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Cite this: *Biomater. Sci.*, 2025, **13**, 2806

Supervised machine learning for predicting drug release from acetalated dextran nanofibers†

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Electrospun drug-loaded polymeric nanofibers can improve the efficacy of therapeutics for a variety of implications. By design, these biomaterial platforms can enhance drug bioavailability and site-specific delivery while reducing off-target toxicities when compared to other conventional formulations. By incorporating biocompatible and biodegradable polymers with tunable degradation rates, such as acetalated dextran (Ace-DEX), drug-loaded nanofibers can enhance the safety and efficacy of treatment regimens while improving patient compliance through controlled release. Despite these benefits, clinical translation of electrospun formulations is challenged by labor-intensive *in vitro* studies for ensuring that release kinetics are accurately characterized and reproducible. In this study, we report a novel workflow for assessing *in vitro* drug release from Ace-DEX nanofibers using machine learning (ML) and develop a predictive model to streamline this rate-limiting step. The developed Gaussian process regression (GPR) model was trained, validated, and optimized using *in vitro* release profiles from thirty electrospun Ace-DEX scaffolds. The results of GPR model simulations reveal consistent performance across all Ace-DEX formulations considered in this study while also demonstrating a drug-agnostic approach to predict fractional drug release over time.

Received 20th February 2025,
Accepted 27th March 2025

DOI: 10.1039/d5bm00259a

rsc.li/biomaterials-science

Introduction

Drug-loaded electrospun nanofibers have shown great promise as a therapeutic platform for various biomedical applications, ranging from cancer therapy to tissue regeneration.^{1–4} With tunable fabrication methods and nanofiber features, electrospinning can efficiently encapsulate a wide range of therapies and generate flexible, fibrous materials to optimize drug delivery. By design, these electrospun scaffolds exhibit a high surface area to volume ratio which promotes continuous and sustained delivery of loaded cargo through a variety of mechanisms.⁵ Furthermore, biocompatible and biodegradable polymers such as polyanhydrides can be used to fabricate these drug-loaded biomaterials which can afford safe and efficacious drug release as the nanofibers degrade under physiological conditions.⁶ For such reasons, electrospinning has been

widely explored and proven to be successful in the preclinical setting; however, many of these nanofiber formulations have yet to see the FDA-approval status which highlights the critical need for tools aimed towards bridging the gap between pre-clinical investigation and clinical application.⁷

With a vast range of applicable electrospinning methods, compatible materials with associated physicochemical properties, and physiological mechanisms governing drug release, drug-loaded electrospun nanofibers require a thorough and laborious preclinical assessment to ensure clinical translation. Optimizing design parameters is critical to early-stage development and can significantly influence the kinetics of drug release. The choice of polymer, for example, must exhibit drug and solvent compatibility when undergoing monoaxial electrospinning, which can directly influence the dynamics of drug release from the formed fibers.⁸ Furthermore, many FDA-approved polymers degrade *via* hydrolysis of ester bonds or enzymatic cleavage with unique rates, offering tunability for drug release when formulated as carriers.^{9,10} These mechanisms can influence not only the persistence of drug-loaded fibers *in vivo*, but also the release rate of the loaded therapeutic cargo. Understanding the features and mechanisms most influential to drug release from such biomaterials is critical to ensure that the optimum drug release rates are well characterized.

A biocompatible and biodegradable polymer widely investigated for drug delivery applications is acetalated dextran (Ace-

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†Electronic supplementary information (ESI) available. See DOI: <https://doi.org/10.1039/d5bm00259a>


DEX).^{11–14} Deriving from dextran, Ace-DEX degradation rates can be tightly controlled during synthesis where longer reaction times yield a higher relative cyclic to acyclic acetal coverage (%CAC) and, thus, a more hydrophobic polymer. Based on %CAC, degradation *via* hydrolysis can persist on the order of days to months, offering unique tunable release profiles of encapsulated drugs.¹⁵ Our group has previously reported the therapeutic potential of drug-loaded electrospun Ace-DEX nanofibers for localized, interstitial treatment of glioblastoma. When paclitaxel was co-delivered with two different %CAC formulations (low %CAC = fast and high %CAC = slow) of Ace-DEX scaffolds (Ace-PTX), the tumor burden and overall survival of mice with orthotopic U87 tumors were significantly improved.¹⁶ The unique rates of degradation and PTX release of the Ace-PTX scaffolds afforded optimum localized delivery of therapeutic cargo, which outperformed PTX-loaded scaffolds electrospun with either FDA-approved polylactic acid or Ace-DEX %CAC scaffold alone.

Another advantage of Ace-DEX over other polymer systems, such as chitosan or polyglycolic acid, is that it can be used to electrospin drug-loaded nanofibers using a wide variety of organic solvent systems.^{17,18} This offers feasibility for encapsulating drugs with different physicochemical properties in monoaxial electrospinning. By tuning the volatility of the solvent system, for example, drug distribution within the fibers as well as the initial rate of release can be controlled.¹⁹ Furthermore, we previously have shown how different drugs loaded into Ace-DEX nanofibers can afford drug-specific release rates, even when electrospun with the same %CAC of the polymer, weight drug loading (%wt/wt), and solvent system.²⁰ Although these differences in release demonstrate how electrospun Ace-DEX nanofibers offer therapeutic versatility, these formulation-specific trends are poorly understood and require laborious *in vitro* assessment to afford a desired rate of drug release.

Our group has recently reported drug-specific properties that influence rates of drug release from Ace-DEX spherical particles through the development of a mathematical and mechanistic model.²¹ Termed the ‘diffusion-erosion model’, constitutive equations governing both drug diffusion and polymer surface erosion of drug-loaded Ace-DEX nanoparticles (NPs) were applied to derive an empirical interpretation for predicting drug release. Observed drug release data were fit to this mechanistic model and used to quantify the effective diffusion coefficient (D) of encapsulated drugs – a critical parameter describing the rate of drug movement through a polymer matrix. Additionally, a neural network, or a machine learning (ML) model useful for identifying inter-parametric trends and computing predictions, was optimized to predict D of drugs through varying %CAC Ace-DEX NPs based on various physicochemical properties. The model revealed that the drug’s polar surface area was the most influential parameter for determining formulation-specific D and can be used in tandem with the diffusion-erosion model for predicting drug release. The results from this study demonstrate how drug diffusion and Ace-DEX degradation *via* NP surface erosion

influence the kinetics of release and change with respect to the encapsulated drug. Furthermore, incorporating ML with the diffusion-erosion model enhanced the model’s predictive power for informing future formulations while also strengthening the preclinical assessment of the relevant polymeric biomaterial.

Our previous work with Ace-DEX NPs takes a model-based approach for predicting drug release with well-defined assumptions for the finite spherical platform. When applying this framework to bulk biomaterials like electrospun nanofibers, this approach becomes less intuitive. This difference can be due to several factors including complex geometry, nanofiber organization, and *in vitro* conditions for assessing drug release from drug-loaded fibers. For example, electrospun nanofibers often take a cylindrical or ribbon-like shape with lengths significantly longer than observed diameters and are organized into a nonwoven matrix.²² This morphology results in a bulk material with varying thickness and porosity, influencing the dynamic behaviors under physiological conditions. Additionally, these materials do not suspend freely in solution like the NP formulations which can result in spatiotemporal differences in the dynamics of drug release characterized *in vitro* (e.g. polymer degradation and drug diffusion). To this end, an alternative data-driven approach for model development can be adapted to discern inter-parametric dependencies and predict drug release from systems that lack pre-defined mathematical assumptions and equations.²³ Various ML frameworks (e.g., linear regressions, decision trees, support vector machines, and Gaussian processes) offer distinct mechanisms for making regression-based predictions by capturing complex relationships between input parameters and the target response.²⁴ Bannigan *et al.*, for example, used a gradient-boosted ML algorithm and drug release data to build a model for predicting time-dependent drug release from polymeric long-acting injectables.²⁵ Their work identified a ML model that adequately predicts drug release based on formulation parameters with the most influential features being the drug and polymer molecular weight. Buoza *et al.* used a similar data-driven approach for characterizing vitamin E sphingomyelin nanosystems (VSNs).²⁶ Their work not only demonstrated reliability for predicting VSN kinetics for drug release but also revealed formulation parameters that influence the drug-loading capacity, colloidal stability, and biocompatibility – all of which are critical to support the clinical translation of drug delivery vehicles.

Although limited, there recently has been an increase in research involving ML and the fabrication of electrospun polymeric nanofibers.²⁷ Many of these studies have identified fabrication parameters that can be used to predict the fiber morphology and diameter *via* ML simulations.^{28,29} However, there is a void in drug delivery research that exploits ML for predicting drug release from polymeric nanofibers. In this work, we aimed to pioneer this space and develop a ML model that can reliably predict drug release from electrospun Ace-DEX nanofiber scaffolds. Through the ML framework described herein, we explore critical features that influence the release rates for



small-molecule drugs encapsulated in electrospun Ace-DEX nanofibers. The resulting model was trained, validated, and refined using *in vitro* release data obtained in-house and demonstrates reliable predictability for a variety of formulations. Furthermore, the model was used to predict protein release from coaxial electrospun Ace-DEX scaffolds demonstrating flexibility and specificity for Ace-DEX formulations. This study highlights future considerations for fabricating drug-loaded scaffolds with Ace-DEX and supports initiatives that aim to improve the clinical translation of electrospun platforms *via* ML.

Experimental

Synthesis and characterization of acetalated dextran (Ace-DEX)

Various formulations of Ace-DEX were prepared similarly to previous descriptions.^{12,16,19,20} In brief, 450–650 kDa dextran from *Leuconostoc* spp. (Sigma) was first lyophilized and dissolved in anhydrous dimethyl sulfoxide (DMSO, Sigma). Pyridinium *p*-toluenesulfonate (Sigma) was added as an acid catalyst before starting the reaction with 2-ethoxypropene (Matrix Scientific) under anhydrous conditions. To obtain Ace-DEX with various degradation rates, the reaction time was varied for each batch of polymer and quenched with triethylamine (TEA, Sigma) upon completion. A liquid–liquid extraction vessel and a 2 : 1 (v/v) ratio of ethyl acetate and Milli-Q® water were used to isolate and purify the synthesized Ace-DEX into a separate organic phase. The solvent was then removed *via* rotary evaporation before re-constituting the dried polymer in ethanol (Fisher). Solubilized Ace-DEX was precipitated in basic water (0.04% TEA in Milli-Q® water) dropwise, vacuum filtered, lyophilized, and stored at –20 °C until use. Spectral analysis of the proton nuclear magnetic resonance (¹H-NMR, Varian Inova 400 MHz) validated the polymer identity and determined the relative cyclic acetal coverage (%CAC) which governs the Ace-DEX degradation rate. See Fig. S1† for an example ¹H-NMR spectrum of Ace-DEX.

Monoaxial electrospinning drug-loaded Ace-DEX scaffolds: fabrication and characterization

All electrospun Ace-DEX scaffolds were prepared in an organic solvent (solvent A or solvent B). For scaffolds made in solvent A, hexafluoro-2-propanol (HFIP) : 1-butanol [60 : 40, v/v] with 1% TEA, an Ace-DEX concentration of 200 mg mL^{–1} was used. For scaffolds made in solvent B, dichloromethane : HFIP : 1-butanol [30 : 30 : 40, v/v/v], an Ace-DEX concentration of 300 mg mL^{–1} was used. For drug-loaded scaffolds, single agent drugs were added in solution with theoretical weight loadings of 5%, 10%, 20%, or 30% (wt/wt). The drugs encapsulated in Ace-DEX scaffolds and used for model development included paclitaxel, everolimus, doxorubicin hydrochloride, erlotinib, and trametinib (PTX, EVR, DXR, ERL, and TRM – LC Laboratories), resiquimod (RESI, Accel Pharmtech), ribociclib (RBC, Tocris Bioscience), and sorafenib (SFN, Biosynth Carbosynth). The solvent used for drug-loaded scaffolds was

determined by whichever provided optimum solubility and stability of the combined Ace-DEX and drug solution.

With a blunt 21 G needle, the prepared Ace-DEX solution was loaded into a glass Hamilton syringe and positioned opposite from a collection plate. A voltage differential of –7.5 kV (at the collection plate) and +7.5 kV (at the syringe needle) was applied over a 13 cm working distance. The solution was ejected from the syringe at a constant flow rate of 1 mL h^{–1} and formed solid, randomly aligned Ace-DEX fibers at the collection plate. The fiber morphology was assessed *via* scanning electron microscopy (SEM, Hitachi S-4700 Cold Cathode Field Emission) at 2 kV on a palladium sputter-coated stub. The fiber diameter (F_d) was measured using ImageJ software. All measurements were reported as an average ± standard deviation of ($n \geq 30$) recorded measurements. Scaffolds were stored at –20 °C until use.

For drug-loaded scaffolds, the experimental drug loading (%Load, wt/wt) was determined *in vitro* using drug-specific analytical methods and quantified with a drug-matched standard curve using eqn (1).

$$\%Load = \frac{\text{drug concentration}}{\text{scaffold concentration}} \times 100\% \quad (1)$$

PTX and EVR loaded scaffolds were dissolved in acetonitrile at 1 mg mL^{–1} and assessed for drug content *via* high performance liquid chromatography (HPLC). A flow rate of 1 mL min^{–1} of the eluent (9 : 1 v/v, acetonitrile : water) through an Aquasil C18 column (4.5 × 150 mm) was used to detect the content of PTX (227 nm, 1.9 min retention) and EVR (278 nm, 3.9 min retention). For scaffolds loaded with RESI, DXR, RBC, ERL, SFN, and TRM, the samples were dissolved at 1 mg mL^{–1} in DMSO and assessed for the drug content *via* absorbance at 260 nm, 480 nm, 350 nm, 330 nm, 304 nm, and 340 nm, respectively.

Coaxial electrospinning bovine serum albumin-loaded Ace-DEX scaffolds

Bovine serum albumin (BSA, Sigma) was suspended at 30 mg mL^{–1} in water with 5% glycerol (v/v, Sigma) for the core solution. 51.6% CAC Ace-DEX was prepared in a 70 : 30 ethyl acetate : butanol solution at 200 mg mL^{–1} for the polymeric shell solution. Both the core and shell solutions were loaded into separate glass Hamilton syringes with a custom coaxial needle (Rame-Hart), which merges the core and shell solutions at the needle tip. The core and shell solutions were ejected at flow rates of 0.3 mL h^{–1} and 1 mL h^{–1}, respectively, with a working distance of 13 cm and a voltage differential of ±7.5 kV. Coaxial electrospun fibers were characterized for surface morphology and fiber diameter *via* SEM and ImageJ measurements ($n = 30$). The %Load of BSA was determined *via* fluorescamine (Sigma) with replicate scaffold samples dissolved at 1 mg mL^{–1} in DMSO, diluted in PBS, and quantified with a BSA standard curve.

In vitro degradation and drug release

The degradation and drug release rates of Ace-DEX scaffolds were assessed *in vitro*. Briefly, 0.6–1.2 mg scaffold samples



were first suspended in phosphate buffered saline (PBS pH 7.4, Corning) at 1 mg mL⁻¹ and added to a shaker plate (37 °C). Incubated scaffolds were agitated for specified time intervals before assessing mass loss and drug release. Upon completion, the samples were removed from PBS, washed with basic water, lyophilized, and reweighed. The scaffold mass loss was obtained using ESI eqn (1).[†] The drug content remaining in the scaffold at each time point was determined as previously described above. To determine the observed fractional drug release at each time, $F(t)$, eqn (2) was used where C_t is the concentration of the drug retained in the scaffold at time t , and C_0 is the empirically measured drug-loading concentration at time 0.

$$\text{Fractional drug release, } F(t) = 1 - \frac{C_t}{C_0} \quad (2)$$

Machine-learning: model development

All observed drug release data and input parameters for model development are included in ESI 1.[†] Drug release profiles, $F(t)$, for thirty unique drug-loaded Ace-DEX scaffolds were included in this study. For each scaffold, four drug-specific parameters including molecular weight (MW), partition coefficient (LogP), polar surface area (PSA), and pK_a reported in the literature correspond to the drug encapsulated in each scaffold (Table S1[†]). Scaffold-specific parameters, including %CAC of Ace-DEX, % drug loading (%Load, drug wt/Ace-DEX wt), fiber diameter (F_d), and time (in days) were also included for a total of 8 input parameters for predicting $F(t)$. A random 80 : 20 partition was applied to the 929 observations within the full data set; 80% for training and 20% for testing within the model developed (ESI 2 and 3[†]). The Regression Learner application within MATLAB R2024a software was used to simultaneously train 28 models available within the machine learning library using the training data set and a k -fold cross-validation of 10. Feature importance was assigned *via* $-\log(p)$ of a regression F -test. Each model was evaluated for performance following model simulations with the 20% testing data. This process was repeated following the incremental removal of lower-ranked parameters for optimizing the model.

Metrics for model comparison and optimization

To evaluate and compare the performance of all simulated models, metrics associated with error and goodness of fit were used as criteria. Models that minimized mean absolute error (MAE), mean squared error (MSE), and root mean squared error (RMSE) as well as maximized R^2 values were considered better performing. The following equations were used to quantify the performance metrics, where n is the total number of observations for the given data, F_i is the observed fractional release for the i^{th} observation, F_i^p is the associated prediction, and $\hat{F}$ is the average observed fractional release (eqn (3)–(6)). Testing and training performance metrics were pooled for each model type to discern the best performing ML algorithm.

$$\text{MAE} = \frac{1}{n} \sum_{i=1}^n |F_i - F_i^p| \quad (3)$$

$$\text{MSE} = \frac{1}{n} \sum_{i=1}^n (F_i - F_i^p)^2 \quad (4)$$

$$\text{RMSE} = \sqrt{\text{MSE}} \quad (5)$$

$$R^2 = 1 - \frac{\sum_{i=1}^n (F_i - F_i^p)^2}{\sum_{i=1}^n (F_i - \hat{F})^2} \quad (6)$$

Model hyperparameter optimization and simulations

The Gaussian process regression (GPR) model kernel function was set as an isotropic zero Matérn 5/2 to balance noise variation and time-dependency (ESI eqn (2)[†]).³⁰ Other hyperparameters, including the noise standard deviation (σ), signal standard deviation (σ_f), and length scale (σ_l), were automatically determined by maximizing the log marginal likelihood of the gradient-based optimizer embedded in the Regression Learner application. The optimized GPR model was extracted from the application as a function used for making future predictions (ESI 7[†]).

GPR model predictions were conducted for a total of 929 *in vitro* observations. To ensure that model performance was consistent for each drug, the error associated with GPR predictions and the corresponding *in vitro* observations were pooled for scaffolds encapsulating the same drug. GPR simulations were also conducted for each scaffold with $n = 100$ time points between zero and the maximum time observed *in vitro*. The performance metrics between GPR simulations and average fractional release observed *in vitro* (from technical replicates) were determined using eqn (3)–(6). Since the GPR model is a probabilistic regression algorithm, predictions are reported with an associated standard deviation (ϕ_i). The 90% confidence interval (90% CI) was determined for each prediction using eqn (7):

$$90\% \text{CI} = F_i^p \pm 1.67 \cdot \phi_i \quad (7)$$

For comparison of GPR model simulations to classically used empirical models for describing drug release kinetics, five different models were used to capture time-dependent release for the thirty scaffolds included in this study (ESI Table S2[†]). Constants for each model were determined by linear transformation of the equations describing fractional release (if not already linear) and linear least-squares regression. Simulations using each model with derived constants were conducted for $n = 100$ time points between zero and the maximum time observed *in vitro*. Performance metrics for each model simulation were measured between the average of technical replicates *in vitro* and the predicted drug released. For comparing model predictability across Ace-DEX formulations, performance metrics for all 30 scaffolds were pooled.



Feature SHapley Additive exPlanations (SHAP) and Spearman correlation assessment

The SHAP assessment was conducted on the 929 GPR model predictions using the 'shapley' function in MATLAB R2024a. The predictors, or the four parameters associated with the optimized GPR model, were ranked according to the absolute mean Shapley value (SV). Linear interpolation of GPR simulations was used to determine the time associated with the specified release including $F(t) = 0.1$ (time_{0.1}), 0.25 (time_{0.25}), and 0.5 (time_{0.5}). Spearman's Pearson correlations between %CAC, %Load, F_d , and three interpolated time points (time_{0.1}, time_{0.25}, and time_{0.5}) were performed in MATLAB using the 'corr' function.

Coding, statistical analysis, and figure rendering

Model development and performance assessment were performed using MATLAB R2024a. All statistical analyses were performed using GraphPad Prism with paired or unpaired *t*-tests. Figures were made using BioRender, GraphPad Prism, and MATLAB R2024a. Supplemental files include all data assessed in this study with MATLAB code availability in ESI S7†

Results and discussion

Drug-loaded Ace-DEX nanofibers exhibit unique molecular and physicochemical properties considered for model development and predicting the fraction of drug released over time

To develop a machine-learning (ML) model for drug release from Ace-DEX nanofibers, the *in vitro* drug release data from 30 electrospun scaffolds encapsulating one of eight small molecule drugs was included in this workflow (Fig. 1A). All scaffolds were electrospun monoaxially and are identified using an associated ID# (Fig. 1B). For developing a data-driven model to predict the fraction of drug released over time, all *in vitro* drug release studies were performed for each of the 30 scaffolds, with replicate samples at each time point, and resulting in a combined total of 929 fractional drug release observations (eqn (1) and Table S1†).

Apart from time, both drug-specific and Ace-DEX formulation-specific properties can influence drug release kinetics from biodegradable polymeric formulations, and thus we sought to identify and define these critical features as additional parameters for model interpretation.²¹ Four drug-specific parameters including molecular weight (MW), par-

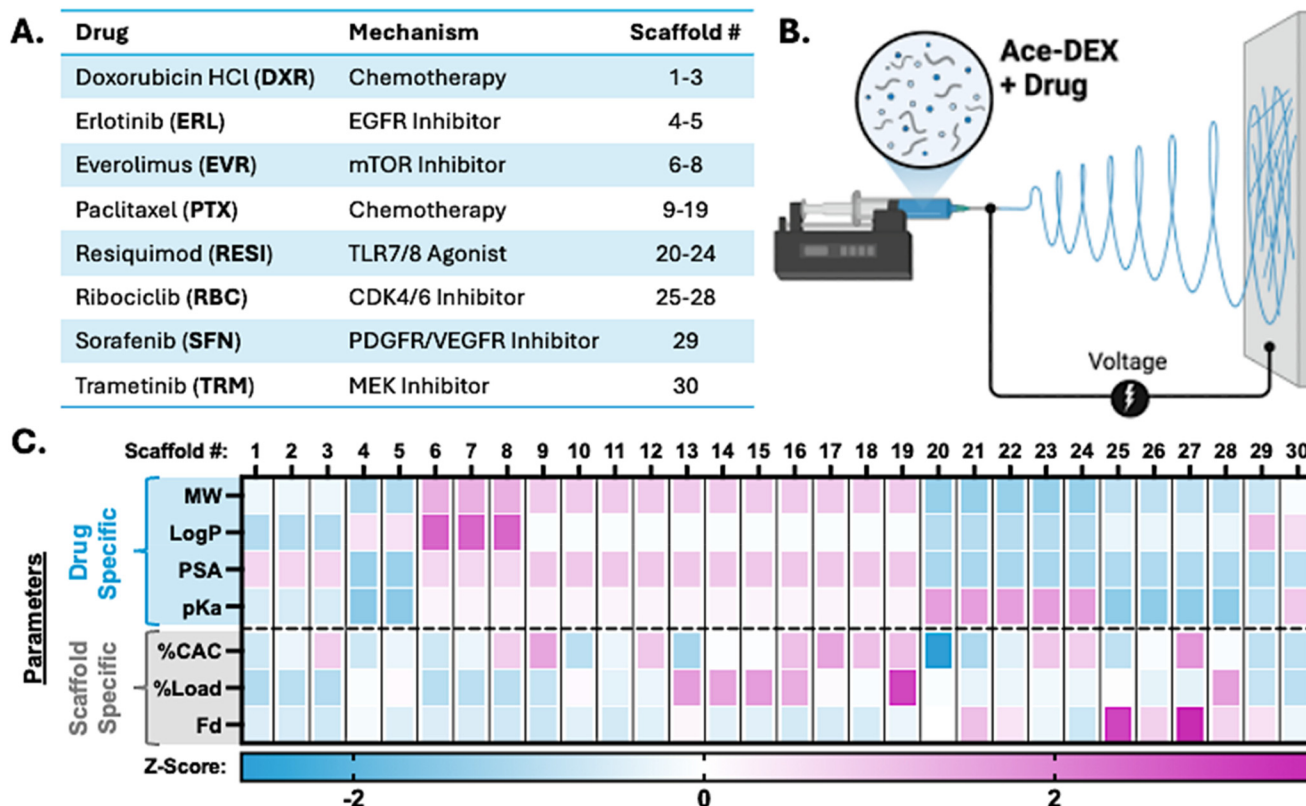


Fig. 1 Drug-loaded electrospun acetalated dextran scaffolds included for machine learning. (A) Table of eight small molecule drugs characterized for release for the prospective study. Scaffolds encapsulating each drug are indicated by the respective range of scaffold ID#s. (B) Schematic of monoaxial electrospinning used for fabricating each of the 30 scaffolds. (C) Heatmap of zeta (Z)-scores for the parameters associated with the 30 scaffolds including four drug-specific parameters and three scaffold-specific parameters separated by a dashed line (see Table S1† for a comprehensive summary).



tition coefficient (LogP), polar surface area (PSA), and pK_a were defined for each observation and were assigned according to the encapsulated drug characterized in the scaffold release study (Fig. 1C). Scaffold-specific properties including the cyclic acetal coverage (%CAC) of Ace-DEX and the characterized weight loading of the drug within each scaffold (%Load) were also defined since these properties can alter the degradation kinetics of the electrospun fibers.²⁰ As is evident from SEM images, these scaffolds also encompass a range of measured fiber diameters (F_d) which is another unique feature for each scaffold and included as a scaffold-specific parameter (Fig. S2†). Lastly, Time (in days) was considered a scaffold-specific parameter since this property is critical to both *in vitro* assessment and determining a time-dependent model for fractional drug release within the observed data. While all other parameters are held constant for each scaffold, Time is the only dynamic property and dependent feature for predicting

the kinetics of drug release. Additionally, the time points chosen for assessing drug release are influenced by the %CAC used since higher %CAC is associated with slower degradation rates (Fig. S3†). In total, eight parameters including four drug-specific and four scaffold-specific parameters were considered in this ML framework. All scaffold data used in developing this model including time-matched fractional drug release can be found in ESI 1.†

Drug-specific parameters are the least important features to model performance

Using the Regression Learner application in MATLAB R2024a, 28 ML models belonging to eight unique classes (Fig. 2A) were simulated simultaneously with a randomly partitioned training subset (80%) and validated with a testing subset (20%) of the 929 *in vitro* observations (ESI 2 and 3†). In MATLAB, the 'cvpartition' function was used to generate the training/testing

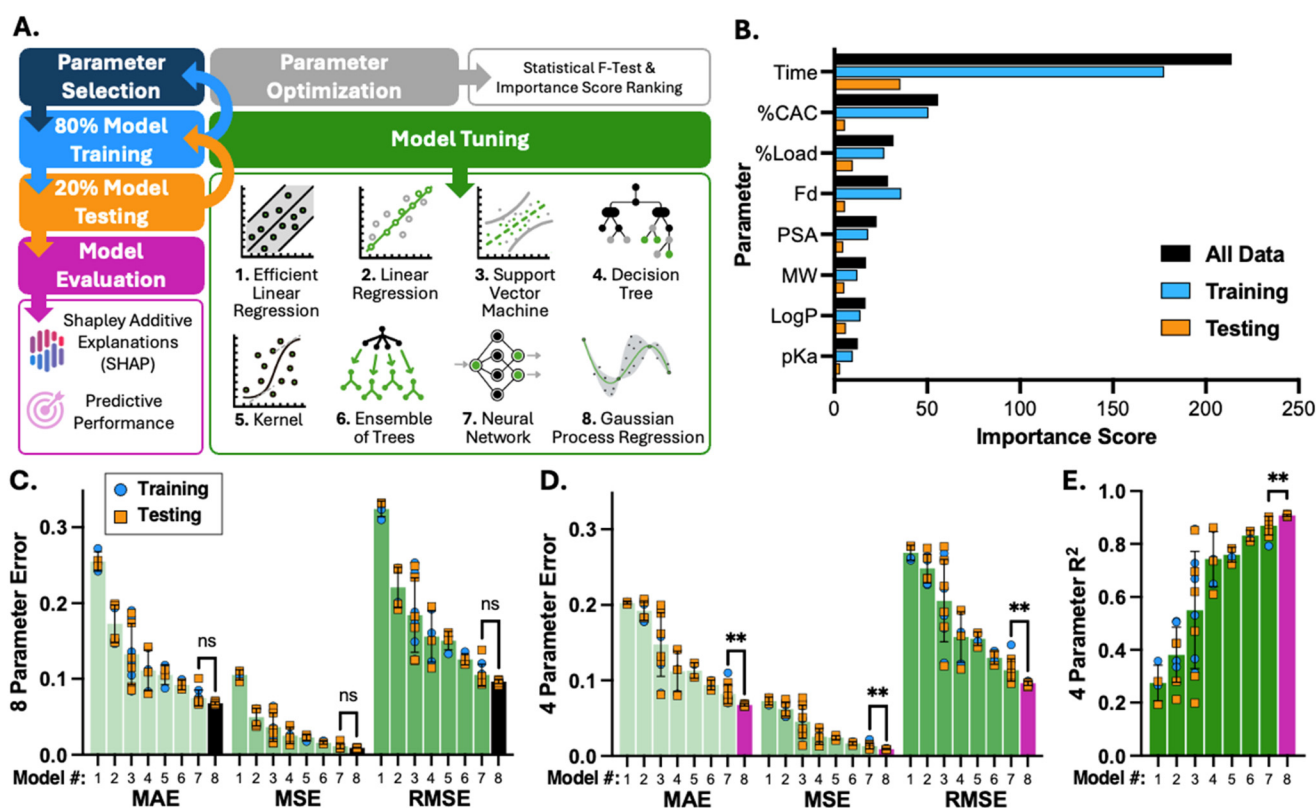


Fig. 2 Machine learning model development. (A) Workflow for using machine learning (ML) to develop a predictive model of drug release from Ace-DEX scaffolds. Parameters are first defined for each of the 929 observations followed by an 80 : 20 randomized split of the data used for training and testing ML models. The 28 ML models assessed are grouped by model type # (see Table S2† for a comprehensive summary). Once training and testing results reveal the best performing model type, model-associated hyperparameters are tuned for optimizing the model structure. The final model is then evaluated via Shapley additive explanations (SHAP) and predictive performance using unseen data. (B) Results from statistical *F*-tests and feature importance ranking within the cumulative 929 data set (All Data), the 80% training data, and 20% testing data. The Y-axis shows the eight parameters included in the initial training and testing of ML models and ranked from top to bottom according to 'All Data' importance scores. (C and D) Error metrics including mean absolute error (MAE), mean squared error (MSE), and root mean squared error (RMSE) for the training and testing results for each model (indicated by individual points) pooled with respect to model type # (as indicated in A). (C) Metrics for eight parameter simulations and (D) metrics following parameter optimization and removal of the four lowest ranking features (as indicated in B). (E) Goodness of fit as an R^2 metric for the four parameter model simulations. ** $p < 0.01$ using a two-tailed, unpaired *t*-test between the top two performing model types by means of pooled training and testing metrics (shown as colored bars with $\pm$ standard deviation). Black/pink bars indicate the best performing model type (#8-Gaussian process regression).



data and ensured that observations from each scaffold are represented in each subset of data (ESI Fig. S4†). The Regression Learner platform was useful for automating data pre-assessment for ML, including standardization and evaluating parameter importance, while applying these considerations to the models available within the library.³¹ First, all eight parameters were considered for each of the trained models, and statistical *F*-tests were performed to determine the feature importance score (IS) for the training data (Fig. 2B). Coinciding with the assumed time-dependency, Time had the highest IS for the training data with an IS of 177.63. Other scaffold-specific features, including %CAC, F_d , and %Load followed in IS ranking. The drug-specific properties, PSA, MW, LogP, and pK_a , had the lowest ISs for the training data. A similar trend was observed for the entire data set where scaffold-specific properties ranked higher in importance than drug-specific properties *via* the *F*-test and IS ranking. This result validates that the training data used for model development reflects similar feature variance and relative importance seen within the entire data set.

The model type selected for further evaluation was determined by comparing the error metrics and goodness-of-fit measures obtained during training with 10-fold cross-validation, as well as the performance results from testing each model on the 20% subset of data that was initially excluded. Out of the eight types of models, all four of the models belonging to the Gaussian process regression (GPR, #8) type had the lowest combined (training + testing) average error including root mean squared error (RMSE), mean squared error (MSE), mean absolute error (MAE), and the highest average R^2 when considering all eight parameters for model development (Fig. 2C, Table S2†).

To avoid developing a model that overfits the data with excessive or redundant parameters as criteria, an important ML step of parameter optimization ensures that the final model is simplified and flexible for making future predic-

tions.³² The lowest ranked parameters, according to the importance score, were incrementally removed from model training and testing to evaluate the influence of these parameters on model performance.

Consistent with 8-parameter simulations, each subsequent simulation identified the GPR model (#8) as best performing by RMSE, MSE, MAE, and R^2 (ESI Fig. S5†). Surprisingly, the performance of GPR models remained largely unaffected by the removal of the four lower-ranked and drug-specific parameters. However, this removal resulted in a statistically significant performance difference between the GPR model and the next best-performing model, the neural network (#7), reinforcing the suitability of GPR as a robust framework for future development (Fig. 2D and E, $p < 0.05$). Furthermore, neural networks are commonly associated with overfitting issues when applied to smaller data sets and are more applicable to models with a large number of parameters.³³ These challenges oftentimes afford more computationally complex algorithms and limit the predictive performance when applied to excluded, or unseen, data.³⁴ Since all four GPR models performed consistently and are more applicable to smaller data sets, the GPR model type was the chosen ML framework for a predictive drug release model.^{35,36}

The optimal number of parameters included in the GPR model was determined by identifying the simulation at which performance was compromised (*i.e.*, increase in error and decrease in R^2). Once the fifth lowest ranked parameter, F_d , was removed from training and testing the GPR models, there was a statistically significant increase in RMSE and, consequently, a reduction in model performance (Fig. 3A and B) ($p < 0.05$). To balance parameter reduction for avoiding redundancy while prioritizing adequate performance, the 4-parameter GPR model, which excludes all four drug-specific parameters, was selected for further development.

Additionally, inter-parametric assessment *via* Spearman correlation validated the exclusion of lower-ranked parameters

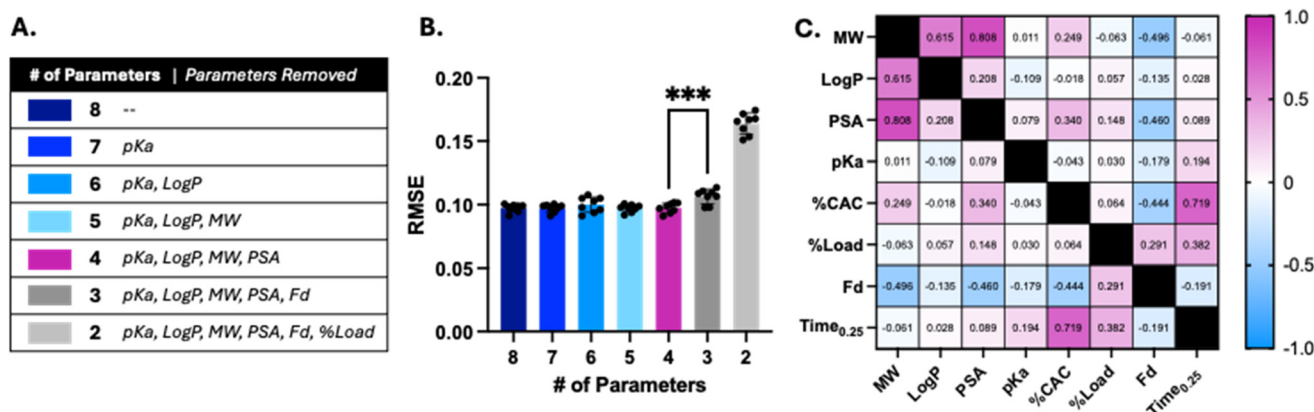


Fig. 3 Parameter optimization. (A) Table of simulations indicated by the number of parameters included. Parameters removed incrementally according to importance score ranking (as in Fig. 2B). Respective colors correspond to (B) average root mean squared error of pooled training and testing results of the Gaussian process regression (GPR) models. Error bars are $\pm$ standard deviation. *** $p < 0.001$ by two-tailed, paired *t*-test between means. (C) Spearman rank correlation matrix for the parameters included for all 30 scaffolds. Time_{0.25} is the time for $F(t) = 0.25$. Cells labeled and colored by correlation value as indicated in the legend.



by observing strong, monotonic correlations among drug-specific properties (Fig. 3C). For example, LogP and PSA both strongly correlate with MW, indicating that removing two of these parameters can offer reduced noise and the computational burden they may add to the model. Furthermore, MW and PSA both have an inverse correlation with F_d , a scaffold-specific parameter retained in the chosen framework. This suggests that drug-specific parameters may influence model behavior indirectly, without the need for explicit interpretation.

Although physicochemical drug properties can influence diffusion and other kinetic behaviors, they may play a less significant role in ML models when compared to formulation-specific parameters. Bannigan *et al.* demonstrated this by showing that during the optimization of a ML model for drug release from polymeric formulations, most drug-specific parameters had limited influence.²⁵ In their refined 15-parameter model, three of the five drug-related features contributed minimally to performance, and another—number of heteroatoms—was excluded entirely. Similarly, in our model, removing all drug-specific properties resulted in robust performance across the datasets, reduced overfitting and redundancy, and ultimately improved generalizability for future applications.

The optimized GPR model predicts drug release data with minimal error and holds true for drug-specific release profiles from Ace-DEX scaffolds

Supervised GPR models consider the probabilistic distribution of outputs (or targets) conditioned on predictors and use kernel-based covariance functions to inform continuous predictions with quantified uncertainty. Optimizing GPR function hyperparameters provides another opportunity to avoid overfitting and refine the performance of the ML model. This step includes selecting the basis function, which describes the mean, or center, for the Gaussian distribution of outputs. Bayesian optimization of the model revealed a basis function of zero as the best fit and is a common assumption used for model simplification.³⁷ Additionally, the kernel function, or relationship between adjacent inputs within the Gaussian space, can be tuned to control model flexibility and influence predictions. Defined by a mathematical equation, the kernel function captures the covariance between predictors and outputs which can be optimized by defining the function structure and associated hyperparameters.^{35,38} To ensure that the model balances smooth, continuous drug release with flexibility, an isotropic Matérn 5/2 kernel was selected as the kernel function (ESI eqn (2)†).³⁹ The length-scale (σ_L), or distance over which inputs are correlated, and the signal standard deviation (σ_F), or amplitude of variance, were automatically determined from the training data set by maximizing the log-marginal likelihood (Table 1). Furthermore, the isotropic kernel ensures consistent length scales for mitigating feature-specific bias. This optimized model provides not only a smooth and continuous interpretation of drug release kinetics but also ensures flexibility for interpreting scaffold-specific parameters and making future predictions.

Table 1 Hyperparameter optimization with performance metrics. Hyperparameters and respective specifications included in the Gaussian process regression (GPR) model optimization. Performance metrics associated with model training (train) and testing [test]

Hyperparameter/performance metric	Specification/value
Basis function	Zero
Kernel function	Isotropic Matérn 5/2
Sigma (σ)	0.091
Length scale (σ_L)	0.734
Signal standard deviation (σ_F)	0.545
k-Fold Validation	10
MAE (train) [test]	(0.071) [0.069]
MSE (train) [test]	(0.010) [0.009]
RMSE (train) [test]	(0.102) [0.096]
R squared (train) [test]	(0.901) [0.904]

The optimized GPR model was applied to the entire data and assessed for goodness-of-fit and error between the predicted and observed fractional release ($F(t)$) from *in vitro* studies (eqn (3)–(6)). Across all 929 observations, the GPR model achieved an R^2 value of 0.931, indicating that 93.1% of the fractional drug release variance is captured by the model with only 6.90% of variance left unexplained (Fig. 4A). Assessment of error metrics between GPR predictions and *in vitro* observations also demonstrates good performance of the optimized model. The residual error was symmetrically distributed across time and the associated predictions indicate that the model avoids systematic bias (Fig. 4B and C). This result was consistent for both training and testing results along with the residual error accrued for each of the other three parameters (ESI Fig. S6†). On average, the predictions for all observations deviated by 5.80% of the total scale (MAE = 0.058), and the low MSE = 0.007 indicates that the model handled outliers effectively. Furthermore, an RMSE of 0.0843 demonstrates that the prediction errors are minimal, occupying only 8.43% of the total fractional drug release range ($F(t)_{\text{Max}} = 1.0$). These results validate an appropriate kernel function and hyperparameters were used to achieve a balance between predictive precision and smoothness.⁴⁰

To discern if model performance varied with respect to the encapsulated drug, the error associated with the GPR model predictions for each drug-specific subset of release data was determined (Fig. S7A and B†). Interestingly, there were some notable differences in MAE and MSE when predictions were grouped by drug type (Fig. S7C and D†). Predictions for doxorubicin hydrochloride (DXR), paclitaxel (PTX), ribociclib (RBC), and sorafenib (SFN) all had MAEs and MSEs significantly different from the combined (“ALL”) data. Moreover, DXR, RBC, and SFN scaffolds had high associated standard deviations for averaged errors which can be attributed to the high degree of noise discerned from *in vitro* quantification methods (ESI 1†). Additionally, the number of predictions varied significantly across drug-specific formulations as the data included at the time of this study was constrained to the availability of *in vitro* data.

To reduce the effect of noise introduced from *in vitro* replicates, a new data set was generated for assessing GPR model performance by averaging the *in vitro* fractional drug release replicates corresponding to the same time point (ESI 5†).



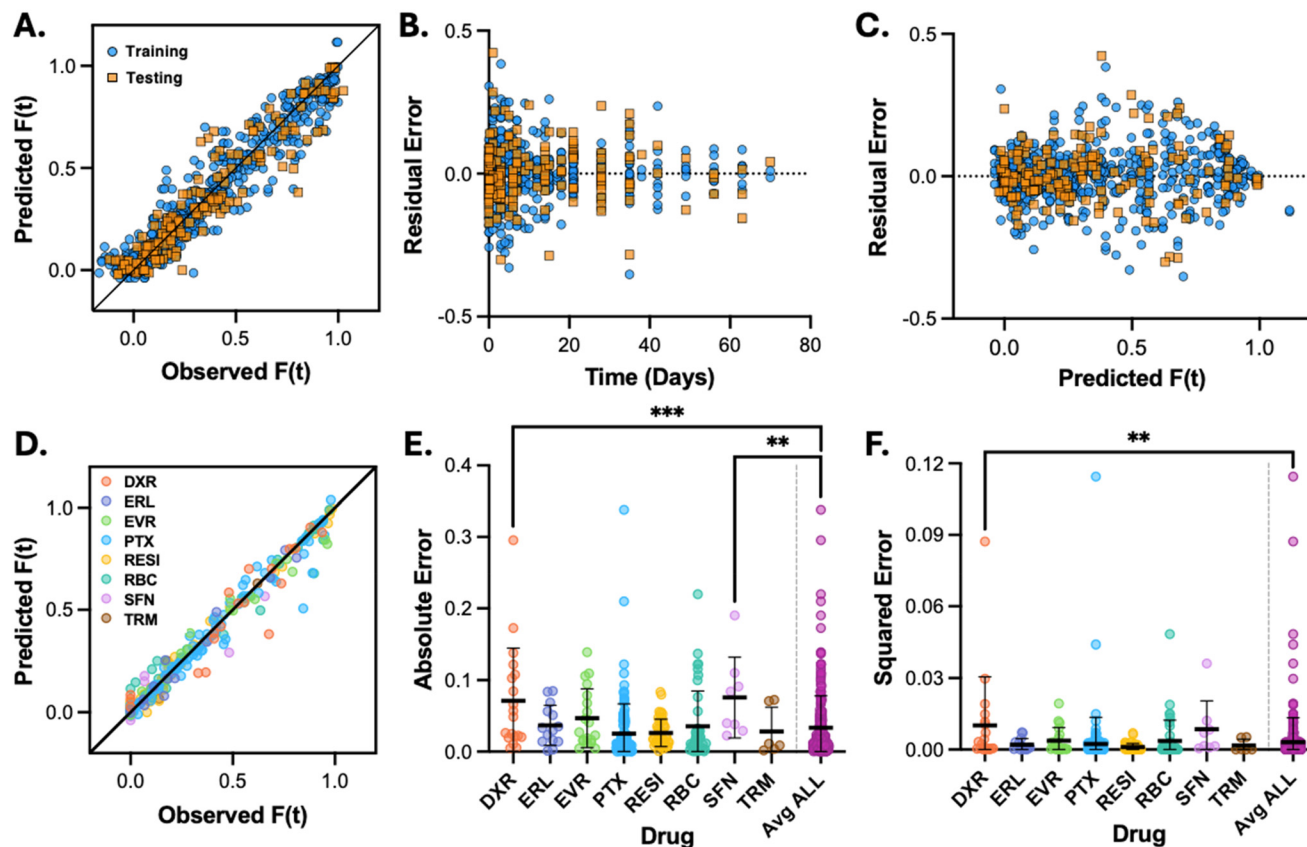


Fig. 4 Optimized GPR model performance across the data. (A) Scatter plot for the 929 predicted versus observed fractional drug release, $F(t)$, from training and testing the optimized GPR model. The black diagonal line is the identity for perfect predictions. (B and C) Residual error for GPR predictions vs. (B) time and (C) $F(t)$ predicted. (D) Scatter dot plots for 276 time-observed averages vs. predicted $F(t)$ and grouped corresponding to the drug characterized. (E) Absolute error and (F) squared error for each of the averaged predictions grouped by drug. "Avg ALL" is all the predictions combined. Black bars indicate the mean absolute error and mean squared error in (E) and (F), respectively. Error bars are $\pm$ standard deviation. $**p < 0.01$ and $***p < 0.001$ using two-tailed, unpaired t -test between means.

These "Avg" data were applied to the GPR model function and assessed for performance as previously described. Unsurprisingly, the model demonstrated good performance across all 276 unique observations and achieved an improved R^2 value of 0.968 (Fig. 4D). The MAE, MSE, and RMSE were also improved to 0.034, 0.003, and 0.056, respectively (Fig. 4E and F). When assessing the error associated with drug-specific predictions, the MAE, MSE, and RMSE were similarly reduced for each drug. Although the mean errors and RMSEs of DXR, everolimus (EVR), RBC, and SFN predictions were greater than that of the combined predictions ("Avg ALL"), the observed deviation from Avg ALL was reduced. The worst performing drug according to error metrics, DXR, achieved an MAE, MSE, and RMSE of 0.071, 0.010, and 0.101 respectively. These metrics, however, are comparable to those observed from training the GPR model and indicate that all drug-specific predictions perform within the projected error determined in model development (Table 1).

To ensure that these trends hold true for drugs encapsulated in similar Ace-DEX scaffold formulations, the GPR model performances for scaffolds 2 and 7 were compared (Fig. 5A

and B). These scaffolds were electrospun with 50% CAC Ace-DEX and a theoretical weight loading of 5% (wt/wt) doxorubicin hydrochloride (DXR) and everolimus (EVR), respectively. Of note, the theoretical loading for each scaffold differs from the experimental loading (%Load parameter) as the encapsulation efficiency *via* electrospinning is not determined until after fabrication. Similarly, the average fiber diameters are comparable but were not predetermined as this would necessitate alteration to electrospinning parameters (*i.e.* polymer molecular weight, viscosity, and voltage differential) and tuned for each scaffold.⁴¹ Although differences between input parameters were marginal, the GPR model was able to perform consistently across two different drug-loaded scaffolds (Fig. 5C). This not only demonstrates high sensitivity for scaffold-specific parameters but also supports the rationale for removing the less important features, or drug-specific properties, and developing a simplified predictive model.

To further assess model performance with respect to scaffold formulation (*e.g.*, Ace-DEX %CAC, drug loading, and fiber diameter), we performed GPR model simulations for paclitaxel (PTX)-loaded scaffolds across a range of scaffold-



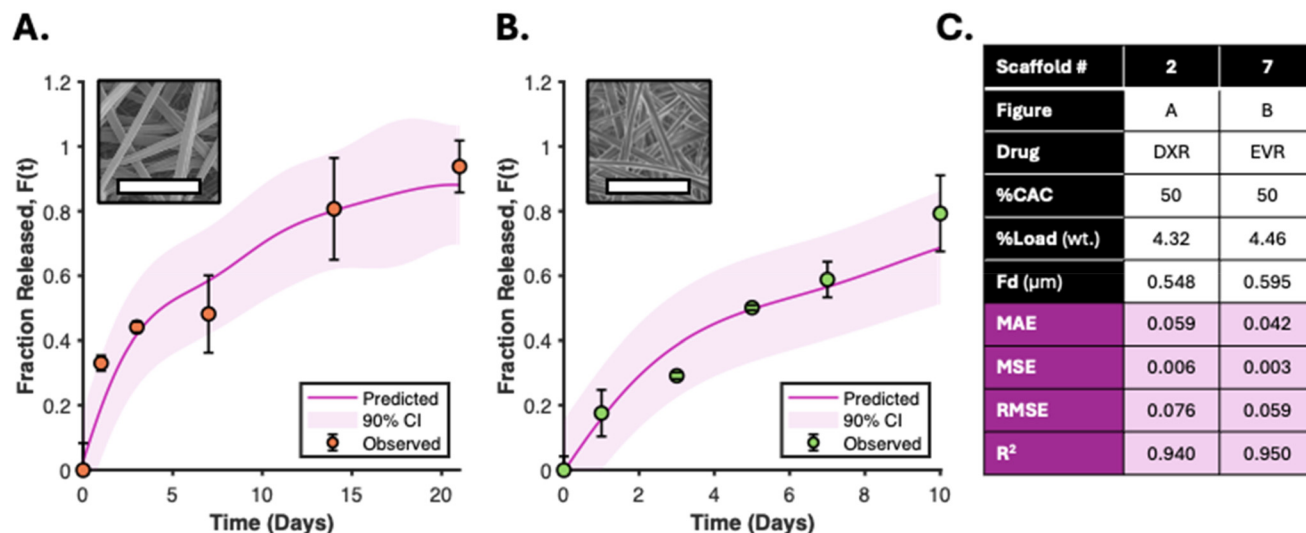


Fig. 5 Comparison of the GPR model performances of drugs released from similar Ace-DEX scaffold formulations. (A and B) Predicted fraction of drug released ($F(t)$) from GPR model simulations for (A) scaffold 2 and (B) scaffold 7. The solid line represents the predicted $F(t)$ with 90% confidence interval (90% CI, shaded region) and individual points represent the average observed $F(t)$ from *in vitro* assessment. Error bars are $\pm$ standard deviation of technical replicates. Inlet images are representative scanning electron microscopy (SEM) photographs for the respective scaffolds. Scale bar = 5 μm . (C) Table of relevant details for scaffolds 2 and 7 including parameters and the associated performance metrics of GPR model predictions including mean absolute error (MAE), mean squared error (MSE), root mean squared error (RMSE), and R^2 .

specific parameters. Scaffolds 10, 11, and 18 were all formulated with a theoretical loading of 10% wt/wt PTX and 45%, 50%, or 61% CAC Ace-DEX, respectively (Fig. 6A–C). Despite having comparable PTX %Load, *in vitro* drug release studies show unique drug release profiles for these scaffolds corresponding to %CAC (Fig. 6D and E). When applying the GPR model, the simulations fit the observed *in vitro* data for each scaffold with an RMSE ≤ 0.051 . Additionally, model performance between PTX-loaded scaffolds with comparable %CACs and fiber diameters but different drug %Loads were compared *via* GPR simulations of scaffolds 11 and 14 (Fig. 6D–F). Scaffold 14 is a 52% CAC Ace-DEX scaffold with a theoretical loading of 20% (wt/wt) PTX (Fig. 6G). As expected, the model fits the data with minimal error (RMSE = 0.035) across all time points revealing that increasing the weight loading of the drug does not negatively affect the model performance (Fig. 6H).

The GPR model captures complex drug release kinetics and outperforms conventional models across Ace-DEX formulations

The developed GPR model can adequately predict drug release over time for Ace-DEX scaffolds based only on scaffold-specific parameters. However, a common limitation of ML model-based solutions is the lack of an intuitive interpretation of inter-parametric interactions for deducing kinetic behavior.⁴² Many conventional models, including our group's previously developed diffusion-erosion model, use mathematical logic to characterize time-dependent release mechanisms including drug diffusion and polymer degradation resulting in an empirical system of equations.^{21,43} Of note, the diffusion-erosion model could not be adapted to the electrospun

scaffolds because it was derived specifically for Ace-DEX nanoparticles. For comparing the performance of the GPR model predictions to that of conventional models for predicting drug release, the fractional drug release data were fit to five additional models classically used for capturing these kinetics from polymeric systems including zero-order, first-order, Higuchi, Korsmeyer–Peppas, and Kopcha models (Table S3†).

Across all time points assessed *in vitro*, the performance metrics for GPR predictions and the conventional model simulations were compared for two different formulations, scaffolds 22 and 26, to demonstrate model applicability (Fig. 7A and J). Scaffold 22 was formulated with 49% CAC Ace-DEX and a 8.40% wt loading of resiquimod (RESI, Fig. 7B). Scaffold 26 was formulated with 51.6% CAC Ace-DEX and a wt loading of 7.82% ribociclib (RBC) (Fig. 7K). These parameters, as well as the average fiber diameter ($1.805 \pm 0.408 \mu\text{m}$ and $2.186 \pm 0.063 \mu\text{m}$ for scaffolds 22 and 26, respectively), were used to simulate the time-associated GPR predictions. Empirical equations, solved *via in vitro* drug release data, were used to simulate the conventional models.

For scaffolds 22 and 26, the GPR model had the lowest MSE and MAE and the highest R squared when compared to all other models. The RMSEs for scaffolds 22 and 26 (0.044 and 0.040, respectively) were also lower than the RMSEs for each of the five conventional models (Table S4†). For scaffold 22, the first-order model was the only conventional type with significantly higher absolute and squared error for all time points assessed *in vitro* (Fig. 7C, D and F). Additionally, the zero-order model was identified as the next-best performing model when comparing all model performance metrics (Fig. 7C, D and E). These results for scaffold 22, however, were not shared for scaffold 26. Following



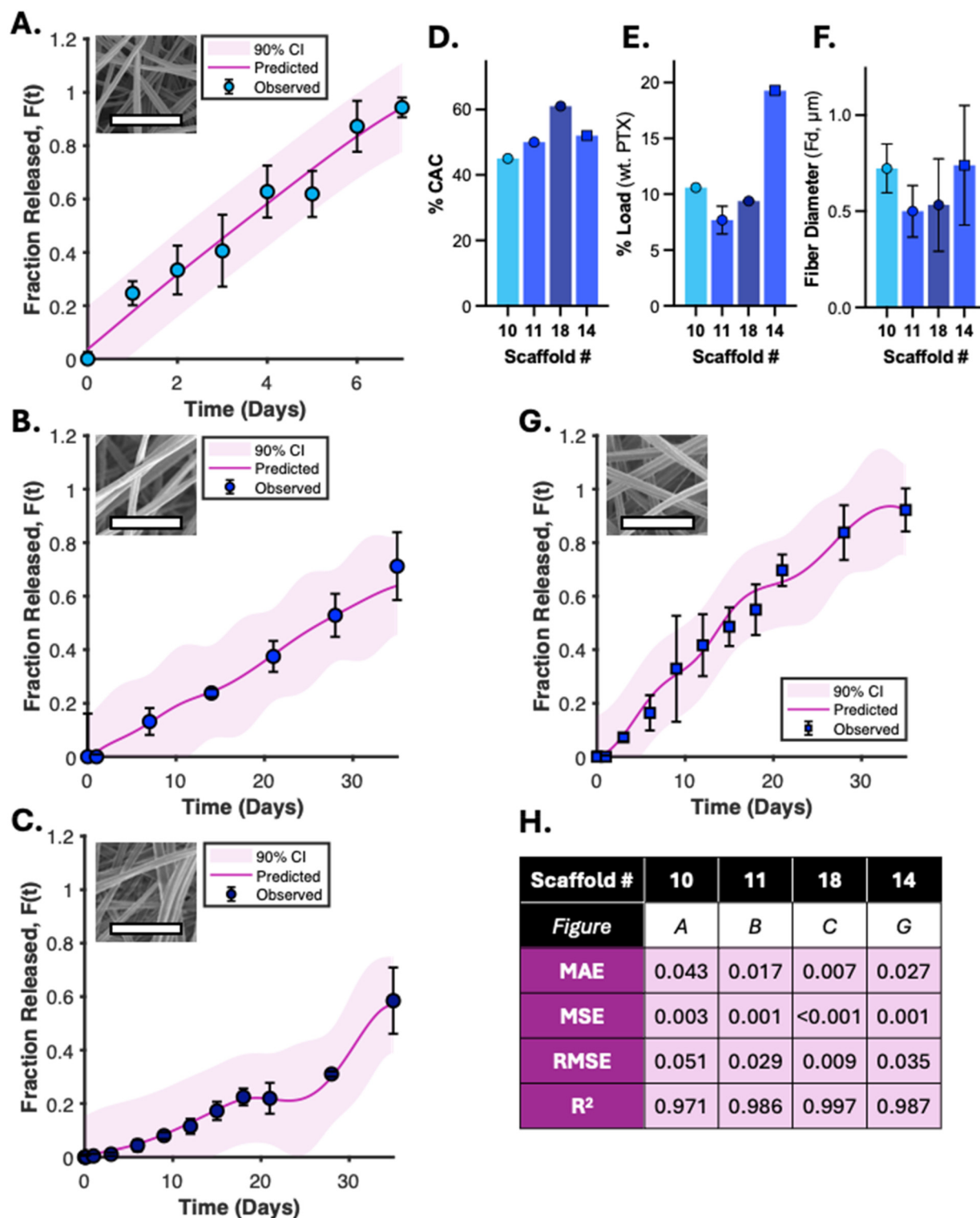


Fig. 6 GPR model performance for paclitaxel-loaded Ace-DEX scaffolds. (A–C) GPR model simulations for fractional drug release, $F(t)$ (solid line), 90% confidence interval (shaded region), and observed *in vitro* release (plotted points $\pm$ standard deviation) for scaffolds (A) #10, (B) #11, and (C) #18; all theoretically loaded with 10% (wt) paclitaxel (PTX). Representative SEM images included respectively with scale bar = 5 μm . (D–F) Relevant scaffold input parameters for GPR simulations including (D) %CAC of Ace-DEX, (E) experimental average % PTX loading (wt, $n = 6$), and (F) average measured fiber diameter, F_d (μm , $n = 30$). Error bars are $\pm$ standard deviation. For assessing GPR performance with respect to drug loading, a scaffold with 52% CAC Ace-DEX and 20% theoretical loading of PTX (scaffold #14) was included for comparison. (G) GPR model simulation (with 90% CI) for scaffold 14 and observed *in vitro* release (plotted points $\pm$ standard deviation). (H) Table showing scaffold #s and figure matched labels with relative GPR performance metrics including mean absolute error (MAE), mean squared error (MSE), root mean squared error (RMSE), and R^2 .



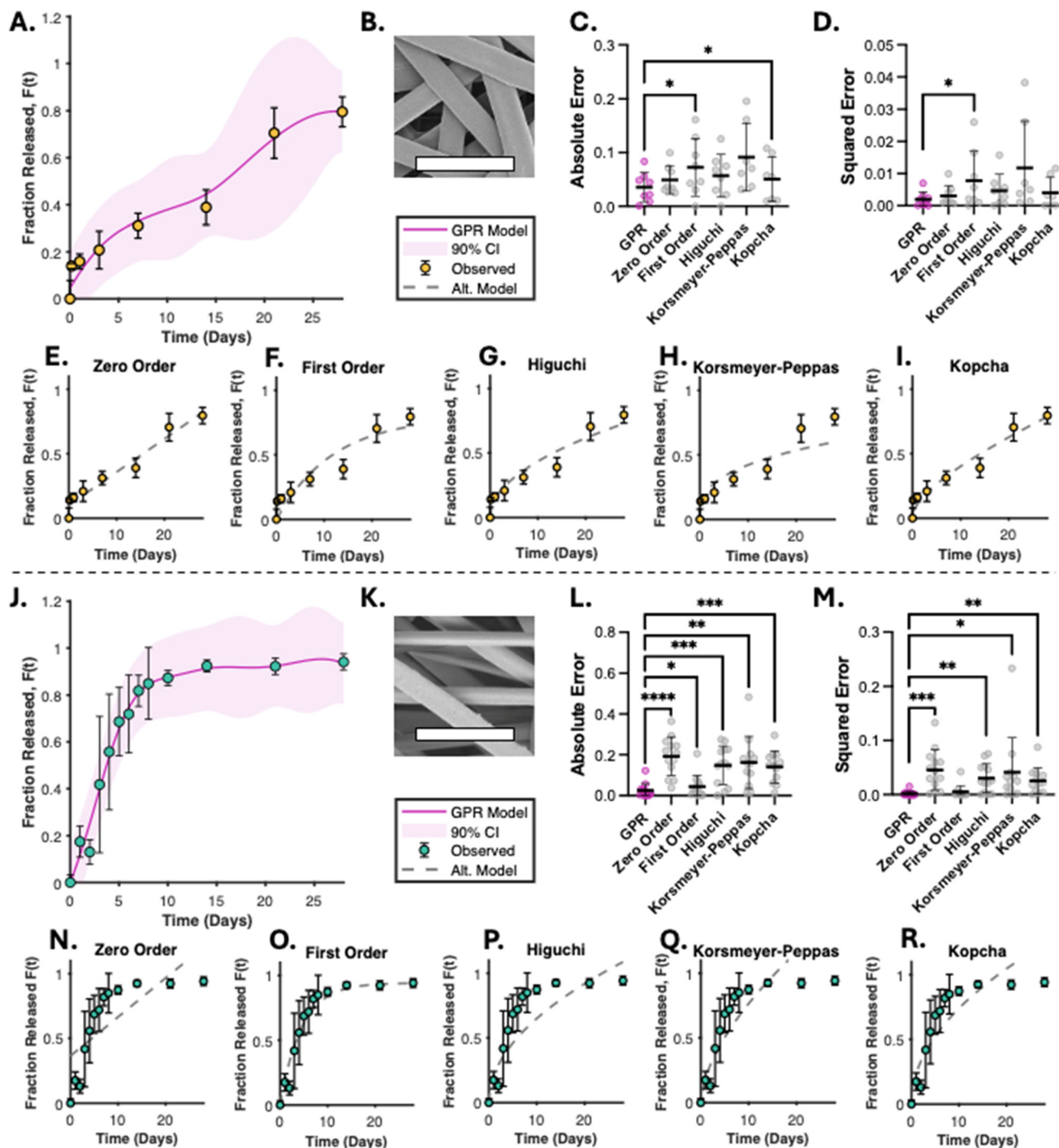


Fig. 7 GPR model comparison with conventional models for drug release. (A–I) Scaffold 22 and (J–R) scaffold 26 results separated by a dashed line. (A and J) GPR model simulation, (B and K) SEM image (scale bar = 10 μm), and model performance metrics including (C and L) absolute error and (D and M) squared error for the alternative ("Alt.") models including (E and N) zero order, (F and O) first order, (G and P) Higuchi, (H and Q) Korsmeyer–Peppas, and (I and R) Kopcha. Individual points represent the average observed *in vitro* fractional drug release $\pm$ standard deviation. For model performance metrics, the overlaid black bars are the respective mean error $\pm$ standard deviation. * $p < 0.05$, ** $p < 0.01$, *** $p < 0.001$, and **** $p < 0.0001$ by one-tailed, paired t -tests between time-matched errors.

the GPR in performance metrics was the first-order model, the only model without significantly higher squared error when compared to the GPR predictions for scaffold 26 (Fig. 7M and O). Furthermore, the zero-order model had the greatest MAE, MSE

and RMSE when comparing metrics across all model simulations (Fig. 7L, M and Table S4†). These conflicting results show how conventional models for drug release have limited flexibility and poor reliability in predicting drug release when applying release

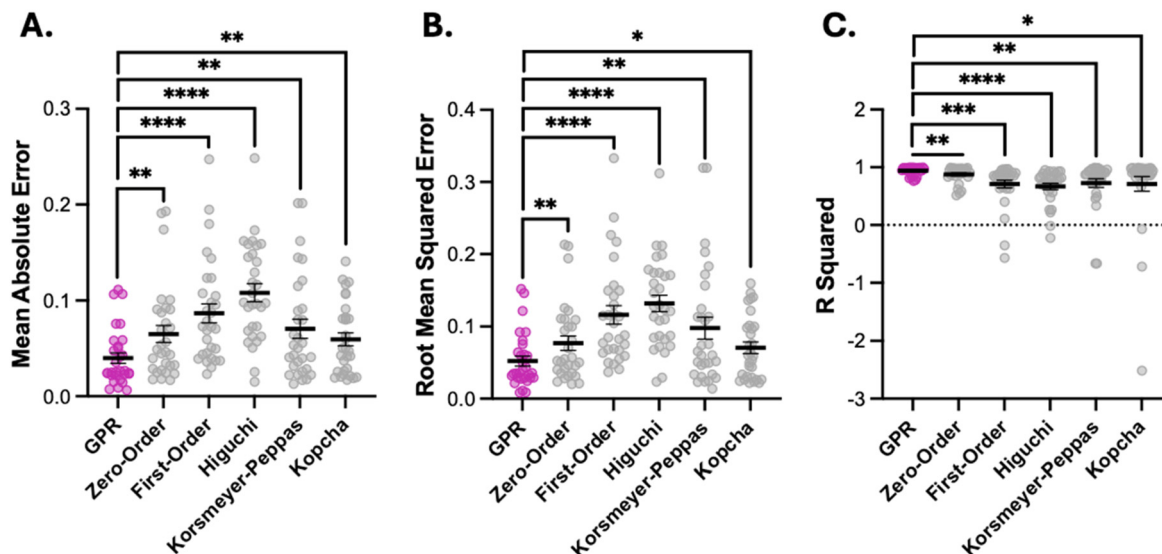


Fig. 8 Model performance metrics. (A) Mean absolute error, (B) root squared error, and (C) R squared for GPR model (pink) and conventional model (gray) simulations. Each individual point represents one of the thirty scaffolds included in the prospective study. Black bars are the mean performance metrics for each model ($\pm$ standard error of the mean). * $p < 0.05$, ** $p < 0.01$, *** $p < 0.001$, and **** $p < 0.0001$ using a one-tailed, paired t -test between mean scaffold errors.

from different Ace-DEX formulations. The developed GPR model, in contrast, provides improved accuracy for predicting drug release across different drug-loaded formulations and considers only the most relevant parameters of the Ace-DEX nanofibers.

To compare the performance of the GPR model across all thirty scaffolds relative to that of the conventional models, the summary metrics including MAE, RMSE, and R^2 of each simulation were pooled with respect to the applied model (Fig. 8A–C). As shown, the GPR model had the smallest combined average MAE and RMSE and the greatest R squared. The differences between all performance means for the GPR model *versus* each conventional model were statistically significant, proving that a more reliable fit was captured by the developed ML model than the classical derivations. Additionally, the GPR model interprets input parameters pertaining to scaffold formulation rather than fitting a trend to the observed data. This allows for enhanced model flexibility and overall specificity for the kinetics of electrospun Ace-DEX scaffolds, which exhibit unique release rates based on the developed formulation.

SHAP analysis of selected parameters reveals temporal changes in feature importance to drug release kinetics

We next sought to investigate how the GPR model performs to arrive at these accurate predictions. SHAP (Shapley additive explanation) analysis is common in ML to assess how model predictions are interpreted from the defined input parameters, or predictors, of the developed algorithm.^{44,45} In this assessment, each feature associated with a prediction is assigned a Shapley value (SV), which quantifies the directional shift that the feature has on the model's prediction relative to the average of all predictions, or the baseline. For the developed GPR model, a swarm chart of predictor SVs for all 929 observations can be used to

visualize how the model interprets each of the four parameters across the relative feature scale (Fig. 9A). On the y-axis, the features are organized vertically by global feature importance where a larger absolute mean Shapley value indicates a higher overall influence that the feature has on the prediction. In line with the feature importance scores determined *via* the F -test (Fig. 2B), Time was the most influential predictor followed by %CAC, % Load, and F_d (Fig. 9B).

SHAP assessment is also useful for discerning how a parameter influence changes with respect to the feature value.⁴⁶ The shading of Shapley value points for each feature in the swarm chart shows the input value interpreted for each observation in the data. The value of time has an overall positive correlation with SVs where lower times (shown in blue) tend to have more negative, or lower, SVs whereas longer times (shown in pink) have more positive SVs. The sign of these SVs ($\pm$) indicates how the feature contributes to the model's prediction relative to the average prediction, or the baseline ($F(t) = 0.303$). If lower time values exhibit a negative SV, there will be a negative shift from the mean contributing to the prediction. This result is relatively intuitive for time-dependent models for drug release since one would expect that the release would be lower than the average predicted release at early time points when compared to the release at later time points. Similarly, % CAC has an overall expected influence on model performance but demonstrates a negative correlation with SHAP. A higher %CAC of Ace-DEX results in slower degrading fibers (Fig. S3†), which corresponds to lower SVs. This result shows that observations that have a higher %CAC will tend to have lower predictions than the average prediction for all formulations.

The two predictors that had the lowest spread in Shapley values and the lowest ranking in feature importance by SHAP



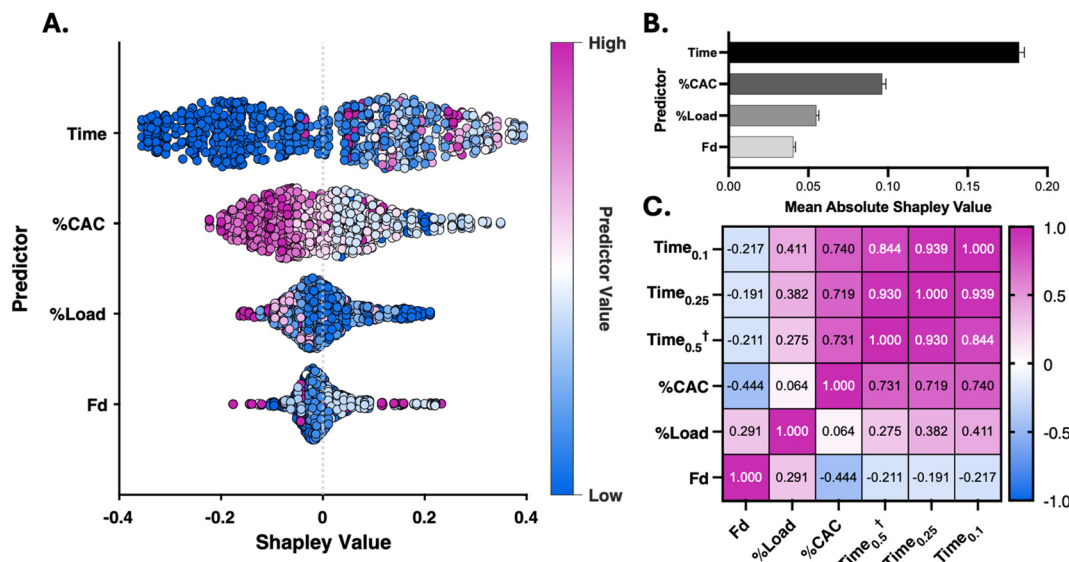


Fig. 9 Shapley values and Spearman's correlation matrix of the 4-parameter GPR model. (A) Swarmchart of Shapley values (x-axis) for each parameter (predictor) included in the developed model (y-axis). 929 Shapley values are plotted for each predictor and are shaded according to the associated feature value magnitude. For each query point, a high predictor value is plotted as pink, and a low feature value is plotted as blue. The associated Shapley value for each point indicates the relative effect that feature has on the determined prediction; a negative Shapley value indicates an associated negative effect on the prediction and a positive Shapley value indicates a positive effect. (B) Mean absolute Shapley value for each predictor. Error bars $\pm$ standard error of the mean. (C) Spearman correlation matrix for the 30 unique scaffold inputs (listed as %CAC, %Load, and F_d on the axes) and the interpolated times for GPR predictions including $F(t) = 0.1$ (time_{0.1}), 0.25 (time_{0.25}), and 0.5 (time_{0.5}). [†] Since $n = 5$ scaffolds did not achieve $F(t) = 0.5$ *in vitro*, the time_{0.5} row and column show the Spearman coefficients for the $n = 25$ scaffolds that did. Values reported in each cell represent the Spearman rank correlation value (r) between pairwise features and are shaded by value according to the heatmap.

were %Load and F_d , respectively. These features have a more concentrated distribution of Shapley values around zero with a less defined trend for the low and high predictor values. This is a common limitation of SHAP analysis because it does not clearly illustrate inter-parametric relationships and, instead, assumes that features contribute to the model independently.⁴⁷ For interpreting how parameters may influence one another and may change with time, Spearman's rank correlation assessment was performed for scaffold-specific parameters along with the GPR model simulation time at which fractional release times of 0.1, 0.25, and 0.5 were predicted (Fig. 9C). For the three interpolated times of fractional release (time_{0.1}, time_{0.25}, and time_{0.5}), there is a consistent monotonic relationship with respect to %CAC, %Load, and F_d . However, F_d was the only parameter to have a negative correlation with time whereas %CAC and %Load had positive correlations. This was interesting to find since %CAC had the opposite relationship discerned from the SHAP assessment. Moreover, there is a negative monotonic correlation between %CAC and F_d ($r = -0.444$) and a positive correlation between F_d and %Load ($r = 0.291$), which suggests that an inter-parametric correlation may influence the model predictions.⁴⁸

Predictive performance of the GPR model for protein release from BSA-loaded Ace-DEX nanofibers

The GPR model considers four scaffold-specific parameters for determining release kinetics and demonstrates a drug-agnostic algorithm for characterizing time-dependent release.

Furthermore, we found that the solvent system used to electrospin did not impact the top four most influential features (Time, %CAC, %Load, and F_d) (Fig. S8A[†]). To validate model sensitivity and drug physicochemical independence, bovine serum albumin (BSA) was encapsulated at 4.8% (wt) loading into a 51.6% CAC Ace-DEX scaffold *via* coaxial electrospinning (Fig. 10A). This is a common method for encapsulating hydrophilic proteins or peptides in an aqueous core solution and the polymer in an outer, organic phase shell solution.^{49,50} As many proteins or biological molecules are susceptible to degradation *via* monoaxial electrospinning (*e.g.*, electrostatic gradients and organic solvent systems), coaxial electrospinning offers improved drug stability and encapsulation for generating protein-loaded nanofibers.⁵¹ The resulting fibers had an average fiber diameter of $0.701 \pm 0.152 \mu\text{m}$ and a similar morphology to monoaxial fibers used for model development (Fig. 10B and Fig. S2A[†]). These input parameters were interpreted to simulate BSA release kinetics using the developed GPR model and assessed for performance. As shown, the resulting performance metrics reveal that adequate predictions were generated by the model simulations (Fig. 10C and D). All observed fractional releases were within the predicted 90% confidence intervals and fit the observed data with an R^2 value of 0.875, demonstrating that the model has reliable predictability when applied to Ace-DEX nanofibers encapsulating proteins (ESI S6[†]).

To visualize how each parameter influences the time-dependent GPR predictions for BSA release, SHAP analysis was per-



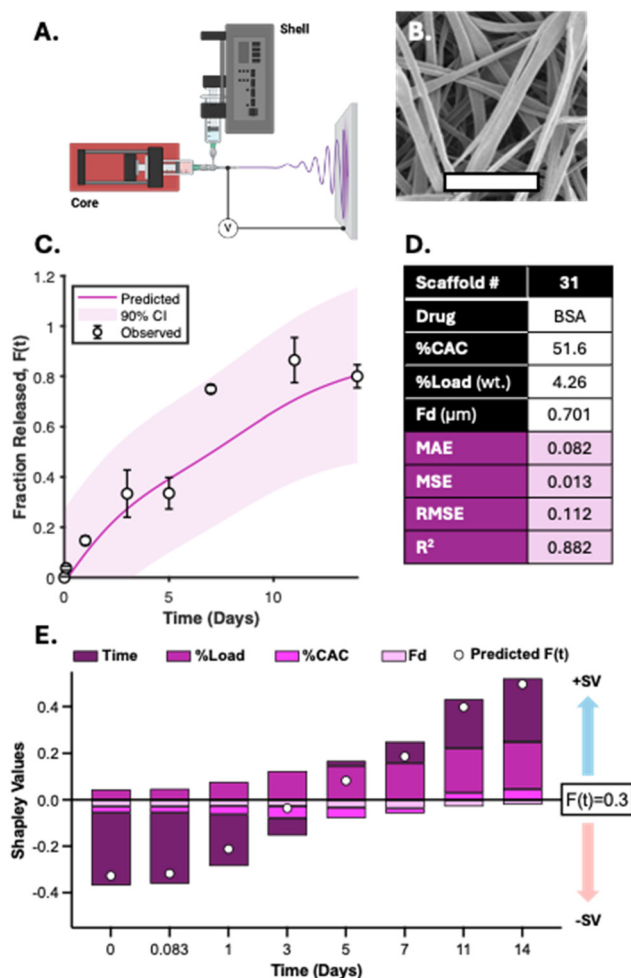


Fig. 10 GPR model performance for predicting protein release from coaxial electrospun Ace-DEX nanofibers. (A) Coaxial electrospinning schematic with bovine serum albumin (BSA) in aqueous core solution and the Ace-DEX polymer in organic shell solution. V = voltage differential between the syringe needle and collection plate. (B) SEM image of BSA-loaded Ace-DEX fibers (scaffold #31). Scale bar = 5 μm . (C) Predicted GPR model simulation of fractional BSA release versus time (solid line) with 90% confidence interval (shaded region). Individual points represent average fractional release observed *in vitro* with error bars as $\pm$ standard deviation of technical replicates. (D) Input parameters (%CAC, %Load, and F_d) and performance metrics for GPR model simulations. (E) Stacked bar plot of Shapley values (SV) for each parameter vs. time of BSA release. Features with SVs < 0 (–SV) indicate a feature-specific negative shift from the average baseline prediction ($F(t) = 0.3$), and those with SVs > 0 indicate a positive shift (+SV). Overlaid prediction points are the cumulative SVs representing the total shift from baseline prediction at corresponding times.

formed for the eight observations from *in vitro* studies. Time was found to be the most influential parameter for GPR performance with the highest absolute mean SV. Interestingly, % Load was the second most influential parameter for model performance instead of %CAC found from the F -test and SHAP analysis performed in prior studies. However, the %Load for this scaffold was 4.26% (wt) which was less, but within error, than the average %Load of all thirty scaffolds used for model

development ($10.0\% \pm 6.1\%$). This change in feature importance is common with SHAP assessment since the results capture the feature influence for the local predictions rather than the influence seen across all formulations. Furthermore, %Load is more influential than %CAC when assessing SVs for all scaffolds with a drug weight loading of less than 5%, demonstrating that predictions for BSA release were achieved similarly to drug release from Ace-DEX nanofibers with comparable parameters (Fig. S8B†). In summary, the GPR model demonstrates high specificity for Ace-DEX scaffold formulations, applicability to monoaxial and coaxial formulations, and reliability for predicting the *in vitro* release of therapeutics ranging from small molecule drugs to therapeutic proteins.

Conclusion

With the growing accessibility of artificial intelligence (AI) and machine learning (ML) technology, there are many opportunities for preclinical researchers to leverage these novel applications and streamline the clinical translation of next-generation therapies.⁵² In particular, *in vitro* drug release characterization from electrospun polymeric nanofibers – a major hurdle for the FDA-approval of electrospun formulations – can benefit from AI/ML tools and mitigate the laborious nature of preclinical assessment. Furthermore, AI/ML applications can help unveil critical mechanisms driving release kinetics while informing future electrospinning methods to ensure that drug release from polymeric nanofibers is reliable and reproducible for therapeutic indications.⁵³ In this study, we demonstrate how these powerful tools can innovate the future of drug-loaded nanofibers through the development of a supervised ML model for predicting time-dependent drug release from electrospun scaffolds.

Specifically, our group has previously shown that the use of acetalated dextran (Ace-DEX) in electrospun nanofibers can improve glioblastoma treatment by offering controlled drug release rates.^{16,19} However, achieving the desired release kinetics requires extensive trial and error with lengthy *in vitro* characterization methods. To streamline this process and leverage this platform for future formulations, a machine learning (ML) model using a Gaussian Process Regression (GPR) algorithm was developed to predict time-dependent drug release from Ace-DEX nanofibers. The model identified scaffold-specific parameters as the most influential, demonstrating high predictive performance with minimal errors.

The refined and developed GPR model does not rely solely on *in vitro* studies but uses a Gaussian distribution of functions with provided confidence intervals to predictions, aligning with FDA recommendations for drug release from semi-solid formulations.⁵⁴ This model outperformed conventional models in assessing drug release profiles for various formulations, proving sound reliability. Furthermore, SHAP analysis provided insights into the model's operation, highlighting Time and %CAC as key parameters. The model's predictive power was further validated by simulating protein release from



Ace-DEX scaffolds, showing reliable and versatile performance specific to electrospun Ace-DEX nanofibers.

In conclusion, this work provides insight into how AI/ML strategies can innovate the future of drug development research. Although the number of observations interpreted in this framework is relatively small for the field of ML, the developed GPR algorithm demonstrates adequate performance for predicting drug release from electrospun Ace-DEX nanofibers. Applications of this ML framework could also be adapted to include other polymer systems that have a defined, tunable feature—like Ace-DEX %CAC—which influences degradation behavior and, thus, drug release. In the future, further investigation into inter-parametric dependencies and the GPR predictive performance will expand our understanding of the mechanisms contributing to drug release from Ace-DEX scaffolds with the ultimate goal of streamlining the clinical translation of this promising therapeutic platform.

Abbreviations

Ace-DEX	Acetalated dextran
CAC	Cyclic acetal coverage
BSA	Bovine serum albumin
DXR	Doxorubicin hydrochloride
ERL	Erlotinib
EVR	Everolimus
PTX	Paclitaxel
RESI	Resiquimod
RBC	Ribociclib
SFN	Sorafenib
TRM	Trametinib
F_d	Fiber diameter
Load	Drug weight load
SEM	Scanning electron microscopy
$F(t)$	Fractional drug released at time (t)
ML	Machine learning
MAE	Mean absolute error
MSE	Mean squared error
RMSE	Root mean squared error
GPR	Gaussian process regression
CI	Confidence interval
IS	Importance score
SV	Shapley value

Author contributions

EGG, EMB, and KMA acquired funding for project support. RNW, EGG, TP, RTS, EMB, and KMA were involved in project conceptualization, methodology, and interpretation. RNW, EGG, KES, and ESP were involved in scaffold fabrication, characterization, and *in vitro* evaluation as part of curating data. RNW, TP, and RTS contributed to ML model development and validation. RNW, EGG, and TP contributed to writing the first draft of the manuscript with EGG, RTS, EMB,

and KMA providing revisions. EMB and KMA provided administrative support and oversight throughout. All authors reviewed the manuscript prior to submission.

Data availability

All data are available in the ESI.

Conflicts of interest

There are no conflicts of interest to disclose.

Acknowledgements

This work was funded internally by the National Institutes of Health (NIH R01CA257009). We are thankful for the resources made available at the Eshelman School of Pharmacy at UNC, Chapel Hill, NC including the NMR core and Chapel Hill Analytical and Nanofabrication Laboratory (CHANL).

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