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DiSCoVeR: a materials discovery screening tool for high performance, unique chemical compositions

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We present Descending from Stochastic Clustering Variance Regression (DiSCoVeR) (https://www.github.com/sparks-baird/mat_discover), a Python tool for identifying and assessing high-performing, chemically unique compositions relative to existing compounds using a combination of a chemical distance metric, density-aware dimensionality reduction, clustering, and a regression model. In this work, we create pairwise distance matrices between compounds *via* Element Mover's Distance (EIMD) and use these to create 2D density-aware embeddings for chemical compositions *via* Density-preserving Uniform Manifold Approximation and Projection (DensMAP). Because EIMD assigns distances between compounds that are more chemically intuitive than Euclidean-based distances, the compounds can then be clustered into chemically homogeneous clusters *via* Hierarchical Density-based Spatial Clustering of Applications with Noise (HDBSCAN*). In combination with performance predictions *via* Compositionally-Restricted Attention-Based Network (CrabNet), we introduce several new metrics for materials discovery and validate DiSCoVeR on Materials Project bulk moduli using compound-wise and cluster-wise validation methods. We visualize these *via* multi-objective Pareto front plots and assign a weighted score to each composition that encompasses the trade-off between performance and density-based chemical uniqueness. In addition to density-based metrics, we explore an additional uniqueness proxy related to property gradients in DensMAP space. As a validation study, we use DiSCoVeR to screen materials for both performance and uniqueness to extrapolate to new chemical spaces. Top-10 rankings are provided for the compound-wise density and property gradient uniqueness proxies. Top-ranked compounds can be further curated *via* literature searches, physics-based simulations, and/or experimental synthesis. Finally, we compare DiSCoVeR against the naive baseline of random search for several parameter combinations in an adaptive design scheme. To our knowledge, this is the first time automated screening has been performed with explicit emphasis on discovering high-performing, novel materials.

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1. Introduction

Guided materials discovery examples have been increasingly prevalent in the literature. Some of these are experimental^{1–9} and computational^{10,11} adaptive design (AD) schemes using high-throughput experimental^{5,12–19} or computational (*e.g.* density functional theory (DFT)^{20–29} and finite element modeling^{30,31}) methods. Such materials discovery projects generally rely on the backbone of a regression model. A non-exhaustive list ordered from oldest to newest by journal publication year is given: GBM-Locfit,³² CGCNN,³³ MEGNet,³⁴ wren,³⁵ GATGNN,³⁶ iCGCNN,²⁷ Automatminer,³⁷ Roost,³⁸ DimeNet++,³⁹ Compositionally-Restricted Attention-Based Network

(CrabNet),⁴⁰ and MODNet,⁴¹ each with varying advantages and disadvantages.

Extraordinary predictions, or predictions which perform close to or better than top performers in the training data are rare.^{42–44} Many of the algorithms used for materials discovery in the literature are Euclidean-based Bayesian optimization schemes which seek a trade-off between high-performance and high-uncertainty regions,^{4,9,11,29,44–51} thereby favoring robust models and discovery of better candidates. These models have born many fruits in materials discovery including the discovery of extraordinary materials, though often for initially small datasets.

Kauwe *et al.*⁵² describe how it is even rarer to discover materials that are fundamentally (as opposed to incrementally) different from existing materials, *i.e.* discover new chemistries. For traditional Euclidean-based Bayesian optimization algorithms, while high uncertainty may be correlated with novelty, they do not explicitly favor discovery of novel compounds.

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Kim *et al.*⁵³ introduced two metrics for materials discovery: predicted fraction of improved candidates and cumulative maximum likelihood of improvement. These metrics are geared at identifying “discovery-rich” and “discovery-poor” design spaces, but again, in the context of high-performance rather than chemical distinctiveness.

In summary, there is a lack of materials discovery algorithms and metrics that explicitly favor the discovery of novel compounds.

In this work, we introduce the Descending from Stochastic Clustering Variance Regression (DiSCoVeR) algorithm, which unlike previous methods, screens candidates that have a high probability of success while enforcing – through the use of novel loss functions (*i.e.* metrics) – that the candidates exist beyond typical materials landscapes and have high performance. In other words, DiSCoVeR acts as a multi-objective screening where the promise of a compound depends on both having desirable target properties and existing in sparsely populated regions of the cluster to which it's assigned. This approach then favors discovery of novel, high-performing chemical families as long as embedded points which are close together or far apart exhibit chemical similarity or chemical distinctiveness, respectively.

2. Methods

The novelty of the DiSCoVeR algorithm consists largely of connecting recent, existing tools (Section 2.1) in conjunction with new proxies for chemical uniqueness (Section 2.2). DiSCoVeR depends on clusters exhibiting homogeneity with respect to chemical classes, which we enforce *via* a recently introduced distance metric: Element Mover's Distance (ELMD).⁵⁴ Dimensionality reduction algorithms such as Uniform Manifold Approximation and Projection (UMAP)⁵⁵ or *t*-distributed stochastic neighbor embeddings⁵⁶ can then be used to create low-dimensional embeddings suitable for clustering algorithms such as Hierarchical Density-based Spatial Clustering of Applications with Noise (HDBSCAN*)⁵⁷ or *k*-means clustering.⁵⁸

Finally, these can be fed into density estimator algorithms such as Density-preserving Uniform Manifold Approximation and Projection (DensMAP)⁵⁹ a UMAP variant or kernel density estimation^{60,61} where density is then used as a proxy for chemical uniqueness. In this work, we use DensMAP in place of UMAP to obtain density estimations directly within the dimensionality reduction step.

Additionally, we describe our data and validation methods (Section 2.3). By combining a materials suggestion algorithm and DiSCoVeR, it is possible to assess the likelihood of a new material existing relative to known materials.

The workflow for creating chemically homogeneous clusters is shown in Fig. 1, and a description of methods and each method's role is given in Table 1.

2.1. Chemically homogeneous clusters

How are chemically homogeneous clusters achieved? The key is in the dissimilarity metric used to compute distances between

compounds. Recently, ELMD⁵⁴ was developed based on earth mover's or Wasserstein distance; ELMD calculates distances between compounds in a way that more closely matches chemical intuition. For example, compounds with similar composition templates (*e.g.* XY₂ as in SiO₂, TiO₂) and compounds with similar elements are closer in ELMD space. In other words, clusters derived from this distance metric are more likely to exhibit in-cluster homogeneity with respect to material class which in turn allows in-cluster density estimation to be used as a proxy for novelty.

In this work, we use DensMAP for dimensionality reduction and HDBSCAN* for clustering similar to the work by Hargreaves *et al.*⁵⁴ † which successfully reported clusters of compounds that match chemical intuition. Removal of the DensMAP step result in a much higher proportion of points classified as “noise” in the clustering results‡ and precludes the use of density-based proxies unless other suitable density estimation algorithms are used.

2.2. Proxies for chemical uniqueness

It is relatively straightforward (albeit computationally costly) to obtain a DFT-calculated bulk modulus value, but this speaks little to chemical uniqueness. Experimental synthesis and characterization would likewise provide information about the chemical, structural, and performance properties, but not chemical uniqueness. Finally, what might be considered “chemically unique” today could be considered “run-of-the-mill” a decade later based on the progress in the field, and so the metric is also largely dependent on what's considered to be in the “training” dataset. Thus, we rely on a dissimilarity metric (ELMD) for which at least some scientists agree that it “intuitively” encodes chemical similarity, and we determine our training dataset based on what is available in a recent snapshot of the Materials Project database.

2.2.1. Density-preserving uniform manifold approximation and projection. A multivariate normal probability density function is assigned to each datapoint embedded in DensMAP space, where the probability is proportional to (eqn (1)):

$$e^{-\frac{1}{2}(X - \mu) \cdot \frac{1}{\Sigma}(X - \mu)} \quad (1)$$

where X , μ , Σ , and \cdot represent DensMAP embedding position at which to be evaluated, train or validation DensMAP embedding position, covariance matrix, and matrix multiplication, respectively.

The covariance matrix used in this work is given by eqn (2):

† In Hargreaves *et al.*,⁵⁴ density-based spatial clustering of applications with noise⁶² was used instead of HDBSCAN*. We use HDBSCAN* because it is generally regarded as a more sophisticated algorithm in that it requires less hyperparameter tuning (https://hdbscan.readthedocs.io/en/latest/how_to_use_epsilon.html) and can be less susceptible to noise.

‡ We clustered without DensMAP dimensionality reduction and found that the number of clusters increased from 24 to 44. As might be expected (<https://umap-learn.readthedocs.io/en/latest/clustering.html>), the percentage of unclassified points increases from 4.8% to 23.2%, highlighting the difficulty of using density-based clustering algorithms with sparse, high-dimensional data.



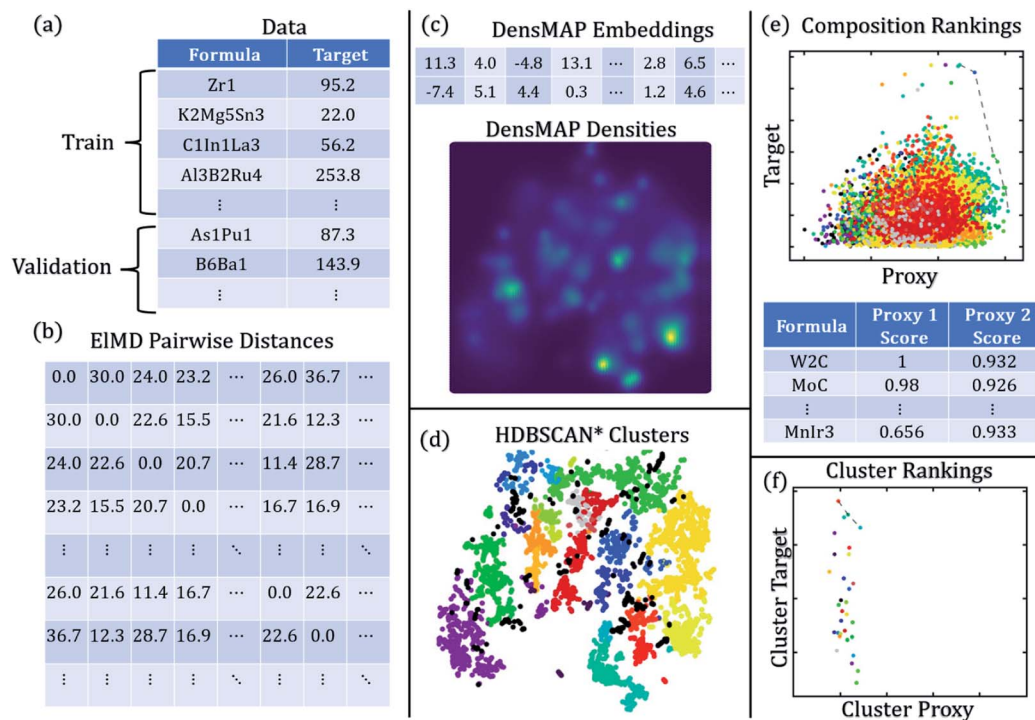


Fig. 1 DiSCoVeR workflow to create chemically homogeneous clusters. (a) Training and validation data are obtained in the form of chemical formulas and target properties (*i.e.* performance). (b) The training and validation chemical formulas are combined and used to compute EIMD pairwise distances. (c) EIMD pairwise distance matrices are used to compute DensMAP embeddings and DensMAP densities. (d) DensMAP embeddings are used to compute HDBSCAN* clusters. (e) Validation target property predictions are made *via* CrabNet and plotted against the uniqueness proxy (e.g. density proxy) in the form of a Pareto front plot. Discovery scores are assigned based on the (arbitrarily) weighted sum of scaled performance and uniqueness proxy. Higher scores are better. (f) HDBSCAN* clustering results can be used to obtain a cluster-wise performance (e.g. average target property) plotted against a cluster-wise uniqueness proxy (e.g. fraction of validation compounds vs. total compounds within a cluster).

Table 1 A description of methods used in this work and each method's role in DiSCoVeR

Method	What is it?	What is its role in DiSCoVeR?
CrabNet ⁴⁰	Composition-based property regression	Predict performance for proxy scores
EIMD ⁵⁴	Composition-based distance metric	Supply distance matrix to DensMAP
DensMAP ⁵⁹	Density-aware dimensionality reduction	Obtain densities for density proxy
HDBSCAN* ⁵⁷	Density-aware clustering	Create chemically homogeneous clusters
Peak proxy	High performance relative to nearby compounds	Proxy for “surprising” high performance
Density proxy	Sparsity relative to nearby compounds	Proxy for chemical novelty
Peak proxy score	Weighted sum of performance and peak proxy	Used to rank compounds
Density proxy score	Weighted sum of performance and density proxy	Used to rank compounds
Pareto front	Optimal performance/uniqueness trade-offs	Visually screen compounds (no weights ^a)

^a A Pareto front is more information-dense than a proxy score in that there are no predefined relative weights for performance *vs.* uniqueness proxy. Compounds that are closer to the Pareto front are better. The upper areas of the plot represent a higher weight towards performance while the right-most areas of the plot represent a higher weight towards uniqueness.

$$\begin{pmatrix} r & 0 \\ 0 & r \end{pmatrix} \quad (2)$$

where r represents extracted DensMAP radius.

We evaluate the sum of densities contributed by all training points evaluated at each of the validation locations (eqn (3)):

$$\sum_{i=1}^{n_{\text{train}}} e^{-\frac{1}{2} (X_{v,j} - \mu_{t,i}) \cdot \frac{1}{\Sigma_{t,i}} (X_{v,j} - \mu_{t,i})} \quad (3)$$

where $X_{v,j}$, $\mu_{t,i}$, $\Sigma_{t,i}$, \cdot , and n_{train} represent j -th validation DensMAP embedding position at which to be evaluated, i -th train DensMAP embedding position, i -th train covariance matrix, matrix multiplication, and total number of train points, respectively.



We refer to this as “train contribution to validation density” which acts as a proxy for chemical uniqueness relative to existing materials. Validation points with a low training contribution to the density exist in sparse regions of the embedded space, whereas validation points with a high training contribution to the density exist in densely populated regions of the embedded space.

It is significant that the proxy for a given validation point does not consider the density contribution from other validation points. To illustrate, consider training and validation datasets containing 1000 and 100 000 points, respectively. In this case, the training data are considered “existing” compounds (*i.e.* low novelty) with a known performance measurement (*e.g.* bulk modulus), and the validation points are considered “unknown” in the sense that the performance and novelty are unknown. If the density contributions from both training and validation points are considered, the proxy then depends on the size and distribution of the validation dataset which can be arbitrarily large, small, sparse, or dense (*e.g.* by the fineness of sampling possible compositions). In other words, for density to act as a proxy for novelty, it need consider (and only consider) how far it is from existing, low-novelty materials (*i.e.* training data).

By combining high-fidelity CrabNet predictions of bulk modulus with DensMAP validation densities, we extract a list of promising compounds at the Pareto front – the line or “front” at which the trade-off between performance and chemical uniqueness is optimal. CrabNet predictions have been shown to be comparable to state-of-the-art composition-based materials regression schemes, and since structure is often not known during a materials discovery search, CrabNet is a reasonable model choice. One partial workaround for the limitation of structure being unknown *a priori* has been explored in the Bayesian optimization with symmetry relaxation algorithm,⁶³ which may be of interest to incorporate into DiSCoVeR in future work.

Additionally, by performing leave-one-cluster-out cross-validation (LOCO-CV),⁶⁴ we accurately sort the list of validation clusters by their average performance with a scaled sorting error of approximately 1%. This proof-of-concept strongly suggests that DiSCoVeR will successfully identify the most promising compounds when supplied with a set of realistic chemical formulae that partly contains out-of-class formulae produced *via* a suggestion algorithm. To our knowledge, this is a novel approach that has never been used to encourage new materials discovery as opposed to incremental discoveries within known families.

2.2.2. *k*-Nearest neighbor average. An average of the bulk moduli for the *k*-nearest neighbors (*k*NNs) is computed as a poor man’s gradient as one type of proxy for chemical uniqueness. In this work, we use *k* = 10 to define the local neighborhood of influence, where *k*NNs are determined *via* the EIMD. Compounds which exhibit high predicted target bulk moduli relative to their *k*NNs, are considered unique in terms of property gradient, despite having similar chemical composition.

Because it is based on nearest neighbors rather than a defined radius, compounds which are in relatively sparse UMAP areas may have neighbors from a chemically distant cluster. In this case, if

all *k*NNs come from the same cluster, and this cluster exhibits similar properties, this can skew the measure to some extent. This artifact can be avoided by instead using a defined radius and a variable number of *k*NNs while ignoring compounds which have no *k*NNs within the specified radius.

2.2.3. Cluster properties. Cluster validation fraction is given by eqn (4):

$$f_k = \frac{n_{\text{val},k}}{n_{\text{val},k} + n_{\text{train},k}} \quad (4)$$

where f_k , $n_{\text{val},k}$, and $n_{\text{train},k}$ represent validation fraction of the *k*-th cluster, number of validation points in the *k*-th cluster, and number of training points in the *k*-th cluster, respectively. This indicates to what extent a given cluster consists of unknown compounds and can be useful in identifying clusters which are chemically distinct from existing compounds.

Cluster target mean is given by eqn (5):

$$E_{\text{avg},k} = \frac{1}{n_k} \sum_{i=1}^{n_k} E_{k,i} \quad (5)$$

where n_k , $E_{\text{avg},k}$, and $E_{k,i}$ represent number of points in the *k*-th cluster, mean bulk modulus of *k*-th cluster, and bulk modulus of the *i*-th point in the *k*-th cluster, respectively. This is useful for identifying clusters that exhibit overall high performance.

2.3. Data and validation

As a proof of concept, we use 10 583 unique chemical formulae and associated bulk moduli from Materials Project^{65,66} to test whether DiSCoVeR can find new classes of materials with high performance. In accordance with materials informatics best practices,⁶⁷ we also sanitize the data. Materials are filtered to exclude noble gases, Tc-containing compounds, and compounds with an energy above hull (`e_above_hull`) value greater than 500 meV. The highest bulk modulus is chosen when considering identical formulae. The motivation here is to ensure that the highest-performing materials are not overlooked; however, this can bias the model towards more difficult to synthesize and/or less stable allotropes (*e.g.* diamond *vs.* carbon). We use CrabNet⁴⁰ as the regression model for bulk modulus which depends only on composition to generate machine learning features; however, a different composition-based model mentioned in Section 1 could have been used instead.

We split the data into training and validation sets using a 0.8/0.2 train/val split as well as *via* LOCO-CV. We report two types of validation tests as summarized in Table 2. One of the validation methods uses a weighted root-mean-square error (RMSE) of various multi-objective Pareto front properties (target *vs.* chemical uniqueness proxy). The target is weighted against the proxy property (eqn (6)):

$$\frac{1}{w_E + w_p} \left(w_E \sqrt{\frac{1}{n_{\text{val}}} \sum_{i=1}^{n_{\text{val}}} (E_{\text{true},i} - E_{\text{pred},i})^2} + w_p \sqrt{\frac{1}{n_{\text{val}}} \sum_{i=1}^{n_{\text{val}}} (p_{\text{true},i} - p_{\text{pred},i})^2} \right) \quad (6)$$



Table 2 Validation methods, splits, notion of best fit, and property used to calculate notion of best fit

Method	Splits	Notion of best fit	Property
Train/val	0.8/0.2	Weighted RMSE	Target vs. density ^a
Train/val	0.8/0.2	Weighted RMSE	Target vs. <i>k</i> -neighbors average
Train/val	0.8/0.2	Weighted RMSE	Target vs. cluster validation fraction ^b
LOCO-CV	25 clusters	Weighted CDF distance	Cluster target mean

^a This density is the sum of all training densities evaluated at the validation location in the embedded DensMAP space. For the *k*-neighbors data, the average of the 10 nearest neighbor properties were used as a proxy. ^b Cluster validation fraction refers to the ratio of number of validation points within a cluster (as opposed to training points) to the total number of points in the cluster. DensMAP densities and cluster fractions are determined simultaneously for both validation and training sets during the DensMAP embedding resulting in computational throughput restrictions. In other words, “predicted” and “true” are identical due to implementation of DiSCoVeR at the time of writing. We plan to address this in future work.

where w_E , w_p , n_{val} , $E_{\text{true},i}$, $E_{\text{pred},i}$, $p_{\text{true},i}$ and $p_{\text{pred},i}$ represent bulk modulus weight, proxy weight, number of validation points, DFT-calculated bulk modulus of the *i*-th validation point, predicted bulk modulus of the *i*-th validation point, true proxy property of the *i*-th validation point, and predicted proxy property of the *i*-th validation point, respectively. We use $w_E = 1$ and $w_p = 1$.

In the current implementation, however, the chemical uniqueness proxy is determined *a priori* and simultaneously using the full dataset; thus, the error contribution from the chemical uniqueness proxy is zero. In other words, while $E_{\text{true},i}$ (DFT calculation) and $E_{\text{pred},i}$ (CrabNet prediction) vary, $p_{\text{true},i}$ and $p_{\text{pred},i}$ are identical. This approach is reasonable for small to medium-sized datasets (e.g. less than 100 000), but can quickly become intractable for large datasets due to memory constraints. We plan to modify DiSCoVeR to be compatible with large datasets (~1 000 000) by utilizing the EIMD metric directly within DensMAP rather than computing a pairwise distance matrix in advance.

Likewise, the score for each compound is a weighted sum of the robust-scaled target and proxy properties (eqn (7)):

$$\frac{1}{w_E + w_p} (w_E E_{\text{scaled},i} + w_p p_{\text{scaled},i}) \quad (7)$$

where w_E , w_p , $E_{\text{scaled},i}$ and $p_{\text{scaled},i}$ represent bulk modulus weight, proxy weight, robust-scaled predicted bulk modulus of the *i*-th validation point, and robust-scaled predicted uniqueness proxy of the *i*-th validation point, respectively. We use $w_E = 1$ and $w_p = 1$.

Without a “true” chemical uniqueness dataset, it’s up to the scientist to decide how important performance is relative to the uniqueness proxy. This could take the form of trial-and-error and evaluating the ranked results based on chemical intuition or interactively exploring the Pareto front plot to decide what areas “seem” most interesting (and finding a suitable weight that favors that area). In other words, it’s subjective. The results are also affected by the choice of “Scaler” (e.g. MinMaxScaler vs. RobustScaler) in how outliers are dealt with during scaling.

The other validation method is a LOCO-CV approach using cumulative density function (CDF) distance (i.e. earth mover’s

or Wasserstein distance) as a metric to determine the sorted similarity of a predicted cluster property vs. a true cluster property using `scipy.stats.wasserstein_distance()`⁶⁸ as follows¶:

```
import numpy as np
from scipy.stats import (
    wasserstein_distance,
)

# positions of weights
nclust = len(avg_true)
u = np.cumsum(np.linspace(0, 1, nclust))
u = np.flip(u)
v = u.copy()

# sort by same indices
sorter = np.flip(avg_true.argsort())
u_weights = avg_true[sorter]
v_weights = avg_pred[sorter]

error = wasserstein_distance(
    u,
    v,
    u_weights=u_weights,
    v_weights=v_weights,
)
```

where `avg_true` and `avg_pred` represent the 1D array of DFT-calculated average bulk moduli for each cluster and the 1D array of predicted average bulk moduli for each cluster, respectively, given by eqn (5). The use of a cumulative sum causes the positions of high cluster bulk modulus averages to be further spaced apart and therefore is more costly to “move earth” between the two distributions. In other words, inaccuracies associated with high-performing clusters are weighted more heavily than inaccuracies for low-performing clusters. This weighted error is then scaled by dividing by a “dummy” error, where `v_weights` is replaced by the average bulk modulus of the training data for each of the training splits (as opposed to the predictions on the validation data) during computation of the Wasserstein distance.

¶ The code was formatted in Black code style via an online formatter: <https://black.vercel.app/>.

§ See `sklearn.preprocessing.RobustScaler`.



3. Results and discussion

One of the primary difficulties in validating a materials discovery tool that considers chemical uniqueness is that while scientists might agree that discovering chemically unique (rather than incrementally different) materials is important, the interpretation of chemical uniqueness can vary significantly. The natural result is a lack of any curated data of “true” chemical uniqueness which makes it difficult to validate the tool in the conventional sense. Where possible, we present validation results; however, the results of DiSCoVeR in this work are largely focused on visualizations that can help to guide the discovery process and generation of rankings for each uniqueness proxy that are actionable, yet subjective.

First, we present characteristics of the DensMAP embedding and clustering scheme (Section 3.1) followed by compound-wise (Section 3.2) and cluster-wise (Section 3.3) Pareto front results. We also discuss results of the LOCO-CV scheme. Finally, we discuss how to use DiSCoVeR in a practical materials discovery scheme (Section 3.4).

3.1. Density-preserving uniform manifold approximation and projection characteristics

We present a DensMAP clustering of EIMD distances between all pairs of compounds (Fig. 2a) and plot the cluster count histogram (Fig. 2b). We then sum densities at equally spaced locations across DensMAP space (Fig. 3a) and color the points according to bulk modulus values (Fig. 3b).

We obtain a total of 25 clusters, plus a non-cluster of unclassified points comprising a small percentage of the data (~5%). The number of clusters gives an estimation of the

number of distinct chemical classes present in the dataset and is also affected by DensMAP and HDBSCAN* model parameters such as local density regularization strength (*dens_lambda*), minimum cluster size (*min_cluster_size*), and distance threshold for merging clusters (*cluster_selection_epsilon*). The unclassified points are typically isolated points in DensMAP space. In other words, unclassified points will likely exhibit high chemical contrast relative to other compositions *via* a low-density proxy. In other cases, unclassified points seem to appear “within” a cluster; however, this likely arises from the use of a density-based clustering algorithm rather than a manifold partitioning clustering algorithm. In other words, the density is low, but appears high when visualized with thousands of points in a 2D plot due to “low magnification”. We further discuss results related to the density proxy in Section 3.2.

A summary of the computational runtimes of the various methods is given in Table 3. Computation of the full pairwise distance matrix takes ~18 s, which is quite fast due to use of a CUDA/Numba⁶⁹ version of the Wasserstein distance that we developed for this work. An NVIDIA GeForce RTX 2060 is used for GPU computations, and an Intel® Core™ i7-10750H CPU @ 2.60 GHz is used for CPU computations. All non-GPU calculations are single-threaded.

3.2. Compound Pareto fronts

We present compound-wise Pareto fronts—a common technique used in multi-objective optimization—with predicted bulk modulus as the ordinate and one of two compound-wise proxies as the abscissa: train contribution to validation log

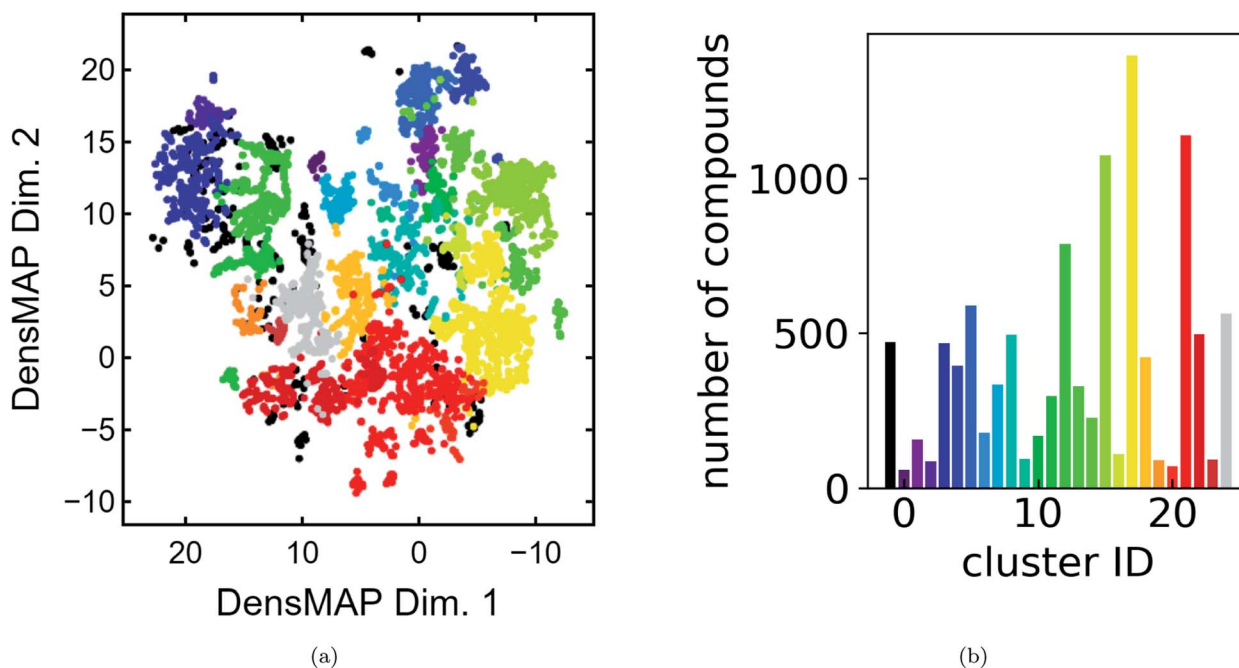


Fig. 2 Summary of cluster properties. (a) DensMAP embeddings based on EIMD distances between compounds colored by cluster. Equal aspect ratio scaling was used. 4.4% of compounds were unclassified. (b) Histogram of number of compounds vs. cluster ID, colored by cluster.



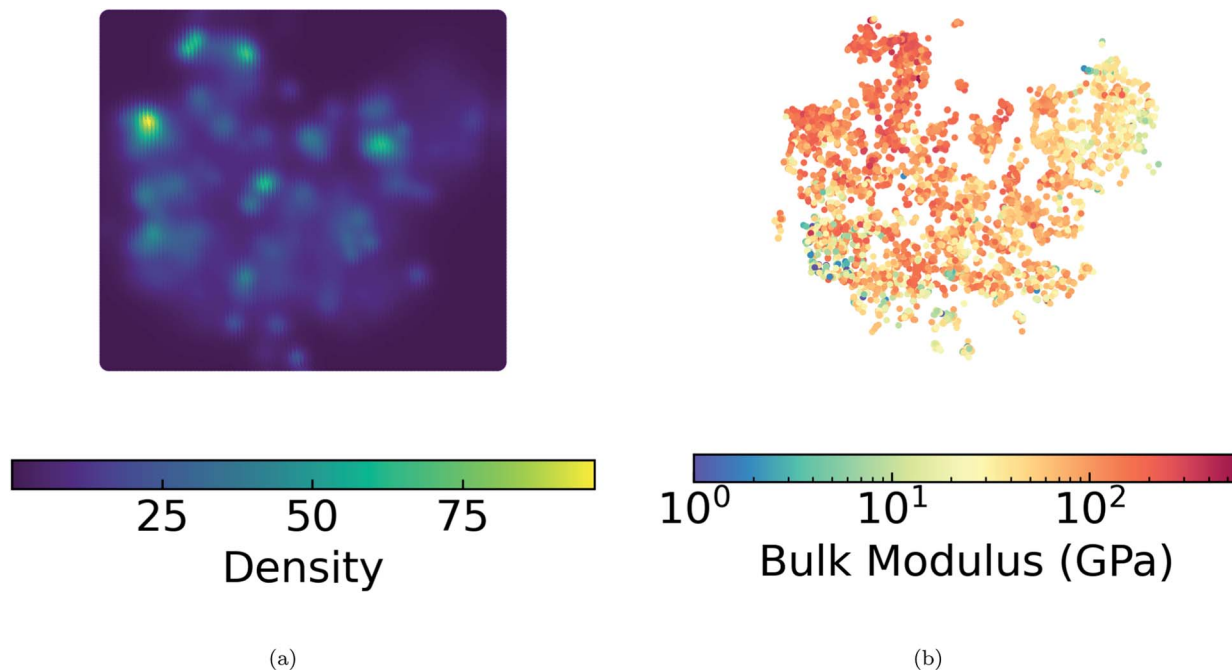


Fig. 3 Density and bulk modulus. (a) DensMAP densities of both training and validation points summed at gridded locations in DensMAP space. (b) 10 583 bulk moduli of training and validation points embedded in DensMAP space. Equal aspect ratio scaling was used for both (a) and (b).

Table 3 Summary of computational runtimes. Procedure, runtime (time), and whether or not a GPU was used (GPU) (Y = yes, N = no) for various steps in DiSCoVeR. Visualization DensMAP (Vis. DensMAP) and 100×100 gridded density summation (100×100 grid) are unnecessary steps to produce rankings; however, they are helpful for visualizations presented in this work. Non-GPU calculations are single-threaded. Reported runtimes should be considered approximate, as they are representative of only a single run

Procedure	Time (s)	GPU
CrabNet	91	Y
EIMD	18	Y
Cluster DensMAP	137	N
Vis. DensMAP	47	N
HDBSCAN*	0.14	N
100×100 grid	11	N
Density-proxy	2.7	N
Total	296	—

density (Fig. 4a) and k NN average (Fig. 4b) as described in Section 2.2.

On the other hand, k NN average acts as a poor man's gradient – in other words, used in conjunction with target predictions, it emphasizes compounds which have much higher predicted bulk modulus than that of its neighbors. In addition to the Pareto front, a parity line is also plotted. Compounds which are far above the parity line are high-performing relative to the surrounding neighborhood.

In terms of discovering materials which are chemically distinct from existing materials, train contribution to validation log density is the preferred proxy. We note that each of the proxies produce distinct plots. In the case of Fig. 4a, clusters

tend to be stratified horizontally, whereas in Fig. 4b, cluster shapes exhibit similar orientations. As expected (Section 3.1), unclassified points appear frequently at or near the first Pareto front owing to the fact that unclassified points are likely to have a lower density proxy and therefore higher score. By contrast, unclassified points appear infrequently at or near the latter Pareto front. Additionally, the unique list of clusters present at the Pareto front are different for each plot. In other words, these are two types of chemical uniqueness – the first emphasizing chemical “distance” from other compounds and the latter emphasizing performance superiority over chemically similar compounds. We believe that either may be successfully used in the domain of materials discovery.

Compounds were assigned scaled discovery scores as described in Section 2.3 for each of the chemical uniqueness proxies. The top-10 ranked candidates for the density and peak proxies are given in Tables 4 and 5, respectively. An outer merge of these two lists is given in Table 6.

It is interesting to note the lack of shared compounds between the top-10 lists of the two proxies. By contrast, in previous tests, we found that increasing the weight of E_{pred} ($w_E = 2$) led to significant overlap between the two lists, although with differing priority (*i.e.* the order of the rankings was different). Because the weights used can have a significant effect on the rankings, it may be worth probing several values for a given study to elucidate and assess behaviors. Indeed, as w_E grows larger, it tends towards a classic approach of searching for high-performance candidates only, yet for very small values of w_E , the performance of the top-ranked compounds may be too low to be of utility in real-world applications.



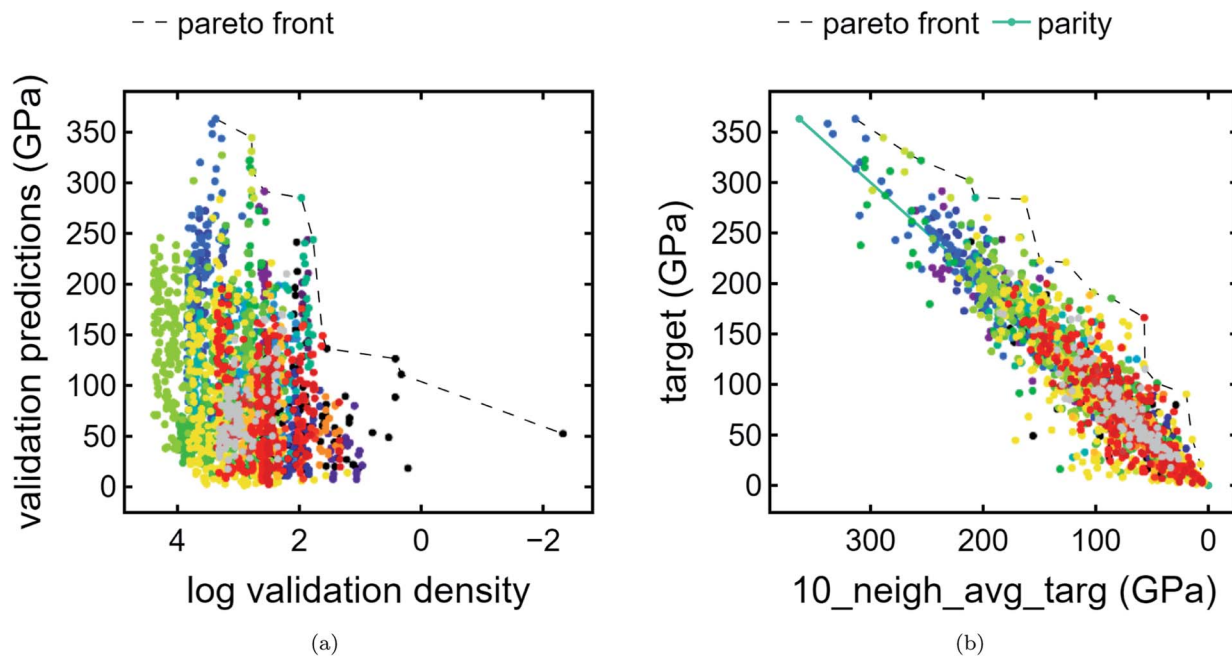


Fig. 4 Compound-wise Pareto plots. (a) Pareto plot of validation bulk modulus predictions (GPa) vs. train contribution to validation log density, colored by cluster. The Pareto front is plotted as a dashed line. (b) Pareto plot of training and validation bulk modulus predictions vs. k NN average bulk modulus (GPa) where $k = 10$. The Pareto front is given by a dashed line. A line of parity is given by a solid teal line to emphasize that compounds well above this line are considered unique.

Table 4 Top-10 ranked high-performing, density-proxy candidates. Formula, predicted bulk modulus (E_{pred}) (GPa), train contribution to validation log density proxy (ρ), and weighted, scaled discovery score based on train contribution to validation log density proxy (s_{ρ})

Formula	E_{pred}	ρ	s_{ρ}
ReB ₂	344.735	16.167	2.738
B ₂ W	331.170	16.183	2.604
UB ₂ Os ₃	285.076	7.146	2.546
MoN	322.441	16.586	2.500
TaN	321.934	16.827	2.485
BMo	315.166	16.625	2.427
Co(BW) ₂	311.329	15.935	2.419
B ₂ Mo	310.618	16.044	2.408
Re ₃ W	363.181	29.179	2.349
TaMoN	291.558	13.128	2.348

Table 5 Top-10 ranked high-performing, peak-proxy candidates. Formula, predicted bulk modulus (E_{pred}) (GPa), k NN average bulk modulus ($E_{\text{pred},k\text{NN}}$) (GPa), and weighted, scaled discovery score based on average k NN bulk modulus proxy ($s_{k\text{NN}}$)

Formula	E_{pred}	$E_{\text{pred},k\text{NN}}$	$s_{k\text{NN}}$
WO ₂	283.530	27.270	5.457
UO ₃	166.335	11.264	5.443
NiH	185.373	19.595	4.830
V ₂ O ₃	221.155	11.704	4.415
FeF ₂	158.245	33.249	4.328
Mg(MoO ₂) ₂	162.200	18.138	4.255
ZrSiO	191.061	12.789	4.238
PaB ₃	188.567	11.816	3.966
NiHO ₂	148.222	41.454	3.827
CrOF ₃	90.328	15.092	3.773

The weighted RMSE for the validation data is 26.5 GPa; however, as mentioned in Section 2.3, the proxy error contribution is zero in this work.

3.3. Cluster Pareto front and leave-one-cluster-out cross-validation

We also present a Pareto front for cluster-wise properties. For the ordinate, we use predicted cluster average bulk modulus Fig. 5a. For the abscissa, we use cluster validation fraction as a proxy for chemical distinctiveness of a cluster. In this example, the data is clustered tightly in the abscissa due to the train/val split being applied randomly without regard to cluster. In a more realistic scenario with much more validation data

than training data, where the validation encompasses previously unexplored chemical spaces, there is likely to be a larger spread. Indeed, such a use-case is the intention for this visualization tool. There is a much wider spread in the ordinate, indicating an interesting feature of the clustering results: compositions which are chemically similar to each other also tend to have, on average, similar bulk moduli. This is reasonable, especially since the regression model used is based purely on composition.

In future work, it may be interesting to replace average bulk modulus with best-in-cluster bulk modulus to explore a different type of high-ranking clusters.



Table 6 Outer merge of top-10 ranked high-performing, density-proxy and peak-proxy candidates. Formula, density discovery score (s_ρ), and peak discovery score (s_{kNN}). Negative scores are possible due to the use of robust-scaling

Formula	s_ρ	s_{kNN}
ReB ₂	2.738	1.795
B ₂ W	2.604	2.145
UB ₂ Os ₃	2.546	3.239
MoN	2.500	-0.117
TaN	2.485	2.471
BMo	2.427	-0.484
Co(BW) ₂	2.419	0.519
B ₂ Mo	2.408	1.162
Re ₃ W	2.349	1.373
TaMoN	2.348	1.991
V ₂ O ₃	1.717	4.415
WO ₂	1.649	5.457
PaB ₃	1.391	3.966
ZrSiO	1.373	4.238
UO ₃	1.196	5.443
NiH	1.018	4.830
Mg(MoO ₂) ₂	0.854	4.255
CrOF ₃	0.280	3.773
FeF ₂	0.153	4.328
NiHO ₂	-0.306	3.827

Finally, we perform LOCO-CV to evaluate the utility of the DiSCoVeR method in identifying clusters with high average cluster bulk modulus. A LOCO-CV parity plot is given in Fig. 5. We accurately sort the list of validation clusters by their average performance with a weighted scaled sorting error (Section 2.3)

of $\sim 1.4\%$. In other words, the out-of-cluster regression is very accurate. This suggests that CrabNet can successfully extrapolate performance predictions for new chemical spaces in accordance with the goal of DiSCoVeR. In future work, we plan to also test the out-of-cluster extrapolation performance for chemical uniqueness proxies (Section 2.3).

3.4. Practical materials discovery

While we believe the results generated by DiSCoVeR to be useful for screening for high-performing, novel materials, it is up to the scientist to manually curate and act on the results. A practical materials discovery approach with examples is summarized in Table 7.

Obtaining the training and validation data (steps 1 and 2) should be guided by materials informatics best practices.⁶⁷ Interactively exploring the Pareto front plots can aid in the choice of hyperparameters such as the performance and uniqueness weights during validation scoring (step 3). The literature search helps in determining which compounds have already been synthesized and how, and which compounds have already been characterized and how. This helps prevent unnecessary repetition of work. Physics-based simulations (step 5) can help to eliminate candidates with unrealistically high property predictions. Synthesis, post-processing, and characterization (steps 6–8) are in a sense the pinnacle of materials discovery for practical applications. These steps appear last in part because they typically represent the highest cost-per-datapoint out of all other steps.

While these steps represent a single materials discovery iteration, the approach can also be modified into an AD scheme.

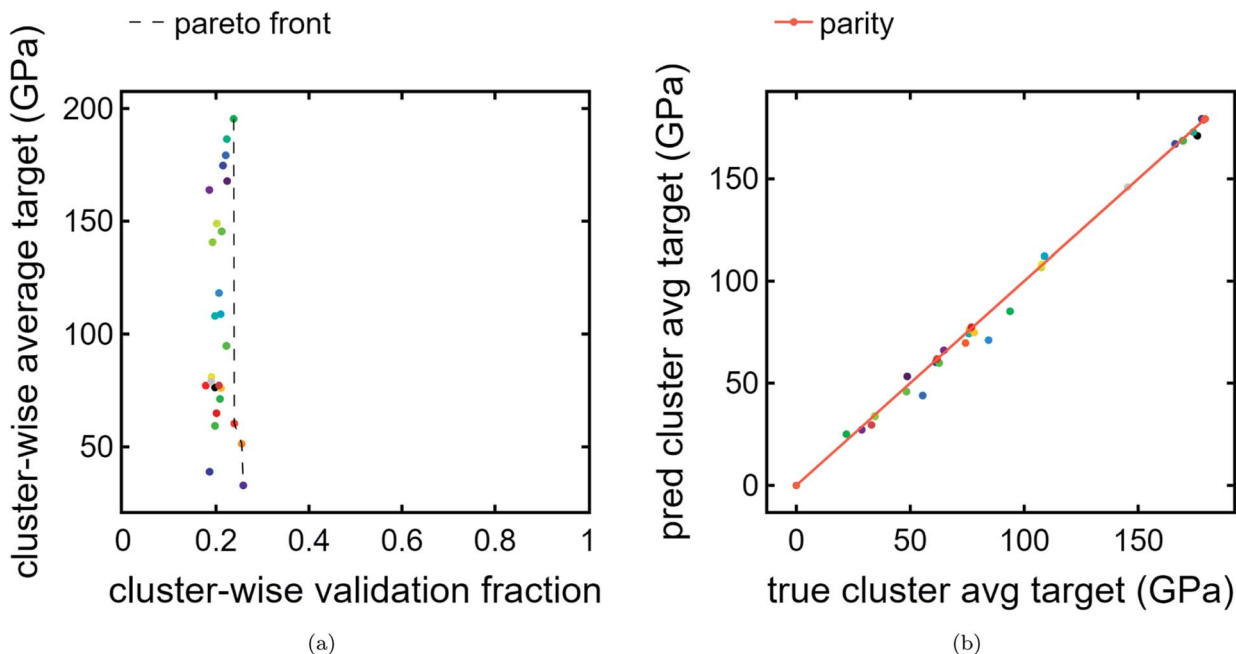


Fig. 5 Cluster Pareto plot and LOCO-CV results. (a) Pareto plot of cluster-wise average bulk modulus predictions (GPa) vs. cluster-wise validation fraction. This emphasizes the trade-off between high-performing clusters and chemically unique clusters relative to the original data. Interestingly, no Pareto front is present because the cluster with the highest predicted average target is incidentally also the cluster with the highest validation fraction. (b) Parity plot of predicted cluster-wise average bulk modulus (GPa) vs. DFT-calculated average bulk modulus (GPa).



Table 7 Summary of steps and example(s) in a practical materials discovery workflow

Step	Example(s)
(1) Obtain training data (chemical formula, properties)	Stable Materials Project chemical formulas with bulk modulus
(2) Obtain validation data (chemical formula)	Stable Materials Project chemical formulas without bulk modulus
(3) Rank validation formulas by score	Use top-100 ranked validation formulas from DiSCoVeR
(4) Literature search	https://citration.com , Synthesis Explorer, ⁷⁰ MatScholar, ⁷¹ MPDS ⁷²
(5) Physics-based simulation	Pymatgen elastic tensor calculations (requires CIF inputs)
(6) Synthesis	Arc-melting, high-pressure synthesis, solid-state, <i>etc.</i>
(7) Post-processing	Powderization or polishing, annealing (reduce surface strain)
(8) Characterization	X-ray diffraction, nanoindenter hardness, diamond anvil/synchrotron

For example, this could mean iteratively moving newly simulated validation data into the training dataset and swapping certain steps based on time and resource constraints (*e.g.* perform literature search after simulation-based AD).

To illustrate an AD scheme and elucidate the effect of DiSCoVeR weighting parameters, we perform a closed-loop AD validation study to compare random search with three DiSCoVeR performance/proxy weighting combinations. We begin by holding out the top 2% of highest-performing bulk modulus Materials Project compounds out of 10 582 candidates. From the non-extraordinary compounds, we randomly select 100 chemical formulas as training data which are fixed across each of the comparisons. The remainder, including the held out “extraordinary” compounds, comprise the validation set or pool of possible candidates. Histograms of the “extraordinary” training/validation split are given in Fig. 6.

For random search, a new chemical formula is selected at random during each AD iteration and added to the training set.

For the novelty-only (no performance contribution), equal, and performance-only (no novelty contribution) weighting combinations, scores are assigned per Section 2.3 and the top-ranked candidate is chosen and added to the training set during each AD iteration.

During the first iteration, the performance and proxy Scaler+ objects are fixed, facilitating gradually increasing emphasis on performance as high-novelty candidates are explored and eliminated and as higher targets are discovered. This mimics the usually desired behavior of Bayesian optimization acquisition functions such as expected improvement which favor exploration during early iterations and exploitation during later iterations.

Five properties are used to assess the performance and novelty of the explored compounds: the best observed bulk modulus, the currently observed bulk modulus, the total number of observed “extraordinary” compounds (top 2%), and the total number of additional unique atoms and chemical formulae templates added. In other words:

- (1) What's the best bulk modulus observed so far?
- (2) What bulk modulus was observed during this iteration?
- (3) How many “extraordinary” compounds have been observed so far?
- (4) How many unique atoms have been explored so far, not counting atoms already in the starting 100 formulas?
- (5) How many unique chemical templates (*e.g.* A2B3, ABC, ABC2) have been explored so far, not counting templates already in the starting 100 formulas?

We note that unlike EIMD, added number of unique atoms and unique chemical templates does not capture the interplay between each other; despite being somewhat naive, we employ these because they are reasonably straightforward and visualizable measures of novelty.

The results for 900 subsequent AD iterations are summarized in Fig. 7. Random search exhibits good explorability, at least for the dataset used; however, the novelty-only weighting produces a much steeper rise in unique atoms explored while retaining a similar rise in unique chemical templates. Neither random search nor novelty-only consistently produce observations of extraordinary compounds. On the other hand, the performance-only weighting has worse explorability, but significantly better exploitation having observed nearly all extraordinary candidates by the end of the 900 iterations. The equal weighting combination offers a good trade-off between

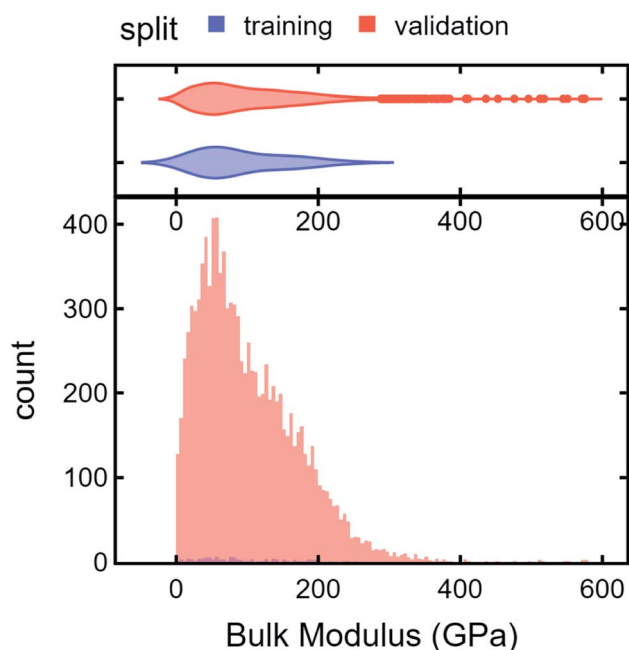


Fig. 6 Histograms of extraordinary training/validation split. Top 2% of compounds were held out before randomly selecting 100 candidates as the training set. The remainder, including “extraordinary” candidates, were assigned as the validation set.



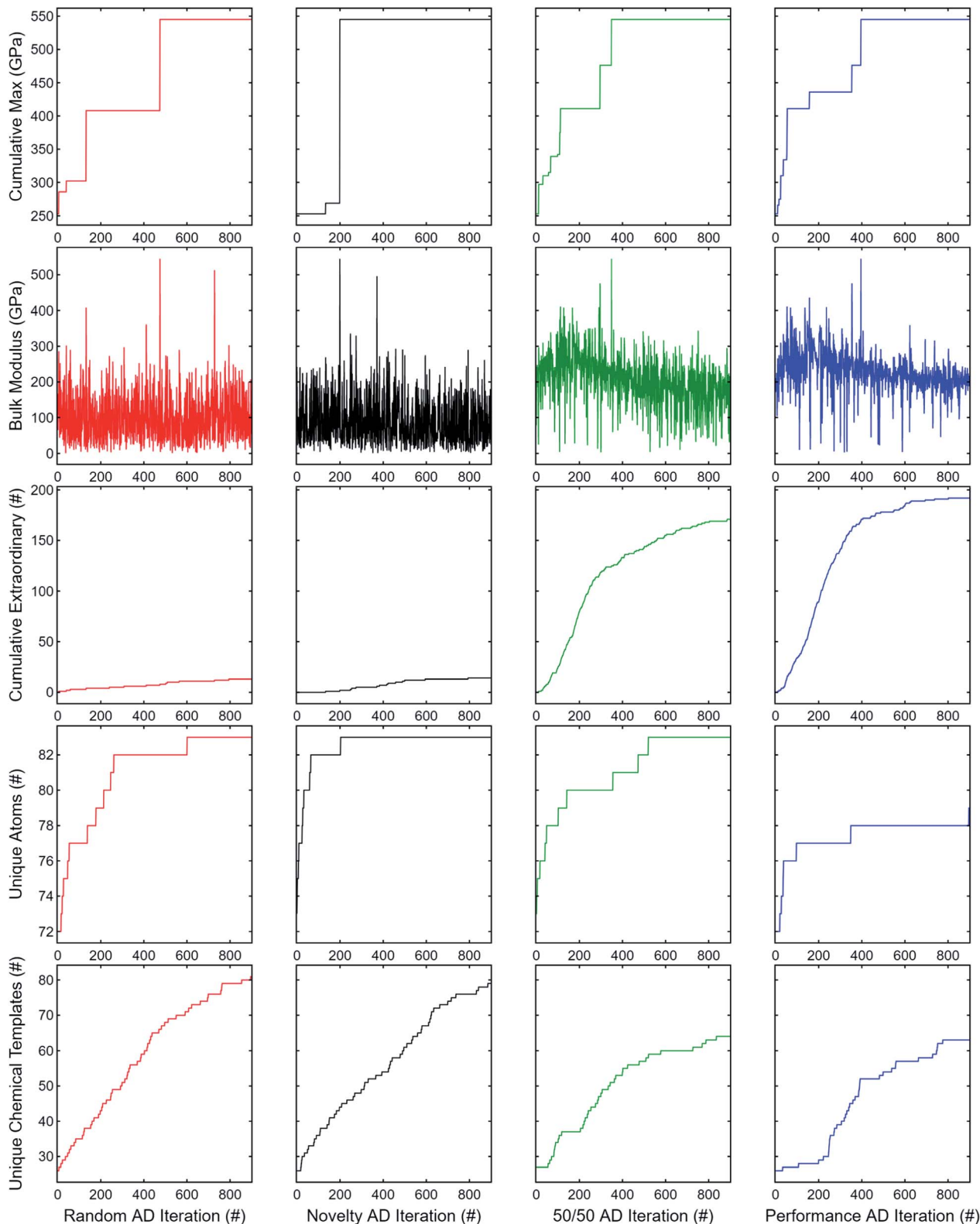


Fig. 7 Adaptive design comparison of random search and DiSCoVeR performance/proxy weightings. The top 2% of compounds were retained exclusively in the validation set, and 100 compounds were used as the initial training set. From leftmost column to right: random search, novelty-only, 50/50 novelty/performance, and performance-only DiSCoVeR weightings. From top row to bottom: best observed bulk modulus (GPa), current observed bulk modulus (GPa), total observed extraordinary compounds, number of additional unique atoms/elements observed, and number of additional unique chemical templates observed. The first three and last two rows contain information about performance and novelty, respectively. Equal weighting (third column) offers a good trade-off between performance and novelty.



performance (properties 1–3) and novelty (properties 4 and 5) such that new elements and chemical templates are explored initially while retaining a high rate of extraordinary discovery nearly comparable to the performance-only results.

4. Conclusion

We embedded EMD distances in DensMAP space and clustered *via* HDBSCAN* to identify chemically similar clusters for 10 583 compositions. We introduced new proxies (*i.e.* metrics) for uniqueness-based materials discovery in the form of train contribution to validation log density, *k*-neighbor averages, and cluster validation fraction. By pairing these with the CrabNet regression model, we visualize Pareto plots of predicted bulk modulus *vs.* uniqueness proxy and obtain weighted uniqueness/performance rankings for each of the compounds. This reveals a new way to perform materials discovery with a focus towards identifying new high-performing, chemically distinct compositions.

Data availability

The raw data required to reproduce these findings is available to download from <https://www.materialsproject.org>. A snapshot of the data as obtained *via* the MPRester API on October 15, 2021 is provided in CrabNet/data/materials_data/elasticity/train.csv. See `generate_elasticity_data.py`⁷⁸ for the MPRester implementation. The processed data required to reproduce these findings is available to download from figshare with DOI: 10.6084/m9.figshare.16786513.v2.⁷⁹ The code required to reproduce these findings is hosted at https://github.com/sparks-baird/mat_discover with DOI: 10.5281/zenodo.5594678.⁸⁰ The version of the code employed for this study is v1.2.1 with DOI: 10.5281/zenodo.5594679.⁷⁸ The code is also packaged on PyPI and Anaconda. GPU and CPU “playground” environments are hosted on Google Colab and Binder, respectively,⁸⁰ and a reproducible Code Ocean capsule is published with DOI: 10.24433/CO.8463578.v1.⁸¹ Finally, interactive Pareto front plots are available.⁸²

Author contributions

Sterling G. Baird: conceptualization, methodology, software, validation, formal analysis, investigation, data curation, writing – original draft, writing – review & editing, visualization. Taylor D. Sparks: supervision, project administration, funding acquisition, conceptualization, formal analysis, resources, writing – review & editing. Tran Q. Diep: conceptualization, methodology, software, formal analysis.

Conflicts of interest

There are no conflicts of interest to declare.

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reduction techniques and Anthony Wang for assistance with the CrabNet repository. The authors thank the reviewers for feedback which has led to significant improvements in the manuscript. Plots were produced *via* either Matplotlib⁷³ or Plotly,⁷⁴ several tables were formatted *via* an online formatter <https://www.tablesgenerator.com/>,⁷⁵ and equations were typeset using the Mathematica⁷⁶ <https://github.com/sgbaird/TeXport> functionality of <https://github.com/sparks-baird/auto-paper>.⁷⁷ This work was supported by the National Science Foundation under grant no. DMR-1651668 and DMR-1950589.

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