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Catalytic resonance theory: parallel reaction pathway control†

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Catalytic enhancement of chemical reactions *via* heterogeneous materials occurs through stabilization of transition states at designed active sites, but dramatically greater rate acceleration on that same active site can be achieved when the surface intermediates oscillate in binding energy. The applied oscillation amplitude and frequency can accelerate reactions orders of magnitude above the catalytic rates of static systems, provided the active site dynamics are tuned to the natural frequencies of the surface chemistry. In this work, differences in the characteristics of parallel reactions are exploited *via* selective application of active site dynamics ($0 < \Delta U < 1.0$ eV amplitude, $10^{-6} < f < 10^4$ Hz frequency) to control the extent of competing reactions occurring on the shared catalytic surface. Simulation of multiple parallel reaction systems with broad range of variation in chemical parameters revealed that parallel chemistries are highly tunable in selectivity between either pure product, even when specific products are not selectively produced under static conditions. Two mechanisms leading to dynamic selectivity control were identified: (i) surface thermodynamic control of one product species under strong binding conditions, or (ii) catalytic resonance of the kinetics of one reaction over the other. These dynamic parallel pathway control strategies applied to a host of simulated chemical conditions indicate significant potential for improving the catalytic performance of many important industrial chemical reactions beyond their existing static performance.

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1. Introduction

The core capability of catalysis is the controlled steering of molecules through preferred chemical pathways *via* manipulation of surface intermediates and transition state energies.¹ The complex reaction networks of even small-molecule chemistries (*e.g.* methanol synthesis, ethylene epoxidation) contain energetically similar pathways to side products such as CO₂, which devalue chemical processes and contribute to climate change.^{2–6} Traditional design aims for specific catalyst structures which preferentially lower the transition states of preferred pathways; catalyst binding strength and configuration are tuned in the

structural shape (*e.g.* pores, pockets) and active site of materials.^{7–10} The limit of this strategy derives from the differences in competing pathway transition states, for which competitive stabilization in many important static catalytic systems has already achieved maximum capability.^{11,12}

An alternative strategy for catalytic reaction control proposes a dynamic catalytic surface, whereby the binding energy (*i.e.*, heat of adsorption) of surface intermediates and associated transition state energies oscillate on the time scale of the catalytic turnover frequency.¹³ The heat of adsorption of hydrocarbons on metals and metal oxides can be altered by several methods^{14,15} including electric and magnetic fields,^{16–19} photocatalysis,²⁰ surface strain,^{21,22} solid electrolytes,^{23–27} catalytic diodes,^{28–30} and back-gated field effect modulation.^{31–33} For each combination of catalyst material, chemical mechanism, and method of external stimulus, the dynamic variables including imposed surface binding energy frequency f and amplitude ΔU comprise a narrow set of conditions which can potentially achieve catalytic turnover frequencies which are orders of magnitude above the static Sabatier maximum (*i.e.*, Balandin–Sabatier volcano peak).³⁴

The mechanism of ‘catalytic resonance’ for enhanced catalytic turnover occurs by matching the frequency of oscillating binding energies to the natural frequencies of catalytic surface

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reactions. As depicted in Fig. 1a, a reaction is generally comprised of three parts (adsorption, surface reaction, and desorption), any one of which can be rate determining. In Fig. 1b, the Balandin–Sabatier volcano curve depicts the system turnover frequency as a function of a system descriptor; the maximum observed turnover frequency delineates the transition from one rate-limiting elementary step to another.^{35–37} An interpretation of catalytic resonance is that the oscillation between surface binding states on either side of the volcano peak permits each elementary step of the catalytic sequence to occur under conditions optimized for that particular step. The amplitude ΔU of the imposed surface binding energy oscillation connects the two conditions as drawn in maroon in Fig. 1b: low binding energy, U_L , and high binding energy, U_H . As the frequency of the imposed surface binding energy oscillation increases approaching the surface reaction frequencies, the maximum overall turnover frequency is achieved.

The introduction of two competing parallel surface reactions raises the question of whether selectivity to specific chemical products can be controlled by prescribed tuning of the imposed surface binding energy oscillation. Parallel reversible reactions of A-to-B and A-to-C as shown in Fig. 1a can have different transition states and different linear scaling relations. The transition state energy of an elementary reaction is linearly proportional to the surface energy by parameter α and offset by parameter β (kJ mol^{-1}).^{38–40} Additionally, the binding energies of surface species B^* and C^* will exhibit different extents of change relative to changes in the binding energy of A^* . A linear relationship between the binding energies of any two species has proportionality parameter $\gamma_{B/A}$ (for the A-to-B reaction) and δ_{B-A} for the energy offset (kJ mol^{-1}).³⁴ It remains to identify parameter space from these operating and chemical reaction variations that preferentially enhance the rate of one elementary reaction over another.

In this work, the parallel reversible elementary reactions of A-to-B and A-to-C with thermoneutral free energy ($\Delta H_{A-B} = \Delta H_{A-C} = 0 \text{ kJ mol}^{-1}$) are evaluated *via* simulation under dynamic binding energy oscillation of all three intermediate species with the goal of assessing the parameter space leading to selective pathway control (*i.e.*, more B than C, or more C than B). Parallel

reactions are simulated in a continuous flow mixed reactor with varying parameters of γ_{B-A} and γ_{C-A} , as well as δ_{B-A} and δ_{C-A} in combination with different applied frequencies and amplitudes of surface binding energy oscillation to understand the conditions leading to pathway tunability.

2. Results and discussion

The competition between parallel catalytic surface reactions under dynamic conditions is most unique when the product surface species vary differently in binding energy. As depicted in Fig. 2, competing reactions of A-to-B and A-to-C are depicted with inverse gamma parameters. The reaction to produce B with $\gamma_{B/A}$ of 0.5 has a multi-state energy profile in Fig. 2a, whereby B^* changes only half as much in binding energy relative to A^* . In contrast, the reaction to produce C with $\gamma_{C/A} \sim 2.0$ has a multi-state energy profile in Fig. 2b, in which C^* changes twice as much in binding energy as A^* .

$$\gamma_{C/A} = \frac{\Delta BE_C}{\Delta BE_A} = 2.0 \quad (1)$$

These two systems are depicted in the gamma–delta plot of Fig. 2c, with the values of slopes γ and point of common binding energy δ between surface reactant and surface product for each elementary reaction. The state whereby B^* and C^* have the same surface adsorption enthalpy occurs in the gamma–delta plot of Fig. 2c at the intersection of the two reaction lines and is identified as δ_{B-C} .

For the case of inverse (2.0 and 0.5) gamma parameters depicted in Fig. 2, the reaction kinetics were evaluated for identical reaction conditions ($\delta_{B-A} = 1.4 \text{ eV}$, $\delta_{C-A} = 1.4 \text{ eV}$). As depicted in Fig. 3a, variation of gamma ($\gamma_{B/A} = 2.0$, $\gamma_{C/A} = 0.5$) produces distinct volcano peak positions and reaction activity. The low $\gamma_{C/A}$ of 0.5 produces a volcano peak of $\sim 5 \text{ s}^{-1}$, while the high $\gamma_{B/A}$ of 2.0 volcano peak maximum is significantly lower ($5 \times 10^{-3} \text{ s}^{-1}$). The key transition in surface coverage of the system occurs at zero relative binding energy of A, at which the surface transitions between high coverage of C and B as the relative binding energy of A increases (Fig. 3b).



Fig. 1 (a) Parallel catalytic reversible reactions of A-to-B and A-to-C. (b) Volcano plot of a single reaction A-to-B turnover frequency as a function of the relative binding energy of B at 1% conversion. Depicted is an oscillation of amplitude ΔU of $\sim 0.8 \text{ eV}$.





Fig. 2 Parameters of parallel reactions with dynamic heterogeneous catalysis. (a) State-enthalpy diagram of oscillating heterogeneous catalyst for the reversible reaction of A-to-B. (b) State-enthalpy diagram of oscillating heterogeneous catalyst for the reversible reaction of A-to-C. (c) Variation of the binding energy of B* and C* linearly scaling with the binding energy of A* with slopes $\gamma_{B/A}$ and $\gamma_{C/A}$ with common points δ_{A-B} and δ_{A-C} . The intersection of the two reaction lines identifies δ_{B-C} .

Oscillation of the binding energy of A (ΔU_A) by 0.6 eV was simulated over ten decades of frequencies ($10^{-6} < f < 10^4$ Hz) and variation of the amplitude position is denoted by the position of the weakest binding energy (*i.e.*, left oscillation endpoint, U_L). As depicted in the results of Fig. 3c, the selectivity

is fully tunable to either product B or C depending on the applied dynamic conditions. At low oscillation frequencies ($f < 10^{-3}$ Hz), the catalytic system achieves nearly perfect selectivity to product C (blue) until about -0.2 eV relative binding energy of A, after which selectivity to both products is the same ($S_B \sim S_C$



Fig. 3 Dynamic heterogeneous catalysis, using a fixed amplitude square waveform, for a parallel reaction system with A-to-B and A-to-C chemistry. (a) Sabatier volcano plots for the consumption of A (black), production of B (red), and production of C (blue), and (b) corresponding surface coverage plot with surface species * (purple), A* (black), B* (red), and C* (blue). (c) Selectivity enhancement towards the production of B with an oscillation amplitude of 0.6 eV, varying oscillation endpoints (-1.64 to 0.16 eV), and varying oscillation frequencies (10^{-6} to 10^4 Hz) and (d) corresponding rate enhancement for the consumption of A. Selectivity to B under static catalyst conditions at varying relative binding energy of A in the above bar. (e) Rate enhancement towards the production of B in the A-to-B single-reaction system, and (f) rate enhancement towards the production of C in the A-to-C single reaction system. Conditions: $T \sim 150$ °C, 100 bar A feed pressure, 1% conversion of A. Parameters: $\Delta H_{OVR} \sim 0$ kJ mol $^{-1}$ for both reactions, BEP parameters of $\alpha \sim 0.6$, $\beta \sim 100$ kJ mol $^{-1}$, linear scaling parameters of $\gamma_{B/A} \sim 2.0$, $\gamma_{C/A} \sim 0.5$, and $\delta_{B-A} \sim 1.4$ eV, $\delta_{C-A} \sim 1.4$ eV. Relative binding energies of A in all panels (a)–(f) can be converted to absolute binding energies of A by adding 1.4 eV to the independent axis.



converts to C^* resulting in a surface covered in C^* . The key transition determining surface coverage dominance is captured in the quantity, δ_{B-C} , which is the energy whereby B^* and C^* have the same surface adsorption enthalpy (identified in Fig. 2c). Alternatively, product B is kinetically favored, since the desorption of B proceeds quickly relative to C in the weaker binding (blue) state. As depicted in Fig. 4c, B^* exhibits faster desorption kinetics. The ultimately favored product in this scenario depends on the overall balance of these two mechanisms (thermodynamic *versus* kinetic), which can shift as the binding energy of A^* changes over the range of the volcano plot.

The two mechanisms enhancing selectivity are observed in the formation of product B in Fig. 3c. At stronger binding energies (oscillation endpoint $U_L > 0$ eV), the product B is produced due to dominance of the surface coverage by B^* . However, the kinetic mechanism exists at relative binding energies below 0 eV in the region of $-0.5 < U_L < 0$ eV. In this range the oscillation amplitude ($\Delta U_A = 0.6$ eV) extends across the A-to-B reaction volcano, and this reaction is kinetically resonance enhanced. The reaction to form B increases from 10^{-3} s^{-1} under the static catalytic condition at the volcano peak (Fig. 3a) to a formation rate of 10^2 s^{-1} under dynamic conditions, even with the existence of the parallel A-to-C reaction. This 10^5 -fold rate enhancement leads to high selectivity to B even when B^* does not dominate the surface coverage.

More complicated behavior is observed when oscillation amplitude becomes a variable. In Fig. 3, the oscillation amplitude of A was fixed at ΔU_A of 0.6 eV. This amplitude was permitted to vary between $0 < \Delta U_A < 1.0$ eV as depicted in Fig. 5a for the same parallel reaction system ($\gamma_{B-A} \sim 2.0$, $\gamma_{C-A} \sim 0.5$, and $\delta_{B-A} \sim 1.4$ eV, $\delta_{C-A} \sim 1.4$ eV). As previously stated, this reaction system does not select for product B in excess of 50% under any condition when operated with a static catalyst, but high selectivity to B becomes possible under dynamic conditions. To

assess the role of amplitude in dynamic catalytic operation, the oscillation amplitude was centered around the volcano peak for the A-to-B reaction (-0.2 eV relative binding energy of A); the reaction to form B transitions between surface reaction (A^* -to- B^*) control and desorption rate limitation (C^* -to-C or B^* -to-B) at the peak. Here, the consumption of A is limited by the desorption of C at the left oscillation amplitude endpoint and the desorption of B at the right amplitude endpoint.

The catalytic resonance of reaction A-to-B under variable amplitude ($0 < \Delta U_A < 1.0$ eV) and frequency ($10^{-6} < f < 10^4$ Hz) is depicted in Fig. 5b. As expected, the selectivity to B at low oscillation frequencies is minimal due to the relatively high production rate of C (the surface coverage dominating species). Preferential selectivity to B (>50% B) is only achieved once the oscillation frequency increases beyond ~ 0.01 Hz, with a maximum selectivity of 93% achieved at moderate oscillation amplitudes of 0.5–0.6 eV. Generally, the consumption of A (Fig. 5c) increases with the oscillation amplitude, since the lower amplitude endpoint, U_L , rises to higher TOFs as oscillation amplitude increases. However, a larger oscillation amplitude is not more favorable for selectivity enhancement, due to the tradeoff between enhancing the production of B *versus* C. Desorption of C proceeds quickly ($1 < \text{TOF}_C < 100 \text{ s}^{-1}$) for all oscillation amplitudes, and higher frequencies above 10 Hz begin to reduce selectivity to product B. In addition, the consumption of A decreases at higher oscillation frequencies as the rate of B production decreases. Oscillation frequencies above 10 Hz are too fast for the desorption of B, which leads to incomplete emptying of surface B^* at the left oscillation endpoint. Instead, C is produced but with minimal rate enhancement as these oscillations do not reach weak enough binding energies.

The linear scaling relationships of surface intermediates A^* , B^* and C^* strongly impact the selectivity behavior of dynamic catalytic systems. Throughout Fig. 3 and 5, the linear scaling

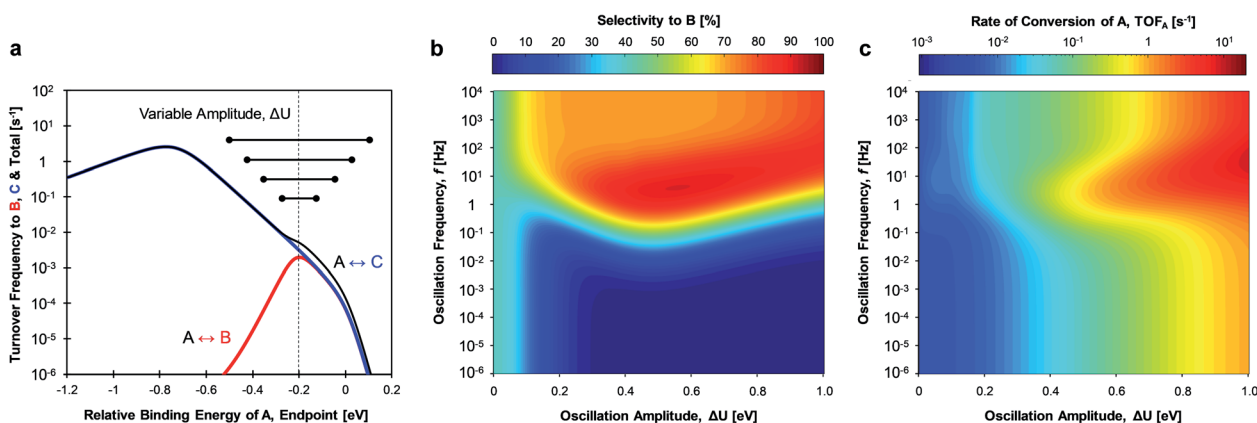


Fig. 5 Dynamic heterogeneous catalysis, using a variable amplitude square waveform, for a parallel reaction system with A-to-B and A-to-C chemistry. (a) Volcano plots for reactant consumption (black) and product formation (red/blue) turnover frequency. Dynamic catalysis oscillations with varying oscillation amplitude are shown as black horizontal bars. (b) Selectivity to the production of B (mol%) with varying oscillation frequency (10^{-6} to 10^4 Hz) and amplitude (0.0 to 1.0 eV). The oscillation midpoint was held constant at the volcano peak for product B formation. (c) Consumption rate of A (s^{-1}) with varying oscillation frequency and amplitude. Conditions: $T \sim 150$ °C, 100 bar A feed pressure, 1% conversion of A. Parameters: $\Delta H_{\text{Ovr}} \sim 0$ kJ mol $^{-1}$ for both reactions, BEP parameters of $\alpha \sim 0.6$, $\beta \sim 100$ kJ mol $^{-1}$, linear scaling parameters of $\gamma_{B-A} \sim 2.0$, $\gamma_{C-A} \sim 0.5$, and $\delta_{B-A} \sim 1.4$ eV, $\delta_{C-A} \sim 1.4$ eV. Relative binding energies of A in all panels a–c can be converted to absolute binding energies of A by adding 1.4 eV to the independent axis.



relationships between the adsorbates were held constant with γ_{B-A} of 2.0 and γ_{C-A} of 0.5. However, studies of gas phase reactions over periodic metals show that each adsorbate pair has quite different γ and δ values, with γ ranging between -20 to 20 and δ being -10 to 10 eV.⁴⁰⁻⁴³ In addition, density functional theory (DFT) calculations of adsorbates bound to common catalysts such as Pt(111) or Ni(111) reveal that the linear scaling relationships (γ and δ) for periodic metals can potentially vary for different external stimuli (*i.e.* stress/strain, electric field, lasers/light) applied to a single metal.⁴³⁻⁴⁶ To account for these variations in catalyst-stimulating methods, the effects of changing linear scaling relationships were evaluated for product selectivity and rate enhancement.

In two case studies, γ_{B-A} was decreased by a factor of $2\times$ and $8\times$ to evaluate the impact on selectivity trends if the ratio of γ between parallel surface catalytic reactions (*e.g.* $\gamma_{B/A}/\gamma_{C/A}$) was greater or less than one. Fig. 6a and b depict the volcano plots for the consumption of A (TOF_A), production of B (TOF_B), production of C (TOF_C), and the surface coverage under static catalytic operation. In these two systems, the surface coverage transition occurs at $\delta_{B-C} = \delta_{A-C} = \delta_{A-B} = 1.4$ eV (which is 0 eV relative

binding energy of A in Fig. 6). Generally, the product with a lower γ dominates the surface coverage and production until a U_L of about -0.5 eV and -0.4 eV for Fig. 6d and f, respectively. This occurs due to a shift in the rate determining step from surface reaction to desorption for the product with the higher γ . This indicates that the selectivity challenge for dynamic catalytic operation is to stimulate the rate of production of the surface species more sensitive to external stimuli (*i.e.*, higher γ).

Fig. 6c and d present heat maps for the TOF for the consumption of A and selectivity to B when $\gamma_{B-A} < \gamma_{C-A}$ (0.25 and 0.50, respectively) as a function of applied frequency ($10^{-6} < f < 10^4$ Hz) and oscillation endpoint (U_L) at fixed total amplitude ($\Delta U_A = 0.6$ eV). In this scenario, the selectivity to B is high only when its desorption is enhanced at weak binding conditions (relative binding energies of -1.64 to -1.0 eV). Once the amplitude achieves an appreciable binding energy ($U_L > -1.0$ eV), the product C is heavily favored over B for frequencies above ~ 1 Hz. However, overall consumption rates of A do not increase when both products exhibit $\gamma < 1.0$, due to the lack of significant surface coverage for A* over a wide range of binding energies. This is further exacerbated by the stronger binding of



Fig. 6 Dynamic heterogeneous catalysis, using a fixed amplitude ($\Delta U = 0.6$ eV) square waveform, for a parallel reaction system with A-to-B and A-to-C chemistry with variable gammas. (a) Volcano plots of two systems with variable gamma parameters. (b) Surface coverage of A*, B*, and C* for two systems. Turnover frequency of A and selectivity to B as a function of frequency and lower amplitude endpoint for system 1 (c and d) and system 2 (e and f). System 1: $\gamma_{B/A} = 0.25$, $\gamma_{C/A} = 0.50$, and $\delta_{B-A} = \delta_{C-A} = 1.4$ eV. System 2: $\gamma_{B/A} = 1.0$, $\gamma_{C/A} = 0.5$, and $\delta_{B-A} = \delta_{C-A} = 1.4$ eV. Relative binding energies of A in all panels (a)–(f) can be converted to absolute binding energies of A by adding 1.4 eV to the independent axis.



both B* and C* at the low γ_{B-A} and γ_{C-A} values that limit the desorption rates of the products.

In the second scenario of Fig. 6, γ_{B-A} is increased to 1.0 revealing similar behavior to the scenario in Fig. 3 where γ_{B-A} was 2.0. Once γ_{B-A} is higher than γ_{C-A} , selectivity to B is low (<10%) across most binding energies less than -0.44 eV, and rate enhancement can only be achieved at weak binding ($U_L < -1.25$ eV) and high frequencies (>100 Hz). This indicates that the ratio of γ between reaction pathways ($\gamma_{B/C} = \gamma_{B/A}/\gamma_{C/A}$) is critical to strategically controlling catalyst dynamics for specific products. High selectivity with a $\gamma_{B/C}$ ratio less than one is readily achievable, while values greater than one require a precise selection of the amplitude and frequency.

The other key surface chemistry parameter controlling dynamic selectivity is δ (depicted in Fig. 2a–c), which identifies the conditions of common binding energy between surface species. In the three scenarios of Fig. 7, the offset for the linear scaling relationship, δ_{B-C} , was varied (by selecting δ_{A-B} and δ_{A-C}) to determine its effect on catalytic selectivity to products under static and dynamic conditions with a fixed amplitude ($\Delta U = 0.6$ eV) and varying oscillation frequency ($10^{-6} < f < 10^4$ Hz). The three scenarios are depicted in Fig. 7a as volcano plots of the turnover frequency of A and as the associated surface coverages in Fig. 7b. Systems 1 and 2 both have the same gamma ratios ($\gamma_{C/A} = 0.5$, $\gamma_{B/A} = 2.0$) and delta for the reaction of A-to-C ($\delta_{A-C} = 1.4$ eV), but the delta for the reaction of A-to-B differs (δ_{A-B} of 0.8 eV for system 1 and δ_{A-B} of 2.0 eV for system 2). The third

system considers the case of similar delta values ($\delta_{A-C} = 1.4$ eV, $\delta_{A-B} = 1.0$ eV) and identical gamma values ($\gamma_{C/A} = \gamma_{B/A} = 2.0$).

System 1 of Fig. 7c–d only selects for product C ($U_L < -0.4$ eV) or an equimolar product mixture of B and C under static catalyst conditions. However, dynamic catalyst operation as square waves of 0.6 eV amplitude leads to parameter space with significant overall rate acceleration in addition to a third selectivity regime which overwhelmingly favors species B at higher frequencies. When δ_{B-A} is 0.8 eV in system 1 as shown in Fig. 7c, TOF_A exhibits two regimes of $\sim 100\times$ rate enhancement as compared to the static optima (Fig. 7a). At $-1.64 < U_L < -1.22$ eV, C* is the dominant surface species under static conditions (Fig. 7b), and resonance with the desorption of C is achieved at oscillation frequencies >100 Hz with $\sim 100\%$ selectivity towards C. Alternatively, the selectivity towards B is enhanced to nearly 100% at $-0.75 < U_L < 0$ eV. This regime is partially attributed to the enhanced formation of B between $-0.75 < U_L < -0.4$ eV, where the system achieves resonance with the pathway to B. At stronger binding energies above $\delta_{B-C} = -0.4$ eV, high selectivity to B is attributed to the dominant surface coverage of B*. This transition, δ_{B-C} , can be predicted from the intersecting binding energy lines of a gamma–delta plot comparable to Fig. 2c or from the following equation based on the parameters of the independent elementary reactions.

$$\delta_{B-C} [\text{eV}] = \frac{(1 - \gamma_{C/A})\delta_{C-A} - (1 - \gamma_{B/A})\delta_{B-A}}{\gamma_{B/A} - \gamma_{C/A}} \quad (2)$$

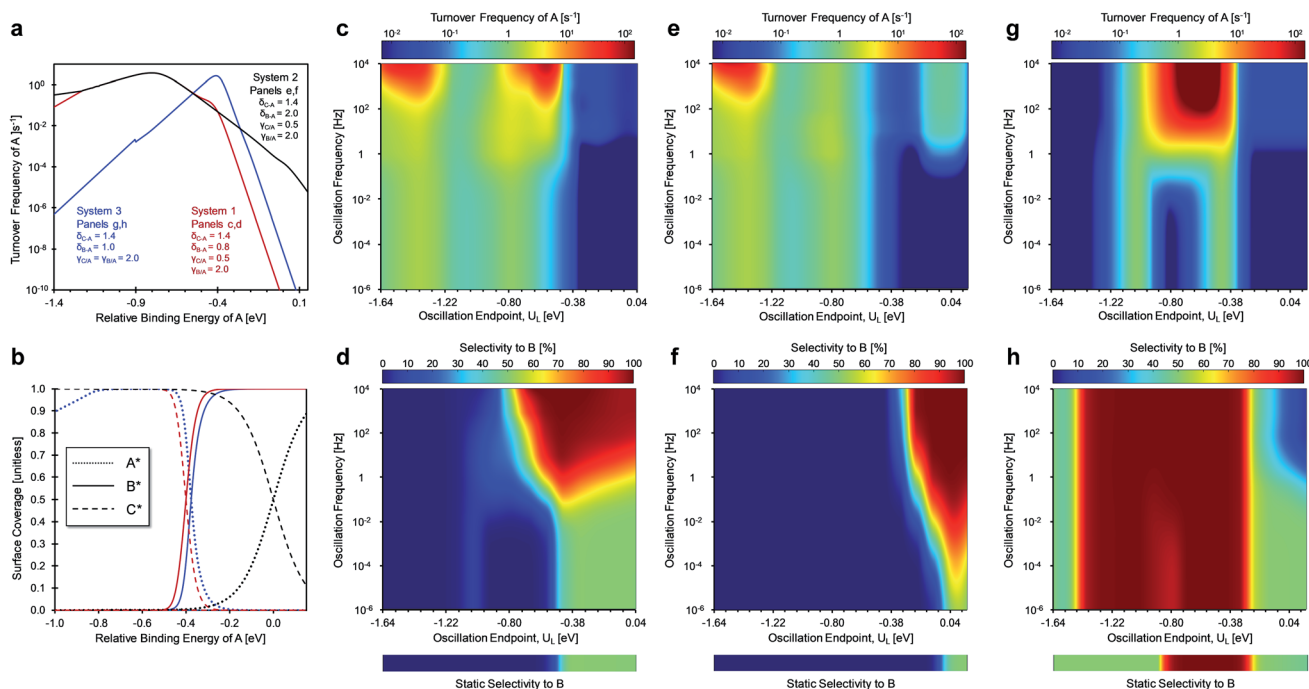


Fig. 7 Dynamic heterogeneous catalysis, using a fixed amplitude ($\Delta U = 0.6$ eV) square waveform, for a parallel reaction system with A-to-B and A-to-C chemistry with variable deltas. (a) Volcano plots of three systems with variable delta parameters. (b) Surface coverages of A*, B*, and C* for three systems. Turnover frequency of A and selectivity to B as a function of frequency and lower amplitude endpoint for system 1 (c and d), system 2 (e and f), and system 3 (g and h). The selectivity to B at static catalyst conditions for varying relative binding energy of A as bars below each of the three systems. System 1: $\gamma_{B/A} = 2.0$, $\gamma_{C/A} = 0.5$, and $\delta_{B-A} = 0.8$ eV, $\delta_{C-A} = 1.4$ eV. System 2: $\gamma_{B/A} = 2.0$, $\gamma_{C/A} = 0.5$, and $\delta_{B-A} = 2.0$ eV, $\delta_{C-A} = 1.4$ eV. System 3: $\gamma_{B/A} = 2.0$, $\gamma_{C/A} = 2.0$, and $\delta_{B-A} = 1.0$ eV, $\delta_{C-A} = 1.4$ eV. Relative binding energies of A in all panels (a)–(h) can be converted to absolute binding energies of A by adding 1.4 eV to the independent axis.



Similar selectivity behavior is observed for system 2 (Fig. 7e and f). When δ_{B-A} increases to 2.0 eV, the kinetic regime of high selectivity to B shifts to stronger binding energies ($U_L > -0.4$ eV) and extends to lower oscillation frequencies ($f > 10^{-2}$ Hz). This occurs due to the dominant surface coverage transition at U_L of 0 eV from species C^* to A^* as the relative binding energy of A increases. The surface coverage transition of the two products only occurs at stronger binding energies associated with δ_{B-C} of +0.4 eV (not shown). Additionally, the enhancement in TOF_A at weaker binding energies due to resonance with the desorption of C is almost identical to the behavior of system 1.

System 3 of Fig. 7g and h exhibited unique behavior when $\gamma_{B/A}$ and $\gamma_{C/A}$ were both equal to 2.0 and δ_{B-A} and δ_{C-A} were 1.0 eV and 1.4 eV, respectively. For static catalyst operation (Fig. 7h), most conditions of amplitude position (U_L) produced equimolar selectivity to B and C; high selectivity to B existed only for $-0.9 < U_L < -0.3$ eV. For square waveform oscillations at ΔU_A of 0.6 eV, the region of high selectivity to B expands to $-1.4 < U_L < -0.4$ eV where the surface coverage of B^* dominates. In this region, significant rate enhancements of $\sim 10\,000\times$ can be achieved at oscillation frequencies greater than 100 Hz, as shown in Fig. 7g. With nearly 100% selectivity to B, this kinetic regime resembles a single A-to-B reaction whereby the system achieves ‘surface resonance’ at these U_L ranges. This particular system is singular; because $\gamma_{B/A}$ and $\gamma_{C/A}$ are the same, the quantity δ_{B-C} does not exist (eqn (2)), and C^* never exhibits high surface coverage. When depicted as a gamma-delta plot similar to Fig. 2c, this system would have two parallel reaction lines that never cross. Notably, selectivity of C is only enhanced at higher frequencies ($f > 1$ Hz) and strong binding energy ($U_L > 0$ eV) where desorption rates to C are higher.

3. Conclusions

The catalytic conversion of A *via* parallel pathways to products B and C was evaluated by simulation for selectivity control *via* applied oscillation of the surface binding energy of A in the form of square waves with variable amplitude and frequency. Implementation of surface dynamics leading to variation in the surface binding energies of all surface species (A^* , B^* , and C^*) required definition of linear scaling parameters (γ and δ) and Brønsted–Evans–Polanyi parameters (α and β) that define the extent of variation of surface intermediate and transition state binding energies. Comparison of kinetically different parallel reactions with broad variation in scaling parameters indicated significant capability for targeting specific products by selection of the dynamic criteria (frequency, amplitude, *etc.*), even when targeted chemical products (B or C) were not possible to selectively produce under static catalyst operation. Two mechanisms were identified leading to dynamic operation for product selectivity: (i) dominant surface coverage of a single species in the strong binding state of the oscillation, and (ii) catalytic resonance of one elementary pathway to rates greater than the competing pathway. Sampling of several disparate combinations of chemical and dynamic parameters indicates significant potential for controlling a wide range of chemistries towards favorable products beyond existing static catalytic methods.

4. Computational methods

Parallel A-to-B and A-to-C and single A-to-B or A-to-C reaction network numerical simulations were conducted in Matlab 2019a/b. Continuously stirred tank reactor (CSTR) model equations were used and appropriate model equations were implemented for three gas-phase (A, B, and C) and surface species (A^* , B^* , and C^*). The conversion of the reactant A was held at 1% throughout the static and dynamic calculations. Pre-exponential factors for adsorption and surface reaction/desorption were taken from collision and transition state theory, respectively.^{47,48} Adsorption steps were assigned a pre-exponential of 10^6 (bar s)⁻¹ and all other steps were assigned 10^{13} s⁻¹. Example differential equations are shown below for the reactant A and its adsorbed state A^* . For either parallel or single reaction systems, adsorption/desorption was described as a mass balance:

$$\frac{d[A]}{dt} = \frac{q\dot{\theta}}{V} ([A]_{\text{feed}} - [A]) - \frac{N_{\text{sites}}}{V} (k_{\text{ads}}[A]RT\theta^* - k_{\text{des}}\theta_A^*) \quad (3)$$

In parallel reaction systems, surface reaction/desorption was described:

$$\begin{aligned} \frac{d\theta_A^*}{dt} = & k_{\text{ads}}[A]RT\theta^* - (k_{\text{des}} + k_{\text{srf},B} + k_{\text{srf},C}) \\ & \theta_A^* + k_{\text{srf},B}\theta_B^* + k_{\text{srf},C}\theta_C^* \end{aligned} \quad (4)$$

In single reaction systems, surface reaction/desorption was:

$$\frac{d\theta_A^*}{dt} = k_{\text{ads}}[A]RT\theta^* - (k_{\text{des}} + k_{\text{srf},B})\theta_A^* + k_{\text{srf},B}\theta_B^* \quad (5)$$

Activation energies for the surface reactions were calculated using Brønsted–Evans–Polanyi (BEP) relationships. The parameter α was set to a typical value of 0.6, and β was set to a moderate value of 100 kJ mol⁻¹ based on literature of calculated BEP relationships.^{39,46,49} Binding energies at each oscillation endpoint were calculated using linear scaling relationships (LSRs) between the surface adsorbates. Previously defined parameters including γ_{ij} and δ_{i-j} were used to fully specify the binding energies of B^* and C^* relative to the binding energy of A. The values of γ_{ij} between 0.25–2.0 and δ_{i-j} between 0.8–2.0 eV were selected to evaluate their effects on static and dynamic reaction behavior. All binding energies were restricted to positive values to avoid nonphysical negative binding energies. Selectivity was defined as the ratio of the rate of production for one product (B or C) over the rate of consumption for the reactant (A).

Volcano plots and surface coverage were calculated for a given set of BEP and LSR parameters at 1% conversion of A. The reaction rates and coverage were sampled at intervals of 0.005 eV, and the built-in ‘fsolve’ function in Matlab was used to obtain values that most closely obtained 1% conversion of A. This calculation was repeated across a binding energy span of 1.0–2.0 eV, and extrapolation was performed using logarithmic extrapolation of rates and coverage.

Dynamic catalysis was implemented using dynamic parameters including oscillation amplitude (ΔU_A), frequency (f),



endpoints (U_L , U_H), and waveform type (square waves). All simulations in this manuscript were conducted using a symmetric square waveform with assigned endpoints and frequency. For each endpoint, a set of adsorption, surface reaction, and desorption rate constants were calculated. Then, the oscillation frequency was used to allow the simulation to run for an allotted amount of time at each endpoint. Time-averaged conversion and turnover frequency were calculated using the built in 'trapz' function in Matlab over the final and one intermediate oscillation period. The simulation was converged if it met two criteria: (i) time-averaged conversion of A of $1.00 \pm 0.01\%$ and (ii) $<1.0\%$ differences in the time-averaged conversion of A sampled at the end and middle of the simulation trial.

Heat maps were generated for the TOF of the consumption of A and the selectivity towards B production using the built in 'heatmap' function in Matlab. Data was obtained at 175–650 discrete data points and then subdivided by 80–130 \times to generate a 2080 \times 2080 grid. The makima (modified Akima piecewise cubic Hermite interpolation) spline fitting procedure was used to construct curves over the discrete data points. A moving average smoothing function was fitted to the data to remove any fitting artifacts and outliers from the data set with a smoothing factor between 0.00–0.25. The jet color scheme was selected in most heat maps to indicate low selectivity or TOF (dark blue) and high selectivity or TOF (dark red). Raw data for all heat maps are provided in the ESI.†

Conflicts of interest

Authors M. Alexander Ardagh and Paul J. Dauenhauer have a patent pending on the ideas presented in this manuscript. All other authors have no conflicts to declare.

Note added after first publication

This version replaces the manuscript published on 11th March 2020. Due to errors inadvertently added during the proofing, equations 2 and 3 contained errors that have now been corrected. The RSC apologises for any confusion.

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