Y. Sowa and R. M. Berry, *Q. Rev. Biophys.*, 2008, **41**, 103–132.
- 23 V. Serreli, C.-F. Lee, E. R. Kay and D. A. Leigh, *Nature*, 2007, **445**, 523–527.
- 24 A. M. Brouwer, C. Frochot, F. G. Gatti, D. A. Leigh, L. c. Mottier, F. Paolucci, S. Roffia and G. W. H. Worpel, *Science*, 2001, **291**, 2124–2128.
- 25 C. Cheng, P. R. McGonigal, S. T. Schneebeli, H. Li, N. A. Vermeulen, C. Ke and J. F. Stoddart, *Nat. Nanotechnol.*, 2015, **10**, 547–553.
- 26 D. A. Leigh, J. K. Y. Wong, F. Dehez and F. Zerbetto, *Nature*, 2003, **424**, 174–179.
- 27 R. A. Muscat, J. Bath and A. J. Turberfield, *Nano Lett.*, 2011, **11**, 982–987.
- 28 Y. He and D. R. Liu, *Nat. Nanotechnol.*, 2010, **5**, 778–782.
- 29 M. R. Ghadiri, J. R. Granja and L. K. Buehler, *Nature*, 1994, **369**, 301–304.
- 30 M. Langecker, V. Arnaut, T. G. Martin, J. List, S. Renner, M. Mayer, H. Dietz and F. C. Simmel, *Science*, 2012, **338**, 932–936.
- 31 S. Hernández-Ainsa, K. Misiunas, V. V. Thacker, E. A. Hemmig and U. F. Keyser, *Nano Lett.*, 2014, **14**, 1270–1274.
- 32 T. Jovanovic-Taliman, J. Tetenbaum-Novatt, A. S. McKenney, A. Zilman, R. Peters, M. P. Rout and B. T. Chait, *Nature*, 2009, **457**, 1023–1027.
- 33 C. J. Moreau, J. P. Dupuis, J. Revilloud, K. Arumugam and M. Vivaudou, *Nat. Nanotechnol.*, 2008, **3**, 620–625.
- 34 A. Koçer, M. Walko, W. Meijberg and B. L. Feringa, *Science*, 2005, **309**, 755–758.
- 35 S. Bhosale, A. L. Sisson, P. Talukdar, A. Fürstenberg, N. Banerji, E. Vauthey, G. Bollot, J. Mareda, C. Röger, F. Würthner, N. Sakai and S. Matile, *Science*, 2006, **313**, 84–86.
- 36 G. Steinberg-Yfrach, J.-L. Rigaud, E. N. Durantini, A. L. Moore, D. Gust and T. A. Moore, *Nature*, 1998, **392**, 479–482.
- 37 L. Ma and S. L. Cockroft, *ChemBioChem*, 2010, **11**, 25–34.
- 38 D. Branton, D. W. Deamer, A. Marziali, H. Bayley, S. A. Benner, T. Butler, M. Di Ventra, S. Garaj, A. Hibbs, X. Huang, S. B. Jovanovich, P. S. Krstic, S. Lindsay, X. S. Ling, C. H. Mastrangelo, A. Meller, J. S. Oliver, Y. V. Pershin, J. M. Ramsey, R. Riehn, G. V. Soni, V. Tabard-Cossa, M. Wanunu, M. Wiggin and J. A. Schloss, *Nat. Biotechnol.*, 2008, **26**, 1146–1153.
- 39 D. Wendell, P. Jing, J. Geng, V. Subramaniam, T. J. Lee, C. Montemagno and P. Guo, *Nat. Nanotechnol.*, 2009, **4**, 765–772.
- 40 G. S. Pulcu, E. Mikhailova, L.-S. Choi and H. Bayley, *Nat. Nanotechnol.*, 2014, **10**, 76–83.
- 41 L. Franceschini, M. Soskine, A. Biesemans and G. Maglia, *Nat. Commun.*, 2013, **4**, 2415.
- 42 F. Olasagasti, K. R. Lieberman, S. Benner, G. M. Cherf, J. M. Dahl, D. W. Deamer and M. Akeson, *Nat. Nanotechnol.*, 2010, **5**, 798–806.
- 43 J. Nivala, D. B. Marks and M. Akeson, *Nat. Biotechnol.*, 2013, **31**, 247–250.
- 44 C.-W. Ho, V. van Meervelt, K.-C. Tsai, P.-J. de Temmerman, J. Mast and G. Maglia, *Sci. Adv.*, 2015, **1**, e1500905.
- 45 M. A. Watson and S. L. Cockroft, *Angew. Chem., Int. Ed.*, 2016, **55**, 1345–1349.
- 46 S. L. Cockroft, J. Chu, M. Amorin and M. R. Ghadiri, *J. Am. Chem. Soc.*, 2008, **130**, 818–820.
- 47 J. Chu, M. González-López, S. L. Cockroft, M. Amorin and M. R. Ghadiri, *Angew. Chem., Int. Ed.*, 2010, **49**, 10106–10109.
- 48 M. A. Holden, D. Needham and H. Bayley, *J. Am. Chem. Soc.*, 2007, **129**, 8650–8655.
- 49 G. Villar, A. J. Heron and H. Bayley, *Nat. Nanotechnol.*, 2011, **6**, 803–808.
- 50 G. Villar, A. D. Graham and H. Bayley, *Science*, 2013, **340**, 48–52.

