Journal of Materials Chemistry C

Materials for optical, magnetic and electronic devices

Accepted Manuscript

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Temperature-dependent Stress-Strain Behavior of Amorphous and Crystalline P3HT

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Abstract

The scalable commercialization of organic electronics wherein π -conjugated polymers serve as the semiconductors hinges on precise control of the material electronic, redox, optical, and mechanical properties, which are each highly influenced by local and long-range morphology. Here, we undertake atomistic molecular dynamics (MD) simulations at three temperatures (150 K, 300 K, and 400 K) to assess the morphological and mechanical response of bulk poly(3-hexylthiophene) (P3HT), a representative homopolymer of interest as an organic semiconductor (OS). As P3HT is a semicrystalline polymer, we characterize mechanical properties for both amorphous and crystalline P3HT models to derive insights into structure-property relationships, including Young's modulus (E) and Poisson's ratio (v). Mechanical behaviors that arise as a consequence of kinetically induced molecular reorientations/transitions are described, including the determination of entanglement properties over the course of polymer deformation. Specifically, we analyze stress-strain curves to (1) elucidate how, and the extent to which, the rather tangled amorphous domains retain their ductility over temperature ranges that span known phase transitions, and (2) uncover the strength and mechanism of inter-chain mechanical coupling across lamellar stackings—a director of charge-carrier transport—as a function of temperature. Generally, this work provides a molecular-level understanding of the thermomechanical behavior of π -conjugated polymers at regions where order or disorder dominates local packing, and prompts a more comprehensive description of the mechanical properties of these systems while recognizing their often inherently semicrystalline nature.

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Introduction

Mechanical deformability offers an avenue to expand the range of applications of electronic devices. Applications such as in nonplanar surfaces acting as electroactive mediums and in portable, sustainable, and recyclable electronic devices with variable form factors necessitate a precise understanding of the deformation of the materials used in these technologies. Organic semiconductors (OS), and OS derived from π -conjugated polymers in particular, boast unique combinations of desirable features due to the ability to chemically fine-tune the electronic, redox, and optical response and deformability, the latter of which arises from the combination of rotatable moieties along the π -conjugated backbones, pendant side chains, and the ability of polymer chain segments to both slip and entangle. While OS are recognized as promising candidate materials in field-effect transistors, light-emitting diodes, energy transforming and storing devices, and biological or environmental sensors, translating these materials into viable commercial applications still requires a deeper understanding of their quantitative structure–property relationships. $^{3, 11-15}$

The molecular-scale structure of π -conjugated polymers is generally characterized by long chains of π -conjugated monomers and alkyl, ether, or aromatic (or some combination thereof)-based side chains. Such polymers can form an array of microstructures, ranging from (semi)crystalline to amorphous, with the semiconductor electronic, redox, and optical properties each being highly influenced by the semiconductor percent crystallinity. In general, locally planar (non-planar) structures are often linked with extended (localized) π wave functions and more ordered/crystalline (disordered/amorphous) morphologies. The chemistries of the polymer backbones and the side chains, in combination with the processing conditions used to develop the OS, influence the chain

The quest for a precise formulation of how microstructural anisotropy and order regulate the properties and function of polymer-based OS motivates an atomistic consideration of how these characteristics can be harnessed to control device performance in various operating conditions.¹⁸, ¹⁹ This understanding is especially critical given that the environmental conditions a device may experience from fabrication until the end of its lifetime are increasingly variable and, in some cases, can be detrimental to device performance.^{8,20} Materials characteristics can vary significantly between the amorphous and crystalline phases. Further, regions identified as the rigid (RAF) and mobile (MAF) amorphous fractions exist in many polymer-based semiconductors; these regions characterize the network of tie chains that extends through the amorphous regions, both looping back into the same crystallite repeatedly and connecting different crystallites.²¹⁻²⁴ This microstructural sophistication further frustrates the development of a complete understanding of the thermomechanical behavior of polymer-based OS.²⁵⁻²⁷

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Here, we use atomistic molecular dynamics (MD) simulations to model the temperature-dependent stress-strain behavior of the crystalline and amorphous regions of regioregular poly(3hexylthiophene) (P3HT), a prototypical, paracrystalline semiconducting π -conjugated polymer. While coexistence of the amorphous (MAF and RAF) and crystalline regions are generally to be expected in P3HT, we opt to simplify the problem through a baseline characterization of fully amorphous (aP3HT) and fully crystalline (cP3HT) systems in isolation, an approach that finds previous application in the literature. ²⁸ Through simulations at temperatures both above and below the glass transition temperature (T_o) , we explore mechanical and structural properties relevant to performance during the processing, packaging, and operational lifetimes of P3HT. By considering three crystalline slabs of varying size, we evaluate the dependencies of performance-relevant properties on the degree of polymerization through models approaching experimental length scales. Finally, we analyze the chain entanglement characteristics of the amorphous domains as functions of strain and temperature to deduce the influence of these topological constraints on the observed mechanical response (such as a strain hardening-like increase in post-yield stress). By connecting the crystalline and amorphous polymer microstructural morphologies to their mechanical response, we offer insights that pave the way to a more complete understanding of the thermomechanical properties of π -conjugated polymer morphology.

Computational Methods

All MD simulations were performed using the GROMACS software suite version 2019.5.^{29, 30} The Visual Molecular Dynamics (VMD) program was used to visualize the resulting trajectories.³¹ All bonded and non-bonded interactions, including modifications to inter-monomer dihedral torsion potentials, were based on the parameterization of P3HT as developed by Huang et al.³² using the OPLS-AA force field.³³ Structure and topology files containing the atomic coordinates, bond connectivity, etc., were prepared for P3HT chains using an in-house script that supports the automated construction of polymers by using generalized repeat-unit templates.

A template for regioregular P3HT – the molecular structure of which is shown in Figure 1(a) – was created based on the parameterization by Huang et al.³² Partial atomic charges were taken as those reported by Huang et al. for neutral chain-end and chain-interior monomers.³² Force field parameterization data is available online as part of the Electronic Supplementary Information (ESI†) and in Figure S1†. Fully outstretched P3HT chains of three different molecular weights –

6.25 kDa (38 monomers), 12.5 kDa (75 monomers), and 25 kDa (150 monomers) – were prepared using this template. The larger molecular weight was chosen to correspond to chain lengths used in experiments and other computational works, while the smaller molecular weights were chosen to yield insights into the relationship between chain length and mechanical properties in the crystalline systems.³⁴⁻³⁷ Based on prior literature, ^{36, 37} molecular weights of 6.25 kDa and 12.5 kDa are not expected to result in significant chain entanglement; thus, to conserve computational resources, all amorphous systems studied and reported used a molecular weight of 25 kDa.

To prepare the amorphous systems, 180 fully outstretched P3HT chains (about 60 nm per chain and approximately 6.8×10⁵ atoms total) were inserted into an empty cubic simulation box of dimensions 75×75×75 nm³ at random positions with random orientations while ensuring no overlap of atomic van der Waal radii. Periodic boundary conditions (PBC) were applied along each axis. After an energy minimization step performed via steepest descent with a force convergence threshold of 10 kJ mol⁻¹, atomic velocities were randomly generated according to a Maxwell distribution at 300 K. The system was then relaxed via a nineteen-step procedure (Table S1†) comprising rapid cycles of compression, annealing, and low-temperature relaxation. The kinetic perturbation procedure, originally developed by Hofmann et al.³⁸ and by Karayiannis et al.,39 then refined by Larsen et. al.,40 was adapted from our previous simulations of conjugated polymers. 41, 42 The approach resulted in a condensed, amorphous P3HT system with an average density of 1.04 g cm⁻³ at 300 K and 1 bar, a value consistent with experiment and previous computational works.^{28, 37}

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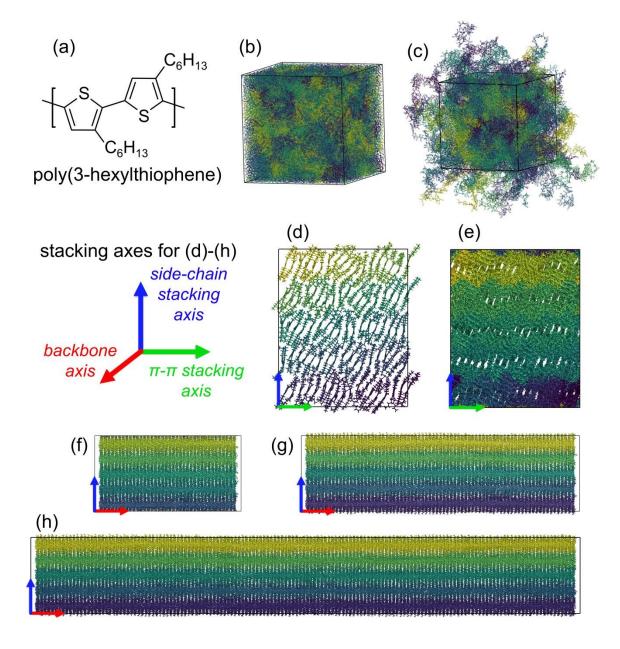


Figure 1. (a) Chemical structure of poly(3-hexylthiophene) (P3HT). (b) Amorphous P3HT system equilibrated at 150 K. The system is cubic with side length 18.792 nm. Periodic boundary conditions (PBC) were applied to chains that cross the system boundaries. (c) The same amorphous P3HT system in (b), but with PBC removed and chains made whole. (d) End view of the 25 kDa/chain crystalline P3HT slab equilibrated at 150 K, with only the first 2-3 monomers visible to highlight the alkyl-stacking and π-stacking axes. (e) The same crystalline slab with all monomers visible. (f) Side view of the 6.25 kDa/chain slab (backbone axis and alkyl-stacking axis) with PBC applied. Slab dimensions: 15.920 nm (backbone axis) × 8.227 nm (alkyl-stacking axis) × 6.740 nm (π-stacking axis). (g) Side view of the 12.5 kDa/chain slab with no PBC. Slab dimensions: 30.252 nm × 8.220 nm × 6.734 nm. (h) Side view of the 25 kDa/chain slab with no PBC. Slab dimensions: 59.371 nm × 8.227 nm × 6.740 nm. Note that for (b)-(h), each chain is highlighted in a different color, but all chains have identical composition.

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All systems began with equilibration to achieve a stabilized system temperature and density. The amorphous system was equilibrated for 20 ns at 300 K and 1 bar. The crystalline system was first equilibrated for 5 ns at 230 K with the system volume fixed, then equilibrated further for 15 ns at the same temperature with a constant pressure of 1 bar. All MD simulations then used the GROMACS leapfrog-based MD integrator setting with a time step of 2 fs. The linear constraint solver (LINCS) was used to constrain hydrogen bonds to their equilibrium lengths. Long-range interactions were modeled using particle mesh Ewald summation, while the short-range van der Waals and Coulombic electrostatic interactions were described using a Lennard-Jones potential with a cut-off range of 1.4 nm. NVT equilibration steps were performed using the velocity-rescale thermostat⁴⁶ with $\tau_T = 0.1$ ps. In addition to this thermostat, NPT equilibration steps were performed using a Berendsen barostat⁴⁷ with $\tau_P = 1.0$ ps. By contrast, all production steps were performed within an NPT ensemble using a Nosé–Hoover thermostat^{48, 49} with $\tau_T = 0.4$ ps and a Parrinello–Rahman barostat⁵⁰ with $\tau_P = 4.0$ ps. Unless noted otherwise, all subsequent NVT and NPT steps were performed using these conditions, with all NPT steps using a pressure of 1 bar.

Following equilibration at their respective initial temperatures, the amorphous and crystalline systems were cooled to 150 K, going well below the reported P3HT glass transition temperature.⁵¹-55 At this point, preparation of the 12.5 kDa and 6.25 kDa variations of the crystalline system involved truncating chains in the equilibrated 25 kDa slab at 150 K, replacing terminal carbon atoms with hydrogen atoms. The in-house script was used to prepare structure and topology files for the 12.5 kDa and 6.25 kDa chains. Figure S2† displays snapshots of the crystalline and amorphous systems at various stages of construction. Figures 1(b) and 1(c) show a snapshot of the equilibrated amorphous system at 150 K with and without PBC, respectively. Figure 1(d) and 1(e) show end views (alkyl-stacking and π -stacking axes) of the equilibrated 25 kDa/chain crystalline slab at 150 K. Figure 1(f), 1(g), and 1(h) show side views (alkyl-stacking and backbone axes) of the 6.25 kDa/chain, 12.5 kDa/chain, and 25 kDa/chain slabs, respectively. While we recognize that the chain lengths and numbers of chains used in the crystalline simulations may be larger than expected in a semicrystalline polymer, we used these model sizes to ensure that the systems were large enough to provide enough physical contacts in these relatively small (compared to experiment) volumes to describe the thermal and mechanical properties.

To study phase transitions arising during heating, the amorphous system was then further cooled to 50 K at a constant rate of 10 K ns⁻¹. After the cooling step, the amorphous system underwent 5 ns of NVT equilibration, followed by 15 ns of NPT production MD to ensure equilibration. The system was then heated to 530 K at a rate of 10 K ns⁻¹. We performed the pre-annealing steps – i.e., cooling and subsequent equilibration – to widen the range of temperatures across which to track thermal transitions during the annealing step. Although the crystalline system also underwent a heating procedure (see Figure S42†), the system remained ordered well beyond the melting

temperature due to a superheating effect that has been widely reported in literature for crystalline slabs, related to the lack of high-free-energy internal surfaces at which melting can initiate.^{43, 44}

To characterize the temperature-dependent stress–strain behavior in the amorphous and crystalline systems, individual snapshots at 300 K and 400 K were extracted from the heating step for comparison with the corresponding system at 150 K. These higher temperature frames were chosen to probe the mechanical properties across a range of operating temperatures relevant to OS devices, with 150 K being well below (and 400 K well above) the experimentally reported glass transition temperature of regioregular P3HT ($T_g \approx 285\text{-}295 \text{ K}$). S1-53 All extracted frames underwent at least 70 ns of additional NVT and NPT equilibrations, with the first 2 ns being NVT, until their temperatures and densities were stabilized. The bulk density of each system, taken as the average from the final 5 ns of production MD performed following equilibration, is reported in Table 1.

Table 1. Bulk density (g cm⁻³) of the P3HT systems after temperature and pressure equilibration at the corresponding temperature, averaged across the final 5 ns of NPT production MD. Section 8 of the ESI† contains further clarification on the 6.25 kDa/chain original and adjusted slabs.

Temperature (K)	Amorphous P3HT	Crystalline P3HT				
	25 kDa/chain	25 kDa/chain	12.5 kDa/chain	6.25 kDa/chain		
150	1.12 ± 0.02	1.13 ± 0.00	1.11 ± 0.00	1.08 ± 0.00		
300	1.07 ± 0.00	1.05 ± 0.00	1.04 ± 0.00	1.01 ± 0.00		
400	1.03 ± 0.00	0.95 ± 0.00	0.93 ± 0.00	$0.92 \pm 0.00 \ (original) \ 1.05 \pm 0.00 \ (adjusted)$		

After convergence, the *deform* keyword in GROMACS was used to produce stress–strain simulations of each of the six groups of systems – i.e., the crystalline and amorphous systems at 150 K, 300 K, and 400 K each. Uniaxial deformation in GROMACS using the *deform* keyword

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requires semi-isotropic pressure coupling and elongates the system along the *z*-axis at a constant rate. For each system, two copies of the undeformed system were rotated to allow deformation along each of the other two axes as well (except for the crystalline system backbone axis). We note that, for all systems studied, only one simulation was performed for the respective thermal and stress-strain evaluations; the combination of relatively large system sizes and simulation times, plus experimental validation where possible, provide statistical confidence in results presented.

Each system was simulated using each of two deformation rates. The faster rate ($\dot{a}_{\rm fast} = da_z/dt = 5\times10^{-3}$ nm ps⁻¹) was used to model the stress–strain response up to 500% strain, whereas simulations using the slower rate ($\dot{a}_{\rm slow} = 5\times10^{-4}$ nm ps⁻¹) extended only to 200% strain. In this work, strain refers to the engineering strain ε , calculated for the uniaxial strain along the *z*-axis as

$$\varepsilon_{zz}(t) = \frac{a_z(t) - a_{z,0}}{a_{z,0}} \tag{1}$$

where $a_z(t)$ and $a_{z,0}$ are the instantaneous and initial box lengths along the z-direction, respectively. Both $\dot{a}_{\rm fast}$ and $\dot{a}_{\rm slow}$ fall within the range of simulated deformation rates used in previous literature; $\dot{a}_{\rm fast}$ is in the middle of the range used in other works, while $\dot{a}_{\rm slow}$ is on the slower end.^{37, 54, 56-59} The uniaxial tensile stress σ_{zz} is calculated from the output of the GROMACS gmx energy command as the engineering stress σ :

$$\sigma_{zz}(t) = -P_{zz}(t) \tag{2}$$

Here, P_{zz} is the negative pressure along the axis of deformation. The double subscript ii indicates uniaxial stresses, σ_{ii} , and strains, ε_{ii} (as opposed to shear stresses, τ_{ij} , and strains, γ_{ij}). As the raw virial pressure (and thus the stress) is noisy when plotted against the strain, we report the stress as a centered moving average (MA), with the period of the MA shrinking at the tail ends of the data

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set. In Figures S3-S5 of the ESI†, we discuss the effect of the MA and demonstrate that it preserves the overall shape of the stress–strain curve.

The estimated values of Young's modulus (E) and Poisson's ratio (v) were computed from the linear elastic region of the stress-strain curves (up to approximately 2% strain), wherein σ_{zz} is linear in ε_{zz} . Young's modulus was calculated as the slope of a linear regression of σ_{zz} on ε_{zz} within the elastic region. Similarly, Poisson's ratio was determined from the negative slope of a linear regression of ε_{xx} on ε_{zz} (or, equivalently, of ε_{yy} on ε_{zz}) within the elastic region. We determined v only for the amorphous systems, as for the highly anisotropic crystalline systems the theoretical limit of 0.5 is not applicable. To examine the effect of the upper bound of the fitting window, the approximate value of $d\sigma/d\varepsilon$ was also determined as a function of strain via the finite difference method across a window of $\Delta \varepsilon = (\varepsilon + 0.5w) - (\varepsilon - 0.5w)$ in the elastic region. Plots of $d\sigma/d\varepsilon$ as a function of ε for different values of w are shown for the amorphous systems in Figures S6-S14 and for the crystalline systems in Figures S15-S32, available in the ESI†.

Finally, to quantify the entanglement properties in the amorphous systems, we applied the Z1+ package developed by Kröger and co-workers. 60-62 At each of the three temperatures for which we performed stress–strain simulations (150 K, 300 K, and 400 K), we took snapshots from the system trajectory every 1% strain; to examine the isotropy of the entanglement characteristics, we repeated this for each of the three uniaxial deformation axes. This resulted in a total of 1800 snapshots across all deformation axes and temperatures.

For each snapshot, we applied a coarse-graining procedure to the polymer chains to simplify the atomic connectivity so that the primitive paths could be determined. A full entanglement analysis was repeated for each of two coarse-graining approaches illustrated in ESI Figure S33†. Results in the main text correspond to the first coarse-graining method, which reduces each thiophene unit to a single bead located at the average (x, y, z) coordinate of the five atoms in the thiophene ring. The second method calculates the position of the bead as the closest point between the vectors defined by the bonds connecting the thiophene unit to the two neighboring units; results for this method, including the primitive path lengths, are available in Figure S34†.

We also analyzed the effect of system size on the entanglement characteristics by preparing "doubled" and "tripled" slabs. To produce these doubled and tripled slabs for each snapshot, we used the dimensions (ma_x, ma_y, ma_z) of the original "single" box (with m = 1) and produced two other boxes using m = 2 and m = 3. For each of these models, a total of $c = m^3$ copies of the original system are placed at each of the translation vectors t_c in the set $\{t_c\} = [n_x a_x, n_y a_y, n_z a_z]$, where $n_i = \{0, 1, ..., m-1\}$. Visual representations of these three slab sizes are shown in Figure S35†. Results in the main text correspond to the tripled slabs to minimize the effects of system size, but a comparison of the entanglement characteristics for different system sizes are available in the ESI as Figures S36-S40†.

Results and Discussion

Thermomechanical Behavior of Amorphous P3HT

We begin our discussion of the amorphous systems with the heating step from 50 K to 530 K, performed to determine the temperatures at which thermal transitions in the system take place. By plotting the system density as a function of temperature, as shown in Figure 2, we observe two transitions, one centered at \approx 220-230 K and the other centered at \approx 370-380 K. These transitions

can be identified by changes in the slope ($d\rho/dT$). To examine the range of temperatures over which the thermal transitions take place, the approximate value of $d\rho/dT$ was determined for each temperature via the finite difference method across a window of $\Delta T = (T + 0.5w) - (T - 0.5w) = w$. Plots of $d\rho/dT$ as a function of T for different values of w are shown in Figure S41†. The discrepancy between the backbone T_g of 285-295 K reported in prior literature⁵¹⁻⁵⁵ and the thermal transitions reported herein may be a result of the continuous heating rate. Although 10 K ns⁻¹ is a relatively slow heating rate for simulation, it is nonetheless much faster than heating rates in experimental systems. Further, the simulated heating rate is expected to affect the value of T_g ; for instance, faster cooling rates are known to lead to artificially elevated transition temperatures.⁴¹ Nonetheless, we observe that the amorphous system has clearly undergone one thermal transition between 150 K and 300 K and another between 300 K and 400 K. It is thus of interest to examine how the stress–strain curves, Young's moduli, Poisson's ratios, and entanglement characteristics vary in these three temperature ranges.

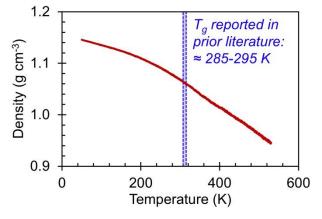


Figure 2. (red line) Amorphous P3HT system density as a function of temperature during continuous heating from 50 K to 530 K at a rate of 10 K ns⁻¹. (blue shaded region) A range of T_g values previously reported in literature for P3HT.⁵¹⁻⁵⁵

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Stress–strain curves showing the uniaxial tensile response of each axis of the amorphous system at 150 K, 300 K, and 400 K are shown in Figure 3. Young's modulus and Poisson's ratio were determined from the elastic region of each system, which is emphasized in Figure 3(b); values of these properties, which agree well with prior atomistic modeling at 300 K,³⁷ albeit at different molecular weights, are reported in Table 2. As expected, Young's modulus is significantly higher at 150 K compared to both other temperatures, with a pronounced upper yield point. This upper yield point disappears at 300 K and 400 K, likely corresponding to the thermal transition observed at 220-230 K. However, the thermal transition occurring at 370-380 K does not appear to qualitatively affect the stress–strain curves – the only noteworthy difference between the two temperatures is the lower overall stress at 400 K.

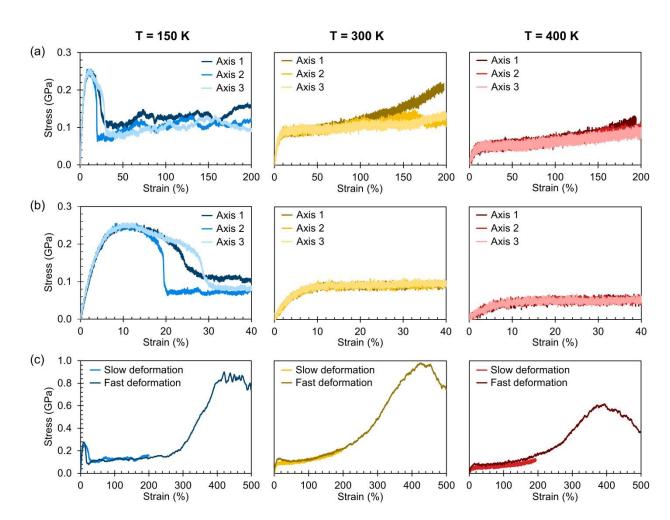


Figure 3. Simulated stress–strain curves for the amorphous systems; a centered moving average of width 20 ps was applied to the stress values. (a) Each axis was deformed up to 200% strain at a rate of 5×10^{-4} nm ps⁻¹ and at temperatures of 150 K, 300 K, and 400 K. (b) Closer view of the curves shown in (a) emphasizing the elastic and post-yield regimes. (c) As shown for Axis 1 specifically, each system was also independently deformed up to 500% strain at a faster rate of 5×10^{-3} nm ps⁻¹.

Table 2. Young's modulus (E) and Poisson's ratio (ν) computed via least-squares regression from 0% to 2% strain for the amorphous P3HT systems (25 kDa/chain).

Temperature (K)	Axis 1		Axis 2		Axis 3	
	E (GPa)	v	E (GPa)	v	E (GPa)	v
150	5.22	0.33	5.32	0.32	5.21	0.32
300	1.80	0.38	1.76	0.38	1.62	0.39
400	0.80	0.39	0.81	0.41	0.86	0.40

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At all three temperatures, the mechanical response (including Young's modulus and Poisson's ratio) remains essentially isotropic up to about 10% strain; the stress becomes anisotropic at this point at 150 K, whereas it remains isotropic until about 50% at 300 K and about 100% at 400 K. The greater isotropy in the higher-temperature systems is likely due to the chains being more mobile at the elevated temperatures; at 150 K, we hypothesize that chains face more difficulty in coming free of entanglements due to the lower thermal energy. The lack of mobility at 150 K can also explain the ruggedness of the stress–strain curves at 150 K compared to those at higher temperatures. Whereas pulling the chains taut between entanglements requires relatively little stress, once the chains are taut, the entanglements become significant obstacles to further deformation until the chains are pulled free, which requires higher stress. At higher temperatures, however, pulling chains free of entanglements becomes easier, leading to a more consistent stress response.

The effect of deformation rate is illustrated in Figure 3(c) for Axis 1. As the fast deformation rate is $10 \times$ faster than the slow rate, each system has less time to respond to the increasing box size. Because the chains cannot respond quickly enough to the deformation, the stress response in the elastic region is higher than in the systems deformed at the slower rate. The fast deformation rate also results in the appearance of upper yield points at 300 K and 400 K, features that are not present in the more slowly deformed systems.

It is noteworthy that, for the slowly deformed systems, Axis 1 appears to be tougher than Axes 2 and 3; beyond the onset of anisotropy at each temperature, the stress–strain curve for Axis 1 is higher than those for the other two axes. The anisotropy of the amorphous systems at higher strain poses a question: Is there a texturing effect present in the amorphous systems prior to deformation that results in the different stress responses along each axis? To examine this question, a series of

plots representing the system texture were prepared by first determining two orientation vectors (OVs) for each thiophene unit in the system. The first vector, \overline{OV}_1 , illustrated at the bottom left of Figure 4, is calculated from the positions of the two carbon atoms neighboring the sulfur atom; this OV roughly corresponds to the tangent vector of the backbone. \overline{OV}_2 , illustrated at the bottom right of Figure 4, is the normal vector of each thiophene unit, calculated as the cross product of \overline{OV}_1 and a proxy vector (defined as starting at the carbon in \overline{OV}_1 and ending at its neighboring carbon). All OVs are normalized and plotted with their tails at the origin. The resulting texture plots are shown for Axis 1 at all three temperatures in Figure 4. Plots showing all three axes at the same temperature are presented in the ESI as Figures S43-S45†. \overline{OV}_1 and \overline{OV}_2 are each represented by a different color for each chain (with all thiophene units in a given chain using the same color).

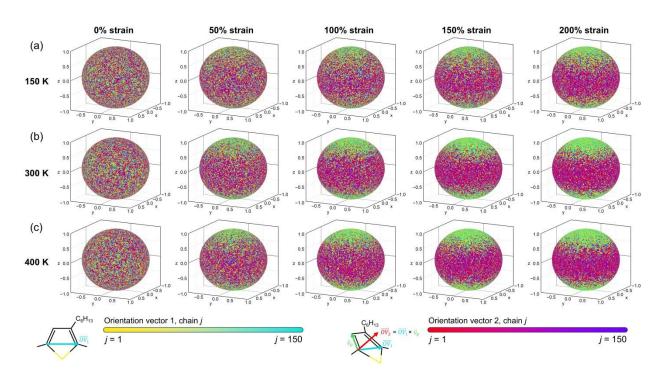


Figure 4. Texture maps showing the alignment of the backbone direction (yellow to cyan circles) and thiophene plane normal directions (red to purple circles) at each temperature for deformation axis 1.

The first feature evident from the texture plots in Figure 4 and in Figures S43-S45 is that the amorphous systems are untextured; as evidenced by the plots at 0% strain, the distributions of \overline{OV}_1 and \overline{OV}_2 are essentially random. With increasing strain, \overline{OV}_1 becomes more highly oriented along the axis of deformation (z), indicating that the backbone is more elongated and linear. By contrast, the values of \overline{OV}_2 become more focused in a ring wherein the z-component is closer to 0. However, the radial symmetry of the \overline{OV}_2 distribution suggests that the thiophene units are not locally planar, instead remaining roughly randomly oriented. We also note that the texture increases not only as a function of strain, but also as a function of temperature – for example, the systems with 50% strain at 400 K appear to be similarly textured as the systems with 100-150% strain at 150 K.

Finally, the entanglement properties of each system are shown in Figure 5. To aid in making comparisons, the stress–strain data is presented again in Figure 5(a), this time grouped by deformation axis. Figure 5(b) shows the average number of entanglements per chain $\langle Z \rangle$. As stated previously, these plots correspond to the "tripled" slabs to reduce the intensity of finite-size effects; as shown in Figures S36-S40 in the ESI†, the differences in the entanglement properties determined for the three slab sizes are relatively minimal. The variation of $\langle Z \rangle$ as the system is strained is not straightforward to parse. On the one hand, for deformation along Axes 1 and 3 at 300 K and at 400 K, the values of $\langle Z \rangle$ and stress appear to increase together beyond approximately 100% strain, a feature that may suggest that an increase in chain entanglement plays a role in producing the strain hardening effect observed at higher strain. However, this trend is not consistent with deformation along Axis 2 and the relationship between stress and $\langle Z \rangle$ at 150 K is unclear. We suggest that increasing strain modulates the rates of entanglement creation and destruction, as well as the effective entanglement lifetime, all three of which in turn influence the stress response of the bulk material.

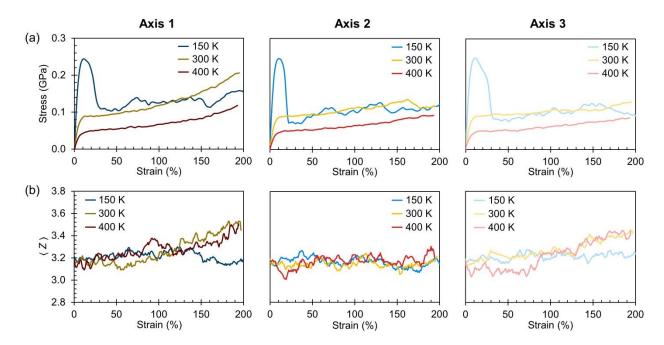


Figure 5. (a) Stress-strain curves shown in Figure 3(a) grouped instead by deformation axis and with a moving average of width 1.5 ns applied. (b) Average number of entanglements per chain $\langle Z \rangle$ as a function of strain for each of the stress-strain curves in (a), also with a moving average of 1.5 ns applied.

Thermomechanical Behavior of Crystalline P3HT

While there are previous efforts to understand the anisotropic charge-carrier transport behavior along the π-stacking and alkyl-stacking axes in organic semiconductors, ^{17, 18, 63-66} the thermal dependence of mechanical properties remain less clear. In Figure 6, we report axis-dependent stress–strain curves at 150 K, 300 K, and 400 K for crystalline P3HT slabs composed of the three molecular weights: 25 kDa (the same chain size as the amorphous systems), 12.5 kDa, and 6.25 kDa. To highlight the effect of chain molecular weight (MW), a zoomed-in view of the elastic regions of the same stress–strain curves is presented in Figure 7 grouped by temperature.

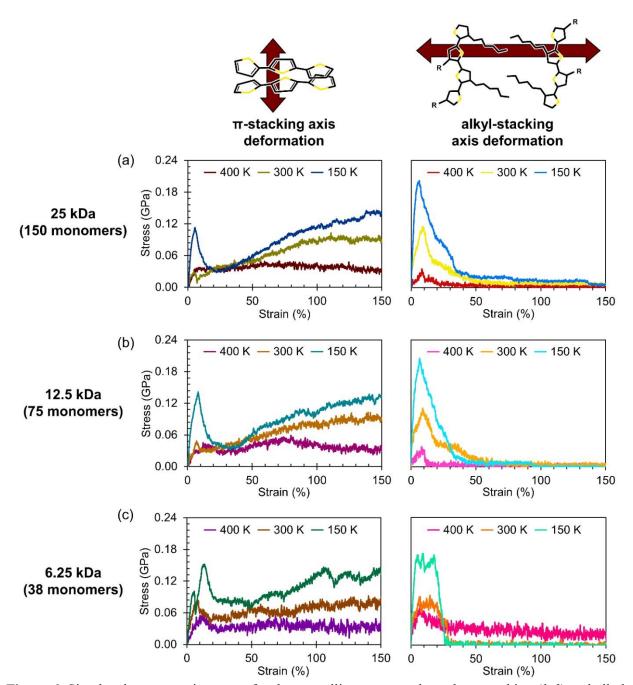


Figure 6. Simulated stress–strain curves for the crystalline systems along the π -stacking (*left*) and alkyl-stacking (*right*) axes; a centered moving average of width 70 ps was applied to the stress values. Chain molecular weights of (a) 25 kDa, (b) 12.5 kDa, and (c) 6.25 kDa are explored through independent stress–strain simulations.

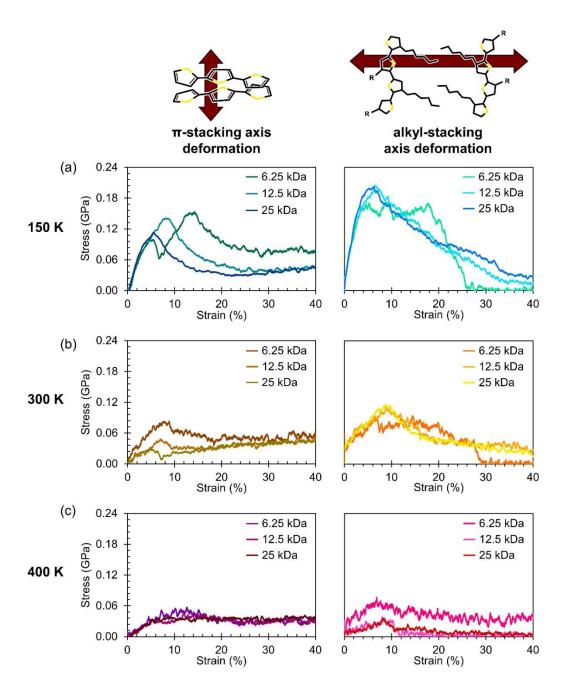


Figure 7. Zoomed view of the elastic region of the simulated stress–strain curves shown in Figure 6. To highlight the effect of chain MW on the Young's modulus, the three MW are compared at temperatures of (a) 150 K, (b) 300 K, and (c) 400 K.

Broadly, it is evident that systems deformed along the π -stacking axis resist fracture to a greater extent than those deformed along the alkyl-stacking axis, irrespective of chain MW. In the π -

stacking deformation series, a sharp elastic region is followed by a yield peak, a lower yield plateau, and then stress values gradually increasing toward an ultimate tensile strength. However, in the case of the 6.25 kDa system at 150 K, there are two characteristic yield peaks, beyond which the system more closely mirrors the other π -stacking deformation systems. At 300 K, the slab yields at a lower stress, and the yield peak itself is significantly less pronounced, while at 400 K, the yield peak has nearly disappeared. The Young's modulus appears relatively insensitive to chain size in these idealized slabs: For most subplots in Figure 7, both in the π -stacking and the alkyl-stacking series, the slope of the elastic region is not significantly affected by the chain MW. The values of the Young's moduli for both chain-stacking series are shown in Table 3.

Table 3. Young's modulus (E) for the crystalline P3HT systems. E is calculated by fitting slope computed at 2% strain. v is not calculated, as the highly anisotropic crystalline slabs lead to a wide deviation from the theoretical limit of 0.5.

	E (GPa), π-stacking axis			E (GPa), alkyl-stacking axis			
Temperatur e (K)	25 kDa/chain	12.5 kDa/chain	6.25 kDa/chain	25 kDa/chain	12.5 kDa/chain	6.25 kDa/chain	
150	3.64	3.48	2.94	5.53	5.45	4.79	
300	1.62	1.38	1.19	1.03	1.25	1.01	
400	0.77	0.64	0.30 ^a (original) 0.90 ^a (adjusted)	0.16	-0.03 ^b	^a (original) 0.23 ^a (adjusted)	

^a After noticing the misalignment of the original slab, we proceeded to adjust the alignment, then repeated the deformation on the new slab orientation.

^b Due to noise within the elastic region, directly applying a least-squares model up to 2% strain to this system results in a negative slope. To better explore the effect of the fitting window on the estimated value of Young's modulus, we applied a finite-difference method with a moving window to the stress–strain data. Plots of $d\sigma/d\varepsilon$ are presented as Figures S6-S32 in the ESI† (see S32).

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Notably, the π -stack series resists fracture up to 150% strain regardless of temperature or chain MW. Upon examination of the morphology, we find that the strong cohesion between π -stacked P3HT fragments leads the morphology to buckle rather than fracture, resulting in a zigzag morphology with high ductility. Snapshots of the amorphous and crystalline systems at a range of values of strain are presented in the ESI† as Figures S46-S48 and Tables S3-S5. It is also interesting to note that the stress-strain curves for the π -stacked series of smaller chain MW are more rugged. We hypothesize that this phenomenon is due to the smaller chains diffusing more easily, while the strong interlayer cohesion helps to prevent delamination.

In the alkyl-stacking deformation series (the columns on the right in Figures 6 and 7), the elastic region is characterized by a steep slope, with the yield strength being high compared to deformation along the π -stacking axis. The slabs still show a pronounced yield peak at higher temperatures, unlike in the π -stacking series, but the yield stress itself greatly decreases. After yielding, the stress does not increase toward an ultimate tensile strength, but rather proceeds monotonically toward failure from the initial yielding regime. Deformation along the alkylstacking axis resulted in fracture within the strain window explored, with only one exception (MW = 6.25 kDa, T = 400 K. Overall, for the alkyl-stacking series, higher chain MW delays the onset of fracture, with fracture occurring within 150% strain at 150 K for the system with 25 kDa chains (Figure 6a), compared to 100% and 25% strain for the systems with chain MW of 12.5 kDa (Figure 6b) and 6.25 kDa (Figure 6c), respectively.

As noted, the system with 6.25 kDa chains at 400 K is an exception to the trends discussed above. During the equilibration process of this system, the slab became misaligned with the strain axes. To make comparisons between results for the π -stacking and alkyl-stacking axes more consistent, we realigned the equilibrated slab, correcting the misalignment but resulting in a parallelepiped Open Access Article. Published on 09 Diteli 2024. Downloaded on 09/10/2024 7:25:34 PM.

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slab shape. Further discussion of this system on its own is available in Section 8 of the ESI†, including comparisons between the stress–strain curves for both the original (equilibrated) slab and the reoriented slab.

Conclusions

In this work, we report the stress–strain curves and associated mechanical characteristics of fully amorphous and fully crystalline P3HT systems obtained via atomistic MD simulations at three temperatures (150 K, 300 K, and 400 K). As expected, the amorphous systems show high isotropy in mechanical characteristics: Independent stress–strain simulations along each of the three coordinate axes result in nearly identical elastic regions, with no significant differences among the three deformation axes until approximately 100% strain. The amorphous systems show high ductility, extending to at least 400% at all temperatures before reaching the ultimate tensile point. We hypothesize that this result is due to chain entanglement, although due to the relatively short chains (25 kDa/chain) compared to experimental MW, we did not observe concrete trends in the chain entanglement data as a function of strain.

In the crystalline slabs, which were designed to have no chain entanglement, the observed ductility is significantly lower, although the Young's moduli along the π -stacking and alkyl-stacking axes are still quite high. Stress–strain simulations, including systems with shorter chains (6.25 kDa/chain and 12.5 kDa/chain, compared to 25 kDa/chain) reveal that a slip-facilitated chain buckling mode along the π -stacking axis enables relatively high ductility in these systems (above 150% strain at all temperatures and for all chain MW). By contrast, deformation along the alkyl-

stacking axis results in a "chain-unzipping" failure within 150% strain for all systems, with one exception (discussed above and in ESI†).

On its own, this work offers insights into the deformation response and failure mode of P3HT in the fully amorphous and fully crystalline phases. More broadly, through this work, we establish a foothold for characterization of the RAF and MAF in P3HT. These regions in semiconducting polymers are influential to the optical, electronic, mechanical, and thermal properties, as well as the bulk morphology, and require further investigation to realize their full impact.

Author contributions

The manuscript was written through contributions of all authors. All authors have given approval to the final version of the manuscript. K.H.F., C.P.C., and C.R. conceived the research. K.H.F. and C.P.C. carried out the simulations and analyses. C.R. supervised the research, established funding for the research, and provided contributions to interpreting the results and drafting the manuscript.

Data availability statement

The data supporting this article are included as part of the ESI. Information pertaining to the force field parameters and structure file are provided as additional files.

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There are no conflicts to declare.

Acknowledgements

This work was supported in part by the Office of Naval Research (ONR) through award number N00014-22-1-2179 (for simulations and data analyses) and the National Science Foundation (NSF) under cooperative agreement number 1849213 (force field development). Supercomputing resources were provided by the Department of Defense (DoD) through the DoD High Performance Computing Modernization Program (HPCMP; Project No. ONRDC40433481) and by the University of Kentucky Information Technology Department and Center for Computational Sciences (CCS).

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Data availability statement

The data supporting this article are included as part of the ESI. Information pertaining to the force field parameters and structure file are provided as additional files.