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# Contact angle determination as a function of solid–liquid molecular characteristics *via* the Kirkwood–Buff route

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The goal of this work is to calculate contact angles as a function of the molecular characteristics of the solid and the liquid. We use Kirkwood–Buff's mechanical route and decompose the normal and transverse components of the pressure tensor into solid and liquid regions. This decomposition leads to the emergence of a new force – the repulsion induced by the liquid displaced by the solid –. We found a neutral state where liquid/wall and displaced-liquid/liquid attractions are balanced. By expanding around this state, we could calculate the density profile within the hard-core van der Waals model at low isothermal compressibility, and establish a relation between the equilibrium contact angle and the microscopic properties of the liquid and solid. This work leads to reformulate Young's equation in a novel manner and sheds new light on the physics of wetting. The density profiles and contact angles obtained theoretically are supported by molecular dynamics simulations using the Lennard–Jones potential.

## Introduction

The first attempt to determine, from first principles, the contact angle in a solid–liquid–vapor system as a function of the molecular characteristics of the solid and the liquid was made by M. Berry.<sup>1,2</sup> Previous approaches<sup>3,4</sup> were insightful but they were not based on first principles. In Berry's work,<sup>1</sup> the Born–Green–Yvon (BGY) equation<sup>5–7</sup> was used to construct an expression for the density profile. Once this was established, a “surface tension profile” and ultimately the contact angle could be calculated. Although this work does not provide a ‘solution’ to the contact angle problem—since the density was a trial function, not an actual solution of the BGY equations—it nevertheless represents a significant attempt to relate, from first principles, the contact angle to the microscopic properties of the fluid and the solid. To the author's knowledge, this work has not been followed by subsequent developments. One inherent difficulty in these approaches is the fact that long-range interactions give rise to nonlinear integral equations, which are challenging to solve.

Later, Benner *et al.*<sup>8</sup> addressed the problem using gradient theory.<sup>9,10</sup> For solid–liquid interfaces, however, a key difficulty lies in the lack of a well-defined boundary condition at the wall. Although calculations can still be carried out, the reliability of the results remains uncertain.

One often finds, in textbooks, expressions—see, for instance,<sup>11</sup>—or order-of-magnitude arguments—for example,<sup>12</sup>—that relate interfacial tensions to the molecular characteristics of the system. The issue is that, in liquids, pressure has two components: a kinetic one, associated with the thermal motion of the molecules, and a static one, arising from intermolecular forces. These two components are of comparable magnitude. If the kinetic component is neglected—thus treating the liquid as a solid—the problem becomes greatly simplified, but a key element of the physics of the system is lost.

Young's equation<sup>13</sup> offers a means to calculate the contact angle by balancing the interfacial tensions between solid–liquid, solid–vapor, and liquid–vapor interfaces. However, because no expressions derived from first principles are currently available, the equation cannot, in practice, be used to compute the contact angle directly. In the field of wetting, a theoretical expression for the contact angle would be highly valuable for structuring reasoning, interpreting experimental results, generalizing findings across different systems, and ultimately devising strategies for optimizing materials. Numerical simulations—such as molecular dynamics (MD) or density functional theory (DFT)<sup>14–16</sup>—provide invaluable data, but they remain black boxes and offer little physical insight or guidance.

The goal of this work is to derive, analytically and from first principles, within a certain framework of approximations, the relationship between the equilibrium contact angle and the molecular characteristics of the liquid and the solid. We will make use of the Kirkwood–Buff equations,<sup>2,6,17–19</sup> which appear particularly well suited to this task, yet have not been thoroughly exploited for this purpose to date.

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## Geometry and intermolecular forces

The geometry under consideration is shown in Fig. 1A. A liquid occupies the space above a wall located at  $z = 0$ . To represent the intermolecular forces within the liquid, induced by its own environment, we consider the case of nonpolar liquids and model the interactions using a hard-sphere truncated van der Waals potential. The expressions for the potential  $V(r)$  and the corresponding force  $f(r)$ , where  $r$  denotes the intermolecular separation, are given by:

$$\begin{aligned} r > \sigma, V(r) &= -4\epsilon \frac{\sigma^6}{r^6}, \quad f(r) = -24\epsilon \frac{\sigma^6}{r^7} \\ r < \sigma, V(r) &= \infty, \quad f(r) = 0 \end{aligned} \quad (1)$$

in which  $\epsilon$  is the interaction energy, and  $\sigma$  the Lennard Jones (LJ) diameter. We use similar expressions for the forces exerted by the solid onto the fluid. We thus have, in the region above the wall ( $z > 0$ ):

$$\begin{aligned} r > \sigma, V_{\text{SL}}(r) &= -4\epsilon_{\text{SL}} \frac{\sigma_{\text{SL}}^6}{r^6}, \quad f_{\text{SL}}(r) = -24\epsilon_{\text{SL}} \frac{\sigma_{\text{SL}}^6}{r^7} \\ r < \sigma, V_{\text{SL}}(r) &= \infty, \quad f_{\text{SL}}(r) = 0 \end{aligned} \quad (2)$$

with, according to Berthelot's rule  $\epsilon_{\text{SL}} = \sqrt{\epsilon_s \epsilon_s}$ , and  $\sigma_{\text{SL}} = \frac{1}{2}(\sigma + \sigma_s)$ , where  $\epsilon_s$  and  $\sigma_s$  are, respectively, the solid energy and solid LJ diameter.

To avoid cumbersome notation, we work in a dimensionless Lennard-Jones system of units. We thus use dimensionless coordinates  $x^* = \frac{x}{\sigma}$  (and similar expressions for the other coordinates), density  $\rho^* = \rho\sigma^3$ , pressure  $p^* = \frac{P}{\epsilon\sigma^{-3}}$ , temperature  $T^* = \frac{k_B T}{\epsilon}$ , where  $k_B$  is the Boltzmann constant, force  $f^* = \frac{f}{\epsilon\sigma^{-1}}$ , potential  $V^* = \frac{V}{\epsilon}$  and remove the stars.

In dimensionless LJ units, for  $r > 1$ , the liquid-liquid and solid-liquid van der Waals forces are given by:

$$f(r) = -24r^{-7} \text{ and } f_{\text{SL}}(r) = -24\zeta r^{-7} = \zeta f(r) \quad (3)$$

$$\text{in which } \zeta = \left(\frac{\sigma_{\text{SL}}}{\sigma}\right)^6 \frac{\epsilon_{\text{SL}}}{\epsilon}.$$

## Calculation of the density profiles

Owing to symmetries, the pressure tensor is diagonal. We thus have  $p_{xx} = p_{yy} = p_T$  and  $p_{zz} = p_N$  in which  $p_T$  and  $p_N$  are respectively, the transverse and normal components of the pressure. We use Kirkwood-Buff's equations (KB)<sup>17</sup> which state that, in the fluid, the normal and transverse pressures are given by (in LJ units):

$$p_N(\rho) = \rho T + p_N^{(S)} \quad (4)$$

$$p_T(\rho) = \rho T + p_T^{(S)} \quad (5)$$

in which  $\rho$  is the fluid density and  $p_N^{(S)}$  and  $p_T^{(S)}$  are the static terms. The first term in the equations (the kinetic term) arises from molecular collisions, while  $p_N^{(S)}$  and  $p_T^{(S)}$  represent contributions from intermolecular forces. Importantly, these equations have been rigorously derived from statistical theory.<sup>18</sup> Although more suited to the analysis of real gases, eqn (5), like Born-Green-Yvon (BGY) equation, are commonly used to investigate liquids. Examples include the determination of contact angles,<sup>1,2,20</sup> and the calculation of density profiles and surface tension at liquid-vapor interfaces.<sup>6</sup>

The expressions of  $p_N^{(S)}$  and  $p_T^{(S)}$  have been established by KB.<sup>18</sup> For  $p_N$ , the principle of the calculation is sketched in Fig. 1B: it consists in summing up attractions of molecules at  $\mathbf{r}_1(x_1, y_1, z_1)$  and  $\mathbf{r}_2(x_2, y_2, z_2)$  below and above a plane parallel to the solid surface, for which the separation vector  $\mathbf{r} = \mathbf{M}_1\mathbf{M}_2 = \mathbf{r}_2 - \mathbf{r}_1$  crosses the surface element  $d\mathbf{S}$  (see Fig. 1B).<sup>6,18</sup> A similar calculation hold for  $p_T$ , with a plane normal to the solid surface (see Fig. 1C). The expression of  $p_N^{(S)}$  and  $p_T^{(S)}$ , as formulated by Irving and Kirkwood,<sup>6,19</sup> read:

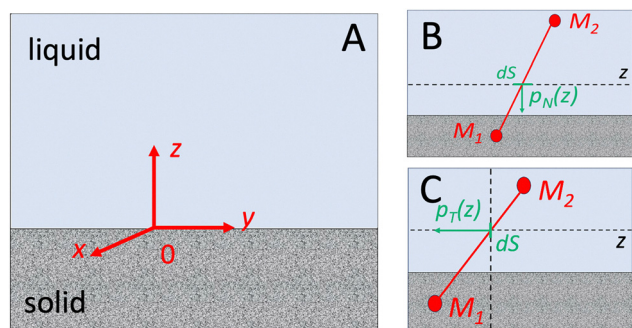
$$p_N^{(S)} = - \int_{z_2 > z} d\mathbf{r} \frac{z_{12}^2}{r} f^*(r) \int_0^1 d\alpha \rho^{(2)}(r, z - \alpha z_{12}, z + (1 - \alpha)z_{12}) \quad (6)$$

$$p_T^{(S)} = - \int_{y_2 > 0} d\mathbf{r} \frac{y_{12}^2}{r} f^*(r) \int_0^1 d\alpha \rho^{(2)}(r, z - \alpha z_{12}, z + (1 - \alpha)z_{12}) \quad (7)$$

in which  $x_{12}, y_{12}, z_{12}$  are the  $\mathbf{r}$  coordinates and  $\rho^{(2)}$  is the two particle distribution functions between positions  $\mathbf{r}_1$  and  $\mathbf{r}_2$ ; depending on whether  $M_1$  or  $M_2$  are located in the liquid or in the solid,  $f^*(r)$  is the liquid-liquid or solid-liquid interaction force. We will assume the following expression for  $\rho^{(2)}$ :

$$\rho^{(2)}(r, z_A, z_B) = \rho(z_A)\rho(z_B)H(r) \quad (8)$$

in which  $\rho(z_A)$  and  $\rho(z_B)$  denote the mean-field densities at positions  $z_A$  and  $z_B$ , respectively, and  $H(r)$  is the Heaviside step function with a discontinuity at  $r = 1$ . This choice, which reflects the hard-sphere van der Waals potential used (see eqn (1)), inherently prevents the development of layering effects.



**Fig. 1** Geometry of the problem. We have  $M_1(x_1, y_1, z_1)$  and  $M_2(x_2, y_2, z_2)$ . (A) The solid (grey) occupies the region  $z < 0$ , while the liquid lies above, in  $z > 0$ . (B)  $p_N(z)$  is the normal pressure acting on  $d\mathbf{S}$ , resulting from the attractive forces exerted by the solid and the liquid located below the dashed line (i.e., for  $z_1 < z$ ) on the fluid located at  $z_2 > z$ . (C)  $p_T(z)$  is the transverse pressure at  $d\mathbf{S}$ , resulting from the attraction exerted by the solid and fluid located at  $y_1 < 0$  (i.e. at the left of the vertical dashed line) on the solid and fluid located at  $y_2 > 0$ , i.e. at the right of the same line.

In eqn (6), the pressure applied on  $\mathbf{dS}$  originates from molecules located in the solid and in the portion of fluid sandwiched between the solid and the plane at height  $z$  (see Fig. 1B). A similar remark holds for eqn (7). The idea here is to decompose  $p_N^{(S)}$  into two contributions: one arising from the sandwiched fluid, and the other from the solid. For that, we abandon  $\alpha$  and return to the variable  $z_1$ , using the relation  $z_1 = z - \alpha z_{12}$ . This leads to the following expressions of  $p_N^{(S)}$ :

$$p_N^{(S)} = - \int_1^\infty \mathbf{dr} \frac{z_{12}}{r} f(r) \int_{z-z_{12}}^z dz_1 \rho(z_1) \rho(z+z_{12}) - \int_z^\infty \mathbf{dr} \frac{z_{12}}{r} \int_{z-z_{12}}^0 dz_1 [\rho_S f_{SL}(r) - \rho(z_1) f(r)] \rho(z+z_{12}) \quad (9)$$

Here, we have extended the domain of definition of  $\rho(z)$ , originally limited to  $z > 0$ , *i.e.*, from 0 to  $+\infty$ , to the entire  $z$  axis  $(-\infty, \infty)$ , by imposing the symmetry condition  $\rho(-z) = \rho(z)$ . The extended fluid density is continuous at  $z = 0$ , while its odd-order derivatives are discontinuous. The first integral thus represents the internal attractive forces inside the extended liquid, *i.e.* the liquid occupying the entire space.

The second integral includes two contributions: (i) the attraction exerted by the solid on the liquid located above the plane at  $z$ , and (ii) the repulsion exerted by a virtual fluid occupying the solid region  $z < 0$  on that same liquid. We refer to this virtual fluid as the displaced liquid, intentionally using the same terminology as in Archimedes' principle. To the best of the author's knowledge, the decomposition (9) is new.

We now take advantage of the cylindrical symmetry of the system to perform the integration over  $x_{12}$  and  $y_{12}$ , with  $z_{12} \geq 1$ . This leads to the following expression for  $p_N^{(S)}$ :

$$p_N^{(S)} = -8\pi \int_1^\infty \frac{dz_{12}}{z_{12}^5} \int_{z-z_{12}}^z dz_1 \rho(z_1) \rho(z+z_{12}) - 8\pi \int_z^\infty \frac{dz_{12}}{z_{12}^5} \int_{z-z_{12}}^0 dz_1 [\rho_S \zeta - \rho(z_1)] \rho(z+z_{12}). \quad (10)$$

Far from the wall, the fluid density is homogeneous, equal to  $\rho_L$ , and the pressure uniform, equal to  $p_0$ . Using eqn (6), we have:

$$p_0 = \rho_L T + p_N^{(S)}(\rho_L) = \rho_L T - a \rho_L^2 \quad (11)$$

with  $a = \frac{8\pi}{3}$ . The same relation holds for the transverse component.  $\frac{a}{T}$  represents the contribution, at high temperature, of the attractive intermolecular interactions to the second virial coefficient, based on LJ potential.<sup>21</sup>

Mechanical equilibrium requires

$$p_0 = \rho T + p_N^{(S)}(\rho) \quad (12)$$

eqn (12) defines an integro-differential equation, which must be solved to calculate the density profile  $\rho(z)$ . The key point is that when the parameter

$$A = \frac{\rho_S \zeta}{\rho_L} - 1 \quad (13)$$

vanishes, eqn (12) admits an exact solution, given by  $\rho = \rho_L$ . This can be checked by inspecting eqn (10): when  $A = 0$  and  $\rho = \rho_L$ , the second integral term cancels out and the normal component of the pressure becomes  $p_N(\rho_L) = \rho_L T - a \rho_L^2 = p_0$ , which is satisfied (see eqn (11)). Therefore, when  $A = 0$ ,  $\rho(z) = \rho_L$  is an exact solution to eqn (12). We will call the corresponding state 'neutral'.

The solution at small  $A$  can be found by expanding densities and pressures into series of increasing powers of this parameter:

$$\begin{aligned} \rho(z) &= \rho_L (1 + s(z)A + \dots) \\ p_N^{(S)} &= -a \rho_L^2 + p_N^{(1)} A + \dots \\ p_T^{(S)} &= -a \rho_L^2 + p_T^{(1)} A + \dots \end{aligned} \quad (14)$$

At zeroth order, eqn (11) is satisfied: in this state, the solid attraction is balanced by the repulsion developed by the displaced fluid and the system behaves as an homogeneous fluid occupying the entire space: this is the neutral state. At first order, we have the following relations:

$$\rho_L s(z) T + p_N^{(1)}(z) = 0 \quad (15)$$

After calculation, we obtain:

$$\kappa_T^{-1} s(z) = \frac{2\pi}{3z^3} \rho_L^2 + K(z) \quad (16)$$

where  $\kappa_T$  is the isothermal compressibility and

$$K(z) = 8\pi \rho_L^2 \left( -\frac{2}{3} s(z) + \int_1^\infty \frac{dz_{12}}{z_{12}^5} \int_{z-z_{12}}^z (s(z_1) + s(z+z_{12})) dz_1 - \int_z^\infty \frac{dz_{12}}{z_{12}^5} \int_{z-z_{12}}^0 s(z_1) dz_1 \right) \quad (17)$$

We now focus on the case of weakly compressible fluids, *i.e.*, such that  $\kappa_T \ll 1$ . In practice, this condition is fulfilled by liquids well below the critical point and gases at high pressures. In the limit of small  $\kappa_T$ ,  $s(z) \sim \kappa_T$  and  $K(z) \sim \kappa_T$  becomes negligible. As a consequence, the eqn (16) loses its integro-differential term and its resolution becomes trivial. This leads to:

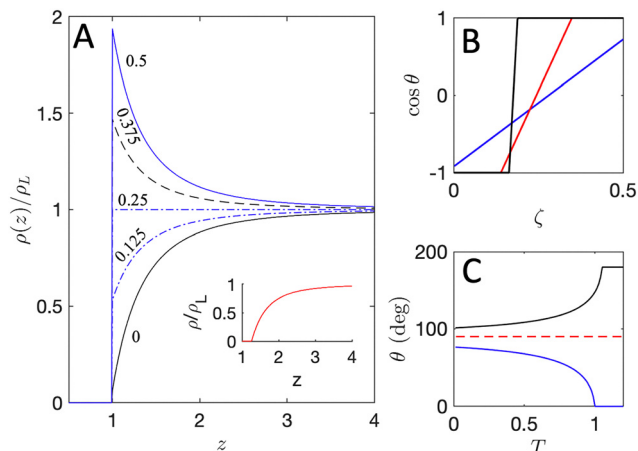
$$s(z) = \frac{2\pi}{3z^3} \rho_L^2 \kappa_T + O(\kappa_T^2) \quad (18)$$

We thus obtain, at first order in  $A$  and  $\kappa_T$ :

$$\rho(z) = \rho_L \left( 1 + \frac{2\pi}{3z^3} \rho_L^2 \kappa_T A \right) \quad (19)$$

eqn (19) tells that, in the interfacial layer, the density excess or depletion decays as  $z^{-3}$ . The density profiles (eqn (19)) are shown in Fig. 2A for  $\zeta$  varying between 0 and 0.5 (with  $\rho_L = 0.8$ ,  $\rho_S = 3.2$  and  $\kappa_T = 0.7$ ). The corresponding values of  $A$  are:  $-1$ ,  $-0.5$ ,  $0$ ,  $0.5$ ,  $1$ .

For positive  $A$  ( $\zeta > 0.25$ ), the fluid density lies above  $\rho_L$ . Interestingly, at the largest  $A$ , densities are so large that we may expect a solid-like layer to form at the wall—a phenomenon



**Fig. 2** (A) Theoretical density profiles (eqn (19)) for  $\rho_L = 0.8$ ,  $\rho_S = 3.2$ ,  $\kappa_T = 0.7$  and various  $\zeta$ , varying from 0 to 0.5 (shown on the figure). The corresponding values of  $\Lambda$  are:  $-1$ ,  $-0.5$ ,  $0$ ,  $0.5$ ,  $1$ . Insert: Density profile for  $\Lambda = -1$  and  $\kappa_T = 1.5$ , showing drying. (B) Evolution of  $\cos \theta$  with  $\zeta$  (eqn (26)), for  $\rho_S = 2.5$  and three temperatures  $T = 1$  (blue),  $1.15$  (red),  $1.3$  (black), with  $\rho_L = (0.7, 0.61, 0.4)$ , and  $\gamma = (0.5, 0.15, 0.013)$ . (C) Evolution of  $\theta$  with temperature, for  $\Lambda = -1$  (black line) and  $1.2$  (blue line), using the same  $\rho_L(T)$  and  $\gamma(T)$  as for (B).

known as van der Waals solidification.<sup>6,11</sup> For ( $\Lambda = 0$  ( $\zeta = 0.25$ )), we recover the neutral state, where the liquid density remains equal to  $\rho_L$  throughout the fluid domain. For negative  $\Lambda$  ( $\zeta < 0.25$ ), the liquid becomes depleted, and for sufficiently negative values, a vapor-like layer forms. Eventually, as shown in the inset (with  $\kappa_T = 1.5$ , assuming the small- $\kappa_T$  approximation remains valid), drying occurs when  $\Lambda < -\frac{3}{2\pi\rho_L^2\kappa_T}$ .

### Calculation of the solid–liquid interfacial tension and the contact angle

We now concentrate on eqn (7) and (10). At first order in  $\Lambda$ , in the small compressibility limit, where, again, terms on the order of  $\kappa_T$  are neglected against terms of order unity,  $p_N^{(S)}(z)$ ,  $p_T^{(S)}(z)$  and the excess pressure  $\Pi(z) = p_N^{(S)}(z) - p_T^{(S)}(z)$  read:

$$p_N^{(S)} = -a\rho_L^2 - \frac{2\pi}{3z^3}\rho_L^2\Lambda, p_T^{(S)} = -a\rho_L^2 - \rho_L^2\Lambda F(z) \quad (20)$$

$$\Pi(z) = p_N^{(S)}(z) - p_T^{(S)}(z) = -\left(\frac{2\pi}{3z^3} - F(z)\right)\rho_L^2\Lambda.$$

where

$$F(z) = \frac{15\pi}{2} \int_1^\infty y_{12}^2 dy_{12} \int_z^\infty \frac{z_{12} - z}{z_{12}(y_{12}^2 + z_{12}^2)^{7/2}} dz_{12} \quad (21)$$

Consequently, the solid–liquid interfacial tension  $\gamma_{SL}$  reads:

$$\gamma_{SL} = \int_1^\infty \Pi(z) dz = -\left(\frac{\pi}{3} - F_0\right)\rho_L^2\Lambda \quad (22)$$

where

$$F_0 = \int_1^\infty F(z) dz \approx 0.11 \quad (23)$$

At first order, the transverse static pressure is therefore on the order of 10% of the normal pressure. This can be

understood by noting that, in the average, the distances between the fluid and solid elementary volumes involved in the calculation of  $p_N^{(1)}$  are shorter than for  $p_T^{(1)}$ .

The interfacial tension  $\gamma_{SL}$  can be decomposed in the following manner:

$$\gamma_{SL} = \gamma_{DL} - \gamma_{SL0} \quad (24)$$

in which  $\gamma_{DL}$  is the displaced-liquid/liquid and  $\gamma_{SL0}$  the ‘bare’ solid/liquid interfacial tensions.

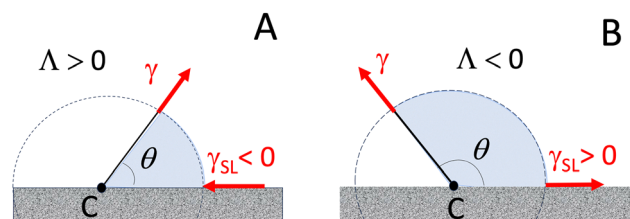
The displaced-liquid/liquid surface tension is a novel concept. To illustrate its physical significance, we may consider a liquid initially at equilibrium, occupying all the space. Its density is uniform, equal to  $\rho_L$ . Creating a solid–liquid interface involves two steps: (i) removing part of the liquid – which depletes its density close to the newly created interface – and (ii) bringing the solid into contact with the new interface – which compresses the liquid near the wall. In this process, the displaced liquid refers to a virtual liquid occupying the volume of fluid that has been removed in order to accommodate the solid. The resulting density profile (eqn (19)) adds two contributions: one arising from the removal of the liquid (depletion), and another from its replacement by the solid (compression). They add up. In the same manner, the interfacial tension components of eqn (24), namely  $\gamma_{DL}$  and  $\gamma_{SL0}$ , add up to define the total interfacial tension  $\gamma_{SL}$ .

Eqn (22) warrants two remarks:

(i) In the case  $\Lambda > 0$ ,  $\gamma_{SL}$  being negative, each fluid element is subjected to a compressive stress in the  $x, y$  plane. For liquid/vapor and liquid/liquid interfaces, such stresses cannot exist because the system would be unstable: a deformation of the interface generates a force which, in turn, increases the deformation. In our case, the instability is suppressed by the wall.

(ii) For  $\gamma_{SL} < 0$ , an elementary volume of fluid, placed on the surface and isolated from the surrounding fluid, will develop an internal force that causes it to spread.  $\Lambda > 0$  is thus associated to wetting. In the opposite case, *i.e.*  $\Lambda < 0$ ,  $\gamma_{SL}$  is positive and the internal force will cause it to dewet the surface.  $\Lambda < 0$  is thus associated to non wetting.

We now calculate contact angles. For that, we first need to consider the case where the solid is in presence of the vapor. Well below the critical point, since gas densities are low, eqn (22) leads to  $\gamma_{SG} \ll \gamma_{SL}$ , consistently with the MD simulations.<sup>22,23</sup> In



**Fig. 3** According to Newton's second law,  $\gamma_{SG}$  being negligible, the forces (shown in red) exerted by the liquid surroundings on the liquid volume under consideration (shown in blue) must balance. This leads to eqn (25). (A)  $\Lambda > 0$ :  $\gamma_{SL} < 0$ , acute contact angle; (B)  $\Lambda < 0$ :  $\gamma_{SL} > 0$ , obtuse contact angle.

this problem, the dry surface plays no role; it is merely a spectator in the process that determines the contact angle.

Thus, neglecting  $\gamma_{\text{SG}}$  and expressing mechanical equilibrium in the far field – as is appropriate in the derivation of Young's law<sup>24</sup> – we obtain (see Fig. 3):

$$\gamma_{\text{SL}} = -\gamma \cos \theta \quad (25)$$

in which  $\gamma$  is the liquid–vapor surface tension (in LJ dimensionless units). Using eqn (20), (22) and (25), we find the following expression for  $\cos \theta$ :

$$\cos \theta = \left( \frac{\pi}{3} - F_0 \right) \frac{\rho_{\text{L}}^2 A}{\gamma} \approx 0.94 \frac{\rho_{\text{L}}^2 A}{\gamma} \quad (26)$$

eqn (26) expresses, in analytical form, the contact angle in function of the molecular characteristics of the liquid and the solid. This was the goal of the paper and this is the first time that a relation of this type is derived from first principles.

To illustrate the behavior of eqn (26), Fig. 2B shows the evolution  $\cos \theta$  for  $\rho_{\text{S}} = 2.5$  and three different temperatures. The corresponding values of  $\rho_{\text{L}}$  and  $\gamma$  are provided in the caption – in practice, to determine  $\rho_{\text{L}}$ , we used the 32-parameters EOS of ref. 25 and, for  $\gamma$ , we used ref. 26. The linearity of  $\cos \theta$  with  $\zeta$ , in the partial wetting range (see Fig. 2B) is a consequence of eqn (26). As we approach the critical point (assuming the theory remains accurate), the curves in Fig. 2B tend toward a stepwise function, indicating that, depending on  $\zeta$  (in fact on the sign of  $A$ ), the system becomes either fully wetting or dewetting. This is critical wetting or drying.<sup>27</sup> The same phenomenon is visible in Fig. 2C, where  $\theta$  is plotted as a function of temperature, for two  $A$  of opposite signs.

### Young's equation

By using (24), Young's eqn (25) can be written in the following manner:

$$\gamma \cos \theta = \gamma_{\text{SL0}} - \gamma_{\text{DL}} \quad (27)$$

In this form, the equation expresses a balance between (i) the liquid/solid, (ii) the displaced-liquid/liquid interfacial tensions and (iii) the liquid/vapor surface tension. Eqn (27) represents an alternative form of Young's equation. It tells that when solid liquid interactions, represented by  $\gamma_{\text{SL0}}$ , prevails, complete wetting is favored. In the opposite case, when liquid cohesion, represented by  $\gamma_{\text{DL}}$ , dominates, dewetting is favored. The partial wetting domain is defined by the condition:

$$-\gamma < \gamma_{\text{SL0}} - \gamma_{\text{DL}} < \gamma \quad (28)$$

The theory thus recovers the three established wetting regimes: complete wetting, partial wetting, and dewetting. Note that eqn (27) is not the only way to express Young's equation. Alternative formulations, closer to the traditional one, can also be found. However, deriving and discussing them would go beyond the scope of this paper.

### Comparison with molecular dynamics simulations performed with LJ fluids

We now compare our theoretical predictions with numerical simulations. The most relevant and well-documented studies of

liquid/solid interfacial regions are based on the Lennard-Jones potential.<sup>22,23,27–33</sup> Several of these studies<sup>22,27,28,30,31</sup> employed the 9-3 wall potential, explored different geometries, or used Lennard-Jones truncated and shifted (LJTS) model. These are different from the assumptions of the present theory. Others<sup>23,32,33</sup> used the standard 12-6 Lennard-Jones potential for both the liquid and the solid and are therefore closer to the situation we consider. Focusing on a [0.7–1] range of temperature, where compressibility is small, we build a data basis including 21 points, with contact angles varying from 30 to 120°,  $\zeta$  between 0.4 and 0.9,  $\rho_{\text{L}}$  between 0.7 and 0.84 and  $\rho_{\text{S}}$  between 0.9 and 7. In such conditions,  $\kappa_{\text{T}}$  does not exceed 0.4. Note that in these studies, as the contact angles are measured on droplets larger than ten nanometers, line tension corrections<sup>34</sup> are neglected.

The numerical results are compared with the density profile and the contact angle given by formulas (19) and (26). To determine  $\rho_{\text{L}}$  as a function of temperature, we use the 32-parameters EOS of ref. 25. The same EOS allows to calculate  $\kappa_{\text{T}}$ . The liquid–vapor surface tension  $\gamma$  is determined by using ref. 26.

The theoretical and numerical density profiles are shown in Fig. 4A and B. The theory (black lines) being mean field, we averaged out the numerical profiles (dashed red lines), over one crystal period (black dots). Fig. 4A shows acceptable agreement between theory and simulation for the wetting case ( $\zeta = 0.9$ ).

In the non-wetting case ( $\zeta = 0.5$ ), although the theory underestimates the depletion near the wall, it remains within the error bars. We thus observe, in the two cases, quantitative agreement.

Fig. 4C compares the contact angles predicted by the theory (see eqn (26)) with those issued from molecular dynamics simulations.<sup>23,32,33</sup> They are close but different. The distribution of the contact angle differences shows a mean value of  $-20^\circ$  and a standard deviation of  $10.2^\circ$ . At this stage, we may conclude that theory and molecular simulations are consistent. The discrepancy may arise from several factors – for example, differences in the interaction potentials (hard-sphere van der Waals in the theory *versus* Lennard-Jones in the simulations), in the pair distribution functions (hard-sphere in the theory *versus* soft-core LJ repulsion in the simulations), or inherent limitations of the Kirkwood–Buff approach in accurately representing a liquid. More work is needed to assess the situation.

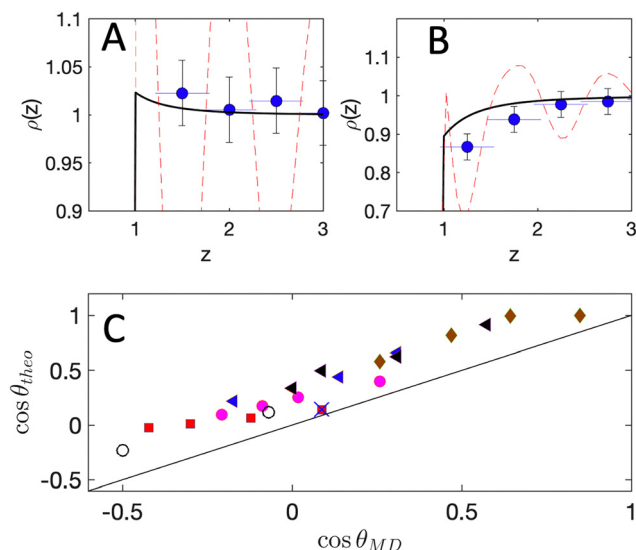
### Introducing corrections for matching MD simulations and theory

From a practical perspective, and to quantify the discrepancy between numerical results and theory in a simple manner, without altering the structures of the theoretical expressions, we amend the expressions of  $A$  and  $\cos \theta$  as follows:

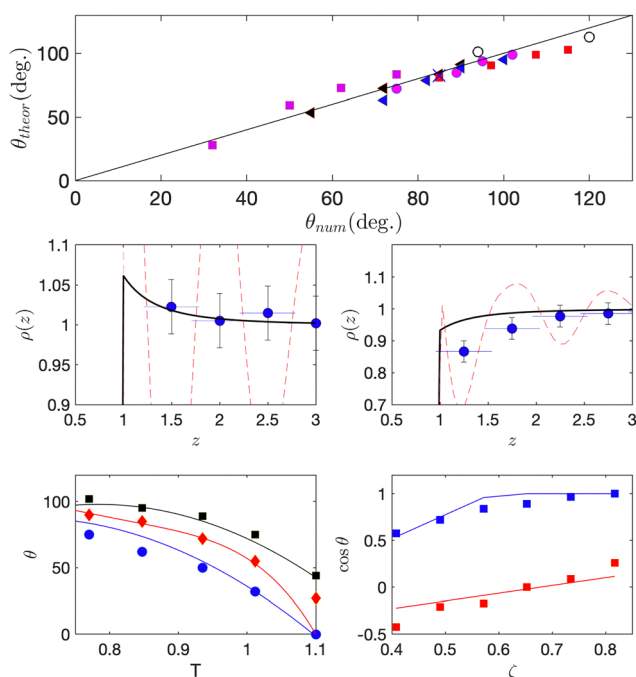
$$A_1 = \frac{\rho_{\text{S}}}{\rho_{\text{L}}} \zeta - q_1 \text{ and } \cos \theta = q_2 \left( \frac{\pi}{3} - F_0 \right) \frac{\rho_{\text{L}}^2}{\gamma} A_1 \quad (29)$$

in which  $q_1$  and  $q_2$  are tuning parameters. These parameters are purely empirical. With  $q_1 = -3T + 3.9$  and  $q_2 = 0.55$ , we obtain Fig. 5.

The figure shows that, with a correction of approximately 40% on  $q_1$  and  $q_2$  (compared to their theoretical value  $q_1 = q_2 = 1$ ), the data collapse closely onto the line of perfect agreement, with a standard deviation of  $6^\circ$ . Similar comments apply to the



**Fig. 4** Theory ( $\cos \theta_{theo}$ ) compared to LJ molecular dynamics simulations ( $\cos \theta_{MD}$ ): (A) density profiles: red dashed line: molecular simulation<sup>32</sup> for  $T = 1$ ,  $\zeta = 0.9$ ;  $\bullet$ : same profile, averaged over a period ( $z$  error bar:  $\pm \frac{1}{\sqrt{12}}$ ;  $\rho$  error bar:  $\pm 1.96\sqrt{3/N}$ , with  $N$  the molecule number of ref. 32); full line: theoretical profile (eqn (19)); (B) same as A, with  $\zeta = 0.5$ ; (C) cosinus of the contact angles  $\cos \theta_{theo}$  (eqn (26)) plotted against MD simulations ( $\cos \theta_{MD}$ ):<sup>23,32,33</sup>  $\circ$ ,<sup>33</sup>  $\diamond$ ,  $\square$ ,  $\triangle$ ,  $\blacktriangle$ ,  $\blacktriangledown$ ,  $\times$ .<sup>32</sup> Note that in the comparison, we increased Bo-Shi's temperatures by 10% to match the LJ critical point.



**Fig. 5** (A) Same as Fig. 4C, but plotting  $\theta$  (instead of  $\cos \theta$ ), and using formula (29), with  $q_1 = -3T + 3.9$  and  $q_2 = 0.55$ ; theoretical contact angles  $\theta$  (degree) plotted against numerical data;<sup>23,32,33</sup> (B) and (C) density profiles: same as Fig. 4A and B, but using formula (29); (D) contact angles plotted with temperature, for three  $\zeta$ : 0.817  $\bullet$ , 0.653  $\diamond$ , 0.490  $\blacksquare$ ; <sup>23</sup> full lines are the theoretical lines, obtained from eqn (29). (E) contact angles  $\theta$ ,<sup>23</sup> plotted with  $\zeta$  for  $T = 0.7$  (red squares) and  $T = 1$  (blue squares); full lines: eqn (29) at the same temperatures.

density profiles (Fig. 5B and C) and the evolution of the contact angle with respect to  $T$  and  $\zeta$  (Fig. 5D and E).

## Conclusion

To summarize, starting from equations derived from the statistical theory of liquids (Kirkwood–Buff equations), and using a hard-core van der Waals potential, we have solved perturbatively, in the limit of small compressibility, the mechanical equations governing the equilibrium of a liquid in contact with a solid. We obtained analytical expressions for both the density profile and the contact angle, in function of the molecular characteristics of the solid and the liquid. The expressions we found are new and are supported by MD simulations.

This study introduces a new concept: the ‘displaced liquid’. It refers to a virtual liquid that occupies the space left by the liquid pushed aside to accommodate the solid. In a manner evoking Archimedes principle, this displaced liquid develops a repulsive force onto the working fluid. The balance between this repulsive force and the attractive forces from the solid determines the density profile and the pressure field in the (working) fluid. This framework naturally leads to a reformulation of Young’s equation.

This work sheds new light on the physics of wetting, offering a more intuitive description of the phenomenon than existing approaches.<sup>35,36</sup> From a practical standpoint, the contact angle expression we obtain could help optimize devices where wetting plays a crucial role, including applications in materials science, surface engineering, biomedical fields, and food science.

The present work concerns the mechanics of the interfacial layer and it would be of interest to see how it relates to the energetic approach extensively developed in the literature since Gibbs’ seminal paper.<sup>37</sup> In the future, it would be interesting to extend the theory to water, where polar interactions dominate. The next step would be to investigate slippage, which strongly depends on wetting.<sup>38</sup> The present approach could also be extended more complex situations, for example involving two immiscible liquids or the presence of films.

## Conflicts of interest

There are no conflicts to declare.

## Data availability

This study was carried out using publicly available data from ref. 22, 23, 27, 28 and 30–33.

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