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Ionic and electronic polarization effects in horizontal hybrid perovskite device structures close to equilibrium†

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The electrical response of hybrid perovskite devices carries a significant signature from mobile ionic defects, pointing to both opportunities and threats when it comes to functionality, performance and stability of these devices. Despite its importance, the interpretation of polarization effects due to the mixed ionic–electronic conducting nature of these materials and the quantification of their ionic conductivities still poses conceptual and practical challenges, even for the equilibrium situation. In this study, we address these questions and investigate the electrical response of horizontal devices based on methylammonium lead iodide (MAPI) close to equilibrium conditions. We discuss the interpretation of DC polarization and impedance spectroscopy measurements in the dark, based on calculated and fitted impedance spectra obtained using equivalent circuit models that account for the mixed conductivity of the perovskite and for the effect of device geometry. Our results show that, for horizontal structures with a gap width between the metal electrodes in the order of tens of microns, the polarization behavior of MAPI is well described by the charging of the mixed conductor/metal interface, suggesting a Debye length in the perovskite close to 1 nm. We highlight a signature in the impedance response at intermediate frequencies, which we assign to ionic diffusion in the plane parallel to the MAPI/contact interface. By comparing the experimental impedance results with calculated spectra for different circuit models, we discuss the potential role of multiple mobile ionic species and rule out a significant contribution from iodine exchange with the gas phase in the electrical response of MAPI close to equilibrium. This study helps to clarify the measurement and interpretation of mixed conductivity and polarization effects in hybrid perovskites with immediate relevance to the characterization and development of transistors, memristors and solar cells based on this class of materials as well as other mixed conductors.

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Introduction

Mixed ionic–electronic conduction is a key feature of hybrid halide perovskites.^{1,2} Particularly, the significant ionic conduction of these compounds at room temperature has been discussed as a challenge in the field of perovskite solar cells, as it greatly affects device reliability and lifetime.^{3–6} On the other hand, it has also opened new avenues for other applications such as memristive devices.^{7–9} Developing detailed understanding of ionic transport in these materials is essential to both tackling the device-related issues related to degradation and unstable output, as well as unlocking the full potential derived from the complexity of their properties.¹⁰ In particular, knowledge of the defect chemistry of hybrid perovskites can help

develop models to decipher their behavior and guide future steps in the design of devices.^{11–13}

Most of the reports on mixed conduction in hybrid perovskites have focused on methylammonium lead iodide (MAPI), the most investigated compound of this material class, while recent studies have also explored the role of composition on the ionic properties of other halide perovskites.^{14–16} These reports have established that MAPI presents p-type electronic conduction in the dark at equilibrium under common preparation conditions. Iodide vacancies are widely considered majority ionic carriers, while other mobile defects have also been discussed.^{17–20} It was also shown that the stoichiometry of MAPI can be effectively accessed *in situ* by varying the halogen partial pressure, highlighting the importance of surface reactivity as a channel for component exchange at low temperature.^{17,21}

Although ion transport in hybrid halide perovskite based devices can be suppressed to some extent through compositional engineering, to our knowledge, no composition

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presenting negligible ion transport at temperatures relevant to the operation of solar cells has been reported to date. Importantly, absence of hysteresis in the current–voltage measurements of hybrid perovskite devices does not imply absence of ion transport. Instead, it can be the result of using scan rates that are either much faster or much slower than the characteristic time scale of ion redistribution.^{22,23} Even if low hysteresis is observed for a wide range of scan rates, this is still compatible with ion transport if the optoelectronic processes that underlie the solar cell response have negligible dependence on ion redistribution.^{24–27} Ultimately, a comprehensive analysis of the optoelectronic device response over an extended range of time scales critically relies on understanding how such redistribution occurs.

A complete picture of the mechanism controlling the polarization behavior, that is the long time scale electrochemical response, observed for perovskite devices is still missing. This is the case for the large perturbation regime, relevant to solar cells measured under light,^{28–30} but even for the simple situation of small perturbation close to equilibrium. Early work on MAPI pellets (symmetrical samples between carbon contacts) showed typical behavior associated with *stoichiometric polarization*, whereby the long time scale voltage evolution is related to the formation of a gradient in stoichiometry across the bulk of the sample in the direction perpendicular to the MAPI/contact interfaces.¹ The kinetics of such polarization is associated with bulk properties, such as the chemical resistance and chemical capacitance of the sample (see also next section). On the other hand, early studies on the capacitance of solar cell devices with variable active layer thickness pointed towards *space charge polarization* to play an important role, as far as the dynamics of thin films in the 1–100 s time scale is concerned.³¹ This type of polarization occurs in mixed conducting devices with ion blocking contacts, for which the capacitive response is predominantly associated with changes in mobile ion concentration localized close to the interfaces with the contacts.^{25–27,32,33} While both stoichiometric and interfacial polarization effects are expected in solar cells based on hybrid perovskites, the relevant parameter ranges in which either or both of these processes dominate the response need to be clarified. To complicate this picture, other factors such as electrochemical reactions with electrodes and iodine evolution,^{34–36} ionic penetration in the contacts,³⁷ the role of multiple mobile ions^{19,20} have also been invoked in the literature to explain the behavior of hybrid perovskite devices under even relatively low bias. Finally, the observation of multiple low frequency features in impedance spectra highlights a complex capacitive and in some cases inductive behavior that still awaits clarification.^{26,38,39}

In this study, we investigate the electrical response of MAPI based devices with horizontal structure in the dark. This architecture is common in the fabrication of field-effect-transistors and memristors, and it is used here to achieve careful control of device properties. By elucidating the role of active layer and contact geometry in the measured polarization time constant and in the observed features of impedance spectra, we show that charging of the perovskite/metal interface

is the dominating polarization mechanism in these architectures under small perturbation and close to equilibrium. Finally, we explore the role of exchange reactions with the gas phase and of multiple mobile ions through equivalent circuit calculations, and we discuss implications for the horizontal devices investigated here as well as for solar cells.

Background

The electrical response of mixed ionic–electronic conductors (MIECs) involves transport, reaction and storage of ionic and electronic charge carriers. This wide range of processes typically implies a complex dependence on the time scale (or frequency) at which the response is evaluated, also depending on the sample properties (e.g. MAPI between ion-blocking contacts, Fig. 1). The behavior of MIECs is described analytically through the Nernst–Planck–Poisson model (NPP, also referred to as drift–diffusion),^{40–42} and it can be conveniently represented in terms of equivalent circuit elements. In this section, we review some fundamental concepts of equivalent circuit modeling of MIECs close to equilibrium, which will be referred to in the discussion of the data in this study. For further reading on this subject, see ref. 41–44.

The transmission line model encapsulates the NPP equations in an electrical circuit in one-dimension (x). Specifically, the model is a representation of the linearized NPP problem and can be used to study the small perturbation behavior of semiconducting and MIEC based devices close to equilibrium. The circuit involves one rail for each mobile charge carrier (electronic or ionic) consisting of electrochemical resistors $R_j(x_i) = \sigma_j^{-1}(x_i)\Delta x/A$ (for the j -th charge carrier) connected along the x dimension (Fig. 2a). Here, $\sigma_j(x_i)$ is the conductivity of the carrier within the slice of MIEC with thickness $\Delta x = x_{i+1} - x_i$ and area A . The potential associated with the nodes on each charge carrier's rail in the transmission line corresponds to the species' electrochemical potential $\tilde{\mu}_j$, more precisely to its deviation, $d\tilde{\mu}_j$ (indicated with v_j in Fig. 2a, $qv_j = d\tilde{\mu}_j$, q is the elementary charge), from the equilibrium value, $\tilde{\mu}_{j,\text{eq}}$ ($\tilde{\mu}_j = \tilde{\mu}_{j,\text{eq}} + d\tilde{\mu}_j$). An additional rail describing the electrostatic behavior of the system involves electrostatic capacitors, $C_g(x_i) = A\epsilon_s\epsilon_0/\Delta x$, also connected along x ($\epsilon_s\epsilon_0$ indicates the static dielectric permittivity of the MIEC). If $\phi = \phi_{\text{eq}} + d\phi$ is the electrostatic potential expressed as its equilibrium value and its deviation from equilibrium, then the potential at the nodes of the electrostatic rail corresponds to the changes in the electrostatic potential $d\phi$, here indicated with v_e . Each charge carrier rail is connected to the electrostatic rail *via* chemical capacitors (Fig. 2a, right side) defined as:

$$C_j^\delta(x_i) = (qz_j)^2 A \Delta x \frac{\partial c_{\{j\}}(x_i)}{\partial \mu_j} \quad (1)$$

where z_j and μ_j are the charge number and chemical potential of species j , respectively. The term $c_{\{j\}}$ refers to the total concentration, including both free (c_j) and trapped ($c_{j,\text{trapped}}$) species, $c_{\{j\}} = c_j + c_{j,\text{trapped}}$.⁴⁵



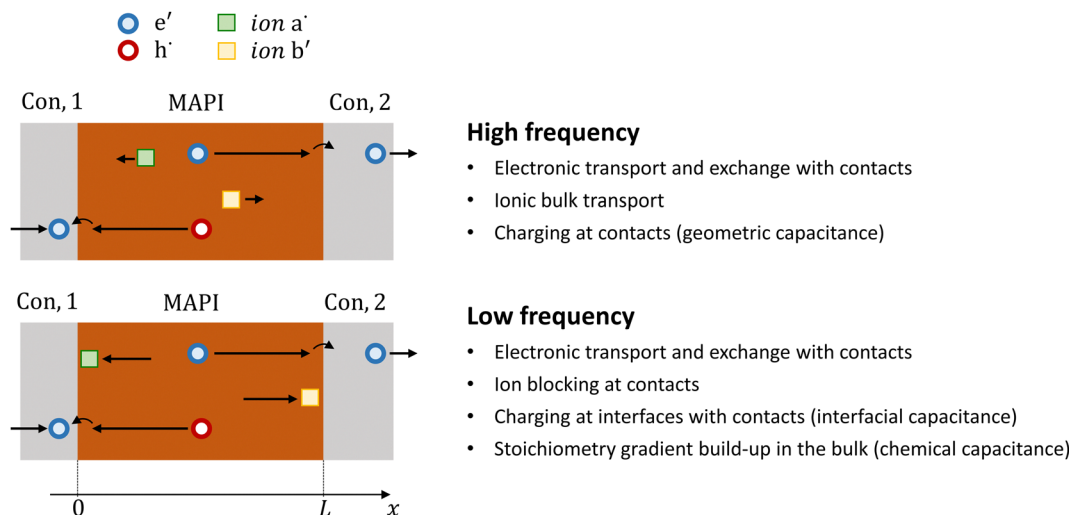


Fig. 1 Schematics showing the processes responsible for the electrical response of a mixed ionic–electronic conductor, such as methylammonium lead iodide (MAPI), of thickness L between ion-blocking contacts and close to equilibrium. Two electronic and two ionic charge carriers are shown (the superscripts $\bullet$ and $\prime$ indicates a positively and a negatively charged defect relative to the perfect crystal). The charge transport and storage behavior of the device depends on the frequency of the applied bias. The separation of processes occurring at either “low” or “high” frequencies depends on the specific properties of the device. Note that the two ions can have very different diffusion coefficients.

Under dilute conditions, we can write:

$$C_j^\delta(x_i) = (qz_j)^2 A \Delta x \frac{c_j(x_i)}{k_B T} \chi_j^{-1}, \quad (2)$$

where χ_j is the trapping factor (differential of the charge carrier concentration that is free with respect to the total, $\chi_j = \partial c_j / \partial c_{j\text{tot}}$) and $k_B T$ is the thermal energy. From the NPP model, it is possible to unambiguously derive the constitutive relations for the circuit elements described above.^{40–42} This means that the resulting transmission line model is a one-to-one representation of the discretized (and linearized) NPP problem.

In general for MIECs, we are interested in the transport of mobile point defects such as conduction band electrons (e' with concentration n), valence band holes (h' with concentration p) and any kind of ionic species. Under the conditions that are relevant to this study, where ion-blocking, non-selective (with respect to electrons and holes) contacts are used and measurements are carried out close to equilibrium, the electron and hole populations are expected to be at equilibrium locally. This means that a single rail can be used to summarize the electronic behavior of the MIEC (see Fig. 2b). Such approximation would not be valid in general (e.g. solar cell architecture with selective contacts), and especially for the characterization of the electrical response out-of-equilibrium.^{25,26,46–49} In Fig. 2b, the total electronic resistance and the total electronic chemical capacitance are R_{eon} and C_{eon}^δ , respectively. The local contribution of a Δx thick slice of the MIEC to these electronic properties is shown as R_{eon}/N and C_{eon}^δ/N , assuming a discretized model with equal spacing (N is the number of mesh points, assumed to be large) and the simple case of homogeneous MIEC. Ionic species are described analogously. In Fig. 2b, we consider one mobile ionic charge carrier with a total transport resistance R_{ion} and ionic chemical capacitance C_{ion}^δ . The role of

multiple ions (multiple ionic rails) and chemical equilibria (additional elements connecting ionic and electronic rails) will be addressed below.

In Fig. 2b, the contribution of the boundary layers on the MIEC side are treated similarly to the bulk. Interfacial contributions due to the contacts are described *via* interfacial resistors and capacitors $R_{\text{ion},c}^\perp$, $R_{\text{eon},c}^\perp$, $C_{g,c}^\perp$. Their values determine the reversibility of the electrodes to each species (ability to enable, small $R^\perp$, or to block, large $R^\perp$, the exchange of charge carriers with the contact) and describe the interfacial electrostatic situation (if the contact is a metal, $C_{g,c}^\perp$ is a double layer capacitance). While accurate, the impedance of the circuit in Fig. 2b has no simple analytical form. A commonly used approximation to such model is the circuit shown Fig. 2c.^{38,42} Here, the chemical capacitors related to electronic and ionic species in the bulk of the MIEC are combined into a chemical capacitance C^δ , as $(C^\delta)^{-1} = (C_{\text{ion}}^\delta)^{-1} + (C_{\text{eon}}^\delta)^{-1}$, which refers to the storage of the relevant component (e.g. iodine in MAPI). As transport of such component involves both electronic and ionic transport, the chemical resistance $R^\delta = R_{\text{eon}} + R_{\text{ion}}$ is also defined. The geometric capacitance C_g encapsulates the contributions of the whole electrostatic rail of circuit 2b. The interfacial behavior is described by the elements $R_{\text{eon}}^\perp$, $R_{\text{ion}}^\perp$, $C_{\text{eon}}^\perp$, $C_{\text{ion}}^\perp$.^{41,44} If the double layer capacitance $C_{g,c}^\perp$ is large, $C_j^\perp$ represents the space charge capacitance at the interface associated with the j -th charge carrier:

$$C_j^\perp = A \epsilon_s \epsilon_0 / L_{D,j}, \quad (3)$$

where $L_{D,j} = \sqrt{\frac{k_B T \epsilon_s \epsilon_0}{q^2 z_j^2 c_{(j)}}}$ is the corresponding Debye length.³⁴ Importantly, $C_j^\perp$ is independent on MIEC thickness, L , as opposed to C_j^δ , which is linearly proportional to L .



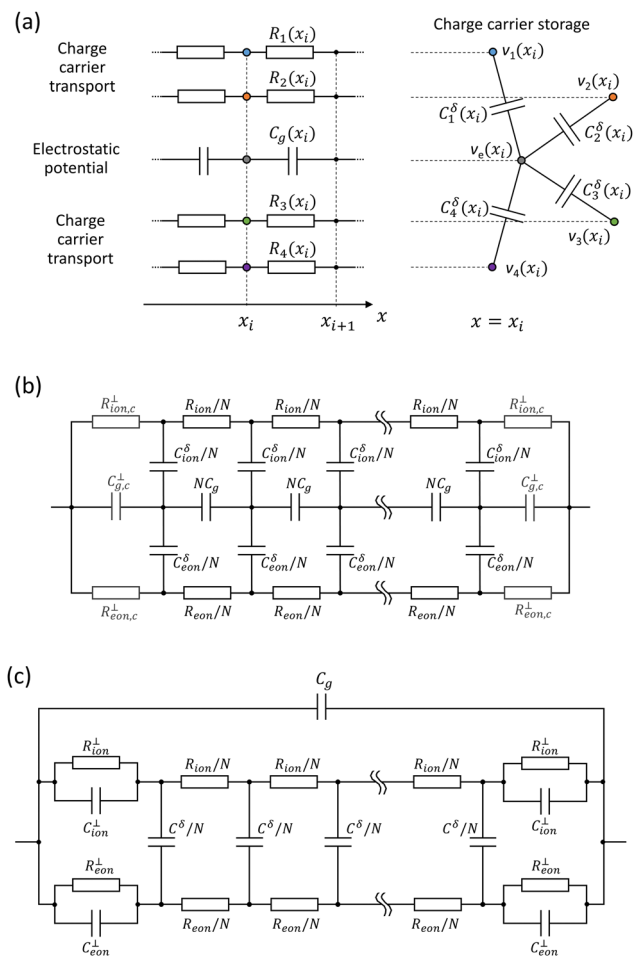


Fig. 2 Transmission line models for mixed ionic–electronic conductors close to equilibrium in the dark. (a) Constituting parts of the transmission line model for the case of four mobile charge carriers: (left) charge carrier transport rails (electrochemical resistors) and electrostatic rail (electrostatic capacitors) along the position axis, x ; (right) charge carrier storage implemented through chemical capacitors (e.g. $C_j^\delta(x_i)$ for the j -th charge carrier) connected between the nodes of each charge carrier rail (here displayed for $x = x_i$) and the electrostatic rail. The potentials v_j refers to the change in electrochemical potential of the j -th charge carrier ($qv_j = d\tilde{\mu}_j$, q is the elementary charge), while v_e is the change in electrostatic potential ($v_e = d\phi$). (b) Transmission line circuit model for two charge carriers (the subscripts *eon* and *ion* refer to electronic and ionic). Resistors and capacitors modeling the interfacial contribution due to the contacts are also included ($R_{eon}^\perp$, $R_{ion}^\perp$, $C_{eon}^\perp$ and $C_{ion}^\perp$). (c) Approximated version of circuit (b): the electrostatic rail is replaced by a single capacitor, and the electronic and ionic chemical capacitors in the bulk are combined. The elements $R_{eon}^\perp$, $R_{ion}^\perp$, $C_{eon}^\perp$ and $C_{ion}^\perp$ describe the interfacial behavior associated with each charge carrier.

Let us consider a situation where contacts show ion-blocking and ohmic behavior, and where $c_{ion} \gg c_{eon}$ (relevant to this study). It follows that $R_{ion}^\perp \rightarrow \infty$, $R_{eon}^\perp \rightarrow 0$ and $C_{ion}^\perp \gg C_{eon}^\perp$. In addition, if $\chi_{eon} \approx 1$, then the chemical capacitance can be approximated as $C^\delta \approx C_{eon}^\delta$ and its value can be very small in the dark. The impedance Z (normalized by A) for the transmission line model in Fig. 2b resulting from such condition is shown with red data points in Fig. 3a for the frequency range $f = 10^{-5}$ – 10^4 Hz (inset in Fig. 3a displays the

corresponding capacitance, calculated as $C = \text{Im}[Z^{-1}](2\pi f)^{-1}$). The data are compared with the calculated impedance obtained when considering a small value of χ_{eon} , shown with cyan data points. This refers to the case of significant trapping of electronic charge carriers, which results in large C_{eon}^δ , and therefore in large C^δ .¹

At high frequency, the impedance in the Nyquist plot forms practically identical semi-circles for the two examples. Such feature is related to the parallel of the ionic and electronic resistances and the overall sample's geometric capacitance C_g . On the other hand, the features associated with the low frequency behavior show a pronounced difference in terms of spectral shape and in the time constant depending on the value of C^δ . The low frequency semicircle for the case of small C^δ can be well explained by the circuit in Fig. 3b, where the blocking of the ions by the contacts gives rise to the space charge polarization behavior.⁴⁴ For the large C^δ data, the polarization gives rise to a Warburg feature (initial increase in impedance at 45° on the Nyquist plot for decreasing frequency), characteristic of ambipolar diffusion. Such feature derives from the dynamics of stoichiometry gradient build-up across the bulk of the sample (see also energy level description¹³ and further discussion in Fig. S1, ESI†).

While both space charge polarization and stoichiometric polarization processes inevitably occur in all MIEC based systems with ion-blocking contacts, only one of the two processes generally dominates the low frequency response. As a result, the low frequency capacitance corresponds to about $C_{ion}^\perp/2$ or $\sim C^\delta/12$ (see inset of Fig. 3a), with a time constant in the order of $(R_{eon} + R_{ion})C_{ion}^\perp/2 = R^\delta C_{ion}^\perp/2$ and $\sim R^\delta C^\delta/12$, respectively (assuming $R_{eon}^\perp \ll R_{ion}^\perp$).^{44,50} The 1/2 and 1/12 terms account for the series of the two space charge capacitors and for the fact that the chemical capacitors are charged to different fractions of the applied voltage and through different networks of resistors depending on their position in the circuit, respectively. It follows that, for a MIEC between metal contacts, the low frequency capacitance is typically $\leq 10^{-4}$ F cm⁻² (depending on the charge carrier concentration and corresponding Debye length) and it is independent on sample thickness for cases where space charge polarization is dominant. On the other hand, it has no upper limit and it is linearly proportional to the sample thickness for cases where the buildup of a stoichiometric gradient in the MIEC is the rate limiting process to the polarization. The scaling of the capacitive response at low frequency with device thickness can be used as a discriminating factor to evaluate the regime under which a MIEC based system is operating. We will use this argument to discuss our results below.

Results and discussion

A. Electrical response of MAPI based horizontal devices

Electrical measurements of MAPI based horizontal devices were conducted in the dark at 40 °C in controlled atmosphere (see Methods section and ref. 14 and 51). The device structure is



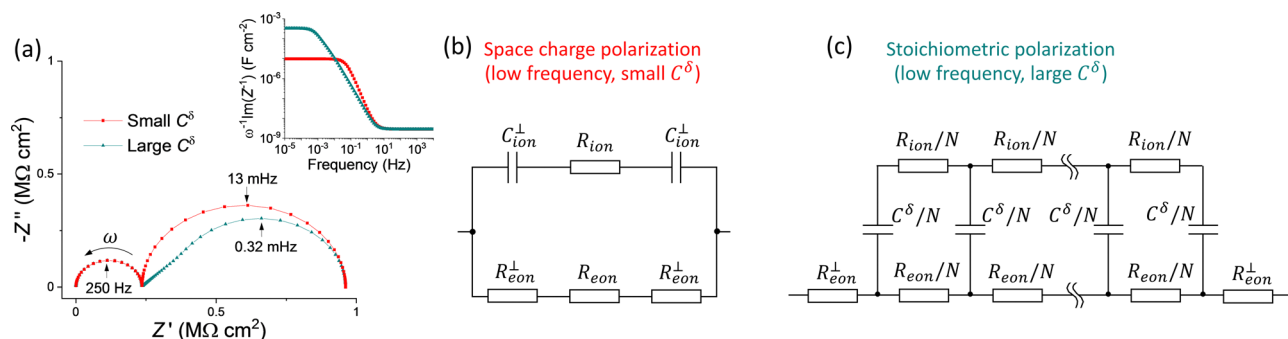


Fig. 3 (a) Nyquist plot of calculated impedance spectra for a MIEC between ion blocking contacts, $R_{ion} \rightarrow \infty$ (angular frequency $\omega = 2\pi f$, with f being the frequency). Two input parameter sets are considered where the value of the ionic chemical capacitance is fixed and the value of the electronic chemical capacitance is either $C_{eon}^0 \sim 3 \times 10^{-2} C_{ion}^0$ giving rise to a large C^δ , or $C_{eon}^0 \sim 3 \times 10^{-11} C_{ion}^0$ giving rise to a small C^δ . All other parameters have the same value (see Methods). The low-frequency behavior can be described in terms of (small C^δ) space charge polarization or (large C^δ) stoichiometric polarization. The inset in (a) shows $\omega^{-1} \text{Im}[Z^{-1}]$ (capacitance of the system for close to equilibrium conditions) plotted vs. frequency. (b) and (c) illustrate the equivalent circuits that describe the low frequency behaviors for the two situations.

displayed in Fig. 4a and b, highlighting the two geometrical parameters, L and L_C , that we explored in the results discussed below. Fig. 4c and d show the DC Galvanostatic polarization and impedance spectroscopy measurements performed on one such device.

The DC measurement indicates an increase in the measured voltage with time (t) on application of a constant current to the sample. The measurement allows us to analyze the polarization occurring in the thousands of seconds time scale ($\tau \sim 1500$ s, Fig. 4f) and extract the long time scale value of the conductivity. Based on the assumption of ion-blocking contacts, such value can be assigned to the electronic component only (in this case $\sigma_{eon} = 3.4 \times 10^{-10} \text{ S cm}^{-1}$).¹ The early time scale behavior of the DC polarization plotted vs the square root of time (Fig. 4e) highlights the initial voltage jump on application of the current, which can be assigned to the total conductivity (ionic and electronic contributions) of the sample. It also displays a trend of the voltage vs. $t^{1/2}$ that appears approximately linear for the early times. The latter feature is typical of a diffusion process and potentially consistent with a Warburg-like low frequency feature in impedance terms. This consideration may point towards stoichiometric polarization dominating the response of the sample.

However, when looking at the impedance response, which allows us to analyze the high and intermediate frequency region (fast and intermediate time scales) more carefully, a different picture arises. At frequencies > 1 Hz, a semicircle in the Nyquist plot can be attributed to the (high frequency) total resistance and geometric capacitance of the device. At lower frequencies, instead of a Warburg feature, we observe a slightly depressed semicircle-like feature. While the response of the sample according to the profile of the DC measurement in Fig. 4e appears as a diffusion process, the low frequency feature of the impedance spectrum indicates a less straightforward behavior. We also observe a relatively small mid-frequency region (frequencies ~ 0.1 – 1 Hz) separating the low frequency polarization from the high frequency semicircle. Importantly, the method to extract the correct value of the total resistance (conductivity)

depends on the nature of this mid-frequency feature, as highlighted with red arrows in the inset of Fig. 4d. Such value might also differ from the one extracted by using the initial jump in the DC measurement as a measure of the total resistance times the current (red arrow in the inset of Fig. 4e). Indeed, the time scale associated with this estimate is dependent on the time resolution of the instrument used (see Section 2 in the ESI†). In order to investigate the nature of these features and to ascertain the role of space charge polarization and stoichiometric polarization in the observed response, we studied devices with systematically varied geometry. With reference to Fig. 4a, we fabricated samples where the values of gap width between the contact fingers, L , and the finger width, L_C , were varied over almost one order of magnitude (between 5–40 μm).

Fig. 5a and b show the DC polarization (normalized data) obtained for devices with variable L and L_C , respectively. The data indicate an increase in the time constant describing the long time scale behavior when either parameter is increased (Fig. S4, ESI†). The electronic conductivity extracted from the measurements, shown in Fig. 5c as function of L or L_C depending on the experiment, is generally reproducible for the different devices, with only a slight increase when increasing the value of L . This trend could be interpreted by considering a finite value of $R_{eon}^\perp$ associated with the MAPI/Au interface. The nature of this resistance may be due to some injection barrier at the interface or to a more complex space charge situation forming in MAPI at the interface with gold and with the alumina substrate (see analysis in Fig. S5, ESI†).⁵² Fig. 5c also displays the ionic conductivity, which was extracted by first evaluating the total conductivity (σ_{tot}) from the high frequency semicircle of the impedance spectra (see discussion below and Fig. S3, ESI†) and evaluating $\sigma_{ion} = \sigma_{tot} - \sigma_{eon}$. As discussed above, the dependence of τ/R^δ on L can provide useful information on the dominant polarization process in these devices. The relatively constant profile of such dataset plotted against the gap width L , displayed in Fig. 5d, suggests that the capacitive component responsible for the polarization is independent of the active layer thickness and is probably of interfacial nature.



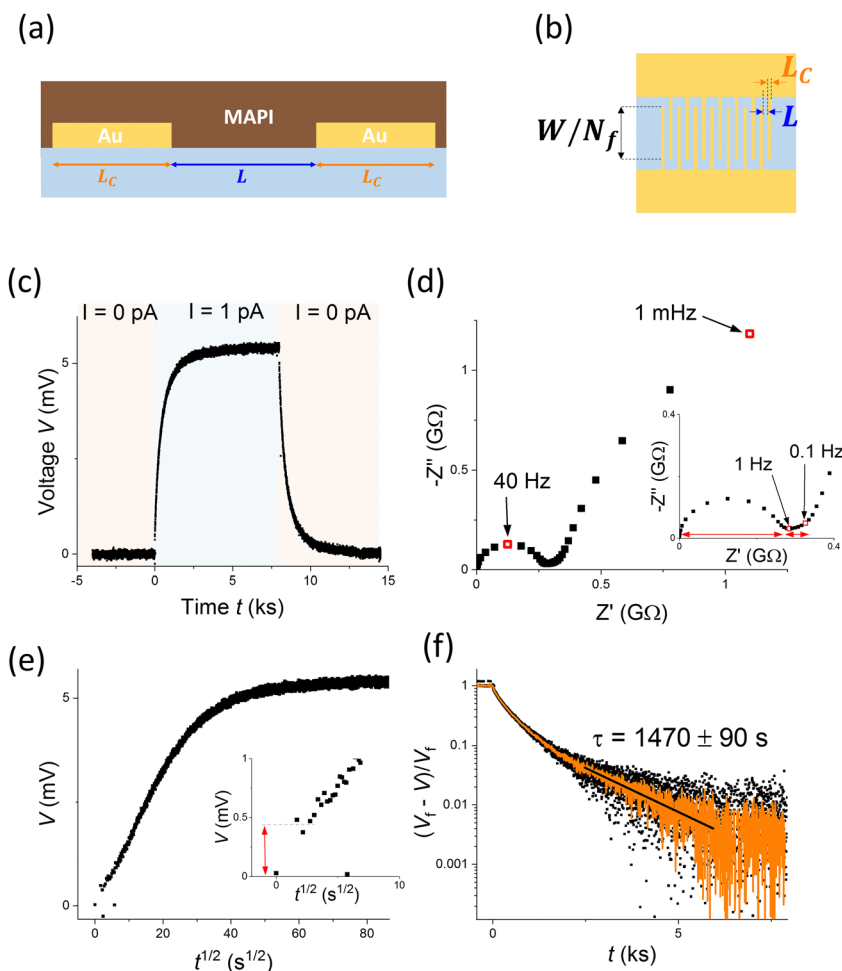


Fig. 4 Electrical characterization of MAPI based horizontal devices. (a) Schematics showing the cross section of the device with the two geometric parameters controlled in this study: L is the distance between the electrodes and L_c is the width of the electrode fingers. (b) Schematics of top view of the interdigitated contacts with total overlap of W (N_f is the total number of fingers). (c) DC Galvanostatic polarization and (d) impedance spectroscopy measurements performed on a device with $L = 10 \mu\text{m}$, $L_c = 5 \mu\text{m}$ and $W = 24.83 \text{ cm}$ in argon atmosphere, in the dark and at 40°C . In (c), a constant voltage baseline ($\sim 0.5 \text{ mV}$) was subtracted from the data. Polarization behavior displayed (e) vs. the square root of time and (f) on a semi logarithmic plot. The orange data points in (f) are obtained by using a smoothed version of the measured voltage data to calculate $(V_f - V)/V$ and are used for the fit to extract the time constant τ (V_f stands for the asymptotic value of the voltage during the polarization).

We find that the dependence of τ/R^δ on L_c is instead approximately linear, indicating that the increase in finger width effectively increases the capacitance involved in the long time scale polarization.

Further insights into the electrical response of the devices is gathered from the analysis of their impedance spectra, displayed in Fig. 6c and Fig. 6d. The trend in the high frequency feature in Fig. 6c indicates the increase of the total resistance following the increase in the value of L . On the other hand, Fig. 6d shows an approximately unvaried high frequency feature for different L_c , but a striking change in the mid-frequency behavior. The region with data points arranged with approximately $\sim 45^\circ$ slope increases in size when increasing the value of L_c .

To interpret this observation, we consider the device geometry and the approximate paths that are taken by ionic and electronic charge carriers. In the region between the contacts,

we expect ionic and electronic charges (holes are the relevant carriers here⁵³) to be transported within the bulk of the halide perovskite. Based on the discussion of Fig. 5, the transport in this region can be modeled with a simplified version of the transmission line circuit in Fig. 2c, where the bulk chemical capacitance is omitted (Fig. 6a). Once the charges reach the gold contact, electronic carriers find a low resistance path while ions are blocked at such interface. The charging of the gold contacts, which gives rise to the observed polarization, occurs *via* charging of the Au/MAPI interface with electronic charges on the gold side and ionic charges on the MAPI side. For the latter to occur, ionic defects need to diffuse in the direction parallel to the MAPI/Au interface over a distance ($L_c/2$, given the symmetry of the interdigitated contacts) that is comparable to the gap between the contacts for this sample geometry. This ion diffusion gives rise to the mid-frequency feature in the impedance spectra. The behavior is analogous to the charge



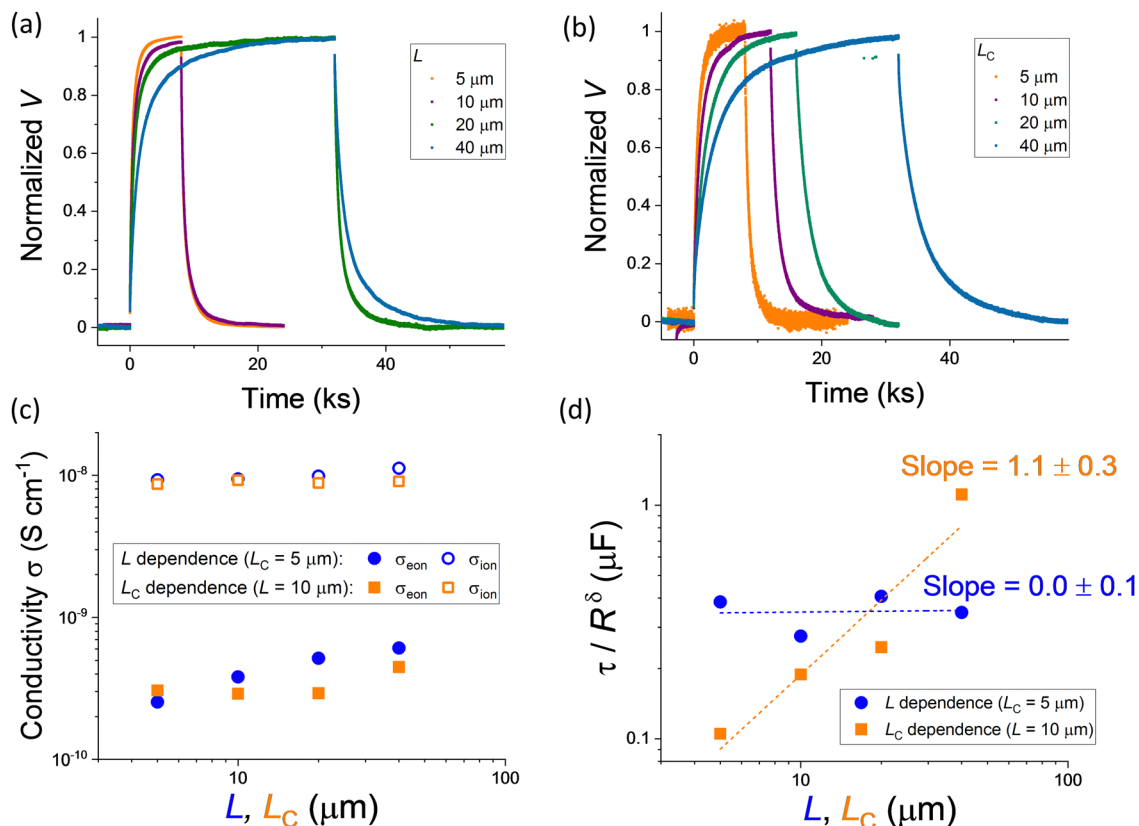


Fig. 5 DC galvanostatic polarization measurements of MAPI deposited on horizontal devices with interdigitated gold contacts. Data for devices with gap width between the contacts and contact finger width in the range 5–40 μm are shown. Normalized voltage measurement upon application of a current step at time = 0 (for all measurements the voltage was < 60 mV) showing (a) the gap width L and (b) the finger width L_c dependence of the polarization behavior. The current was applied for a variable time depending on the device. (c) Electronic and ionic conductivities extracted from the measurements in (a) and (b) (impedance measurements were also used in the analysis, see text). (d) Long time scale capacitive behavior of the devices evaluated from the analysis of the time constant extracted from the data in (a) and (b) divided by the chemical resistance $R^\delta = R_{\text{eon}} + R_{\text{ion}}$.

diffusion observed in electrolytes penetrating porous conductive electrodes, as discussed by de Levie.⁵⁴ This interpretation is confirmed by the change in the size of the mid-frequency transition relative to the overall impedance for the L dependent data. Such intermediate region almost disappears, in relative terms, for the device with the longest gap width ($L = 40 \mu\text{m}$). Indeed, in this case the width of the contact is significantly shorter than L .

Based on the observed trends, a simplified way to model the two-dimensional problem at the MAPI/Au interface is to consider a one-dimensional transmission line, where the electronic resistance on the metal side is practically zero and the ionic resistance of the layer on top of the contact ($R_{\text{ion}}^\parallel$) is related to the ionic conductivity in MAPI (Fig. 6a). The capacitance $C_{\text{ion}}^\perp$ is, in this case, a distributed contact capacitance and its meaning is associated with both the chemical and the electrostatic components of the interfacial charging at each position.⁵⁵ By “condensing” such transmission line model within an open Warburg element (W_O), we derive the equivalent circuit in Fig. 6b. The result of fitting such model to the data is displayed in Fig. 6c and d (see dotted lines), from which we obtain the value of R_{ion} , used to evaluate the ionic conductivity

displayed in Fig. 5c. Note that, based on the equivalent circuit model in Fig. 6b, the total conductivity can be extracted from the high frequency semicircle without accounting for the mid-frequency feature (see Fig. 3d). We also emphasize the dependence of the parameter $W_O \cdot T$, which is the time constant associated with the Warburg element, on L and L_c . This fitted parameter scales approximately with the square of L_c , as expected for a diffusion process, while it is much less sensitive to variations in L (Fig. 6e). The complete set of fitting results is shown in Fig. S6 (ESI†).

As a consistency check, we can use two methods to extract the value of the effective distance d between the electronic and ionic charges in the gold and in MAPI, respectively, on charging. A first method involves evaluating such distance from the value of capacitance observed for the DC polarization measurement (τ/R^δ). Alternatively, we can use the parameter $W_O \cdot T$ and extract d based on the ionic diffusion in the MAPI region on top of the metal contact (see Methods section for more details).⁵⁶ The results are displayed in Fig. 6f and show distances in the range of 0.1–1 nm, if one assumes a relative dielectric permittivity of this region of 32.¹ These values correspond to specific capacitance values of the electrode/MAPI interfaces as high as 20–200 $\mu\text{F cm}^{-2}$.

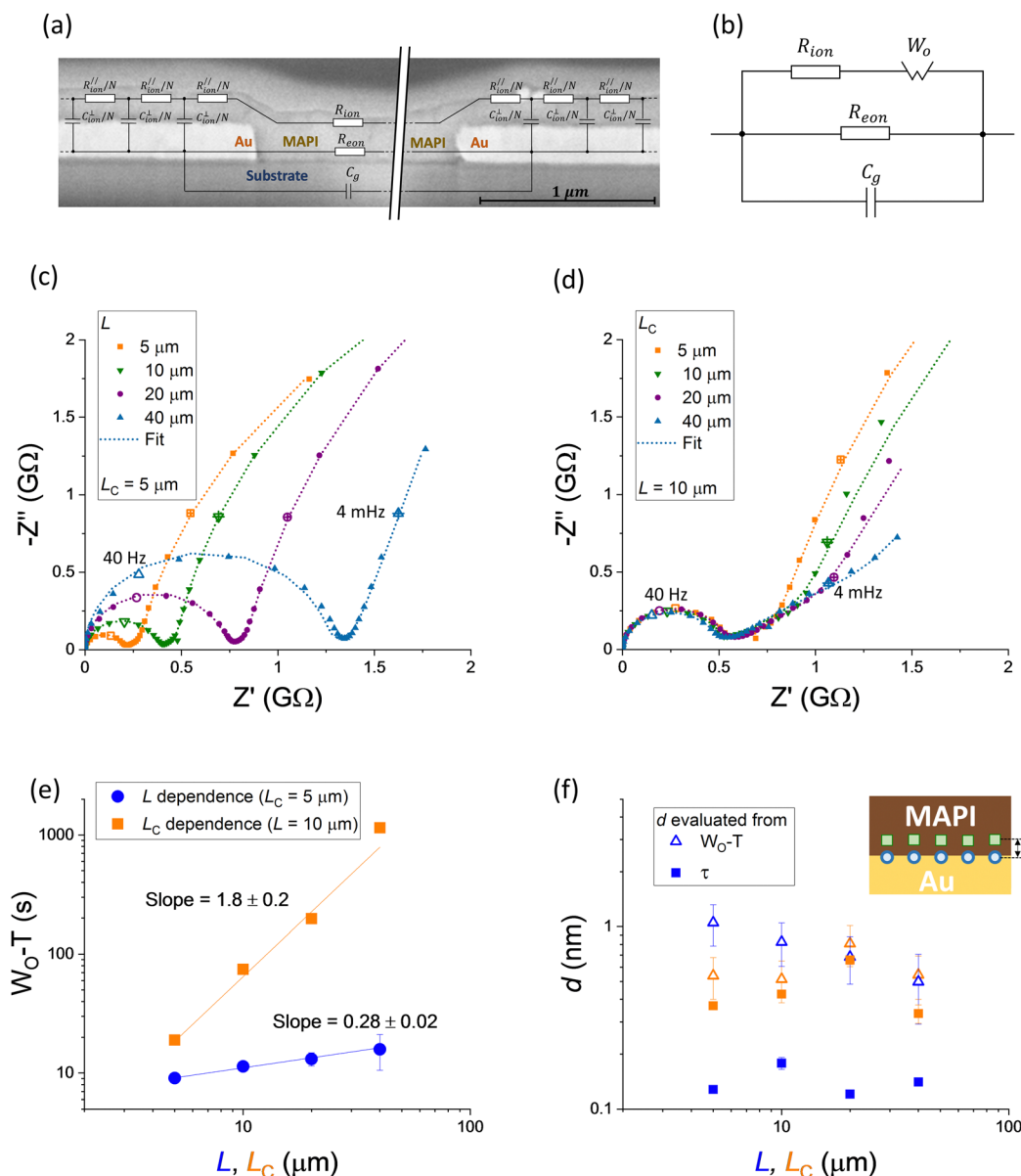


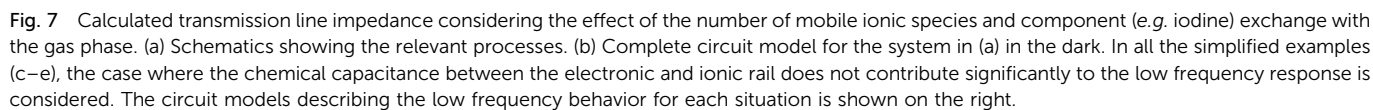
Fig. 6 Impedance measurements on MAPI based devices with horizontal architecture and interdigitated gold contacts (same as Fig. 4). (a) and (b) Extended and compact equivalent circuit model fitted to the experimental data (see discussion in text). The circuit in (a) is superimposed to a cross-sectional SEM image of a device. Impedance spectra measured for devices with (c) variable gap width L and (d) variable finger width L_C . The dotted lines are fits obtained using the circuit in (b). The empty symbols and the crossed empty symbols indicate the complex impedance of the samples measured at 40 Hz and 4 mHz, respectively. (e) Dependence of the W_o-T parameter describing the finite Warburg element (associated with the mid-frequency behavior of the impedance) on L and L_C . (f) Effective distance d between the charges at the metal/MAPI interface, extracted from either W_o-T or τ . We assign the value of d to the Debye length in MAPI.

The results interpreted in terms of space charge polarization in MAPI (assuming very large capacitance for the gold contact and the core separating MAPI and the metal) imply a value of the Debye length (λ) in the order of 1 nm and a charging mechanism that effectively occurs over the first ionic layer(s) (the iodide ionic radius is ~ 0.21 nm). This estimate of λ is roughly consistent with our previous estimate obtained from the analysis of ionically-generated space charges between MAPI and metal oxides,⁵² and points towards ionic defect concentrations in MAPI in the order of 10^{19} cm^{-3} (mobility $\sim 10^{-9} \text{ cm}^2 \text{ V}^{-1} \text{ s}^{-1}$).

B. Effects of multiple mobile ionic species and halogen exchange with the gas phase

We explore other possible effects that can contribute to the observed electrical response of hybrid perovskite devices close to equilibrium by performing impedance spectra calculations of one dimensional transmission line equivalent circuit models (Fig. 7a). First, we describe the exchange of iodine with the gas phase. Based on the equilibrium reaction $\text{I}_1^X + \text{h}^\bullet \rightleftharpoons \frac{1}{2}\text{I}_2 + \text{V}_1^\bullet$, fixing the iodine partial pressure $P(\text{I}_2)$ in the gas phase





corresponds, in equivalent circuit model terms, to applying a potential difference between the electronic and the (iodide) ionic rails *via* an impedance element Z_{exc} . The latter describes the exchange reaction kinetics at the solid/gas interface.⁵⁵ Because we are interested in the small signal behavior of the circuit, only Z_{exc} contributes to the impedance calculation.

Second, we consider the description of two ionic species, indicated with *a* and *b* (e.g. transport of iodide and methylammonium defects in MAPI).^{19,20} Following the transmission line approach in Fig. 2, we include two ionic rails of resistance $R_{\text{ion},a}$ and $R_{\text{ion},b}$ that are connected to the electrostatic rail *via* chemical capacitors $C_{\text{ion},a}^{\delta}$ and $C_{\text{ion},b}^{\delta}$. If the ionic disorder reaction between the two defects establishes local equilibrium at a fast enough rate compared to the ionic transport through the device, a single ionic rail can be used, where the total ionic resistance is $R_{\text{ion}} = \frac{R_{\text{ion},a}R_{\text{ion},b}}{R_{\text{ion},a} + R_{\text{ion},b}}$ and the total ionic chemical capacitance is $C_{\text{ion}}^{\delta} = C_{\text{ion},a}^{\delta} + C_{\text{ion},b}^{\delta}$ (see Fig. S7 in the ESI†). In this case, the circuit reduces again to the one in Fig. 2b. Below we explore the situation where ionic disorder is not at equilibrium (at the time scale of the impedance analysis), and therefore two separate rails for the two ions are needed. Fig. 7b shows the resulting circuit model including two ionic species (not at equilibrium) and the component exchange impedance. In the discussion that follows, we further simplify this circuit by focusing on its approximated versions at low frequencies, for different situations (see also analytical treatment in Section 6 of the ESI†). We also neglect the chemical capacitance between electronic and ionic charges in the system (see Fig. 5 and 6 and discussion above) and consider negligible values for the interfacial electronic resistance $R_{\text{eon},c}^{\perp}$.

Fig. 7c considers the effect of component exchange for the one mobile ion case. Because the NZ_{exc} elements connect the electronic and ionic rails, ionic conduction can contribute to the low frequency conductivity despite the ion blocking properties of the contacts, as evidenced by the impedance data (here Z_{exc} is assumed to be a resistor $Z_{\text{exc}} = R_{\text{exc}}$). When $R_{\text{exc}} < R_{\text{eon}}$, the size of the semicircle associated with the low frequency impedance reduces. For very low values of R_{exc} , the ionic and electronic rails are essentially connected in parallel and the electrical response tends to a purely resistive behavior (see also the decrease in the low frequency capacitance for decreasing R_{exc}). The low frequency response can be described with the equivalent circuit model in Fig. 7c. For the case of MAPI based devices, we can interpret this result as follows: while the application of an electrical bias would establish a gradient in iodine chemical potential in the sample (along the *x* direction), the fixed $P(\text{I}_2)$ in the gas phase eliminates such gradient for low enough values of R_{exc} . As a result, the DC response of the system involves, in addition to the steady state flow of electronic charges in MAPI, a flow of iodide defects as well as an equal and opposite flow of iodine ($\frac{1}{2}\text{I}_2$) in the opposite direction in the gas phase. Importantly, the electronic conductivity in the sample could be overestimated when associating the very low frequency (or very long time scale) resistance with R_{eon} , without

accounting for the contribution from R_{exc} . Secondly, because the high frequency semicircle resistance remains unchanged on varying the value of R_{exc} , the extracted ionic conductivity can, on the other hand, be underestimated when using the formula $\sigma_{\text{ion}} = \sigma_{\text{tot}} - \sigma_{\text{eon}}$.

Next, we consider the situation where two mobile ionic defects (*a* and *b*) are at play. We define the chemical capacitance describing the storage of *ab* (e.g. MAI in MAPI) for ions that are not at equilibrium based on $(C_{\text{ion},ab}^{\delta})^{-1} = (C_{\text{ion},a}^{\delta})^{-1} + (C_{\text{ion},b}^{\delta})^{-1}$. If the ionic concentration of *a* and *b* is large, the value of $C_{\text{ion},ab}^{\delta}$ can be significant, implying that the two ionic rails shown in Fig. 7b are effectively in parallel in the relevant frequency range. A single ionic rail can then be used, as shown in the left circuit in Fig. 7d (note that the interfacial capacitance $C_{\text{ion},ab}^{\perp}$ is calculated referring to the Debye length that includes contributions from both ions). If $\sigma_{\text{ion},b} \ll \sigma_{\text{ion},a}$, the contribution of *b* to the impedance is negligible, although a slight variation in the shape of the low frequency feature is observed compared with the $\sigma_{\text{ion},b} = 0$ case. More significant changes occur if the two ions contribute to σ_{ion} to a similar extent (here we consider $\sigma_{\text{ion},a} = \sigma_{\text{ion},b}$). In the Nyquist plot in Fig. 7d, the pink data points (large $C_{\text{ion},ab}^{\delta}$) refer to such situation, assuming the same ionic concentration and mobilities for the two defects as for the one ionic defect in the reference case (red data points). Compared with the case of a single mobile ion, a smaller high frequency semicircle (lower ionic resistance) and a larger capacitance at low frequencies (shorter Debye length) are observed for the two mobile ion case. Another interesting scenario occurs if $\sigma_{\text{ion},a} = \sigma_{\text{ion},b}$, but at least one of the two ionic defects is low in concentration, resulting in a low value of $C_{\text{ion},ab}^{\delta}$. This implies that the rails associated with the two ions can no longer be considered in parallel for the evaluation of the low frequency polarization, as shown in the right circuit of Fig. 7d. As an example, we consider *b* to have four orders of magnitude lower concentration and four order of magnitude higher mobility than *a*. The blue data points in Fig. 7d show that two features appear at low frequencies. The difference in the time constants associated with the two features is due to the different values for the interfacial capacitors for each ionic rail, which are related to each ionic defect concentration as discussed above ($R_{\text{ion},a}C_{\text{ion},a}^{\perp}/2 \neq R_{\text{ion},b}C_{\text{ion},b}^{\perp}/2$).

Finally, we consider the two effects discussed in Fig. 7c and d occurring simultaneously. In Fig. 7e, two mobile ionic species (e.g., iodide and MA vacancies) with equal value of mobility and concentration (large $C_{\text{ion},ab}^{\delta}$ case) and different values of R_{exc} are considered. The exchange with the gas phase effectively allows for a constant flux of one of the ionic species at steady state but not of the other. As a result, a stoichiometric polarization involving the two ionic defects is established at low frequencies. In our example, a gradient in the chemical potential of MAI is generated across the active layer thickness (along *x*), its formation dominating the very low frequency response of the sample. As evident from the calculated impedance, an additional (Warburg) feature at low frequencies arises for low enough values of R_{exc} , which is attributed to stoichiometric polarization. The capacitance associated with such feature



(see inset in Fig. 7d) can become larger than the capacitance related to the series of the interfacial capacitors, approaching $C_{\text{ion},ab}/12$ as discussed for Fig. 3.

We now discuss whether these effects can be relevant for measurements of mixed conduction in hybrid perovskite devices in the dark, in relation to the experiments performed on MAPI presented in this study. The effect of iodine exchange on the measured impedance can be tested by comparing samples with and without encapsulation. An insulating layer on top of the perovskite is expected to significantly increase the value of Z_{exc} . In Fig. 8a, we show that the electrical response and conductivities obtained from such analysis for measurements in argon are comparable. This suggests that the kinetics of component exorporation in argon is not critical to the evaluation of the partial conductivities in MAPI under these conditions. However, the contribution of Z_{exc} to the measured electrical response may become important when the sample is investigated under a fixed $P(\text{I}_2)$. The $P(\text{I}_2)$ dependence of the ionic and electronic conductivities for a MAPI sample, extracted as described above, are plotted in Fig. 8b. We observe a relatively unvaried ionic conductivity (value similar to the one measured under argon) over about two orders of magnitude change in $P(\text{I}_2)$ and an increase in the electronic conductivity that follows approximately $\sigma_{\text{eon}} \propto P(\text{I}_2)^{0.5}$. The trend was the same irrespective of device geometry (see Fig. S9 and S10, ESI†) and is consistent with previous reports from our group and others.^{17,21} The results confirm the p-type electronic conduction within the intrinsic regime.⁵³ Furthermore, we can rule out a dominant contribution of the iodine exchange with the gas phase as an “alternative path” for the measured electrical conduction at low frequencies close to equilibrium. Indeed, this path involves the flow of ionic charges in the device, which is limited by the ionic conductivity of MAPI, as illustrated in Fig. 7c. Because the data in Fig. 8b show that $\sigma_{\text{eon}} > \sigma_{\text{ion}}$ at large enough $P(\text{I}_2)$, they confirm that conduction at low frequencies is dominated by electronic transport in the active layer. As a consequence, the impedance spectra associated with devices measured at high $P(\text{I}_2)$ can be analyzed using the circuit model in Fig. 6b, as shown in Fig. 8c. The data show that the larger the $P(\text{I}_2)$, the more the electronic conductivity dominates the impedance response, with the low frequency feature associated with the space charge polarization shrinking in magnitude. No significant changes are observed in the capacitance spectra when varying $P(\text{I}_2)$ (inset of Fig. 8c). The results are consistent with the space charge capacitance dominating the low frequency response and the approximately unvaried ionic defect concentration (and Debye length) expected when varying stoichiometry within the intrinsic region of MAPI.⁵³

Finally, we cannot rule out a significant contribution coming from the transport of two different ionic species to the observed electrical response of the devices. This is however unlikely, in that the mobility of MA and Pb defects have been established to be much lower than that for iodide.¹⁷ The role of protons may be relevant for devices prepared and/or measured under humid atmosphere, which was not the case for our experiments.⁵⁷ We conclude by pointing out that other effects, such as a second

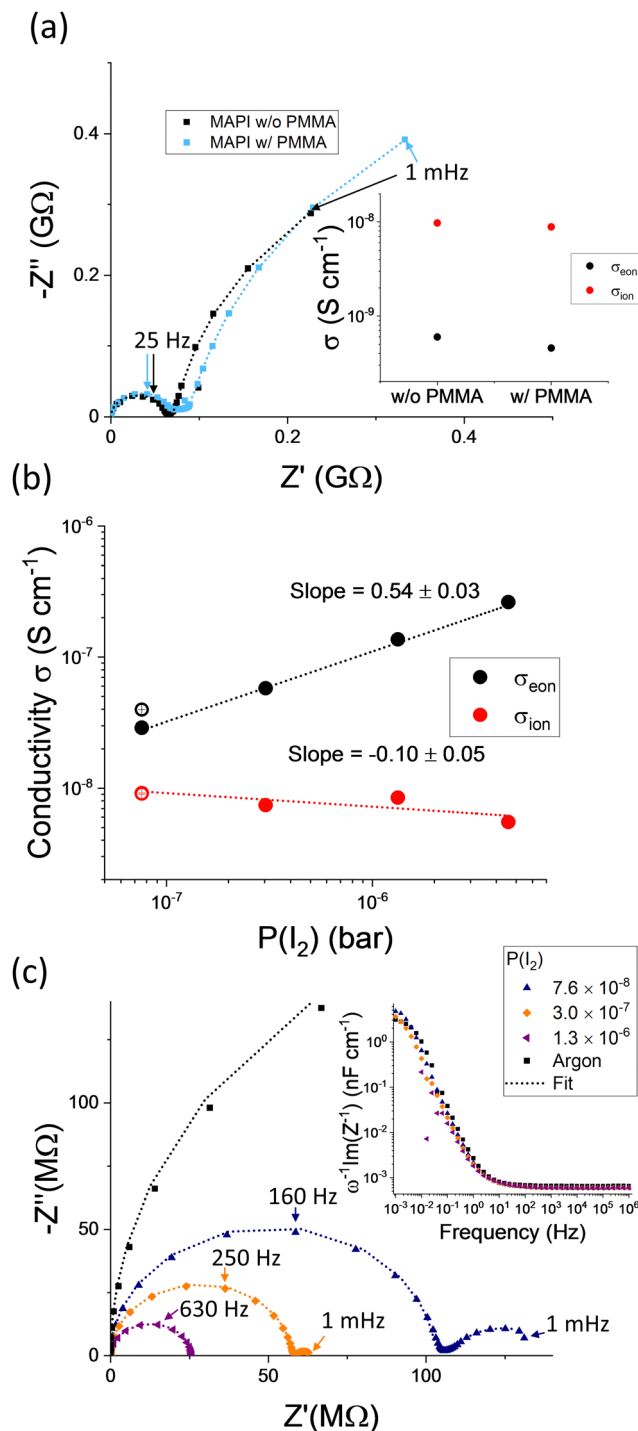


Fig. 8 Electrical measurements on MAPI based horizontal devices with $L_c = 5 \mu\text{m}$ and $L = 10 \mu\text{m}$ performed in the dark close to equilibrium. (a) Comparison of impedance spectra and conductivities for devices with and without a PMMA encapsulation layer coated on top of the MAPI film (measurements performed in argon). Iodine partial pressure dependence of (b) the ionic and electronic conductivities, (c) the impedance spectra and (inset) capacitance of a MAPI device without encapsulation (the capacitance is expressed in F cm^{-1} as it is normalized by W only). The empty symbols in (b) are measurements performed at the end of the experiment to check for reversibility.



ionic species that is lower in concentration but higher in mobility (see Fig. 7d), as well as grain boundary contributions, could also explain the presence of the mid-frequency feature observed in our impedance measurements. However, the device geometry trend presented in this study clearly assigns such feature to the diffusion of mobile ions in MAPI on top of the metal electrodes. In Section 8 of the ESI,[†] we discuss how the interpretation described above should be modified in presence of significant grain boundary resistance, which may be relevant to other halide perovskite compositions or preparation protocols.

In terms of implications for design and characterization of hybrid perovskite devices, the results presented in this study indicate that, for application relevant thicknesses (value of L in the horizontal devices investigated here), space charge polarization determines the dynamics of ionic redistribution and electric field screening in MAPI based devices close to equilibrium.^{58,59} This work also outlines a self-consistent approach for the study of mixed ionic–electronic conductivity in thin films using horizontal architectures. These structures enable the investigation of mixed-conducting properties of thin films within devices with well-defined geometry. The bottom contact structure used here (electrodes fabricated on substrate before active layer deposition) enables direct contact of the perovskite layer with metal electrodes, allowing one to analyze the active layer's behavior without significant interfacial space charge influence from the electrode side. A similar approach can be implemented in vertical structures too,⁶⁰ provided that no metal penetration in the active layer occurs during metal deposition. Transferring such analysis to conventional solar cell device structures with vertical architecture presents a number of challenges, including control of active layer thickness homogeneity and ion interactions (penetration, reaction) with the contacts, and should be addressed in the future. We note that the importance of device geometry, including two dimensional effects, can become relevant to vertical devices with rough and/or inhomogeneous interfaces, potentially introducing additional mid-frequency features associated with slow ion motion in these areas. The use of contact materials other than metals, including organic and inorganic semiconductors, can complicate the analysis due to the presence of significant space charges not only in the perovskite, but also on the contact side of the interfaces. These effects originate from electronic and, importantly, also from ionic equilibration (adsorption or exchange).^{52,61} The latter process can potentially introduce slow dynamics in the observed response on electrical biasing. The investigation of ionic conductivity and polarization effects close to equilibrium is therefore an important basic characterization step for these devices, enabling the identification of the processes dominating their dynamic behavior as function of the solar cell's parameters.

Conclusions

We performed a systematic electrical characterization of mixed ionic–electronic conductivity in methylammonium lead iodide

devices with horizontal structures. The data show that charging of the metal contact/MAPI interface dominates the long time scale response in the dark close to equilibrium of devices with effective thickness (gap width between contacts) up to tens of microns. This confirms that space charge polarization is the relevant low frequency process for devices with relatively thin active layers (or channel length) such as solar cells and transistors, when measured close to equilibrium and close to room temperature. The data suggest ionic charging at the contact/MAPI interface occurring *via* ion diffusion on top of the contact and in direction parallel to such interface, a feature relevant to horizontal devices with the structure considered in this study. We estimate a Debye length of ~ 1 nm width, suggesting a large ($\sim 10^{19}$ cm⁻³) mobile ionic defect concentration. We could also conclude that, when evaluating conductivities in these systems, information from DC measurements and also from impedance spectroscopy are necessary to accurately establish the contribution of the different components at different time scales (frequencies). Our analysis emphasizes the importance of accounting for sample geometry and presents a simple equivalent circuit model that can be used to investigate partial conductivities in devices with horizontal structures. Finally, from the impedance calculations presented, we highlight possible influence of multiple mobile ionic species and of iodine exchange with the gas phase affecting the estimation of the electronic and ionic conductivities, and we rule out significant contribution from the latter effect in the analysis performed on MAPI under the conditions explored in this work. Our study provides a framework to evaluate mixed ionic–electronic conduction in hybrid perovskites close to equilibrium, an important step towards the analysis of the more complex device response under bias.

Methods

Sample fabrication and characterization

Thin films of MAPI were deposited on alumina substrates with interdigitated electrodes using a previously reported procedure.^{51,52} The MAPI precursor solution consisted of 1.5 M MAI and 1.5 M PbI₂ dissolved in DMSO. The film processing was performed through spin coating and by using the anti-solvent method (chlorobenzene was used). The films were annealed at 100 °C for 5 minutes. The thickness of the films was determined *via* cross-sectional SEM, performed at the end of the experiments (see Fig. S12, ESI[†]). The electrodes on the substrate were patterned using a photo-lithography process and involved 20 nm of chromium used as an adhesion layer and 200 nm of gold. For both the L and the L_C dependent studies, the four devices shared the same substrate, meaning that a single MAPI film was used for each investigation. This approach enabled more careful analysis of the geometrical effects compared with similar experiments performed on separate substrates with different electrode geometries. For conductivity measurements, the samples were loaded in a measuring cell which enabled control of the sample temperature, the environmental



conditions and electrical connection to the sample. Measurements were performed at 40 °C, and under argon gas flow (O₂ concentration <30 ppm) or under fixed iodine partial pressure using argon as carrier gas. DC polarization measurements were performed using a Keithley source meter, while AC impedance was performed using a Novocontrol spectrometer. The displayed data were obtained after letting the sample stabilize at any given condition. Under argon, small changes in the long time scale behavior were still present between measurements after more than one week of continuous measurements (as expected for the case of P(I₂) not being fixed). Such changes occurred at a time scale that was slower than the measured polarization. We measured samples using X-ray diffraction (Panalytical Empyrean (Cu K_α, λ = 0.154 nm)) in Bragg-Brentano and grazing-incident geometry in a gas-tight dome to prevent exposure to air. Measurements performed before and after the electrical characterization showed negligible degradation of the perovskite (see Fig. S13, ESI†).

Data analysis

From the relevant resistances (e.g. R_{ion}) extracted from electrical measurements, we evaluated the corresponding conductivity using the relation $\sigma_{\text{ion}} = \frac{1}{R_{\text{ion}}} \frac{L}{Wl}$, where l is the thickness of the MAPI layer between the gold contacts (a value of 200 nm was considered, see Fig. 6a and Fig. S12, ESI†). Fitting of equivalent circuit models to the impedance data was performed using Z-view. For DC polarization measurements, a linear function was fitted to the data (see Fig. 4f) in a semilogarithmic plot. For some datasets, the single exponential fitting yielded slightly different results for the time constant and for the asymptotic value of the polarization voltage, depending on the initial time chosen for the fitting range. For simplicity, a single exponential function was used in all cases. The value of the initial time for the fit was increased until the fitting parameter associated with the asymptotic voltage value V_f yielded an approximately linear profile for the function $(V_f - V)/V_f$ at long time scales. The final time for the fitting was chosen such that the fitted data $(V_f - V)/V_f$ (before smoothing) in the fitted range were predominantly positive (negative values would yield imaginary logarithm values and would affect the accuracy of the fitting). We note that very slow stoichiometric polarization processes (due to slower ionic defects) may be occurring and giving rise to the dispersive polarization observed in some of the measurements (slightly depressed semicircle in Fig. 4d and 7d for the $\sigma_{\text{ion},b} \ll \sigma_{\text{ion},a}$ case). The values of d displayed in Fig. 6f were extracted based on two methods as discussed in the text. The first method involves considering an effective distance associated with the capacitive term displayed in Fig. 5d, $d = \epsilon_0 \epsilon_r [R^\delta + (W_{\text{O}} - R/2)]/\tau$ (ϵ_0 is the dielectric permittivity of vacuum, while the dielectric permittivity of MAPI ϵ_r was assumed to be 32¹). The factor $(W_{\text{O}} - R/2)$ is included here to account for the additional ionic resistance of the MAPI region on top of the gold contact (for the data measured in argon and shown in Fig. 6 this value is negligible compared to R^δ , such

that $d \approx \epsilon_0 \epsilon_r R^\delta/\tau$). The second method involves the parameter

$$W_{\text{O}} - T, \text{ for which we can write } d = \frac{\epsilon_0 \epsilon_r}{W_{\text{O}} - T \sigma_{\text{ion}} l} \left(\frac{L_{\text{C}}}{2} \right)^2 \text{ according to}$$

the analysis of the kinetics of space charge storage for the case of dual-phase transport.⁵⁶ Here l'' is the thickness of MAPI on top of the gold contact (we assumed $l'' = (200 \pm 50)$ nm, see Fig. 6a and Fig. S12, ESI†). We note that stoichiometric effects leading to the stretched behavior discussed above could also lead to some overestimation of the time constant due to interfacial charging evaluated from DC polarization. This could partially explain the discrepancy in the values of d calculated from τ compared to the ones calculated from $W_{\text{O}} - T$.

Impedance spectra calculations

The calculations were performed using a MATLAB code that evaluates the impedance of a given equivalent circuit model by solving a system of equations, each representing Kirchhoff's current law at all nodes minus one. Values for the electronic and ionic transport and charge storage parameters were explored based on literature values and to evaluate the role of different possible polarization behaviors. These values are listed in Section 11 of the ESI.† By using the model in Fig. 2b as a starting point, additional components have been investigated (e.g. two mobile ions, equilibrium with gas phase) as described in the Results section and in Fig. 7. The mesh for the calculations involved a finer spacing close to the boundaries and was refined based on an *a posteriori* error estimation. Accuracy in the order of 0.5% is estimated for all calculations with the following method. First, the numerical problem is solved with a fine mesh, yielding a reference solution for the impedance Z_{ref} . The calculation is run for other three meshes with much coarser spacing (by a factor of 5, 10 and 20). The error associated with the latter solutions with respect to the reference solution is calculated as $\text{Err} = \sqrt{(Z_{\text{calc}} - Z_{\text{ref}})^2 / Z_{\text{ref}}^2}$ averaged over the frequency range considered (10^{-5} – 10^4 Hz). From a linear fit in double logarithmic scale of the error vs the number of mesh points, the estimated number of mesh points needed to obtain an error with respect to the reference solution below the set tolerance, Tol, is calculated. Based on the slope of the error vs the number of points (α_{Err}), one can estimate the actual error for the optimized number of points as $\text{Tol} / (1 - (N_{\text{opt}}/N_{\text{ref}})^{\alpha_{\text{Err}}})$. A minimum ratio $N_{\text{opt}}/N_{\text{ref}} = 1/4$ is guaranteed by the code. If the resulting mesh is coarser than such factor, the solution is calculated. Conversely, another reference solution is calculated based on a mesh that is at least 4 times finer than the one defined by N_{opt} . The iteration stops when the above mentioned condition is met. The same protocol is applied to both the number of points associated with the interfacial regions and with the bulk. Typical values of the total number of nodes and of the number of interfacial points amounted to $N = 500$ and $N_{\text{int}} = 10$ – 200 (depending on the value of the circuit elements considered).

Conflicts of interest

There are no conflicts of interest to declare.



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