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Performance of machine learning for ozone modeling in Southern California during the COVID-19 shutdown†

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We combine machine learning (ML) and geospatial interpolations to create two-dimensional high-resolution ozone concentration fields over the South Coast Air Basin (SoCAB) for the entire year of 2020. The interpolated ozone concentration fields were constructed using 15 building sites whose daily trends were predicted by random forest regression. Spatially interpolated ozone concentrations were evaluated at 12 sites that were independent from the machine learning sites and historical data to find the most suitable prediction method for SoCAB. Ordinary kriging interpolation had the best performance overall for 2020. The model is best at interpolating ozone concentrations inside the sampling region (bounded by the building sites), with R^2 ranging from 0.56 to 0.85 for those sites. All interpolation methods poorly predicted and underestimated ozone concentrations for Crestline during summer, indicating that the site has a distribution of ozone concentrations that is independent from all other sites. Therefore, historical data from coastal and inland sites should not be used to predict ozone in Crestline using data-driven spatial interpolation approaches. The study demonstrates the utility of ML and geospatial techniques for evaluating air pollution levels during anomalous periods. Both ML and the Community Multiscale Air Quality model do not fully capture the irregularities caused by emission reductions during the COVID-19 lockdown period (March–May) in the SoCAB. Including 2020 training data in the ML model training improves the model's performance and its potential to predict future abnormalities in air quality.

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Environmental significance

In the spring of 2020, shifts in emissions and subsequent air pollution levels associated with COVID-19 lockdown measures were significantly different compared with any previous period in the Anthropocene. We investigate the utility of deterministic and machine learning models in capturing the observed anomalies in ozone concentrations across the South Coast Air Basin, a region with spatially heterogeneous formation of secondary pollutants. The directionality of model biases before, during, and after the lockdown period gives insight into the NO_x and VOC limited characteristics of locations across the Basin, which guides future emissions reduction strategies.

1. Introduction

In the atmosphere, the non-linear relationship between nitrogen oxides (NO_x), volatile organic compounds (VOCs), and ozone is complex. In the United States, the COVID-19 pandemic and the ensuing shutdown presented an unintentionally optimal period to observe, revise, and improve our existing air quality models and observe the sensitivity of the NO_x –VOC–

ozone relationship in real time. In California, the pandemic shutdown began on March 16, 2020, when significantly reduced traffic volume was observed. In Los Angeles and Ventura Counties, there was approximately a 30% decrease in vehicle miles traveled (VMT) on weekdays and up to a 40% decrease on weekends in 2020.¹ This unusual event temporarily changed the conventional distribution of primary and secondary air pollutants in the South Coast Air Basin (SoCAB). Since NO_x and VOC emissions declined with the reduction in traffic flow,² we expected significant changes in ozone concentrations in Southern California. Several studies were published regarding the pandemic that investigated the effects of the COVID-19 shutdown on air pollutants. For instance, Jiang *et al.*, used WRF-Chem to simulate the major air pollutants before lockdown and during lockdown and found an increase in ozone in urban areas due to emission reductions during the lockdown.² The COVID-19 shutdown also provided an estimation of the impacts

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of future large-scale emission reduction strategies on ozone concentrations in SoCAB.³

Of particular interest is the exploration of possible differences in ozone prediction performance of different modeling approaches during periods of significant emissions and meteorological anomalies. The Community Multiscale Air Quality (CMAQ) modeling system, developed by the U.S. Environmental Protection Agency (EPA), is widely-used for multi-day air quality simulations to estimate air pollutant concentrations with prescribed emissions and meteorology inputs (Ooka *et al.*, 2011; Rao *et al.*, 1996; Wong *et al.*, 2012).^{4–6} From the model outputs, scientists and regulators can better predict the interactions between future emissions, meteorology, and air pollutants to strengthen recommendations for emissions control programs. Chemical transport models (CTMs), such as CMAQ, are based on first principles equations and are initiated with interpolated observation data, hence avoiding most obstacles introduced by data missingness in observations. Machine learning (ML) as an alternative modeling approach has attracted more attention from air quality researchers. Although ML and CTMs have a similar goal to accurately predict air pollution, ML heavily depends on the quality and quantity of historical data. In contrast with CTMs, which produce larger scale, spatially resolved outputs, ML only provides accurate predictions strictly at trained locations when used for ambient air quality applications.

As most ML approaches depend heavily on observational data, we introduce spatial interpolation as a central procedure for increased comparability with the CMAQ data. Also, the relative sparseness of monitoring stations and the locality of air pollutants have been shown to misrepresent spatially-varying air quality over a large area.⁷ Spatial interpolation methods (*e.g.*, nearest neighbors, linear or polynomial interpolation, continuous natural neighbor interpolation, *etc.*) have proven useful for overcoming these limitations.⁸ Yu *et al.* evaluated 14 unique spatial modeling methods for eight air pollutants in Atlanta, Georgia for developing spatiotemporal air pollutant concentrations fields.⁹ Wong *et al.*, assessed four spatial interpolation methods (spatial averaging, nearest neighbor, inverse distance weighting (IDW), and kriging) to estimate ozone and PM₁₀ concentrations.¹⁰ In California, the South Coast Air Quality Management District (SCAQMD) operates 38 air monitoring stations in Southern California over an area of approximately 10 743 square miles, including SoCAB, portions of the Salton Sea Air Basin, and Mojave Desert Air Basin, with an average of 283 square miles per monitoring station.^{11,12} Therefore, spatial interpolation is expected to enhance the observational analyses that follow.

This paper focuses on the performance of deterministic and ML models under rapid changes in emissions and meteorological conditions, specifically during the COVID-19 lockdown period in March through May of 2020. We compare three spatial interpolation techniques to the CMAQ model and evaluate biases related to COVID-19 lockdown anomalies. Furthermore, we aim to answer the question of whether there were other periods with emissions changes similar to the COVID-19 lockdown period within the past few decades and how those

changes impacted the behavior of ozone in different regions of Southern California.

2. Study area and datasets

This study targeted the Southern California region, including Los Angeles, Orange, Riverside, and San Bernardino counties. The region has been historically challenged with poor air quality, with especially higher ozone concentrations than the rest of the United States. The coastal areas tend to have higher relative humidity (RH) and lower temperatures than inland Southern California. Since the turn of the century, SoCAB has been designated as a nonattainment area for the 1997 8 hour ozone standard (80 ppb), with design values for ozone well above the 2015 standard of 70 ppb (Fig. 1). In 2019, the maximum daily 8 hour average (MDA8) ozone concentration in SoCAB was 108 ppb at the design value location with a classification of “extreme” (Redlands, California).¹³

2.1 Model input data

The input meteorological data for the CMAQ simulation were generated using the Weather Research and Forecasting (WRF) model. WRF was initiated using initial and boundary condition meteorology data from the North American Mesoscale (NAM) Forecast System integrated with high-resolution sea surface temperature (SST) from the Group for High Resolution Sea Surface Temperature. We used the WRF Objective Analysis program to improve the meteorological simulation, and this step blends observed surface and upper air observations with the background WRF fields. The surface and upper air observations were sourced from NCEP ADP Global Surface Observational Weather Data (ds461) and NCEP ADP Global Upper Air Observational Weather Data (ds351) *via* the National Center for Atmospheric Research's Research Data Archive, respectively.¹⁴

We re-projected gridded 4 km emissions from 2019 for the year 2020 using a two-step adjustment to account for changes

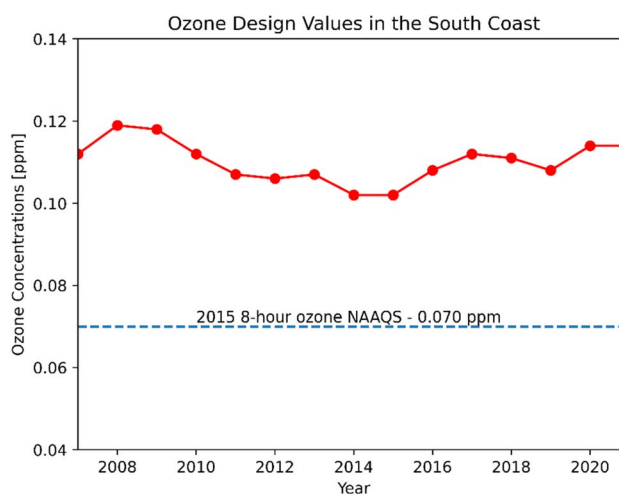


Fig. 1 Ozone design values for the South Coast Air Basin from 2006 to 2020 (<https://www.epa.gov/air-trends/air-quality-design-values>).



due to the COVID-19 lockdown.¹⁵ In the first step, a linear projection factor (eqn (1)) was applied to 2019 gridded emissions based on SCAQMD basin-wide, total annual emissions spanning from 2012 to 2034, where the District's future projections began in the year 2020. The correction factor was calculated for seven air pollutant groups (total organic gases, reactive organic gases, CO, NO_x, SO_x, NH₃, PM).

$$\text{Linear projection factor} = \frac{2020 \text{ emis} - 2019 \text{ emis}}{2019 \text{ emis}} \quad (1)$$

The second step accounted for traffic reductions due to the COVID-19 lockdown, and reductions were highest from March to May 2020, then slowly but not fully rebounding to pre-lockdown levels toward the end of 2020.¹ SCAQMD basin-wide projections understandably did not reflect the decrease in mobile source emissions due to unforeseen traffic reductions. Moreover, weekly traffic metrics in 2020 were acquired for the total flow, flow change, and speed change at 2991 locations in Southern California.¹⁶ Since the traffic data were not evenly distributed over the study domain, we used *k*-nearest neighbors

(*k*-NN) to obtain the traffic data for grid cells (locations) that had no more than five reported data points (*k* value ≤ 5). For the grid cells with more than five reported data points, we normalized traffic volume and then averaged the normalized data.

2.2 Machine learning inputs

We used two air quality features (NO₂ and NO) and four meteorological features (temperature, relative humidity, wind speed, and wind direction) from 15 air monitoring sites in SoCAB (Fig. 2). Hourly meteorological and air quality data used for ML training and validation were obtained from the Air Quality System (AQS) Data Mart (https://aqs.epa.gov/aqswb/airdata/download_files.html#Raw, last access Jan 19, 2023). We checked the data to ensure that hourly data were available for all training features. If there was a missing data point for one of the features, we removed the invalid hour and all corresponding features. The date range of the model training data was 2009–2010 and 2016–2019 for all 15 sites (Fig. 2). The period from 2011–2015 was not included in our models due to the limited availability of wind direction and wind

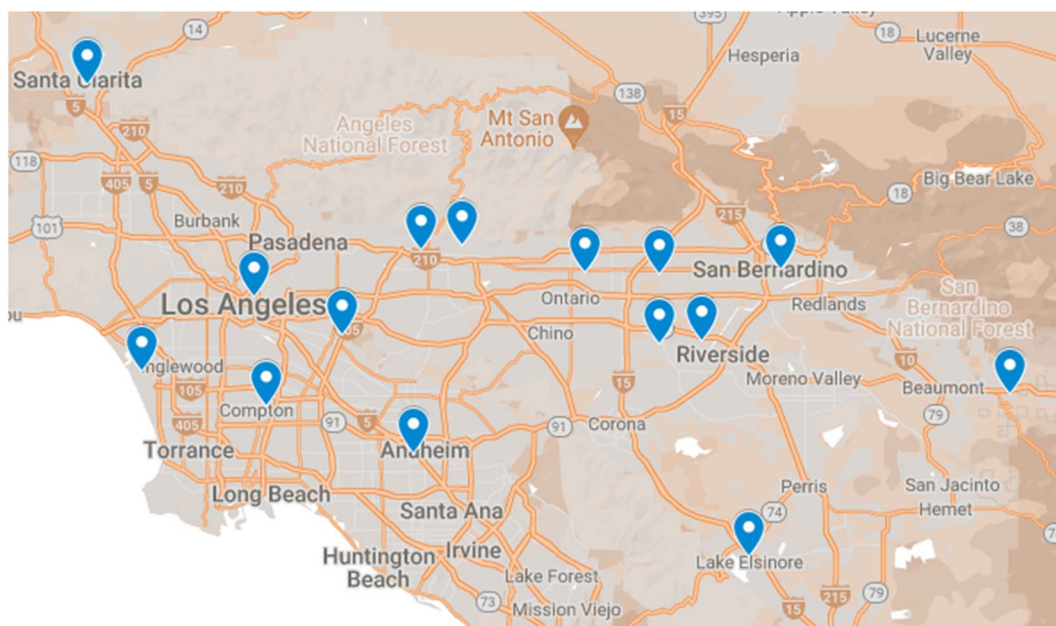


Fig. 2 Data from 15 air monitoring stations (Anaheim, Azusa, Banning, Compton, Fontana, Glendora, Lake Elsinore, LAX, LA North Main Street, Mira Loma, Rubidoux, San Gabriel, Santa Clarita, San Bernardino, Upland) were used for ML model predictions of ozone concentrations.

Table 1 Data summary for machine learning modeling

Ground Monitoring Locations	Anaheim, Azusa, Banning, Compton, Fontana, Glendora, Lake Elsinore, Los Angeles International Airport (LAX), LA North Main Street, Mira Loma, Rubidoux, San Gabriel, Santa Clarita, San Bernardino, Upland
Features	NO ₂ , NO, temperature, relative humidity, wind speed, wind direction
Label	Ozone
Data sources	EPA AQS data mart, CARB air quality and meteorological information system (AQMIS)
Training years	2009, 2010, 2016, 2017, 2018, 2019
Evaluation year	2020



speed at the sites. We used 2020 data for model testing and evaluation (Table 1).

3. Methods

We carried out a parallel approach using both ML and CMAQ to predict 2-D ozone concentrations as shown in Fig. 4. The deterministic model (top panel) utilized WRF and CMAQ to simulate ozone concentrations based on the emissions and meteorological inputs described above. In contrast, the ML model (bottom panel) relied on observational meteorology and air quality data to predict ozone concentrations. ML and CMAQ models were evaluated with observational data to assess their performance, especially in response to the irregular emissions patterns of 2020. Additionally, predictions from ML and interpolation were explored to examine the NO_x and VOC limited regimes in Southern California, providing insights into how the models perform in different regions.

3.1 CMAQ modeling

In this study, we compared the performance of both CMAQ and ML with spatial interpolations of ozone concentrations in SoCAB for the year 2020.^{17,18} The CMAQ simulation covered three distinct periods to study the impact of COVID-19 lockdown on air pollutant concentrations: pre-lockdown (Jan 1st to Mar 15th), lockdown (Mar 16th to May 15th), and post-lockdown (after May 16th) periods. Meteorological modeling was carried out using the Weather Research and Forecasting (WRF) model version 3.9 with 4 km horizontal grid spacing, 11 vertical layers for the finest domain (10 layers near the surface), and 156 × 102 grid cells (Fig. 3). There were two parent domains with coarser horizontal grid spacing (36 km and 12 km for domain 1 and domain 2, respectively). WRF configurations were optimized for SoCAB, and they included the use of United States Geological Survey (USGS) land use, thermal diffusion surface physics, and Yonsei University planetary boundary layer scheme (Hong *et al.*,



Fig. 3 The third and inner-most domain (red boundary) with 4 km horizontal grid spacing covered the entire SCAQMD region (thick black lines).





Fig. 4 Flow diagram of the deterministic (CMAQ) and ML models for predicting 2-D ozone concentrations in Southern California, where SST is sea surface temperature, MET IC and MET BC are meteorological initial and boundary conditions, CHEM IC and CHEM BC are chemistry initial and boundary conditions, AQ data is air quality data (NO and NO₂), and MET data is meteorology data (temperature, relative humidity, wind speed, and wind direction).

2006; Huang *et al.*, 2014).^{17,18} The CMAQ simulation used the modified 2020 emissions and previously described WRF simulations as inputs. The choice of chemical mechanism was SAPRC07tc_ae6_aq, *i.e.*, SAPRC07tc photochemical mechanism, aerosol module 6, and aqueous chemistry (Byun & Schere, 2006; Carter, 2010).^{19,20}

3.2 Machine learning

In a preceding study, we tested multiple ML algorithms to obtain a better method that resulted in the highest prediction accuracy for ozone concentrations in the SoCAB. Those included neural network, support vector machine, *k*-nearest neighbors, and random forest.²¹ Here, we selected random forest regression (RFR), as RFR is the most suitable ML algorithm for predicting ozone concentrations in SoCAB. We also conducted a 10-fold cross-validation over the training data to fine tune the training RFR model in the previous study.²¹

The random forest (RF) algorithm is a supervised learning method employing a tree-based ensemble approach. Each decision tree is derived from training data and represents a subset of the training data. In our model, we have a vector \mathbf{x} with n features, denoted as $\mathbf{x} = (\mathbf{x}_1, \dots, \mathbf{x}_n)^T$. The goal is to find a function $f(\mathbf{x})$ for predicting ozone concentrations. RF is a collection of decision trees consisting of J trees that are split

into j branches from h_1, \dots, h_j . The learning function computes the average of all decision trees, expressed as $f(\mathbf{x}) = \frac{1}{J} \sum_{j=1}^J h_j(\mathbf{x})$.

RF is a combination of multiple decision trees trained on an independent collection of input variables. To reduce the model bias, RFR selects a random subset of features from the input features for each tree, and the output of RFR is the average result from all the decision trees (Rodríguez-Galiano *et al.*, 2015; Zhang & Ma, 2012).^{22,23}

In this study, we selected six training features to predict ozone concentrations, which included two air quality features (NO and NO₂) and four meteorological features (temperature, relative humidity, wind speed, and wind direction). The two air quality features are directly related to ozone formation in the troposphere. Ozone undergoes the photolytic cycle during the day and is removed by NO_x during nighttime.^{24–26} The four meteorological features were well studied in our previous work and were shown as the most important features to capture the variability in annual ozone, especially in SoCAB.^{27–29}

We used the scikit-learn 0.22 library supported by the Python programming language to train our RFR model. Again, the input features are NO₂, NO, temperature, relative humidity, wind speed, and wind direction, and the label is ozone. We tuned the algorithm by varying the number of

Table 2 Optimal RFR configurations for the study

Hyperparameter	Description
<code>n_estimators = 16</code>	The number of trees in the forest
<code>max_features = 'auto'</code>	The number of features to consider when looking for the best split
<code>max_depth = none</code>	The maximum depth of the tree
<code>min_samples_split = 5</code>	The minimum number of samples required to split an internal node
<code>min_samples_leaf = 30</code>	The minimum number of samples required to be at a leaf node
<code>min_weight_fraction_leaf = 0</code>	The minimum weighted fraction of the sum total of weights required to be at a leaf node
<code>max_leaf_nodes = none</code>	Best nodes are defined as relative reduction in impurity



decision trees, the depth of the tree, sample split, and the sample leaf to obtain the best prediction accuracy. We used the same model tuning approached described in Do *et al.* (2023) (Table 2).²¹

3.3 Spatial interpolation

To generate a 2-D ozone concentration map, we first ran the RFR model to obtain the ozone concentrations at each air monitoring location (15 sites), which served as the model building sites. In other words, we applied a pointwise ML algorithm to predict ozone concentrations at each trained location. Next, we spatially interpolated the output over the target Southern California region. We applied three different spatial interpolation methods (ordinary kriging, inverse distance weighting (IDW), and bicubic interpolation) and comparatively evaluated the performance of each method. Each interpolation approach is described below.

Ordinary kriging was applied to interpolate ozone concentration at 10 km resolution over the study area. Generally, kriging predicts the values for unknown locations by performing a series of linear combinations of values at known locations. Eqn (2) expresses the generic form of the estimator to predict the optimum value Z^* of an unknown location by combining the known values Z_i with their weights λ_i .³⁰ We can write the variance σ^2 as an optimization problem (eqn (3)) that can be solved using the Lagrange multiplier μ (eqn (4)).

$$Z^*(u) = \sum_{i=1}^n \lambda_i Z(u_i) \quad (2)$$

$$\sigma^2(u) = \text{Var}[Z(u) - Z^*(u)] = -\sum_{j=1}^n \sum_{i=1}^n \lambda_j \lambda_i \gamma(u_i - u_j) + 2 \sum_{i=1}^n \lambda_i \gamma(u_i - u) \quad (3)$$

$$\sum_{j=1}^n \lambda_j (u_i - u_j) + \mu = \gamma(u_i - u) \quad (4)$$

and

$$\sum_{j=1}^n \lambda_j = 1 \quad (5)$$

μ is the Lagrange multiplier, u_i and u_j are the distance of known locations from unknown locations u , γ is the variogram, and $i = 1, \dots, n$. Eqn (2) and (3) are called the kriging system, and λ is the kriging weight. The values for λ_i and the optimum value Z^* are obtained by solving the kriging system and eqn (4).³¹

Bicubic interpolation is another method for interpolating data points on a 2-D grid. The interpolated surface can be written in terms of two variables (eqn (6)). The polynomial p consists of sixteen coefficients a_{ij} that are solved with sixteen boundary conditions (*i.e.*, $(x = 0, y = 0)$, $(x = 1, y = 0)$, $(x = 0, y = 1)$, $(x = 1, y = 1)$) and its derivatives with respect to x, y , and xy .³²

$$p(x, y) = \sum_{i=0}^3 \sum_{j=0}^3 a_{ij} x^i y^j \quad (6)$$

The IDW interpolation method accounts for the distances between the interpolated points and the measured locations. The assumption for IDW is that points close to each other are more alike and have more significant influence than those farther apart. Thus, the nearest measured values have greater weights assigned. Eqn (7) shows that the predicted value $Z(x)$ is inversely proportional to the distance between the measured and interpolated points $d(x, x_i)$.

$$Z(x) = \frac{\sum_{i=1}^n \frac{Z_i}{d(x, x_i)^p}}{\sum_{i=1}^n \frac{1}{d(x, x_i)^p}} \quad (7)$$

$Z(x)$ is the predicted value, d is the distance, x is the unknown point, x_i is the known location, Z_i is the value of a known location, and p is the power.³³

4. Model evaluation

Fig. 5 shows a snapshot of the ozone concentrations over the interpolation region at 4:00 PM on June 22, 2020 (the highest ozone episode of the day), using ordinary kriging. The colored dots with a white border are the actual values at the evaluation sites, and those without a white border are the RFR predicted values for training sites. The model successfully reconstructed the spatial trends in the region, where the lowest ozone levels were in the southwest (coastal) and the highest were in the east (inland), and there was good agreement with the actual ozone concentrations. Fig. S2 and S3† show the heatmap for bicubic and IDW interpolation for the same timestamp. Although all interpolation methods predicted the lowest ozone concentrations in the Southwest, the highest ozone concentrations were predicted in the Northeast of the study region for bicubic and in the North for IDW. The concentration gradient increased from south to north for bicubic and IDW, but from west to east for ordinary kriging.

The performance of the models was evaluated based on commonly used statistical metrics: mean bias (MB), correlation coefficient, root mean square error, and R^2 (equations listed in ESI†). The models were evaluated based on data from 27 air monitoring stations in SoCAB, of which 15 sites were used to



Fig. 5 Hourly ozone heatmap (16:00 on June 22, 2020) using ordinary kriging. The dots with white borders are the evaluation sites, and dots without borders are the training sites.



evaluate the training sites, and the other 12 sites were used to evaluate the performance of the three interpolation methods at non-training sites. Tables 3 and 4 highlight R^2 for daily average ozone for the bicubic, IDW, and ordinary kriging interpolations, as well as R^2 for the CMAQ comparison. We used the entire year to evaluate the interpolation methods, but we only used the five highest ozone months from May to September for the CMAQ evaluation.

The bicubic R^2 indicates the poorest performance of the three interpolation methods. IDW showed a significant improvement compared to bicubic interpolation. Since IDW accounts for the distances between the interpolation points and the data points, farther data points have less influence on the interpolation points. Ordinary kriging resulted in the best interpolation method because the method not only accounts for the distance between building points and interpolated data by assigning larger weight λ_i to the near neighbors, but it also

considers the variability of data by considering the variance of input data, σ^2 .³⁴

ML with interpolation gave a poor performance for Crestline and Winchester locations. Crestline is located in the mountains and to the northeast of SoCAB, which is elevated terrain associated with upper air and a different air mass at times. Crestline ozone was not well-correlated with coastal or inland sites. Thus, interpolated Crestline ozone based on coastal or inland data points will likely yield poor results. The Winchester air monitoring site is located near the Skinner Reservoir (Fig. S1†), far away from other data points (Lake Elsinore and Banning). Low R^2 for Winchester can be explained by the influence of the lake and local meteorology and air quality. The ordinary kriging model performed well for locations bounded by data points with R^2 above 0.56. However, poor interpolation results occurred for peripheral locations in SoCAB (Crestline, Mission Viejo, and Winchester). LAX ozone levels were not well correlated with meteorology, and training the ML model with fewer meteorological features did not affect the performance of the LAX location. Overall, model performance increased from the West to the East, with better prediction for inland sites.

The distribution of the monthly mean bias (MB) for ordinary kriging interpolation centered around zero with the range between +9 ppb for Compton (August) and −11 ppb for Glendora (October). Eleven building sites have a net positive monthly MB, and four have a net negative monthly MB (Fig. 6). The results from the CMAQ simulation overestimated the ozone levels. CMAQ's best performance was from May to October when the MBs were the smallest. CMAQ underestimates the ozone concentrations at the LAX location, due to the site's proximity to the Pacific Ocean, colder model temperatures, and potential discrepancies in aviation emissions. In general, ozone concentrations in the SoCAB are highest during the summer and lowest in the winter, corresponding with the temperature. Although the CMAQ simulation captures diurnal variation, the seasonal variation is not as well-represented (Fig. S4, S5, S7, and S11†). Lower performing CMAQ results could come from uncertainties in emissions estimates. CMAQ generally overestimated ozone concentrations because the simulated nighttime ozone concentrations were higher than those observed, potentially due to underestimated nighttime NO_x emissions.¹⁵ In other words, there was not enough NO_x emitted in the model during the daytime for ozone formation and at night for ozone removal.^{35,36}

Training features can be varied to study the sensitivity to modeled ozone response. For example, we can perturb the temperature, RH, or emissions values and examine the ozone levels corresponding to the change in the features. However, because the formation of ozone results from a complex combination of chemical reactions, resulting impacts are nonlinear and interdependent. Therefore, when using ML to test for sensitivity to a feature, one should consider feature dependencies. For example, in testing temperature impacts on ozone concentration, we must consider both how temperature impacts photolysis rates (NO_2 degradation) as well as simultaneous correlations/anticorrelation with other meteorological variables, such as RH or wind speed.

Table 3 Daily average R^2 at the 15 building sites for three interpolation methods for the year 2020. R^2 for CMAQ was computed using the five highest ozone months May–September of 2020

Sites	Bicubic R^2	IDW R^2	Ordinary kriging R^2	CMAQ R^2
Anaheim	0.66	0.67	0.74	0.41
Azusa	0.52	0.64	0.77	0.59
Banning	0.17	0.46	0.73	0.26
Compton	0.65	0.67	0.77	0.48
Fontana	0.88	0.89	0.87	0.59
Glendora	0.46	0.53	0.72	0.52
Lake Elsinore	0.52	0.70	0.79	0.56
LA North Main ST	0.36	0.67	0.78	0.48
LAX	0.31	0.48	0.65	0.25
Mira Loma	0.56	0.71	0.86	0.67
Rubidoux	0.46	0.65	0.86	0.68
San Bernardino	0.68	0.85	0.86	0.67
San Gabriel	0.53	0.77	0.81	0.62
Santa Clarita	0.27	0.72	0.84	0.61
Upland	0.76	0.80	0.86	0.61

Table 4 Daily average R^2 at 12 evaluation sites, and these were not used spatial interpolation. R^2 for CMAQ was computed using the five highest ozone months, May–September of 2020

Sites	Bicubic R^2	IDW R^2	Ordinary kriging R^2	CMAQ R^2
Crestline	0.35	0.42	0.42	0.23
La Habra	0.75	0.80	0.77	0.44
Long Beach	0.46	0.60	0.56	0.30
Mission Viejo	0.15	0.36	0.49	0.39
North Hollywood	0.67	0.67	0.79	0.59
Pasadena	0.55	0.71	0.78	0.57
Perris	0.55	0.72	0.80	0.56
Pomona	0.71	0.83	0.84	0.68
Redlands	0.60	0.74	0.71	0.57
Reseda	0.63	0.63	0.71	0.01
West LA	0.29	0.56	0.60	0.28
Winchester	0.37	0.40	0.39	0.45





Fig. 6 Monthly mean bias computed for 2020 for 15 sites using the kriging interpolation method (panel a), and CMAQ simulation (panel b). The colors of the lines correspond to the evaluation locations.

Although the interpolation R^2 values for the 15 building sites are high, the accuracies of the 12 evaluation sites are somewhat lower than those reported in other studies. In our previous work, where we employed RFR to predict O_3 levels in Fontana, we achieved an R^2 of 0.86. Additionally, Lyu *et al.* utilized the RFR method to predict ozone concentrations in the Beijing–Tianjin–Hebei region, achieving a monthly R^2 of 0.93 (Lyu *et al.*, 2022).³⁷ Two factors contribute to the performance of the evaluation sites in our approach. First, the estimation of O_3 concentrations in evaluation sites relied on historical data from neighboring building sites. However, the building sites are not evenly distributed in Southern California, and the performance of the interpolating locations is inversely proportional to the distance of the building sites. Second, O_3 levels are more locally influenced in SoCAB, and the relationship between NO_x and VOC is not strictly linear. Therefore, the estimation from interpolation might not fully capture this locality. We also note that the choice of averaging period will impact R^2 , such that comparison of daily vs. monthly values will lead to discrepancies that favor a longer averaging period.

5. Discussion

The reduction in traffic volumes during the lockdown from March to May led to a decrease in observed CO and NO_x .^{3,16} As a result, we expected an overall reduction in ozone levels over the SoCAB region. The average diurnal ozone concentrations before the lockdown (Jan–Feb) in 2020 were noticeably greater than the average from 2016–2019 for all 15 building sites. Fig. 7 shows the averaged diurnal profiles of three 2020 periods for inland sites, Lake Elsinore and Fontana: pre-lockdown (a and d), lockdown (b and e), and post-lockdown (c and f) periods. Before the lockdown, the 2020 ozone concentrations (red line) in Lake Elsinore and Fontana exceeded the four-year average (blue line), indicating a recent worsening of ozone trends in Southern California. The ML model with the interpolation

method (black line) successfully predicted this ozone trend before the lockdown. During the lockdown, observed ozone levels in 2020 significantly decreased in Lake Elsinore, dropping below the four-year average. After the lockdown, ozone levels in 2020 rebounded but remained lower than the pre-lockdown period. The ML model effectively captured these ozone trends throughout the three periods of 2020 for the Lake Elsinore site. In contrast, ozone levels in Fontana did not decrease significantly below the four-year average during the lockdown and remained high afterward. It is important to note that Lake Elsinore is located in a remote area surrounded by trees. During the lockdown, Lake Elsinore showed a drop in ozone concentrations, indicating that the location is in a NO_x limited atmosphere, where fluctuations in NO_x have a significant impact on ozone levels. On the other hand, Fontana is an urban site, and the ozone levels did not exhibit significant improvement during the lockdown, suggesting that Fontana is located in a VOC limited atmosphere.

Post-lockdown differences compared to the four-year average were not significant across the 15 sites. The RFR model captured ozone trends throughout 2020, although slightly lower during lockdown and despite the observed reduction in NO_x , suggesting that meteorological features would play an important role in predicting ozone levels during anomalous episodes in addition to air quality features. Actual and modeled discrepancies also indicate anomalous ozone behavior during lockdown. For instance, several sites in the SoCAB showed an increase in ozone levels based on the diurnal profile implying that the urban locations in the SoCAB were in VOC limited regimes, where there was NO_x reduction-initiated ozone enhancement.³⁸

The diurnal NO_x concentrations at all sites in Southern California exhibit a consistent pattern, in which both pre-lockdown and post-lockdown NO_x levels were significantly higher than during the lockdown period. In Fig. S13,[†] the diurnal changes in NO_x levels are illustrated for pre-lockdown





Fig. 7 Averaged diurnal profiles of 2016–2019 (blue), actual 2020 (red), and ML predicted 2020 (black) ozone concentrations (ppb) at Lake Elsinore (a–c) and Fontana (d–f) for three different periods: (a and d) pre-lockdown (Jan to Feb), (b and e) lockdown (Mar to May), and (c and f) post-lockdown (after May). The shaded area is the standard deviation of the 2016–2019 measurements. Additional sites are provided in the ESI.†

(blue), lockdown (orange), and post-lockdown (green) between the 2020 NO_x and the average from 2016–2019. Positive values before the lockdown suggest an increase in NO_x levels in 2020 compared to the historical average of 2016–2019. However, during the lockdown, the differences are negative, indicating a significant decrease in 2020 NO_x levels compared to the historical data due to a substantial decrease in traffic and anthropogenic activities.

We computed the diurnal differences between 2020 O_3 and historical O_3 (average from 2016 to 2019) for both actual 2020 O_3 and ML 2020 O_3 (Fig. S17 and S18†) to show the trends in

O_3 concentrations for the pre-lockdown, lockdown, and post-lockdown periods. During the lockdown (orange line), the Lake Elsinore site exhibits negative changes of -4 ppb at 15:00, the peak O_3 concentration time of the day. However, in the early morning, the O_3 changes turn positive (~ 3 ppb), attributed to the reduced NO_x titration. Post-lockdown (green line) shows mostly positive differences, indicating an increase in O_3 concentrations due to rising emissions and transition to summertime. In Fontana, O_3 trends do not show significant differences across the three periods. Notably, during peak O_3 hours (13:00–16:00), O_3 levels are more than 3 ppb higher





Fig. 8 Flow chart of the ML model to summarize the ML method and the evaluation results in the South Coast Air Basin.

compared to historical values, suggesting that the reduction in emissions has an inverse effect on O_3 concentrations. It's worth noting that the ML model successfully predicted O_3 trends in Lake Elsinore for all three periods. However, the ML model failed to predict the behavior of O_3 in Fontana, as it estimated a decrease in O_3 during the lockdown. The summary of the machine learning method and its performance across different regimes in the SoCAB is illustrated in Fig. 8.

To illustrate the variations in NO_x corresponding to changes in O_3 for three periods (pre-lockdown, lockdown, and post-lockdown), we calculated the O_3 sensitivity using the ratio of differences in O_3 and NO_x between 2020 and historical data, as shown in eqn (8).

$$O_3 \text{ sensitivity} = \frac{dO_3}{dNO_x} = \frac{2020 O_3 - \text{historical } O_3}{2020 NO_x - \text{historical } NO_x} \quad (8)$$

In the VOC limited regimes, we forecast the sensitivity of O_3 to be minimal regarding the changes in NO_x . This is evident for areas with substantial NO_x emissions, such as Azusa, Fontana, and Upland (Fig. 9), where the sensitivities of O_3 (dO_3/dNO_x) during the lockdown are minimal. Conversely, in NO_x limited regimes, we expect to observe a reduction in O_3 corresponding to the decrease in emissions. Therefore, the sensitivities of O_3 in NO_x limited regimes are maximized during the lockdown, as illustrated in Fig. 9 for Lake Elsinore and Banning. At hour 14:00, O_3 concentrations in Lake Elsinore decreased more than 12 ppb per 1 ppb reduction in NO_x .

The ML model with interpolation successfully predicted O_3 trends by utilizing four meteorological parameters and two observed ozone precursors (listed in Table 1). It is important to note that O_3 exhibits strong relationships with meteorology, NO_x , and VOCs. Due to data availability, VOC data were omitted from the training set. The current ML model has some weaknesses for testing the sensitivity of O_3 to anomalous precursor levels and meteorology. Our ML model performs well in predicting O_3 levels where the test data resembles the training data. However, the model struggles to

give accurate predictions when the test data significantly differs from the training sets. For instance, during the lockdown, the model failed to predict the O_3 concentrations in the VOC limited regimes. This suggests that relying on ML models to predict future scenarios may be unreliable under new regimes. Considering additional features, such as VOCs in the training sets, may enhance the model's ability to predict accurately when extrapolating beyond the feature space. To our understanding, there are no ML models known for effective extrapolation of the training data to provide reliable predictions.

6. Conclusion

This study highlights the advantages of spatial interpolation methods for ozone predictions during anomalous environmental events. With modern processor architectures (*e.g.*, AMD Zen 3 or Intel Alder Lake), training the RFR model and



Fig. 9 O_3 sensitivity for six locations in Southern California during the lockdown period reflecting the change in O_3 with respect to the change in NO_x between 2020 data and historical data.



performing high-resolution interpolation over the SoCAB region for one prediction year took less than five minutes of walltime with a 16-core processor. In contrast, CMAQ walltime was 16 days for a year-long simulation for the SoCAB region. Further, ozone modeling for 2020 was challenging because of unforeseen emissions conditions from March to September, during which traffic volume significantly decreased (up to 40% reduction in some locations). We hypothesized that mid-2020 ozone levels would decrease semi-proportionally due to the decline in traffic volume. However, the changes in ozone levels in the SoCAB were small in magnitude, but directionally the changes were informative for future emissions reductions planning (increased ozone indicates VOC limitations).

Ordinary kriging interpolation using ML building provided daily data, addressed data missingness, and captured 2020 ozone trends with low bias despite the sudden change in emissions. The ML model with the interpolation method successfully captured ozone trends throughout three periods in 2020, particularly in locations operating under a NO_x limited regime, such as Lake Elsinore. However, it faced challenges in predicting ozone levels during the lockdown period in areas characterized by a VOC limited regime, like Fontana. ML inherently relies on patterns learned from historical data to make predictions, especially for inputs that resemble past occurrences. In this study, the ML model struggled to make accurate predictions for VOC limited regime, suggesting that events akin to the COVID-19 lockdown had not been encountered in the past. Unfortunately, due to the unavailability of speciated VOC data, we didn't incorporate them as a training feature in the model. Since ozone formation exhibits a non-linear correlation with both NO_x and VOC, the inclusion of speciated VOC data would likely enhance the model's accuracy, especially for regions with a VOC limited atmosphere. Our ML model provides regulators with valuable insights into NO_x and VOC limited regimes across the Southern California domain, enabling policymakers to devise more effective emission reduction strategies and improve air quality at hyperlocal scales.

Data and source codes

All training and evaluating air quality and meteorology data are available at https://aqs.epa.gov/aqsweb/airdata/download_files.html#Raw. Weekly traffic observations in Southern California and emissions are available upon request. Source codes for ML and interpolation were uploaded to GitHub: <https://github.com/kdo037/Machine-Learning-with-Spatial-Interpolation>.

Conflicts of interest

There are no conflicts to declare.

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