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Smoothed profile method for direct numerical simulations of hydrodynamically interacting particles

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A general method is presented for computing the motions of hydrodynamically interacting particles in various kinds of host fluids for arbitrary Reynolds numbers. The method follows the standard procedure for performing direct numerical simulations (DNS) of particulate systems, where the Navier–Stokes equation must be solved consistently with the motion of the rigid particles, which defines the temporal boundary conditions to be satisfied by the Navier–Stokes equation. The smoothed profile (SP) method provides an efficient numerical scheme for coupling the continuum fluid mechanics with the dispersed moving particles, which are allowed to have arbitrary shapes. In this method, the sharp boundaries between solid particles and the host fluid are replaced with a smeared out thin shell (interfacial) region, which can be accurately resolved on a fixed Cartesian grid utilizing a SP function with a finite thickness. The accuracy of the SP method is illustrated by comparison with known exact results. In the present paper, the high degree of versatility of the SP method is demonstrated by considering several types of active and passive particle suspensions.

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1 Introduction

The dynamics of particles dispersed in a host solvent, *i.e.*, how they react to and affect the motion of the fluid, is fundamental to many areas of the physical sciences and provides the basis for many engineering applications.¹ A proper understanding of this dynamical behavior is required to explain the macroscopic physical properties of colloidal dispersions (*e.g.*, viscosity, elastic modulus, and thermal conductivity), the mechanics of protein unfolding,² the kinetics of bio-molecular reactions,³ and the tumbling motion of bacteria,⁴ among many other processes. All these examples share one common characteristic: as they move, the particles generate long-range disturbances in the fluid, resulting in long-range hydrodynamic interactions between all particles present in the system. The non-linear, many-body, and long-range nature of these interactions makes these systems incredibly challenging to study.

Theoretical approaches have been limited to simple idealized systems (*i.e.*, spheroidal particles in dilute suspensions), while experiments can be difficult to analyze, leaving computer simulations as one of the preferred methods. While this still requires advanced simulation methods and considerable

computational resources, significant progress has been made in the past few decades, and there are now several well-established numerical techniques to explicitly account for the hydrodynamic interactions in a suspension of particles.^{5–11} However, not all of these methods can be (easily) applied to dispersions with non-Newtonian host solvents, or solvents with internal degrees of freedom, which severely limits the physical and biological systems they can study. To address this issue, we have proposed a direct numerical simulation (DNS) method called the smoothed profile (SP) method,^{12,13} which simultaneously solves the coupled equations of motion for both the host fluid and the particles, and allows for complex non-Newtonian fluids at arbitrary Reynolds numbers. The basic idea behind our method, and the key to its simplicity and efficiency, is to replace the sharp particle interfaces with smoothed (diffuse) profiles. This allows us to directly couple the fluid and particle motions, effectively treating the system as a single component fluid. This leads to the main advantage of our model with respect to alternative approaches, which is the ability of using a fixed Cartesian grid to solve the fluid equations of motion, as this allows for improved accuracy and efficiency (*e.g.*, by adopting pseudo-spectral solvers based on the Fast-Fourier transform). We note that our method is closely related to Araki and Tanaka's fluid particle dynamics (FPD) method,¹⁴ which models the particles as a highly viscous fluid. Furthermore, while a similar approach to deal with the solid–fluid interaction has been

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proposed in earlier work,¹⁵ our proposed method presents a more general and robust framework.

The SP method is our approach to include the hydrodynamic interactions in a colloidal suspension. As presented here, it uses a DNS in which the Navier–Stokes equation is solved numerically. However, it is also possible to achieve the same goal without solving this equation directly by using a proxy which yields the correct hydrodynamics. The three most popular of these alternative computational fluid dynamics (CFD) methods, often used to simulate soft matter, are the lattice Boltzmann method (LBM),^{10,16–20} the dissipative particle dynamics (DPD) method,²¹ and the multi-particle collision dynamics (MPC)^{22–27} method. While the implementation details and inherent approximations vary between each of these methods (LBM, DPD, MPC, and DNS), they all rely on the same physical principle to couple the particle and fluid motion: local conservation of momentum. In fact, the SP method has also been successfully used together with the LBM.²⁸

Originally, we developed the SP method to simulate colloidal particles in liquid crystals^{29,30} and electrolyte solutions.^{13,31–34} It has now been extended to study diffusion,^{35–37} coagulation,^{38,39} sedimentation,^{40–45} and rheological processes^{46–51} of colloidal particles in incompressible fluids. Recently, the method has also been adapted to allow for arbitrarily shaped rigid bodies,⁵² active particles,⁵³ and self-propelled micro-swimmers.^{54–60} Extensions for complex host fluids such as compressible,^{61–63} viscoelastic,^{64,65} and multi-phase^{66–69} fluids have also been developed. Important contributions for further extending the SP method have also been published independently by other groups.^{70–72} The purpose of this paper is to provide a comprehensive summary of the SP method and its application to several problems of particulate systems in which the hydrodynamic interactions play crucial roles.

2 Simulation method

2.1 Basic equations for particulate systems in fluids

The SP method allows us to solve the motion of solid particles in a continuum medium.¹³ In principle, it can be applied to solid particles of arbitrary shape and is not limited to simple liquids, as we are free to use any constitutive equation for the stress, including multi-component complex fluids and rheological constitutive models discussed in the subsequent sections, as well as continuum models of active matter, such as an active turbulent fluid.⁷³ To explain how the motion of the particles and the flow is coupled by the SP method, we will consider in this section the motion of arbitrarily shaped solid particles in a Newtonian fluid.⁵² A schematic representation of a freely moving disk is shown in Fig. 1, here represented as a rigid ensemble of spherical beads. The incompressible flow of the Newtonian medium is governed by the continuity and Navier–Stokes equations:

$$\nabla \cdot \mathbf{u}_f = 0, \quad (1)$$

$$(\partial_t + \mathbf{u}_f \cdot \nabla) \mathbf{u}_f = \rho_f^{-1} \nabla \cdot \boldsymbol{\sigma}, \quad (2)$$

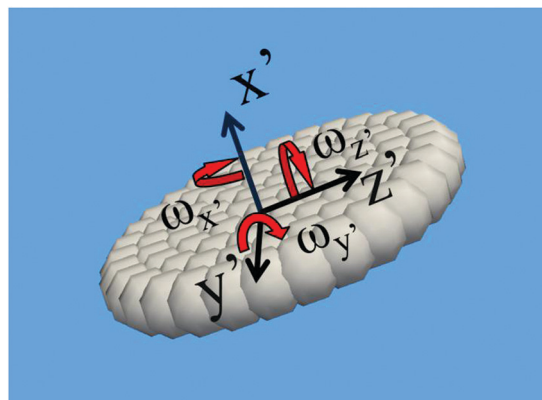


Fig. 1 Schematic representation of the motion of a disk-like object in a 3D domain where the motion is characterized by three translational and three rotational degrees of freedom. Primed variables refer to components measured in the co-rotating body reference frame.

$$\boldsymbol{\sigma} = -p\mathbf{I} + \eta[\nabla \mathbf{u}_f + (\nabla \mathbf{u}_f)^t] \quad (3)$$

where \mathbf{u}_f , ρ_f , η , and $\boldsymbol{\sigma}$ are the velocity, mass density, viscosity and stress of the fluid, respectively; p the pressure; \mathbf{I} the unit tensor; and $(\dots)^t$ indicates a transpose. Unless otherwise stated, we will assume a density-matched suspension, such that $\rho_f = \rho_p = \rho$. We apply the stick or no-slip condition at the solid–fluid interface, *i.e.*, $\mathbf{u}_f = \mathbf{u}_p$ on the solid surface, where \mathbf{u}_p is the particle velocity at the surface. The motion of an ensemble of N rigid particles, with the I -th particle ($I = 1, \dots, N$) having mass M_I and moment of inertia I_I , is described by the Newton–Euler equations:⁷⁴

$$\dot{\mathbf{R}}_I = \mathbf{V}_I, \quad \dot{\mathbf{Q}}_I = \text{skew}(\boldsymbol{\Omega}) \cdot \mathbf{Q}_I, \quad (4)$$

$$\mathbf{M}_I \dot{\mathbf{V}}_I = \mathbf{F}_I^H + \mathbf{F}_I^C + \mathbf{F}_I^E + \mathbf{G}_I^V, \quad (5)$$

$$\dot{\mathbf{J}}_I = \mathbf{N}_I^H + \mathbf{N}_I^C + \mathbf{N}_I^E + \mathbf{G}_I^O, \quad (6)$$

where \mathbf{R}_I and \mathbf{V}_I are the center of mass position and velocity vectors, respectively, \mathbf{Q}_I and $\boldsymbol{\Omega}_I$ the corresponding orientation matrix and angular velocity, respectively, and $\mathbf{J}_I = \mathbf{I}_I \cdot \boldsymbol{\Omega}_I$ is the angular momentum. The orientation matrix associates the fixed (lab) coordinate system, $\{e_i\}$ ($i = 1, 2, 3$), with a time-dependent coordinate system that rotates with the particles, $\{\tilde{e}_i\}$ ($i = 1, 2, 3$) as $\tilde{e}_i = \sum_{j=1}^3 e_j Q_{ji}$. The time-evolution of the rotation matrix is determined by the (skew-symmetric) angular velocity matrix, derived from the angular velocity vector, $[\text{skew}(\boldsymbol{\Omega})]_{ij} = -\sum_{k=1}^3 \varepsilon_{ijk} \Omega^k$, where ε_{ijk} is the Levi-Civita symbol, as

$$\text{skew}(\boldsymbol{\Omega}) = \begin{pmatrix} 0 & -\Omega^z & \Omega^y \\ \Omega^z & 0 & -\Omega^x \\ -\Omega^y & \Omega^x & 0 \end{pmatrix}. \quad (7)$$

The particles will be subject to forces \mathbf{F} and torques \mathbf{N} coming from their environment. Here, we have separated out the contributions to the forces (torques) in terms of the interactions coming



from the medium, which is composed of the hydrodynamic forces \mathbf{F}^H and the thermally fluctuating forces \mathbf{F}^V , the direct inter-particle interactions \mathbf{F}^C , and those due to external fields \mathbf{F}^E , such as gravity. Note that the precise form of these terms will depend on the system under consideration and will be discussed separately.

We will now explain how to solve the system of coupled equations shown above with the SP method. In this approach, the velocity field is defined over the whole domain, in order to include both the host fluid and the solid particles, as

$$\mathbf{u}(\mathbf{x}, t) = (1 - \phi)\mathbf{u}_f(\mathbf{x}, t) + \phi\mathbf{u}_p(\mathbf{x}, t), \quad (8)$$

$$\phi\mathbf{u}_p(\mathbf{x}, t) = \sum_{I=1}^N \phi_I[\mathbf{V}_I + \boldsymbol{\Omega}_I \times \mathbf{r}_I], \quad (9)$$

where $\mathbf{r}_I = \mathbf{x} - \mathbf{R}_I$ is the distance from the center of mass and $\phi_I = \phi_I(\mathbf{x}; \mathbf{R}_I, \mathbf{Q}_I) \in [0, 1]$ defines an order parameter for the particle domain, which is 1 inside of the particle and 0 outside. In the SP method, instead of a sharp interface, a continuous diffuse interface domain of thickness ξ is explicitly introduced in the ϕ function. Setting the interface domain to have a finite width has two merits for achieving practical numerical calculations: first, the interface location is supported over the finite grid used in the fluid solver; second, the solid–fluid interactions can still be correctly described, as shown below.

There are two main difficulties when describing the whole domain, including the solid and fluid regions, as a continuum, which is what we propose for the SP method. First, the continuum field must satisfy the boundary condition at the particle surface. Second, the hydrodynamic forces need to be evaluated to solve for the particle dynamics. Here, it is crucial that the particle boundary conditions and the hydrodynamic forces be evaluated consistently with each other. To solve this problem, several methods have been developed. In the distributed Lagrange multiplier (DLM) method,⁷⁵ a Lagrange multiplier field is introduced in the continuum equation, within the particle domain, in order to simultaneously solve for both the fluid velocity field and the particle velocity. In the fictitious boundary method based on a multi-grid finite element approach,⁷⁶ hydrodynamic forces are explicitly calculated by introducing a fictitious boundary indicator. In the immersed-boundary method (IBM),^{77–79} markers distributed over the particle surface are used to apply frictional forces between the particle and the fluid velocity field near the surface. It is also possible to have a direct forcing of the particle velocity field in the particle domain, rather just at the particle surface, by adopting a volume-of-fluid representation for the particle.¹⁵ In the force coupling method (FCM),⁸⁰ all forces on the particle, other than the hydrodynamic ones, are used to define a force field (assuming a Gaussian profile) that is then applied to the particle domain in the continuum equations. In the fluid particle dynamics (FPD) method,^{14,81} in addition to the particle force field, a large artificial viscosity is applied within the inner particle region to penalize fluid-like behaviour and thus enforce the rigid-body constraints on the velocity field. In the SP method, the calculation of the hydrodynamic forces and the boundary

conditions are separated by using a fractional-step approach, without introducing an artificially large viscosity in the particle domain (in contrast to FPD).

2.2 Implementation of the SP method

The velocity field is governed by a modified version of the continuity and Navier–Stokes equations:

$$\nabla \cdot \mathbf{u} = 0, \quad (10)$$

$$(\partial_t + \mathbf{u} \cdot \nabla)\mathbf{u} = \rho^{-1} \nabla \cdot \boldsymbol{\sigma} + \phi \mathbf{f}_p, \quad (11)$$

where $\phi \mathbf{f}_p$ acts as a penalty force to impose the rigid-body constraints within the particle domain, and where the stress tensor is defined exactly as in eqn (3), but now in terms of the total velocity \mathbf{u} . The terms responsible for the coupling with the rigid-body dynamics, $\phi \mathbf{f}_p$, \mathbf{F}_I^H and \mathbf{N}_I^H , are determined at a temporally discretized level as follows. Let \mathbf{u}^n be the velocity field at the n -th time step $t_n = nh$ with time increment h . First, eqn (11) is solved without the $\phi \mathbf{f}_p$ -term and the particle positions and orientations are propagated as

$$\mathbf{u}^* = \mathbf{u}^n + \int_{t_n}^{t_n+h} ds \nabla \cdot [\rho^{-1} \boldsymbol{\sigma} - \mathbf{u}\mathbf{u}], \quad (12)$$

$$\mathbf{R}_I^{n+1} = \mathbf{R}_I^n + \int_{t_n}^{t_n+h} ds \mathbf{V}_I, \quad (13)$$

$$\mathbf{Q}_I^{n+1} = \mathbf{Q}_I^n + \int_{t_n}^{t_n+h} ds \text{skew}(\boldsymbol{\Omega}) \cdot \mathbf{Q}_I. \quad (14)$$

at which point the particle velocity field must also be updated even if the particle velocities remain unchanged. The hydrodynamic forces and torques are expressed in terms of the corresponding momentum impulses, by assuming momentum conservation for the unperturbed velocity \mathbf{u}^*

$$\left[\int_{t_n}^{t_n+h} ds \mathbf{F}_I^H \right] = \int d\mathbf{x} \rho \phi_I^{n+1} (\mathbf{u}^* - \mathbf{u}_p^n), \quad (15)$$

$$\left[\int_{t_n}^{t_n+h} ds \mathbf{N}_I^H \right] = \int d\mathbf{x} [\mathbf{r}_I^{n+1} \times \rho \phi_I^{n+1} (\mathbf{u}^* - \mathbf{u}_p^n)]. \quad (16)$$

Then, the velocities of the particles are updated to \mathbf{V}_I^{n+1} and $\boldsymbol{\Omega}_I^{n+1}$, from which ϕ_I^{n+1} , the final particle velocity field $\phi^{n+1} \mathbf{u}_p^{n+1}$ is obtained, by Eqn (9). Finally, the forcing needed to impose the rigid-body constraint on the particle velocity field is also applied as a momentum impulse

$$\mathbf{u}^{n+1} = \mathbf{u}^* + \left[\int_{t_n}^{t_n+h} ds \phi \mathbf{f}_p \right], \quad (17)$$

$$\left[\int_{t_n}^{t_n+h} ds \phi \mathbf{f}_p \right] = \phi^{n+1} (\mathbf{u}_p^{n+1} - \mathbf{u}^*) - \frac{h}{\rho} \nabla p_p, \quad (18)$$

with the pressure due to the rigidity constraint obtained from the continuity equation $\nabla \cdot \mathbf{u}^{n+1} = 0$. Since the viscous stress is applied over the whole domain, the relevant no-slip condition on the particle surface will be satisfied within the limits of the interfacial scale ξ .



2.3 The smoothed profile function

We now explain how to construct the Smoothed Profile (SP) function ϕ_I for a particle of arbitrary shape. This function defines the particle domain, introducing an interface of finite width ξ , to smoothly connect the inner particle domain $\phi = 1$ with the fluid domain $\phi = 0$. For a spherical particle, several analytical forms of the SP function are presented in ref. 12. One example of such a SP function for spherical particles is^{14,29}

$$\phi_I = \frac{1}{2} \left[\tanh \left(\frac{a - |r_I|}{\xi} \right) + 1 \right], \quad (19)$$

where a is the sphere radius. The interfacial scale ξ is a free parameter to be specified, though it is typically set to be one or two times the grid spacing for numerical stability. Fig. 2 shows a cross section of a sphere, with interfacial thickness ξ , to illustrate the separation between the particle and fluid domains.

For non-spherical particles, Luo *et al.*⁷⁰ have generalized the definition of the SP function to arbitrary geometries by replacing $|r_I(\mathbf{x}, t)| - a$ with a signed distance function $d_I(\mathbf{x}, t)$ to the surface of the I -th particle. However, to define d_I , this requires that we define the position of the particle surface. Alternatively, complex shapes can be constructed using a set of spherical beads,⁵² which is the approach we have adopted.

For this, consider the I -th particle as being composed of a collection of n_I spherical beads. Since the constituent beads can overlap, a large class of particle geometries can be easily represented as an assembly of spherical beads. The SP function for such an assembly of beads is constructed as

$$\Phi_I(\mathbf{x}, t) = \sum_{i=1}^{n_I} \phi_{I,i}(\mathbf{x}, t), \quad (20)$$

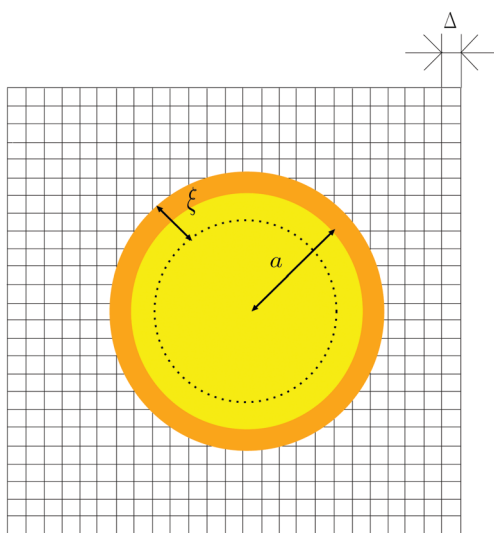


Fig. 2 Schematic representation of the cross section of a spherical SP particle. Δ is the lattice spacing, a is the particle radius, and ξ is the interfacial thickness. The particle surface now has a finite volume $\sim \pi a^2 \xi$ supported by several grid points on a fixed 3D Cartesian grid. Reproduced from *Phys. Rev. E*, **71**, 036707,¹² Copyright 2005, with permission from the American Physical Society.

$$\phi_I(\mathbf{x}, t) = \frac{\Phi_I}{\max(\Phi_I, 1)}, \quad (21)$$

where $\phi_{I,i}$ is the SP function of the i -th spherical bead, belonging to the I -th rigid particle.

Once the SP function of a complex shape has been defined, the hydrodynamic impulse on a particle and the corresponding momentum impulse on the medium are evaluated using eqn (15), (16) and (18).

Since the fluid inertia is solved for in the above SP algorithm, the added mass effect is accounted for in the hydrodynamic impulse in eqn (15). To specify the inertial effect, the integrand of the hydrodynamic impulse (15) is decomposed as

$$\begin{aligned} \rho \phi_I^{n+1} (\mathbf{u}^* - \mathbf{u}_p^n) &= -\rho \phi_I^{n+1} (\mathbf{u}_p^{n+1} - \mathbf{u}^*) + \rho \phi_I^{n+1} (\mathbf{u}_p^{n+1} - \mathbf{u}_p^n) \\ &= -\rho \int_{t_n}^{t_{n+h}} ds \phi_I \mathbf{f}_p - h \nabla p_p \\ &\quad + \rho \phi_I^{n+1} [\mathbf{V}_i^{n+1} - \mathbf{V}_i^n + (\boldsymbol{\Omega}_i^{n+1} - \boldsymbol{\Omega}_i^n) \times \mathbf{r}_i^{n+1}], \end{aligned} \quad (22)$$

Spatial integration of this equation with $\int d\mathbf{x} \phi_I \mathbf{r} = 0$ yields

$$\mathbf{F}_I^H = - \int d\mathbf{x} \rho \phi_I \mathbf{f}_p - \int d\mathbf{x} \phi_I \nabla p_p + M_I \frac{\rho}{\rho_{p,I}} \dot{\mathbf{V}}_I, \quad (23)$$

where $\rho_{p,I}$ is the mass density of the I -th particle. From this equation, the hydrodynamic force in eqn (15) is found to be composed of the counter-action of the rigidity constraint and the added mass force.

The accuracy of the flow field obtained from the SP method will depend on both the time increment h and the interfacial thickness ξ . Luo *et al.*⁷⁰ reported that the accuracy does not improve monotonically as h decreases, but instead reaches an optimal value when $\xi^2 = O(\eta h / \rho)$. This relation reflects the fact that a sufficiently large interfacial scale is required to resolve the viscous Stokes layer generated by the rigidity constraint impulse (18).

Due to the fractional step approach used in the SP method, it is relatively easy to apply different hydrodynamic solvers. In fact, the SP method has already been applied in combination with different flow solvers: the pseudo-spectral method,^{12,13,31,35-40,46-49,54,61} spectral element method,^{70,82} finite difference method,⁸³ finite volume method,⁷¹ and LBM.²⁸

3 Applications

3.1 Brownian motion and coagulation

3.1.1 Thermal fluctuations. Let us consider the Brownian motion of spherical particles dispersed in an incompressible fluid. Following eqn (4)–(6), the motion of the i -th particle is now governed by a set of Langevin equations:

$$\dot{\mathbf{R}}_i = \mathbf{V}_i, \quad (24)$$

$$M_i \dot{\mathbf{V}}_i = \mathbf{F}_i^H + \mathbf{F}_i^C + \mathbf{G}_i^V, \quad (25)$$

$$\mathbf{I}_i \cdot \dot{\boldsymbol{\Omega}}_i = \mathbf{N}_i^H + \mathbf{G}_i^\Omega. \quad (26)$$



where the external forces/torques are set to be zero, and it is assumed that the inter-particle interactions are given by a central-force potential, such that $\mathcal{N}^C = 0$.

The stochastic forces \mathbf{G}_i^V and torques \mathbf{G}_i^R satisfy the following properties:

$$\langle \mathbf{G}_i^n(t) \rangle = 0, \quad \langle \mathbf{G}_i^n(t) \mathbf{G}_j^n(0) \rangle = \alpha^n \mathbf{I} \delta(t) \delta_{ij}, \quad (27)$$

where the square brackets denote an equilibrium ensemble average. Here, α^n represents the noise intensity associated with each of the translational ($n = V$) and rotational ($n = R$) degrees of freedom of the particles. The noise intensity is controlled in such a way that the variance in the linear and angular velocities is constant, that is, $\langle \mathbf{V}_i^2 \rangle = C_1$ and $\langle \mathbf{\Omega}_i^2 \rangle = C_2$, where C_1 and C_2 are constant parameters. The time evolution of the noise intensity is described by $\alpha^V(t+h) = \alpha^V(t)e^{1-V_i^2(t)/C_1}$ and $\alpha^R(t+h) = \alpha^R(t)e^{1-\Omega_i^2(t)/C_2}$, which play the role of a thermostat. The temperature of the system is defined by the diffusive motion of the dispersed particles. The translational particle temperature $k_B T^V$ is determined by the long-time diffusion coefficient D^V of a spherical particle, as given by the Stokes–Einstein relation, $k_B T^V = 6\pi\eta a D^V$, with D^V obtained from the simulations. Similarly, the rotational particle temperature $k_B T^R$ can be determined by the rotational diffusion coefficient D^R .

3.1.2 Velocity auto-correlation of a single particle. To test the validity of the present approach, we first consider the translational and rotational motions of a single Brownian particle in an incompressible Newtonian fluid. The translational velocity auto-correlation function $\beta_V \langle \mathbf{V}_i(t) \cdot \mathbf{V}_i(0) \rangle$ is shown in Fig. 3. Our numerical data (+) clearly approach the analytical solution in the long-time limit, exhibiting the appropriate power law decay $Bt^{-3/2}$. A similar trend is found for the rotational velocity auto-correlation function $\frac{1}{3} \langle \mathbf{\Omega}_i(t) \cdot \mathbf{\Omega}_i(0) \rangle$, as shown in Fig. 4.

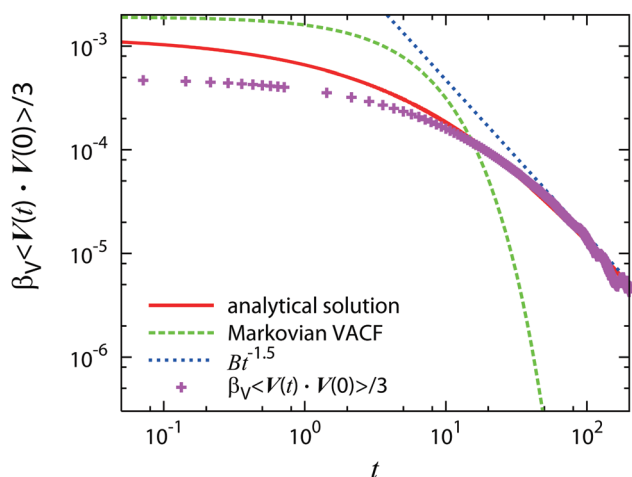


Fig. 3 Pluses (+): translational velocity auto-correlation function for Brownian particles at $\beta_V = 1.2$ and $\varphi = 0.002$. The solid line is obtained from the analytical solution for the translational particle velocity of the corresponding drag problem. The dotted line shows the power-law $Bt^{-3/2}$, where $B = 1/12\rho_f(\pi\nu_f)^{3/2}$, whereas the dashed line shows the exponential decay obtained from the Markovian Langevin equation. Reproduced from *J. Phys. Soc. Jpn.*, **77**, 074007,³⁵ Copyright 2008, with permission from the Physical Society of Japan.

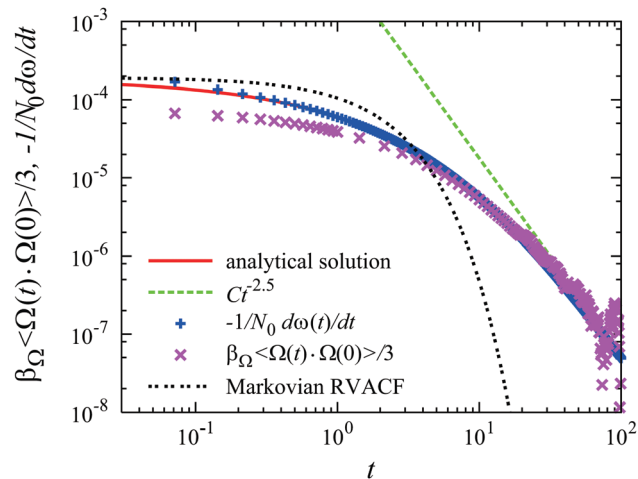


Fig. 4 Crosses (x): rotational velocity auto-correlation function for Brownian particles at $\beta_R = 1$ and $\varphi = 0.002$. Pluses (+): the relaxation response of the angular velocity of a particle under a constant external torque N_0 . The solid line is obtained from the analytical solution for the angular velocity of the corresponding drag problem. The dashed line shows the power-law $Ct^{-2.5}$, where $C = \pi/32\rho_f(\pi\nu_f)^{5/2}$, and the dashed-dotted line shows the exponential decay obtained from the Markovian Langevin equation. Reproduced from *J. Phys. Soc. Jpn.*, **77**, 074007,³⁵ Copyright 2008, with permission from the Physical Society of Japan.

3.1.3 Brownian coagulation with hydrodynamics. For over 100 years, ever since Smoluchowski presented his theory of Brownian coagulation in colloidal dispersions, there have been numerous theoretical, experimental, and simulation studies performed to assess the validity of this theory. Based on balance equations and a simple kinetic theory of coagulation, but ignoring the effect of inter-particle interactions, Smoluchowski's theory predicts a coagulation rate that is twice that of actual colloidal dispersions.^{84–88} To address this discrepancy, it has been suggested to introduce a correction factor into the coagulation rate, so as to account for the contributions from these missing inter-particle interactions.^{89–91} Several experimental evaluations of this correction factor have been performed, and they suggest that the reduction in the aggregation rate is mostly caused by the (repulsive) hydrodynamic lubrication forces between the particles.^{84–88,92} However, it should be noted that these examinations assume the validity of the correction factor itself. To understand the role played by the hydrodynamic interactions it is necessary to directly measure them.

We have performed simulations of monodisperse spherical particles of diameter $\sigma = 2a$, with $a = 4\Delta$, $\xi = 2\Delta$, in a Newtonian host fluid. All simulations have been performed in a 3D cubic box, of length $L = 256$, under periodic boundary conditions, starting from a random initial configuration of particles. The number of particles was set to $N_p = 187, 281, 375, 625, 938, 1877, 3754$ and 6258 . These conditions correspond to a particle volume fraction of $\varphi = 0.003, 0.0045, 0.006, 0.01, 0.015, 0.03, 0.06$ and 0.1 , respectively, where $\varphi = \pi\sigma^3 N_p / 6L^3$. The particles interact *via* a modified Lennard–Jones (LJ) potential, defined as

$$V_{LJ}(r) = 4\epsilon[(\sigma/r)^m - (\sigma/r)^n] \quad (28)$$



with $n:m = 200:100$, where r is the inter-particle distance and ε is the interaction strength. The large value of the exponent in eqn (28) results in a very short-range interaction, appropriate for the rapid coagulation of sticky particles. For the results presented here, we chose a strong enough attractive potential, so that coagulated particles were prevented from breaking apart due to thermal fluctuations. For this, the value of ε was fixed to be $7.03k_B T$. To improve the statistical significance of the data, five independent simulations were performed for each set of parameter values, and the results were averaged over.

The units of all variables are based on the three fundamental constants Δ , μ , and ρ_f . Accordingly, the unit of time is $\tau = \rho_f \Delta^2 / \mu$, and the unit of energy is $\varepsilon_0 = \Delta \mu^2 / \rho_f$. Unless otherwise stated, we set $\Delta = 1$, $\tau = 1$, $\mu = 1$, $\rho_f = 1$, $\rho_p = 1$, $a = 4$, $\sigma = 8$, $\xi = 2$, the Lennard–Jones time unit $\tau_M = ((M_f \sigma^2) / \varepsilon)^{1/2} \approx 131$. Assuming dispersions of neutrally buoyant particles of radius $1 \mu\text{m}$ in water at room temperature, our unit length Δ and time τ correspond to $0.25 \mu\text{m}$ and $0.0625 \mu\text{s}$, respectively. The discretized time step is $h = 0.07481$. Although this value is chosen from the stability condition of the Navier–Stokes equation, it can be used safely for the particle's equations because h is smaller than the oscillation period of the particle in the potential well $\tau_v = 2\pi(M_i / \ddot{V}_{LJ}(2^{1/100}\sigma))^{1/2} \approx 11.7$.

The volume fraction dependence of Smoluchowski's coagulation rate K , normalized by the early-stage coagulation rate K^0 , is shown in Fig. 5. This ratio is seen to asymptotically approach a fixed value in the dilute volume fraction limit, as $\phi \rightarrow 0$, whereas it gradually increases with increasing volume fraction. The coagulation rate we have obtained in the dilute limit is approximately 0.3–0.5 times smaller than that predicted by

Smoluchowski's theory, in good agreement with previous experimental results (shown as open symbols in the figure), which reported values of K/K^0 between 0.4 and 0.6.^{84–88} Likewise, the increase at higher volume fractions is in qualitative agreement with experiments and simulation results.^{85,93–95} The solid line in Fig. 5 shows the ratio of the coagulation rates K/K^0 in the high-concentration limit, as given by the regression formula of Heine *et al.*⁹³

$$K/K^0 = \alpha^0 \left(1 + \frac{2.5}{1-\phi} (-\log \phi)^{-2.7} \right). \quad (29)$$

with $\alpha^0 = 1$. This equation by Heine *et al.* reduces to the Smoluchowski result $K/K^0 = 1$ in the dilute volume fraction limit, when $(-\log \phi)^{-2.7} \ll 1$. However, since this formula was obtained from simulations using Langevin dynamics, it ignores the hydrodynamic interactions between the particles. To account for these missing contributions, we can treat α^0 as a scaling or correction factor. Using a least-squares fit of α^0 to our simulation results, we obtained $\alpha^0 = 0.326$. This result agrees well with the form of eqn (29), despite the differences in the way that the hydrodynamic interactions are considered. From this, we can conclude that while hydrodynamic interactions affect the magnitude of the coagulation rate, they do not affect the particle concentration dependency, at least in the dilute limit.

3.2 Hindered settling

3.2.1 Settling velocity at small Re. We now consider the sedimentation of non-Brownian ($T = 0$) spherical particles interacting *via* a truncated LJ or Weeks–Chandler–Anderson potential

$$V_{LJ}(r) = \begin{cases} 4\varepsilon \left[(\sigma/r)^{24} - (\sigma/r)^{12} \right] + \varepsilon, & r \leq 2^{1/2}\sigma, \\ 0 & r > 2^{1/2}\sigma. \end{cases} \quad (30)$$

under a gravitational force $\mathbf{F}_i^E = (0, 0, -F_g)$. Simulations are performed using cubic simulation boxes, of length $L = 64\Delta$, 128Δ or 256Δ , under periodic boundary conditions, with Δ being the grid spacing and our unit of length. The particle radius a is set to 4Δ and the particle volume fraction ranges from 0.01 to 0.5. To avoid any inertial effects, and remain within the Stokes regime, we perform all simulations at a particle Reynolds number of $\text{Re} = \rho_f a V_s / \eta = 0.14$, with $V_s = \frac{2}{9} g a^2 (\rho_p - \rho_f) / \eta$ being the corresponding Stokes velocity for a single particle.

To account for the sedimentation of colloidal dispersions, we need to consider the fact that a sedimenting particle will experience a hindered settling due to the presence and the motion of the other particles. This includes the drag force induced by the back flow of the fluid, as well as any direct particle–particle interactions. The net effect of these interactions is to reduce the average settling velocity of the suspension, in comparison with the terminal velocity of a single isolated particle sedimenting under the same gravitational force. If a simulation is to reproduce this hindered settling, which has been amply studied, both theoretically^{96–101} and

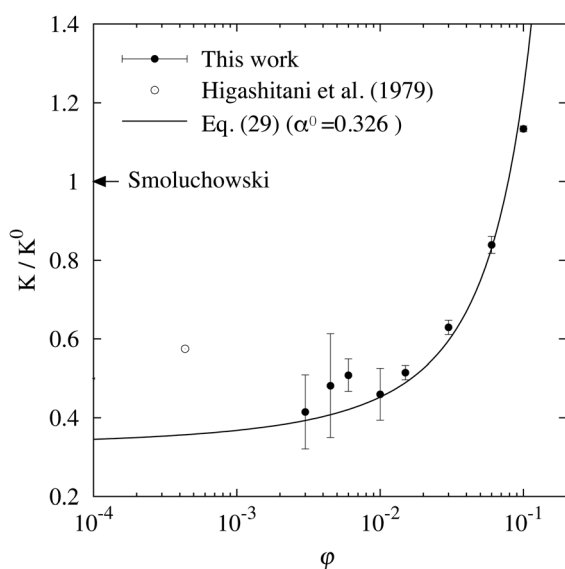


Fig. 5 The volume fraction dependence of the normalized coagulation rate K/K^0 . The filled symbols show our simulation results, and the open symbols the experimental results of Higashitani *et al.*⁸⁶ The arrows indicate Smoluchowski's prediction, while the solid line shows the fit to the data using eqn (29). Reproduced from *Phys. Rev. E*, **86**, 051403,³⁹ Copyright 2012, with permission from the American Physical Society.



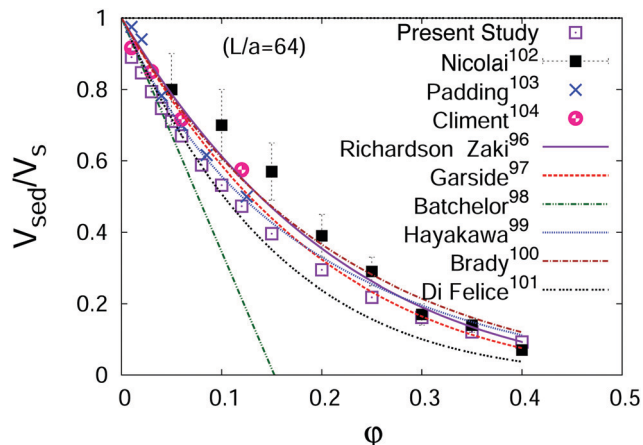


Fig. 6 Average particle settling velocity V_{sed} , normalized by the Stokes velocity V_s , as a function of the particle volume fraction. This observed reduction with volume fraction highlights the hindered settling of these particles. Solid lines show the various theoretical predictions,^{96,98–101} and the symbols represent the experimental¹⁰² and simulation¹⁰³ data. Reproduced from *Soft Matter*, **9**, 10056–10068,⁴⁰ Copyright 2013, with permission from the Royal Society of Chemistry.

experimentally,¹⁰² it must accurately characterize the many-body hydrodynamic interactions at their origin. Thus, this hindered settling presents itself as a suitable parameter to assess whether or not the hydrodynamic interactions are properly described. We verify our SP method by comparing its predictions for the average settling velocity of a suspension, with theoretical,^{96–101} experimental¹⁰² and alternative simulation^{103,104} results, as shown in Fig. 6. The simplest semi-empirical relation to describe this behaviour is the power-law function proposed by Richardson and Zaki,⁹⁶ $V_{\text{sed}}/V_s = (1 - \phi)^n$, where $V_{\text{sed}} = \langle V_{iz} \rangle$ is the average settling velocity of the particle and n is the power law exponent. Different studies^{97,101–105} have obtained different values for this exponent, ranging from 4.7 to 6.55 in the Stokes flow regime. From our results, we find that a value of 5.3 provides the best fit to the data, which is well within the range of previous values. Our results are also in good agreement with the theoretical work of Hayakawa *et al.*,⁹⁹ which also considers the effect of the hydrodynamic interactions. The agreement of our simulation results with previous experimental, theoretical, and simulation studies further validates our method.

3.2.2 Settling velocity at $Re > 1$. Let us now consider the inertial effects on the sedimentation of non-Brownian particles. For this, we vary the Reynolds number Re between 0.05 and 10, by increasing the strength of the gravitational force. In principle, our method is also applicable for $Re > 10$, but this requires that we reduce the time step and decrease the grid spacing, dramatically increasing the computational cost of our simulations. Our simulation results, presented in Fig. 7(a–c), show that the theoretical predictions obtained for the Stokes regime are no longer applicable due to the presence of inertial effects. To capture this deviation, one can use a modified expression for the sedimentation velocity, of the form:

$$V_{\text{sed}}/V_t = k(1 - \phi)^n, \quad (31)$$

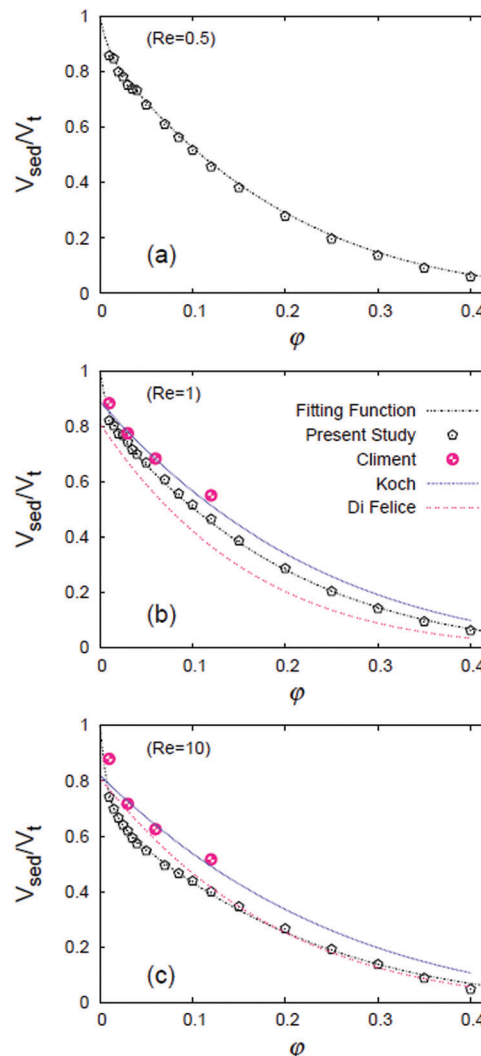


Fig. 7 Average sedimentation velocity V_{sed} , normalized by the terminal velocity V_t of an isolated sphere, as a function of the volume fraction for $Re = 0.5, 1$ and 10 . Simulation results are fitted to the hindered settling function of eqn (33) and compared with other theoretical predictions^{101,106} and simulation results.¹⁰⁴ Legends apply to all three figures. Reproduced from *RSC Adv.*, **4**, 53681–53693,⁴³ Copyright 2014, with permission from the Royal Society of Chemistry.

where the terminal velocity, as a function of Re , is computed according to $V_t = Re\eta/\rho_f\sigma$. Here, both the scaling factor k and the exponent n are allowed to vary with Re . Koch *et al.* have reported k values of 0.92 ± 0.03 and 0.86 ± 0.04 for $Re = 1$ and 10 , respectively, and suggested to use the following quadratic polynomial for n :

$$n = 4.23 - 0.0526Re + 0.00111Re^2. \quad (32)$$

Previous work by Koch and Di Felice details the mechanism responsible for the initial decay in the hindered settling function at a low volume fraction, but their proposed mathematical expressions cannot be applied at $\phi \approx 0$. In order to include this missing information, we suggest a modified hindered settling expression:

$$V_{\text{sed}}/V_t = k(1 - \phi)^n + (1 - k)\exp(-\phi/0.008), \quad (33)$$



where the values of k and n are, respectively, determined by

$$k = \begin{cases} 1, & \text{Re} \leq 0.1, \\ -0.065 \ln \text{Re} + 0.85, & 0.1 < \text{Re} \leq 10 \end{cases} \quad (34)$$

and

$$n = \begin{cases} 5.3, & \text{Re} \leq 0.1, \\ -0.161 \ln \text{Re} + 4.932, & 0.1 < \text{Re} \leq 10 \end{cases} \quad (35)$$

These simple fitting functions capture the behaviour of sedimenting particle dispersions as a function of Re and volume fraction. We note that these expressions are reduced to the Richardson and Zaki⁹⁶ law at $\text{Re} \leq 0.1$, whereas at $0.1 < \text{Re} \leq 10$ the second term ($0.1 < \text{Re} \leq 10$) provides for the fast decay in the sedimentation velocity, as shown in Fig. 7.

3.3 Shear flow and rheology

3.3.1 Implementation of sheared boundary conditions.

Understanding the macroscopic rheological properties of colloidal dispersions remains a challenging problem in colloidal science, particularly when considering non-Newtonian host fluids and non-spherical particles. Of particular interest are the non-Newtonian behaviours that appear whenever the suspension is subjected to shear, such as shear thinning or shear thickening, both of which are strongly related to changes in the microstructure of the suspension. In addition to experiments, DNSs are left as the only viable tool to measure the rheology. The SP method is an ideal tool for these studies, as it allows us to directly solve the Navier–Stokes equation for (Brownian and non-Brownian) arbitrarily shaped rigid particles under shear. We can account for the fluid and particle inertial effects and do not require the separation of time scales between fluid and particle relaxation times.

The easiest way to introduce a simple shear flow $\mathbf{U} = \dot{\gamma} \mathbf{e}_x$ in the system is to add an external forcing term $\rho \mathbf{f}_s$ into the modified Navier–Stokes equation (11), the role of which is to maintain the target shear flow ($\dot{\gamma}$). When performing bulk 3D simulations under periodic boundary conditions, a linear zig-zag (possibly time-dependent) profile with two kinks (where the force is applied) can be used to satisfy the boundary constraints.^{46,47} The results obtained using this external forcing are in good agreement with alternative DNS methods and theoretical predictions, but the method presents some considerable drawbacks: first, the shear rate is not a precisely controlled quantity; second, there are non-physical kinks where the velocity gradient changes sign (at which point particles translate with no net rotation); and third, the zero-wavevector transport coefficients cannot be obtained (as the technique uses a finite-wavelength perturbation). To overcome these difficulties, one can adopt Lees–Edwards boundary conditions, solving the continuum equations on an (oblique) time-dependent coordinate system whose points are advected by the shear flow. Fig. 8 presents a schematic illustration of this coordinate transform. At time $t = t_0$, a solid spherical particle is shown dispersed in a solvent, which is discretized on a rectangular grid (Fig. 8(a)). After the shear-flow is applied ($t > t_0$), both the particle and the grid points are convected by the flow,

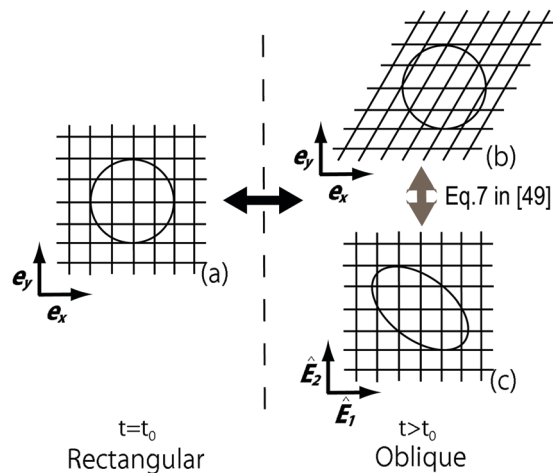


Fig. 8 A schematic representation of the coordinate transformation used to model the effect of shear-flow in the DNS simulations. (a) A solid spherical particle is discretized on a rectangular lattice at time $t = t_0$. Both the particle and the solvent, represented by the grid points, are convected by the applied shear-flow ($t > t_0$). While the grid is deformed, the shape of the solid particle remains unchanged. This is depicted in (b) the fixed or laboratory reference frame and (c) the transformed or oblique reference frame. The transformation between (b) and (c) is defined in eqn (7) of our earlier paper.⁴⁹ Reproduced from *J. Chem. Phys.*, **134**, 064110,⁴⁹ Copyright 2011, with the permission of AIP Publishing.

with the grid undergoing a shear-induced deformation, in contrast to the particle whose shape remains unchanged. This situation can be represented in a fixed coordinate system (Fig. 8(b)), as well as a time-dependent oblique coordinate system which tracks the shear-flow (Fig. 8(c)), and in which the particle shape is deformed. This formulation is equivalent to the SLLOD algorithm used in non-equilibrium MD simulations to model (arbitrary) homogeneous and divergence-free flows, but the implementation of this algorithm within a grid-based system requires a careful treatment.^{49,108,109} The appropriate contravariant form of the Navier–Stokes equation for the peculiar velocity $\xi = \mathbf{u} - \mathbf{U}$ within this time-dependent oblique coordinate system, with basis vectors ($\hat{\mathbf{E}}_1 = \mathbf{e}_x + \gamma(t)\mathbf{e}_y$, $\hat{\mathbf{E}}_2 = \mathbf{e}_2$, $\hat{\mathbf{E}}_3 = \mathbf{e}_3$), is given as⁵¹

$$\rho \left(\partial_i + \hat{\xi}^j \hat{\nabla}_j \right) \hat{\xi}^i = \hat{\nabla}_j \hat{\sigma}^j + \hat{\phi} \hat{f}^i - 2\dot{\gamma}(t) \hat{\xi}^2 \delta^{i,1} \quad (36)$$

$$\hat{\nabla}_i \hat{u}^i = \hat{\nabla}_i \hat{\xi}^i = 0 \quad (37)$$

where a caret ($\hat{\cdot}$) is used here to denote tensorial components in the oblique frame. After the flow equations are solved, we transform back to the fixed laboratory frame to compute the particle–fluid interactions and solve for the particle dynamics.

Within this formulation, the instantaneous volume-averaged stress of the flowing dispersion is defined in terms of the particle constraint force as

$$\Sigma = \frac{1}{V} \int dx [\boldsymbol{\sigma} - x \rho \phi \mathbf{f}_p + \mathbf{x} \mathbf{u} \cdot \nabla (\rho \mathbf{u})], \quad (38)$$

and the particle contribution to the stress can be obtained by subtracting the average fluid contribution, $\mathbf{s} = \Sigma - \langle \boldsymbol{\sigma} \rangle$. In the case of zig-zag shear flow, a similar expression is obtained but



with the external force field $\rho\mathbf{f}_s$ appearing instead of the particle constraint force $\rho\phi\mathbf{f}_p$. The apparent and intrinsic viscosities of the dispersions, η and $[\eta]$, respectively, are defined as

$$\eta = \eta_f + \frac{\langle s^{12} \rangle}{\dot{\gamma}} \quad (39)$$

$$[\eta] = \frac{\eta - \eta_f}{\eta_f \phi} = \frac{\langle s^{12} \rangle}{\eta_f \phi \dot{\gamma}} \quad (40)$$

with $\eta_f = \langle \sigma^{12} \rangle / \dot{\gamma}$.

3.3.2 Rheology of dilute suspensions. The suspension viscosity for dilute systems of spherical and non-spherical particles is calculated and compared with analytical results at zero Reynolds numbers, as well as the results obtained using alternative (high-precision) methods. SP method simulation results for a single particle under simple shear can reproduce the known analytical solutions for the fluid velocity, stress distribution and particle angular velocity.¹¹⁰ Furthermore, the results at finite Reynolds numbers ($Re \lesssim 10$) are also in agreement with the detailed finite element simulations of Mikulencak and Morris¹⁰⁷ (see Fig. 9). Simulations for two-particle systems give similarly accurate stress predictions, in agreement with Stokesian dynamics calculations, provided that the surface-to-surface distance between the particles is larger than the grid spacing. When this condition is violated, we cannot expect the SP method to correctly account for the lubrication forces. However, if required, such lubrication corrections can be directly incorporated into the inter-particle interactions.¹¹¹ The results for rigid linear bead chains are also in good agreement

with theoretical predictions and SD simulations, allowing us to reproduce Jeffery's orbits, as well as the time-varying particle contribution to the stress.¹¹² Simulations of Brownian flexible and rigid bead chains have revealed a tumbling motion, with a frequency F that depends only on Pe , following $F \propto Pe^\alpha$, and which exhibits a crossover between Brownian $\alpha = 2/3$ and shear-flow $\alpha = 1$ dominated behaviour.⁴⁸ Furthermore, this transition in the tumbling frequency is shown to correspond to the transition between shear thinning and the second Newtonian regime,⁵⁰ as first predicted by Hinch and Leal.^{113,114}

3.3.3 Rheology of non-dilute suspensions. To understand the relationship between the non-Newtonian viscosity of spherical particle dispersions and the underlying microstructural changes, we report simulation results over a wide range of volume fractions $\phi \lesssim 0.56$ and Peclet numbers $Pe = 6\pi\eta_f a^3 \dot{\gamma} / k_B T$ ($10^{-2} < Pe < 10$). For low to intermediate particle volume fractions $\phi \lesssim 0.3$, the viscosities are constant over the examined range of Peclet numbers, signalling Newtonian behaviour. However, for higher volume fractions ($\phi \gtrsim 0.4$), shear-thinning behaviour is obtained, with a sharp decrease in the viscosity at high Peclet numbers. The low- and high-shear limiting viscosities (shown in Fig. 9), both monotonically increasing functions of volume fraction, are in good agreement with the semi-empirical Krieger–Dougherty relationship. Analysis of the structural relaxation time τ_p , defined as the time required for the Brownian particles to diffuse a distance equal to their radius, shows that shear thinning starts at approximately $\tau_p \dot{\gamma} \sim 1$, reminiscent of the non-Newtonian behaviour of supercooled liquids.¹¹⁵ Furthermore, to study the viscoelastic properties, we also consider an oscillatory

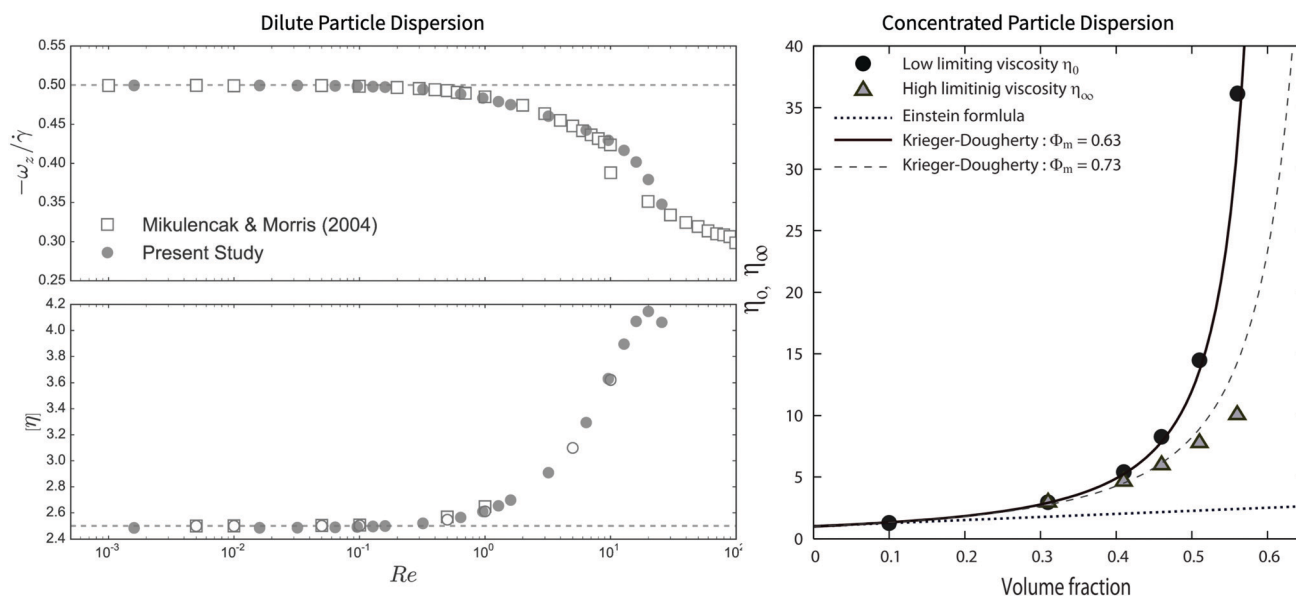


Fig. 9 (left) Angular velocity ω_z and intrinsic viscosity $[\eta]$ of a single spherical particle as a function of Re . Filled symbols are from SP method simulations using Lees–Edwards boundary conditions, with a particle radius-to-system size ratio of $\varepsilon/L = 0.0625$; open symbols are from the finite element simulations of Mikulencak and Morris,¹⁰⁷ for $\varepsilon = 0.01$ (squares) and $\varepsilon = 0.1$ (circles). (right) SP method results, with $\varepsilon = 0.0625$ and $10^{-3} \lesssim Re \lesssim 1$, under zig-zag shear for the low-shear η_0 - and high-shear η_∞ -limiting viscosity of concentrated particle dispersions as a function of the particle volume fraction. Solid and dashed lines show the fits to the data using the Krieger–Dougherty relations, with Φ_M being the packing volume fraction at which the viscosity diverges. The left figure is reproduced from *J. Fluid Mech.*, **792**, 590–619,⁵¹ Copyright 2016, with permission from Cambridge University Press. The right figure is reproduced from *Phys. Rev. E*, **80**, 061402,⁴⁶ Copyright 2009, with permission from the American Physical Society.



shear flow and measure the storage and loss moduli, which are shown to be in excellent agreement with experimental data.⁴⁷

3.4 Colloids in compressible media

In this section, we review our studies on the propagation of hydrodynamic interactions using the SP method,^{12,13} which can be applied to both compressible and incompressible fluids.⁶¹ Considering the fluid compressibility allows us to capture the sound propagation. We consider a two-particle system in a compressible fluid and investigate the correlated motion of the particles. In particular, we estimate the velocity relaxation of the particles in response to the application of an impulsive force on one of the particles.

In contrast to incompressible fluids, for which the speed of sound is infinite and the hydrodynamic interactions propagate instantaneously, followed by a temporal evolution due to viscous diffusion, in compressible fluids the sound propagates at finite speeds. This difference strongly affects the time evolution of the hydrodynamic interactions. To quantify the relative importance of the sound propagation, compared to the viscous diffusion, we define the compressibility factor ε as

$$\varepsilon = \frac{\tau_c}{\tau_\nu} = \frac{\nu}{ac} \quad (41)$$

where $\tau_\nu = a^2/\nu$ and $\tau_c = a/c$ are the time-scales associated with the viscous diffusion and sound propagation over a distance equal to the particle size, respectively.

The fluid dynamics is now governed by the following hydrodynamic equations:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0, \quad (42)$$

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \nabla \cdot (\rho \mathbf{u} \mathbf{u}) = \nabla \cdot \boldsymbol{\sigma} + \phi \mathbf{f}_p, \quad (43)$$

where $\rho(\mathbf{r}, t)$ and $\mathbf{u}(\mathbf{r}, t)$ are the fluid mass density and velocity fields, respectively. The stress tensor is given by

$$\boldsymbol{\sigma} = -p\mathbf{I} + \eta[\nabla \mathbf{u} + (\nabla \mathbf{u})^T] + \left(\eta_\nu - \frac{2}{3}\eta \right) (\nabla \cdot \mathbf{u})\mathbf{I}, \quad (44)$$

where $p(\mathbf{r}, t)$ is the pressure, η is the shear viscosity, and η_ν is the bulk viscosity. As before, a body force $\phi \mathbf{f}_p(\mathbf{r}, t)$ is added to the Navier–Stokes equation in order to satisfy the particle rigidity constraint. We consider a barotropic fluid with $p = p(\rho)$ and assume a constant speed of sound c , such that

$$\frac{dp}{d\rho} = c^2. \quad (45)$$

Eqn (42)–(45) constitute a closed system of equations for the variables ρ , \mathbf{u} , and p , without consideration of the conservation of energy.

We perform 3D simulations for two spherical particles ($a = 4$), labelled 1 and 2, in a cubic simulation box ($L = 256$), under periodic boundary conditions, for various compressibility factors. At $t = 0$ an impulsive force is exerted on particle 2, and their correlated motions are analyzed in order to characterize the hydrodynamic interactions between them. The cross-relaxation

tensor γ_{12} is defined as the normalized change in the velocity of particle 1:

$$V_1(\mathbf{R}_1, t; \mathbf{R}_2) = \frac{\mathbf{P}_2}{m} \cdot \gamma_{12}(\mathbf{R}, t), \quad (46)$$

$$\gamma_{12}(\mathbf{R}, t) = \gamma_{12}^{\parallel}(\mathbf{R}, t) \hat{\mathbf{R}} \hat{\mathbf{R}} + \gamma_{12}^{\perp}(\mathbf{R}, t) (\mathbf{I} - \hat{\mathbf{R}} \hat{\mathbf{R}}). \quad (47)$$

where \mathbf{P}_2 is the impulsive force exerted on particle 2 at $t = 0$. The cross-relaxation tensor can be characterized through its components along only two directions of motion, parallel and perpendicular to the center-to-center vector \mathbf{R} . From the fluctuation–dissipation theorem, the cross-relaxation tensor is equivalent to the velocity cross-correlation function of the fluctuating system:

$$\gamma_{12}(\mathbf{R}, t) = \frac{m}{k_B T} \langle V_1(0, 0) V_2(\mathbf{R}, t) \rangle, \quad (48)$$

We examine both the parallel correlation γ_{12}^{\parallel} and the perpendicular correlation γ_{12}^{\perp} by adjusting the direction of the impulsive force \mathbf{P}_2 . We consider two cases, one in which the impulse is applied perpendicular to the line connecting the centre of mass of the particles and one in which it is parallel and pushes the particles apart. The velocity fields around the particles at $t/\tau_\nu = 6.25 \times 10^{-1}$, separated by $R^* = 7$, are shown in Fig. 10, for compressibility factors of $\varepsilon = 0.1$ and 0.6. An expanding doublet flow, with a strength given by the divergence of the velocity field $\nabla \cdot \mathbf{u}$, is observed. In the case of a small compressibility $\varepsilon = 0.1$, the doublet flow has just arrived at the left particle at this time. In contrast, for the large compressibility $\varepsilon = 0.6$, the doublet flow has not yet arrived at the left particle. Further discussions on the effect of compressibility on the velocity cross-correlation between two particles (γ_{12}^{\parallel} and γ_{12}^{\perp}) are found in our earlier paper.⁶²

3.5 Particles in multi-phase fluids

3.5.1 A model for ternary systems. We now consider the adsorption of solid particles at the fluidic interface of moving droplets, which is relevant to many industrial processes, including the stabilization of emulsions and foams,¹¹⁶ the armoring of droplets in capillary tubes,¹¹⁷ and the recovery of mineral particles by rising gas bubbles.^{118,119} The encapsulation of air bubbles in seawater presents another striking example in which the addition of solid particles dramatically changes the dynamics of these multi-phase systems.¹²⁰ Performing DNS of such a ternary, fluid–fluid–particle system is challenging due to the complexity of capturing all the relevant physical mechanisms, including capillary effects, three-phase flow hydrodynamics, and inter-particle interactions. Most studies have focused on the dynamics of single particles trapped at planar fluidic interfaces^{121–123} or at the fluidic interface of an immobile spherical droplet.^{124,125}

Consider a ternary system in which solid particles are dispersed in a binary fluid mixture. A schematic representation of this setup is given in Fig. 11. The field $\phi(\mathbf{x}, t)$ will denote the volume fraction of the solid constituent at position \mathbf{x} and time t . The binary fluid mixture will separate into its two immiscible fluid constituents, ‘‘A’’ and ‘‘B’’. Constituent A represents the



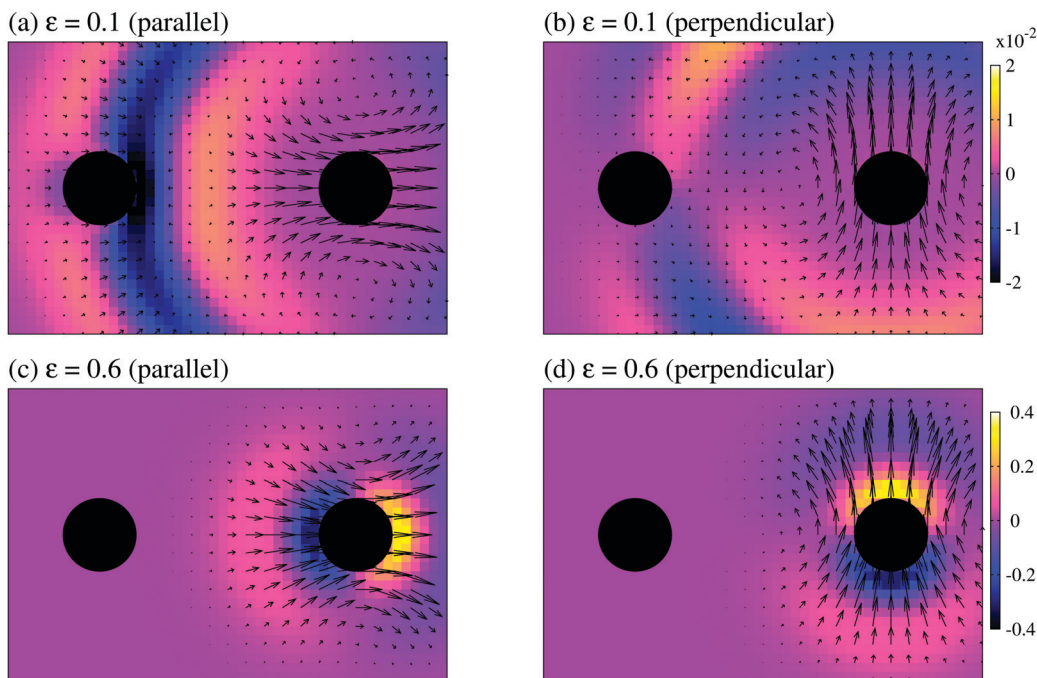


Fig. 10 Velocity field around particles in a compressible fluid after the application of an impulsive force on the right particle in the parallel (a and c) or perpendicular (b and d) direction. Simulation results at $t/\tau_v = 6.25 \times 10^{-1}$ for compressibility factors with values (a and b) $\varepsilon = 0.1$ and (c and d) $\varepsilon = 0.6$. The divergence of the velocity field $\nabla \cdot v$ is described by a colour scale extending from negative (darker) to positive (lighter) divergence. The value of divergence is normalized by τ_v/Re_p . Reproduced from *Phys. Fluids*, **25**, 046101,⁶² Copyright 2013, with the permission of AIP Publishing.

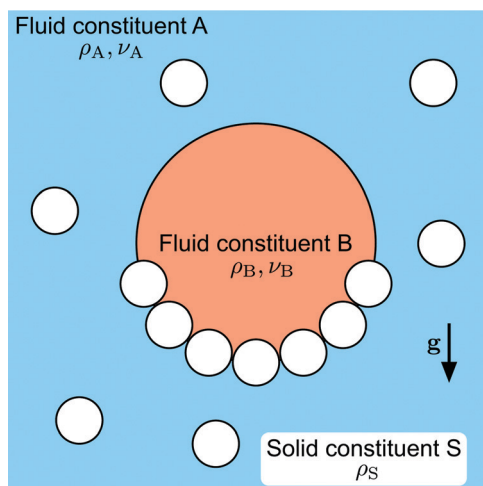


Fig. 11 Schematic representation of a reference ternary system, showing a fluid (B) droplet rising in the host fluid (A). The solid particles (S) adsorb at the fluidic interface of the binary fluid. Reproduced from *Phys. Rev. Fluids*, **3**, 094002,⁶⁸ Copyright 2018, with permission from the American Physical Society.

host fluid, whereas constituent B represents the fluid inside the droplet phase. The volume fractions of the two fluid constituents are denoted as $\phi_A(\mathbf{x}, t)$ and $\phi_B(\mathbf{x}, t)$. The separation of the binary fluid mixture into A and B phases is driven by the minimisation of the following free energy functional:

$$\mathcal{F} = \frac{k_B T_0}{v_0} \int_{\mathcal{V}} f(\phi_A, \phi_B, \phi) d\mathbf{x}, \quad (49)$$

where \mathcal{V} denotes the spatial extent of our ternary system, k_B is the Boltzmann constant, T_0 is the reference temperature, v_0 is the reference unit volume, and f is the non-dimensional free energy density. The variables (ϕ , ϕ_A , and ϕ_B) in the free energy density f are usually referred to as “order parameters”.¹²⁶ Because the sum total of the volume fractions is constrained to be unity $\phi_A + \phi_B + \phi = 1$, the free energy density can be conveniently recast as a function of only two order parameters, which we take to be $\psi = \phi_A - \phi_B$ and ϕ . For simplicity, we refer to ψ as “the” order parameter and ϕ as the particle or fibre (*i.e.*, bead-chain) volume fraction. Consistent with previous studies,^{127,128} we adopt the following form for the free energy densities of the mixture:

$$f(\psi, \phi) = f_0(\psi) + f_1(\psi, \phi) + \frac{\xi^2}{2} |\nabla \psi|^2, \quad (50)$$

$$f_0(\psi) = \frac{1}{4} (1 - \psi^2)^2, \quad (51)$$

$$f_1(\psi, \phi) = \frac{3}{2} \phi^2 (\psi - \psi^*)^2, \quad (52)$$

where $f_0(\psi)$ is a double well function with minima at $\psi = -1$ and $\psi = +1$, $f_1(\psi, \phi)$ is an energy penalty introduced to impose $\psi = \psi_0$ inside the particles, ψ^* is a control parameter that sets the affinity of the beads to the fluid phases, and ξ is the interfacial thickness defined in eqn (19).

The bulk term $f_b = f_0 + f_1$ is a function with a single minimum located at $\psi = \psi_0$ inside the particle domain (see Fig. 12). This bulk term ensures that $\psi = +1$ in fluid A, $\psi = -1$ in



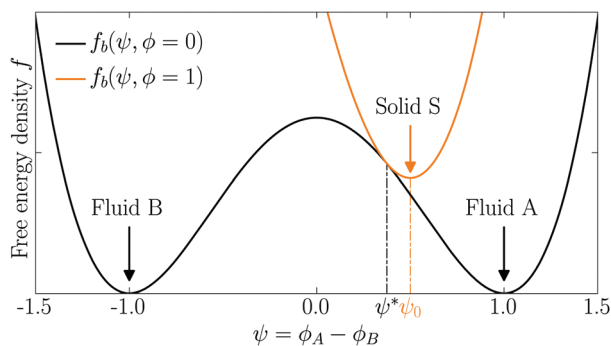


Fig. 12 Bulk free energy density $f_b = f_0 + f_1$. Reprinted from *J. Comp. Phys.*, **409**, G. Lecrivain, T. B. P. Grein, R. Yamamoto, U. Hampel, and T. Taniguchi, Eulerian/Lagrangian formulation for the elasto-capillary deformation of a flexible fibre,⁶⁹ 109324, Copyright 2020, with permission from Elsevier.

fluid B, and $\psi = \psi_0$ in each solid bead. The last term in eqn (50), $\xi^2 |\nabla \psi|^2 / 2$, gives an excess energy contribution across each diffuse interface. We note that the control parameter ψ^* and the position of the single well minimum ψ_0 are dependent on each other. At equilibrium, $\delta f_b / \delta \psi = 0$, which results in the following dependency:

$$\psi^* = \frac{2\psi_0 + \psi_0^3}{3}. \quad (53)$$

As suggested by Araki and Tanaka,¹²⁹ imposing $\psi = \psi_0$ inside the solid domain determines the bead affinity. A positive value $\psi^* > 0$ results in a stronger affinity to fluid A, whereas $\psi^* < 0$ results in a stronger affinity to fluid B, and $\psi^* = 0$ results in an equal affinity to the two fluid phases. In fact, for the special case when $\psi^* = 0$, it can be shown that the bulk driving force term $\delta f_b / \delta \psi$ coincides with that suggested by Kim,¹³⁰ resulting in a factor of 3/2 for the f_1 term in eqn (52). We stress the fact that ψ^* is an input parameter, while ψ_0 is an output parameter. In all the simulations we have performed, the value of ψ_0 coincides exactly with the theoretical prediction of eqn (53). Because it is straightforward to verify that $\psi = \psi_0$ from a contour of the order parameter, we only specify the value of ψ_0 in what follows.

The order parameter $\psi(x, t)$ is updated in time following a modified Cahn-Hilliard equation:

$$\frac{\partial \psi}{\partial t} + \mathbf{u} \cdot \nabla \psi = M \nabla^2 \mu_\psi \quad (54)$$

where M is the mobility of the binary fluid, \mathbf{u} is the velocity field, and $\mu_\psi = \delta \mathcal{F} / \delta \psi$ is the chemical potential associated with the order parameter ψ .

We use the SP method to solve for the coupled hydrodynamics and particle dynamics. For the type of system we are interested in, namely the deformation of flexible fibres, capillary effects provide the dominant contributions. Since a mismatch in the fluid densities or viscosities would only alter the transient dynamical behavior, but not the equilibrium steady-states, we will only consider the case of low-Reynolds number flows with equal densities and viscosities for all

constituents, such that $\rho_A = \rho_B = \rho$ and $\eta_A = \eta_B = \eta$. As such, the two volume fractions of the pure fluid phases, ϕ_A and ϕ_B , are not directly needed for our implementation. The total fluid velocity, satisfying the incompressibility condition $\nabla \cdot \mathbf{u} = 0$, is advanced in time by solving the following modified Navier-Stokes equation:

$$\rho \frac{\partial \mathbf{u}}{\partial t} = -\nabla p + \eta \nabla^2 \mathbf{u} + \rho \phi \mathbf{f}_p - \psi \nabla \mu_\psi - \phi \nabla \mu_\phi, \quad (55)$$

where $\phi \mathbf{f}_p$ is again the penalty term that enforces the rigid-body constraints on the beads and $\mu_\phi = \delta \mathcal{F} / \delta \phi$ is the chemical potential with respect to the fibre volume fraction ϕ . The last source term $\phi \nabla \mu_\phi$ is motivated by the ternary fluid studies of Boyer *et al.*,¹³¹ but our tests show that it is only necessary to improve the stability of the solution in 2D. For 3D simulations, remarkable agreement with theory can be achieved without it.⁶⁸

3.5.2 Elasto-capillary deformation of a fibre. For simplicity, we have solved the equations in their non-dimensional form, using the Reynolds number Re , the Weber number We , the Peclet number Pe , and the elasto-capillary number Ec , defined as

$$Re = \frac{\rho_0 U_0 L_0}{\eta_0} \quad (56)$$

$$We = \frac{\rho_0 U_0^2 L_0}{\sigma_0} \quad (57)$$

$$Pe = \frac{U_0 L_0}{D_0} \quad (58)$$

$$Ec = \frac{k_0}{\sigma_0} \quad (59)$$

where $\rho_0 = \rho$, $\eta_0 = \eta$, $L_0 = \Delta$, and U_0 are the reference density, viscosity, length and velocity scales, respectively. Here U_0 can be the terminal velocity of a single particle in the reference/host fluid. The diffusion coefficient is defined as $D_0 = e_0 M$, where $e_0 = k_B T_0 / v_0$ is the reference free energy density of eqn (49). The reference surface tension is given by $\sigma_0 = e_0 L_0$. The term k_0 is a measure of the fibre stiffness, with the axial beam force between adjacent beads at a separation r given by $|F^b(r)| = k|(r - 2a)|$. The two limiting cases of $Ec = 0$ and $Ec \rightarrow \infty$ correspond to independent (non-attached) beads and a fully rigid fibre, respectively.⁶⁹ We find that the dynamics of the ternary system is particularly sensitive to the ratio of the Weber number to the Reynolds number We/Re . For $We/Re \gtrsim 1$, we observe large amplitude oscillations in the motion of the fibre at the A/B fluidic interface, which can require long simulation times to reach equilibrium. For this reason, in what follows we set this ratio to be $We/Re \simeq 10$.

We report on simulations to study the capillary-induced tumbling of a fibre in a stratified fluid, which allow us to assess the validity of our ternary fluid model by checking the equilibrium orientation. We consider a stagnant fluid with no externally imposed flow, such that the fibre rotation is driven solely by the capillary effects at the three-phase contact line. Fig. 13 shows simulation snapshots illustrating the capillary-induced tumbling



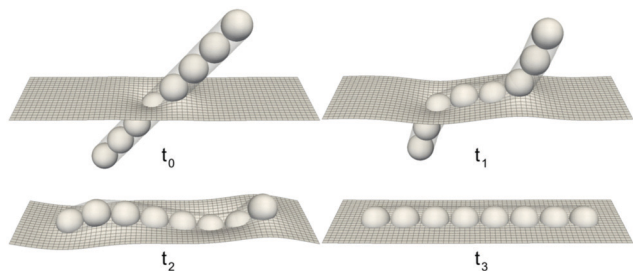


Fig. 13 Capillary-induced tumbling of a flexible fibre in a 3D stratified system. Reprinted from *J. Comput. Phys.*, **409**, G. Lecrivain, T. B. P. Grein, R. Yamamoto, U. Hampel, and T. Taniguchi, Eulerian/Lagrangian formulation for the elasto-capillary deformation of a flexible fibre,⁶⁹ 109324, Copyright 2020, with permission from Elsevier.

of a flexible fibre with equal affinity to the two fluid constituents in a stratified 3D system. The A/B fluidic interface is represented by the $\psi = 0$ isosurface, drawn here using a wire-frame representation. These results are obtained for a fiber with the number of beads $N_b = 8$, bead radius $r_b = 6$, particle interfacial thickness $\zeta = 2\Delta$, in a rectangular system of size $120 \times 120 \times 32$, under periodic boundary conditions. The Reynolds, Weber, Peclet, and elasto-capillary numbers are $Re = 0.02$, $We = 0.1$, $Pe = 1$, and $Ec = 10$, respectively. Further simulations can be found in ref. 69.

Next, we have considered the bending of a fibre at the interface of a fluid droplet. At time $t = 0$, the droplet is initialised to a sphere filled with the fluid constituent A, that is, $\psi = 1$. Fig. 14 shows the simulation snapshots of the equilibrium solutions, for a fibre with an equal affinity to both fluid constituents, $\psi_0 = 0$. The droplet is represented by the $\psi = 0$ isosurface. Details regarding the unsteady dynamics leading up to the encapsulation process can be found in ref. 69. These results are obtained with $N_b = 10$, $r_b = 6$, $\zeta = 2\Delta$, $Re = 0.02$, $We = 0.1$, $Pe = 1$, for a system size of $128 \times 120 \times 120$.

3.6 Electrophoresis of charged colloids

3.6.1 A model for charged colloidal dispersion. The dynamics of charged colloidal dispersions is crucial to many physical, chemical, and biological systems, as well as of great importance for the engineering field.¹ Among them, the electrophoresis of charged colloidal particles is one of the most

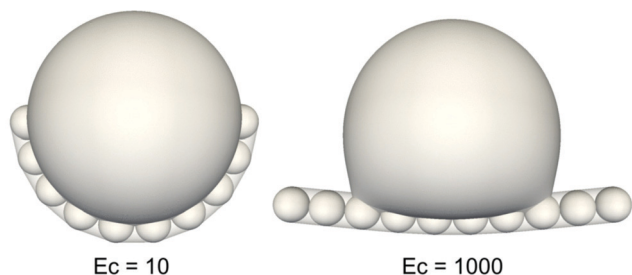


Fig. 14 3D equilibrium solutions of droplet encapsulation for high values of Ec . Reprinted from *J. Comput. Phys.*, **409**, G. Lecrivain, T. B. P. Grein, R. Yamamoto, U. Hampel, and T. Taniguchi, Eulerian/Lagrangian formulation for the elasto-capillary deformation of a flexible fibre,⁶⁹ 109324, Copyright 2020, with permission from Elsevier.

salient examples. When a charged particle is placed in an electrolyte solution, it will develop an electric double layer (EDL), as a cloud of counter-ions is attracted to the surface of the particle. Upon the application of an external electric field, this charged particle will move with an electrophoretic mobility determined by the balance between the electrostatic driving force and the hydrodynamic frictional force acting on the particle. This mobility will depend strongly on the EDL whose distribution becomes anisotropic due to the external field and the friction between the ions and the fluid. The time evolution of the colloidal particles, the ions, and the host fluid are described by the coupled equations for the rigid-body dynamics, hydrodynamics (Navier–Stokes), and electrostatics (Poisson) with the appropriate boundary conditions on the surface of the colloidal particles. We briefly outline our numerical model for such charged colloidal dispersions and how it differs from the standard model discussed in the introduction, and then demonstrate the reliability of the SP method by comparing our numerical results with well-established approximate theories.^{132–135} Finally, the electrophoretic mobilities of dense dispersions, where simulation results deviate from mean-field type theories,^{136,137} as well as the field-induced pearl formation, are presented.

Let us consider N charged spherical particles of total charge Ze (e being the unit charge) distributed uniformly on its surface. We define the spatial distribution of the surface charge to be $eq(\mathbf{r}) = Ze|\nabla\phi|/4\pi a^2$, with ϕ being the SP function. The particles are dispersed in a host fluid containing ions of species α , with charges $Z_\alpha e$. The local number density of the α -th ionic species is $C_\alpha(\mathbf{r}, t)$ at time t , and the total charge density is smoothly defined over the entire domain by $\rho_c(\mathbf{r}) \equiv \sum_\alpha Z_\alpha e C_\alpha + eq$. The complete dynamics of the system is obtained by solving the following time evolution equations.^{12,13}

(i) The Navier–Stokes equation:

$$\rho(\partial_t + \mathbf{v} \cdot \nabla) \mathbf{v} = -\nabla p + \eta \nabla^2 \mathbf{v} - \rho_e \nabla(\Psi + \Psi_{ex}) + \phi \mathbf{f}_p, \quad (60)$$

with the incompressibility condition $\nabla \cdot \mathbf{v} = 0$, where $\Psi_{ex} = -\mathbf{E} \cdot \mathbf{r}$ is the electrostatic potential due to the imposed external electric field \mathbf{E} . The electrostatic potential $\Psi(\mathbf{r})$ is determined by solving the Poisson equation $\epsilon \nabla^2 \Psi = -\rho_c$ with ϵ being the dielectric constant of the host fluid. For simplicity we consider only dielectrically matched particles, such that $\epsilon_f = \epsilon_p = \epsilon$.

(ii) Newton's and Euler's equations of motions:

$$\dot{\mathbf{R}}_i = \mathbf{V}_i, \quad M_i \dot{\mathbf{V}}_i = \mathbf{F}_i^H + \mathbf{F}_i^c, \quad \mathbf{I}_i \cdot \dot{\mathbf{\Omega}}_i = N_i^H, \quad (61)$$

We include all the electrostatic interactions, which consist of the driving from the external electric field \mathbf{E} , as well as the forces due to the distribution of charges in the system, in \mathbf{F}_i^H .

(iii) Advection–diffusion equation:

$$\partial_t C_\alpha^* = -\nabla \cdot C_\alpha^* \mathbf{v} + f_\alpha^{-1} \nabla \cdot ((\mathbf{I} - \mathbf{nn}) \cdot C_\alpha^* \nabla \mu_\alpha), \quad (62)$$

where f_α is the ionic friction coefficient, \mathbf{I} is the unit tensor, and \mathbf{n} is a unit-vector field defined by $\mathbf{n} = -\nabla\phi/|\nabla\phi|$. In our method, the physical ionic density fields are actually $C_\alpha(\mathbf{r}, t) = (1 - \phi(\mathbf{r}, t))C_\alpha^*(\mathbf{r}, t)$, which are defined using the auxiliary density field $C_\alpha^*(\mathbf{r}, t)$. This definition explicitly avoids the



penetration of ions into the colloidal domains without using any artificial potentials, which would require smaller time increments. The operator $(\mathbf{I} - \mathbf{nn})$ in eqn (62) ensures the conservation of C_α by enforcing the no-penetration condition, as $\mathbf{n} \cdot \nabla \mu_\alpha = 0$ is directly assigned at the diffuse particle interface. In this way the total charge neutrality $\int \rho_e d\mathbf{r} = 0$ of the system is guaranteed. The chemical potential is defined as^{138,139}

$$\mu_\alpha = k_B T \ln C_\alpha^* + Z_\alpha e (\Psi + \Psi_{\text{ex}}), \quad (63)$$

If we set $\mathbf{v} = 0$ in eqn (62), the equilibrium ($t \rightarrow \infty$) ionic density corresponds to the Boltzmann equation:

$$C_\alpha^* = \bar{C}_\alpha \exp[-Z_\alpha e (\Psi + \Psi_{\text{ex}})/k_B T]. \quad (64)$$

The bulk salt concentration \bar{C}_α is related to the Debye screening length $\kappa^{-1} = 1 / \sqrt{4\pi\lambda_B \sum_\alpha Z_\alpha^2 \bar{C}_\alpha}$, where $\lambda_B = e^2/4\pi\epsilon k_B T$ is the Bjerrum length, which is approximately 0.72 nm in water at 25 °C.

Simulations are performed in a 3D cubic box, of length $L = 64\Delta$ ($\Delta = 4\pi\lambda_B$ is the grid spacing and our unit of length), under periodic boundary conditions. We use spherical particles of radius $a = 5$ and interfacial thickness $\xi = 2$. The host fluid contains a 1:1 electrolyte composed of monovalent counterions ($\alpha = +$) and co-ions ($\alpha = -$). The units of energy and electrostatic potential are $k_B T$ and $k_B T/e$, respectively. The non-dimensional mobility parameter $m_\alpha = 2\epsilon k_B T f_\alpha / 3\eta e^2$ is set to be $m_+ = m_- = 0.184$, which corresponds to that of KCl solution at 25 °C. Finally, our unit of time $\tau = \Delta^2 f_+ / k_B T$ would correspond to 0.44 μs .

3.6.2 Electrophoresis of charged colloids. We first consider a single charged particle moving with velocity $\mathbf{V} = (-V, 0, 0)$ under a constant external electric field $\mathbf{E} = (E, 0, 0)$. The electrophoretic mobility V/E as a function of the zeta potential ζ , defined as the electrostatic potential on a slipping plane, is given by

$$V/E = f\epsilon\zeta/\eta \quad (65)$$

in the limit when ζ is small.¹ The Smoluchowski equation, corresponding to $f = 1$, is valid in the limiting case when $\kappa a \rightarrow \infty$,¹³² while the Hückel equation, corresponding to $f = 2/3$, is valid in the opposite limit of $\kappa a \rightarrow 0$.¹³³ An expression for $f = f_H(\kappa a)$ that is valid for an arbitrary κa has been derived by Henry.¹³⁴ These equations all predict a mobility that is proportional to ζ ; however, this is not true for large values of ζ , when the relaxation effects due to deformation of the EDL can no longer be neglected. O'Brien and White have proposed an approximate theory that is also valid for larger values of ζ .¹³⁵

We perform simulations for the electrophoresis of a single particle in the linear response regime $E \lesssim 0.15$ and compare their results with the O'Brien–White theory. A constant uniform electric field of magnitude $E = 0.1$ is applied. The terminal velocity V is calculated as a function of the charge on the particle, for $50 \leq -Z \leq 750$, with $\kappa^{-1} = 10$, which would correspond to a salt concentration of 11 $\mu\text{mol l}^{-1}$ at 25 °C in water. In particular, we set the surface charges to be $Z = -50$,

-100 , -200 , -300 , -400 , -500 , and -750 , corresponding to a dimensionless zeta potential of $y \equiv e\zeta/k_B T = 0.525, 1.044, 2.035, 2.927, 3.692, 4.332, \text{ and } 5.510$, respectively. We choose $\nu = \eta/\rho = 5$ to maintain a small Reynolds number $\text{Re} = aV/\nu$. In our simulations, as well as the O'Brien–White theory, the zeta potential is assumed to be the electrostatic potential at the particle surface, $\zeta = \Psi|_{\text{surface}}$. Our simulation results are in excellent agreement with the O'Brien–White theory, even in the non-linear regime $y \geq 2$, with an error of only a few percent.³¹ This agreement is unprecedented when compared to alternative simulation methods at this level of description.

Our simulation method applies just as easily to dense dispersions, allowing us to examine the effect of particle concentration on the electrophoretic mobility. The linearized theory for the mobility of a single particle, as described by eqn (65), is still valid for dense dispersions, as long as E is small; however, f now depends on both κa and ϕ . Simulations for $Z = -100$ and $E = 0.1$, at various particle volume fractions $\phi \equiv 4\pi a^3 N/3L^3$, are performed to measure the value of $f(\kappa a, \phi) = \eta V/e\zeta E$. We consider Debye lengths κ^{-1} of 5 and 10, which correspond to $\kappa a = 1$ and 0.5, and salt concentrations of 44 $\mu\text{mol l}^{-1}$ and 11 $\mu\text{mol l}^{-1}$, respectively. Fig. 15 shows typical simulation snapshots for systems with $\kappa a = 1$ and (a) FCC, (b) BCC, and (c) random particle configurations.¹⁴⁰ The colour map indicates the charge density, shown over a cross-sectional slab perpendicular to the z -axis. In the case of FCC and BCC, E is applied perpendicular to the (1, 0, 0) and (1, 1, 1) faces, but we obtain very small differences in the electrophoretic mobility (within only 1%).

The mobility coefficient $f(\kappa a, \phi)$ for $\kappa a = 1$ and 0.5 is plotted as a function of ϕ in Fig. 16(a and b), respectively. It is seen that f decreases rapidly with increasing ϕ . Furthermore, we see no significant difference in f with respect to the particle configurations (FCC, BCC, or random). A theoretical model for the electrophoretic mobility based on the cell model has been proposed by Levine and Neale.¹³⁶ For this, they have studied a spherical particle (radius a) at the center of a spherical container or cell (radius b), and calculated the velocity V as a function of κa and $\phi = (a/b)^3$. A similar expression for the mobility coefficient f , also based on this cell model, has been proposed by Ohshima.¹³⁷ Ohshima's prediction is shown in Fig. 16, together with our numerical results. The agreement between our simulations and Ohshima's theory is generally good for small Debye lengths ($\kappa^{-1} = 5 = a$), but shows considerable deviations at large Debye lengths ($\kappa^{-1} = 10$). In both cases, the simulation results predict larger values of f than Ohshima's theory as ϕ increases. We consider that this deviation arises because of the overlapping of the EDLs for larger ϕ , as this effect is completely neglected in the theory. To test this, we estimate the effective particle radius $a + \kappa^{-1}$ of the ionically dressed particles and define an effective volume fraction $\phi_{\text{eff}} \equiv 4\pi(a + \kappa^{-1})^3 N/3L^3 = (1 + (\kappa a)^{-1})^3 \phi$. Fig. 16 clearly shows that our results agree well with Ohshima's theory for $\phi_{\text{eff}} \leq 1$, where the overlap effect is small. However, for $\phi_{\text{eff}} > 1$, where the degree of EDL overlap is large, deviations between our simulations and the theory are notable. These are the first simulations to



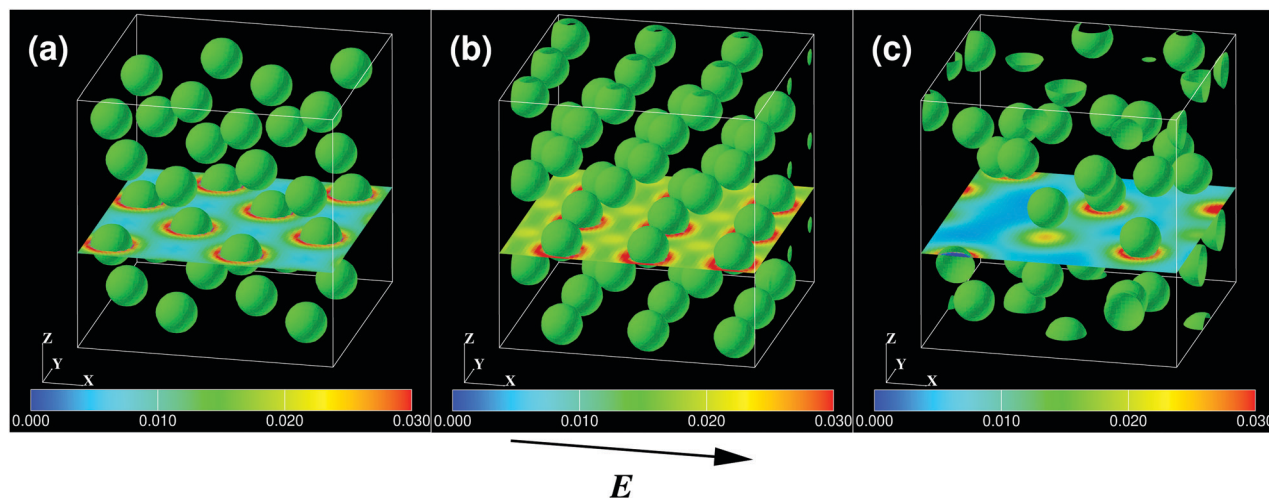


Fig. 15 Simulation snapshots for the electrophoresis of dense dispersions with (a) FCC, (b) BCC, and (c) random particle configurations. The colour map represents the total ionic charge density $\sum_x eZ_x C_x$ in a plane perpendicular to the z -axis. The electric field is applied in the $+x$ direction, normal to the $(1, 0, 0)$ face for the FCC and BCC lattices. Reproduced from *Phys. Rev. Lett.*, **96**, 208302,³¹ Copyright 2006, with permission from the American Physical Society.

provide quantitative data necessary to examine the reliability of Ohshima's theory in dense colloidal dispersions. Our results are consistent with more recent studies that have taken EDL overlap into account.^{141–143}

3.6.3 Field-induced order formation. The field-induced anisotropic interactions between like-charged colloidal particles is studied using the SP method. In particular, we are able to include the polarization of the EDL under external AC electric fields (at frequency ω^*) explicitly. Consider a field that is parallel to the distance vector between two particles, such that the induced dipoles (arising from the polarization of the EDL) are aligned in an end-to-end fashion, with the partial positive charge on one particle attracted to the partial negative charge of its neighbour. This situation is depicted in Fig. 17, where particles in the same row feel an attractive inter-particle force (whereas particles on opposite rows are repelled). If the induced dipoles are strong enough to overcome their Coulombic repulsion, *i.e.*, if the field strength is large enough, the particles will experience an effective attraction. Since this attractive interaction depends on the polarization of the EDL, it will also depend strongly on ζ and κa . For a fixed value of the field strength E_0 , the interaction is attractive for small ζ but repulsive for large ζ . This is due to the fact that at large ζ (high surface potential) more counter-ions are attracted to the charged particle surface, leading to an increase in the charge density around the particle. In turn, this makes the particle more insensitive to external perturbations and more difficult to polarize. In the end, this results in smaller induced dipole-dipole interactions between the particles. Similarly, for thin double layers (large κa) the EDL is more difficult to polarize, compared to thick double layers (small κa), because the counter-ions are more strongly bound to the particle surface. Furthermore, we find that the dynamic response of the colloids and ions is frequency dependent. In particular, we observe two dynamically distinct regimes, corresponding to whether ω^* is

faster or slower than the ionic diffusion rate ω_{κ}^* over the size of the EDL. In the low-frequency regime $\omega^* < \omega_{\kappa}^*$, the polarization of the EDL has enough time to develop in response to the electric field $E(t)$ and can therefore induce a strong inter-particle force. In contrast, in the high-frequency regime $\omega^* > \omega_{\kappa}^*$ the ions cannot follow the field fast enough to fully polarize the EDL. This results in an inter-particle force that decreases with increasing ω^* , up until the point where the system reproduces the results in the absence of an external electric field $E_0 = 0$.

3.7 Colloids in viscoelastic media

In colloidal suspensions in Boger fluids, which are one class of viscoelastic fluids,^{144,145} shear thickening has been experimentally reported even at dilute concentrations.^{146–151} This sharply contrasts with Newtonian media, where shear thickening occurs only in concentrated suspensions. The shear rheology of suspensions in viscoelastic media has been studied by using DNS of many-particle systems, for both 2D¹⁵² and 3D systems^{64,153} under periodic boundary conditions, as well as 3D systems under wall-driven shear flow.^{150,154} Since DNS with surface-conforming meshes^{155–163} have a limit on the number of particles that can be considered, due to the increasing computational costs, DNS using a fluid mesh independent of the moving boundaries (particles)^{64,150,152,153,164–168} and smoothed-particle hydrodynamics (SPH) simulations, which employ a mesh-free method, are more suitable to suspensions in viscoelastic media.¹⁵⁴

To characterize a viscoelastic suspending medium using the SP method, the viscoelastic stress is added to the continuum eqn (11):

$$\rho(\partial_t + u \cdot \nabla)u = \nabla \cdot \sigma + \nabla \cdot \sigma_p + \rho \phi f_p, \quad (66)$$

where σ_p is a “polymer” stress that is governed by a certain constitutive equation.^{169–173} If there is no specific interaction



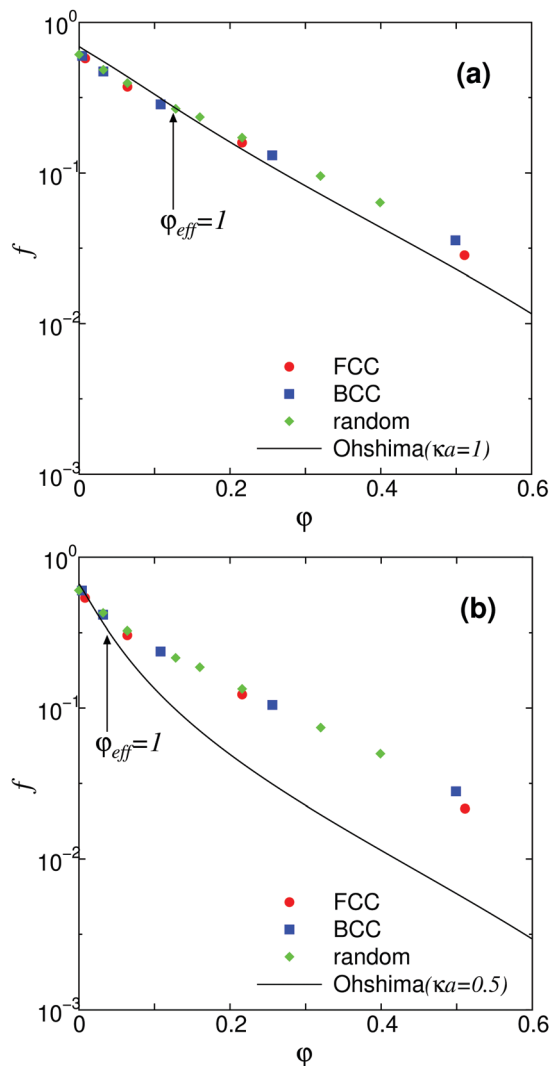


Fig. 16 The mobility coefficient $f(\kappa a, \phi)$ as a function of the volume fraction ϕ for (a) $\kappa a = 1$ and (b) $\kappa a = 0.5$. The solid lines show the results given by the approximate theory proposed by Ohshima.¹³⁷ This theory is confirmed to be accurate for $\phi_{\text{eff}} \leq 1$ but tends to deviate from our numerical results for $\phi_{\text{eff}} > 1$, where the overlap of the EDLs becomes notable. Reproduced from *Phys. Rev. Lett.*, **96**, 208302,³¹ Copyright 2006, with permission from the American Physical Society.

between the polymers in the suspending medium and the solid surface, then $\phi\sigma_p = 0$ holds.

The shear rheology of a suspension in an Oldroyd-B fluid is investigated by using the SP method.^{64,65} The Oldroyd-B model exhibits a shear-rate-independent viscosity and finite elasticity, which serves as a model for Boger fluids. The polymer stress in the single-mode Oldroyd-B fluid is governed by

$$\sigma_p = \frac{\eta_p}{\lambda}(\mathbf{C} - \mathbf{I}), \quad (67)$$

$$(\partial_t + \mathbf{u} \cdot \nabla)\mathbf{C} = (\nabla\mathbf{u})^t \cdot \mathbf{C} + \mathbf{C} \cdot \nabla\mathbf{u} - \frac{\mathbf{C} - \mathbf{I}}{\lambda}, \quad (68)$$

where \mathbf{C} , η_p , and λ are the conformation tensor, polymer viscosity, and relaxation time, respectively. The single-mode

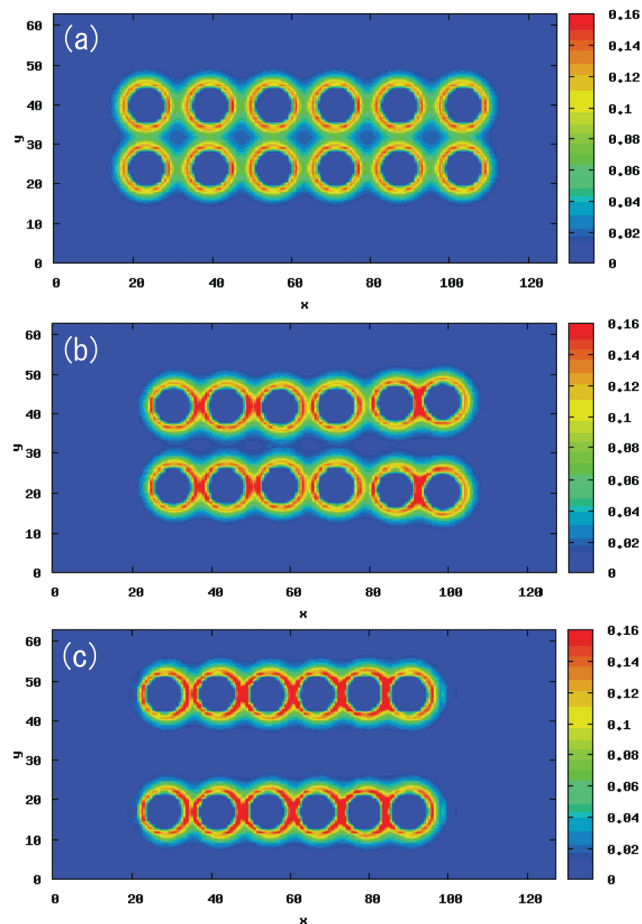


Fig. 17 Simulation snapshots depicting the time evolution of 12 free particles, initially configured as two stacked linear chains aligned parallel to the oscillating electric field, for $\zeta = 0.5$, $\kappa a = 2.5$, $E = 0.3$, and $\omega^* = 0.001$. Assuming a colloidal radius of $1 \mu\text{m}$ and an ionic diffusion constant of $D_x = 2 \times 10^{-9} \text{ m}^2 \text{ s}^{-1}$, the simulation times t correspond to (a) $2.1 \times 10^{-4} \text{ s}$, (b) $1.4 \times 10^{-2} \text{ s}$ and (c) $8.4 \times 10^{-2} \text{ s}$. The colour map represents the charge density. Reproduced from *Soft Matter*, **14**, 4520–4529,³⁴ Copyright 2018, with permission from the Royal Society of Chemistry.

Oldroyd-B fluid is characterized by two non-dimensional parameters, namely, the viscosity ratio $\beta = \eta_s/(\eta_s + \eta_p)$, where η_s is the viscosity in Newtonian stress, and the Weissenberg number $Wi = \lambda\dot{\gamma}$. Suspension flow under simple shear flow is solved under periodic boundary conditions in the same way as described in Section 3.3.1.⁵¹

Since shear thickening in Boger fluid media occurs at dilute concentrations, this thickening is attributed mainly to the interaction between a particle and the viscoelastic stress around the particle. The flow around a particle has been previously examined by different DNS studies.^{64,154,163} Since the flow is forced to circumvent the particle, the direction of the shear flow necessarily changes around the particle. Depending on the conformation orientation, the elastic stress caused by the stretched conformation contributes to an increase in either the macroscopic shear stress or the macroscopic first normal stress difference. Variations in several quantities along a recirculating streamline around a particle at $Wi = 2$ and $\beta = 0.5$ are



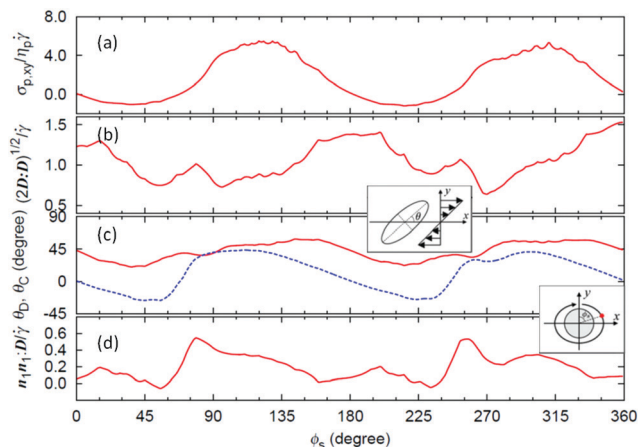


Fig. 18 Variations in several quantities along a recirculating streamline around a particle at $Wi = 2$ and $\beta = 0.5$: (a) the polymer stress normalized by $\eta_p \dot{\gamma}$, (b) the magnitude of the strain-rate tensor normalized by the applied shear rate, (c) the angles of the primary directions of \mathbf{D} (red solid line) and \mathbf{C} (blue dashed line) defined in the left inset, and (d) the effective elongation rate in the primary direction of \mathbf{C} . The abscissa is the clockwise angle ϕ_s from the velocity gradient direction in the xy -plane, depicted in the right inset.

shown in Fig. 18. The location in Fig. 18 is specified by the angle ϕ_s from the velocity gradient direction. When $\sigma_{p,xy}/\eta_p \dot{\gamma} > 1$, the elastic stress contributes to bulk shear thickening (Fig. 18(a)). For elastic thickening to occur, both the strong stretch of the conformation and the appropriate orientation of the conformation are necessary. For the conformation to be stretched, a large shear rate is not necessarily required (Fig. 18(b)), but the alignment of the major axes of the conformation and the strain-rate tensors, *i.e.*, $\theta_C \approx \theta_D$ in Fig. 18(c), is important. The efficiency of the conformation stretch can be evaluated by the effective molecular elongation rate,¹⁷⁴ $\dot{\epsilon}_p = n_1 n_1 : \mathbf{D}$ shown in Fig. 18(d), where n_1 and \mathbf{D} are the primary directions of \mathbf{C} and the strain-rate tensor, respectively.⁶⁴ Furthermore, the flow modulated by a particle is almost irrotational in front of and behind the particles,^{64,154,163} which promotes conformation stretching because the vorticity induced misalignment of \mathbf{C} from \mathbf{D} is suppressed. These effects of a suspended particle do not depend on the particle shape; therefore, elastic thickening is expected to occur even in suspensions of non-spherical particles.

Simulations of multi-particle systems in an Oldroyd-B fluid succeeds in quantitatively reproducing the experimentally measured shear-thickening behaviour with a Boger fluid matrix up to $\varphi \leq 1$ for the first time.⁶⁵

3.8 Dynamics of micro-swimmers

3.8.1 A model for swimming systems. Micro-swimmers, defined as particles that self-propel in a viscous fluid, among which we find spermatozoa, bacteria, and algae, are ubiquitous in biology and life sciences and are one of the main representatives of active matter systems. From a purely theoretical standpoint, the study of active matter presents itself as fertile ground on which to test and develop theories of non-

equilibrium systems. From an applied perspective, particularly with the introduction of synthetic micro-swimmers, there is also the prospect of developing novel medical applications, such as cargo transport systems for targeted drug delivery. However, understanding the role played by hydrodynamic interactions in determining the physical properties of the system remains an incredibly challenging task.¹⁷⁵

We focus here on a generic model for micro-swimmers called squirmers. Originally developed by Lighthill and Blake as a model for the ciliary propulsion of paramecia,^{176,177} this model has become standard for studying the hydrodynamic interactions of rigid micro-swimmers.¹⁷⁸ Instead of modelling the synchronized beating of cilia at the surface, which would result in a computationally prohibitive description, one can reproduce the same effects (at the scale of the particle size) by imposing a prescribed boundary condition at the surface of the rigid particle. Here, we consider only spherical swimmers (radius a), but extensions of the squirmer model to spheroidal particles also exist.^{179,180} Let $\{\tilde{e}_i\}$ denote the ortho-normal basis vectors defining the body-axis reference frame, with $\tilde{e}_3 = \tilde{e}$ being the fixed swimming axis of the particle. A given point on the particle surface is parametrized in terms of the polar (colatitude) θ and azimuthal λ angles, with θ and λ being the corresponding unit tangent vectors, \mathbf{q} the unit vector in the radial direction and $\theta = \arccos \mathbf{q} \cdot \tilde{e}$. The imposed “slip” velocity for the squirmer (assuming zero radial velocity) is¹⁸¹

$$\mathbf{u}^{\text{sq}} = \sum_{n=1}^{\infty} \frac{2}{n(n+1)} B_n P'_n(\cos \theta) \sin \theta \boldsymbol{\theta} + \sum_{n=1}^{\infty} C_n P'_n(\cos \theta) \sin \theta \boldsymbol{\lambda} \quad (69)$$

where P'_n is the derivative of the n -order Legendre polynomial and B_n and C_n are the coefficients for the n -th order polar and azimuthal modes, respectively. Most studies neglect the azimuthal modes ($C_n = 0$) and all polar modes beyond the second order $B_n = 0$ ($n > 2$), as this results in the simplest non-trivial model that can represent both pushers (generating propulsion at the back) and pullers (generating propulsion at the front). In this case, the surface velocity becomes ($\alpha = B_2/B_1$)

$$\mathbf{u}^{\text{sq}}(\theta) = B_1 \left(\sin \theta + \frac{\alpha}{2} \sin 2\theta \right) \boldsymbol{\theta} \quad (70)$$

where B_1 determines the steady-state swimming speed for a single particle in an unbounded fluid ($U = 2/3B_1$) and B_2 is the strength of the stresslet. The ratio of these modes α (also denoted as β in the literature) determines the type of swimmer, with $\alpha > 0$ and $\alpha < 0$ corresponding to pullers and pushers, respectively, and $\alpha = 0$ to the so-called neutral or potential swimmers. A schematic diagram of the squirmer representation for pushers/pullers, together with the different kinds of self-generated flows, is shown in Fig. 19. The nature of swimming strongly affects the hydrodynamics of the generated flow, with the flow generated by neutral swimmers undergoing 3D decay as r^{-3} , while pullers (pushers) generate contractile (extensile) flows with a weaker decay as r^{-2} .¹⁸¹ This has important consequences for collective behaviour, as shown below.



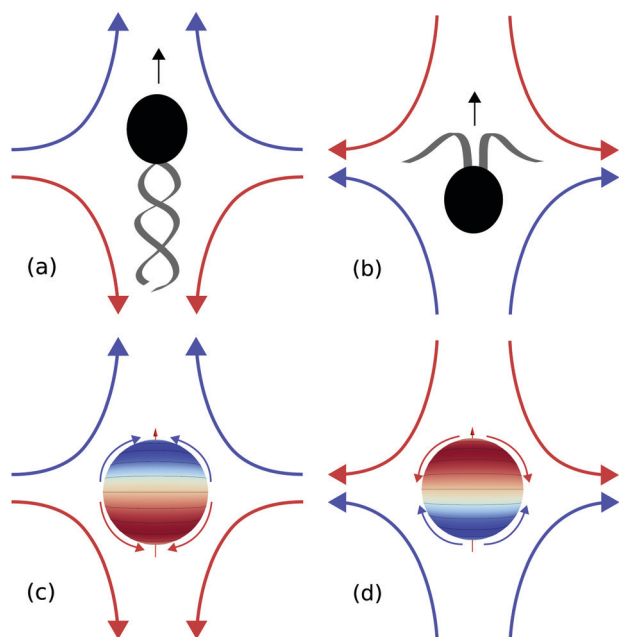


Fig. 19 Schematic representation of the propulsion mechanism and flow profiles of a pusher and a puller (a and b), respectively. These swimmers can be represented using Blake's squirmer model, in which the detailed propulsion mechanism is replaced by a specified slip velocity at the surface of the particles for pushers and pullers (c and d), respectively. Reproduced from *Soft Matter*, 9, 4923–4936,⁵⁴ Copyright 2013, with permission from the Royal Society of Chemistry.

To solve for the hydrodynamics of these micro-swimmer suspensions using the SP method, we introduce an additional constraint force ϕf_{sq} to the continuum eqn (11) to enforce the slip velocity at the surface^{54,58}

$$\rho(\partial_t + \mathbf{u} \cdot \nabla) \mathbf{u} = \nabla \cdot \boldsymbol{\sigma} + \rho \phi \mathbf{f}_p + \rho \phi \mathbf{f}_{sq} \quad (71)$$

To solve this equation, we incorporate an additional step in the fractional-step approach. After updating for the advection and viscous terms and obtaining \mathbf{u}^* , but before enforcing the rigidity constraints through $\phi \mathbf{f}_p$, we solve for the surface constraint force $\phi \mathbf{f}_{sq}$ to obtain an updated velocity field \mathbf{u}^{**} that satisfies the squirmer boundary conditions. For this, we consider an additional SP function ϕ^{sq} , which is non-zero only within the interface domain of the particle

$$\phi_I^{sq} = (1 - \phi_I) \frac{|\nabla \phi_I|}{\max(|\nabla \phi_I|)} \quad (72)$$

The new velocity field can then be obtained as

$$\mathbf{u}^{**} = \mathbf{u}^* + \left[\int_{t_n}^{t_n+h} ds \phi \mathbf{f}_{sq} \right] \quad (73)$$

$$\left[\int_{t_n}^{t_n+h} ds \phi \mathbf{f}_{sq} \right] = \sum_I^N \phi_I^{sq} \left(\mathbf{V}_I^\dagger + \boldsymbol{\Omega}_I^\dagger \times \mathbf{r}_I + \mathbf{u}_I^{sq} - \mathbf{u}^* \right) + \sum_I^N \phi_I (\delta \mathbf{V}_I + \delta \boldsymbol{\Omega}_I \times \mathbf{r}_I) - \frac{h}{\rho} \nabla p_{sq} \quad (74)$$

where the first term is the one that actually fixes the slip boundary conditions, the second term is added to ensure local momentum conservation (*i.e.*, the squirmer experiences a counteracting force if it pushes the fluid at the boundary), and the third term guarantees that the final fluid velocity field is incompressible. Since the updated particle velocities are not yet known at this point of the calculation, we adopt an iterative solution and enforce the slip velocity with respect to \mathbf{V}_I^\dagger (\mathbf{W}_I^\dagger) using the velocities at the previous time step at an initial guess. The hydrodynamic force and torque are computed as before, using \mathbf{u}^{**} instead of \mathbf{u}^* , and used to update the particle velocities. This procedure is iterated to ensure consistency between the velocities \mathbf{V}_I^\dagger used to enforce the slip boundary conditions and the particle velocities at the next time step \mathbf{V}_I^{t+1} . The method has been validated for the motion of a single swimmer, where both the particle velocity and the fluid velocity show good agreement with theoretical predictions.⁵⁴

3.8.2 Self-diffusion of a micro-swimmer. Experiments of tracers in swimming suspensions show that hydrodynamic interactions with swimmers, which continuously stir the fluid, are responsible for enhancing the tracer diffusion (beyond that due to thermal fluctuations).^{182,183} Theoretical predictions based on a kinetic theory approach, as well as simulations and experiments, show that this induced diffusion scales with the flux of swimmers ($\propto U \Phi_{swimmer}$).^{184,185} Early simulations of squirmer suspensions indicated a similar diffusive behaviour for swimmers, but with a diffusion coefficient D_T that decreases with increasing volume fraction ($\propto \Phi_{swimmer}^{-1}$).¹⁸⁶ This difference is due to the distinct dynamics of tracers and swimmers, where the former can move only as a result of interactions with other particles, while the latter propel themselves along straight paths, deviating only when interacting with other particles. These interactions can be either hydrodynamic or steric in nature. The hydrodynamic interactions, which give rise to rapidly decaying velocity fluctuations as the particles respond to the evolving configuration of the system, are expected to similarly affect both tracers and swimmers. This short time scale is given approximately by the average time it takes for a swimmer to move a distance equal to its diameter. In contrast, the velocity fluctuations caused by the steric interactions decay over a time scale determined by the average time between collisions, which can be estimated to be $\propto \Phi_{swimmer}^{-1}$ from kinetic theory arguments. Clearly, the contributions to the dynamics of the swimmers coming from the hydrodynamic interactions are completely masked by their intrinsic motion. This is the reason why the diffusion coefficients of tracers and swimmers show opposite tendencies.¹⁸⁷ However, with a careful choice of reference system, it is possible to define an effective diffusion coefficient for the swimmers \tilde{D}_T , in which the contributions from the particle's self-propulsion have been removed. This effective diffusion is measuring only the contribution from the hydrodynamic interactions. This is done by computing the particle displacements in the rotating body frame and subtracting the average contribution of the swimming motion along \hat{e} . In this way, we can show the correspondence between tracer diffusion



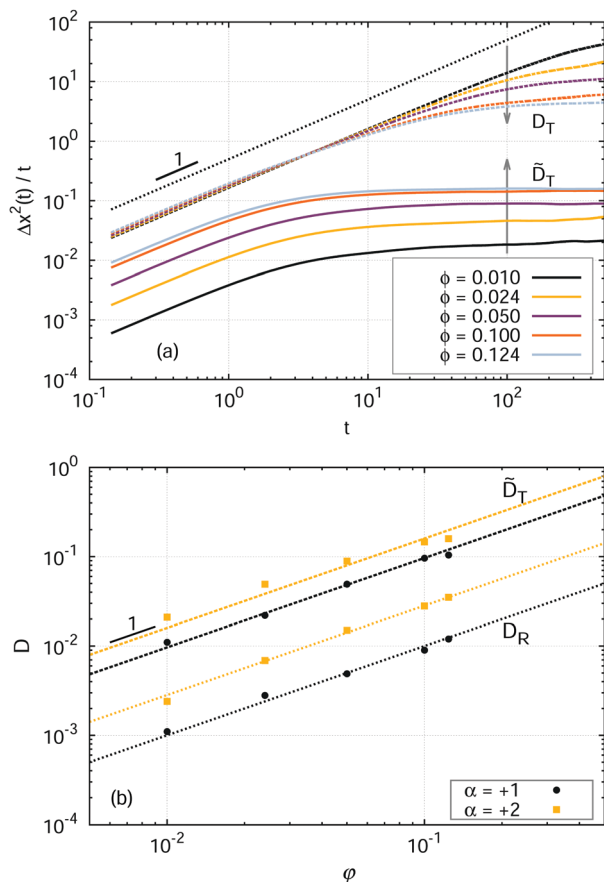


Fig. 20 (top) Mean-squared displacements for a suspension of pullers ($\alpha = +2$) at various volume fractions. Dashed lines show the full mean-squared displacements, as measured in the laboratory frame, while solid lines show the effective mean-squared displacements (after removing the self-propulsion term) in the body frame of the swimmers. (bottom) Effective translational \tilde{D}_T and rotational D_R diffusion coefficients as a function of volume fraction for pullers with $\alpha = +1, 2$. Adapted from *Soft Matter*, **9**, 4923–4936,⁵⁴ Copyright 2013, with permission from the Royal Society of Chemistry.

and (effective) swimmer diffusion (see Fig. 20).^{54,56} At high swimmer concentrations, both factors are essentially the same, while at low concentrations the asymmetry of the flow field generated by the swimmers gives rise to a negative correlation in the tracer velocity (as the swimmer moves past) and thus reduces the diffusion coefficient.

3.8.3 Collective dynamics of micro-swimmers. It is well known that squirmers in bulk fluid tend to exhibit polar order¹⁸⁸ provided $|\alpha|$ is small, with the highest degree of order obtained for $\alpha = 0$. As there are no direct alignment interactions, this collective behaviour is due exclusively to the hydrodynamic interactions among particles. Furthermore, this non-zero polar order is stronger at lower volume fractions, which suggests that it could arise from repeated binary interactions. Indeed, using collision data from dilute simulations, we have computed the transition probabilities for the incoming and outgoing angles of the particles and used them to develop a coarse-grained binary collision model.⁵⁹ Using this simplified representation, we are able to predict the bulk polar order of

swimmer suspensions arising from repeated binary collisions. Our results are in good agreement for dilute suspensions of pushers and neutral swimmers but show large discrepancies for pullers, particularly for intermediate α . This can be explained as a breakdown of the binary collision hypothesis, as these systems are known to form transient dynamic clusters in bulk fluid.¹⁸⁹

In practice, swimmers usually move in complex environments near boundaries or interfaces, which strongly affects their dynamics and the nature of the hydrodynamic interactions.¹⁹⁰ Studies indicate that varying the strength and type of confinement can give rise to dramatically different collective behaviours.^{191,192} Simulations of swimmers between flat parallel walls, with a narrow confinement $\sim 2\sigma$ that results in quasi-2D systems, show that neutral squirmers exhibit dense/dilute phase separation, whereas pushers and pullers tend to exhibit a hexagonal phase.¹⁹³ Even though the hydrodynamics are strongly screened by the walls, the near-field hydrodynamic interactions play a crucial role in the particle alignment, and polar ordering is observed only for neutral particles.⁵⁵ Upon increasing the separation of the wall, squirmers tend to accumulate at the boundary in a manner that depends on the swimmer type.¹⁹¹

We have performed simulations of squirmers under confinement between two flat parallel walls and shown that when the wall separation is large enough ($\geq 40\sigma$, *i.e.*, larger than the characteristic size of the propagating flock), weak pullers develop travelling density waves that bounce back and forth between the walls.⁵⁸ A similar travelling wave-like motion has been reported in systems with explicit alignment interactions between the particles,^{194,195} but our results show that hydrodynamic interactions alone are enough to yield this type of collective behaviour. We observe that the strength and type of swimming (pusher *vs.* puller) are crucial to observe this behaviour but not the degree of global alignment. Furthermore, this behaviour is a manifestation of the bulk behaviour of the suspension and is not due to the presence of walls. This is evidenced by the fact that the velocity of these waves is found to correspond to the sound velocity measured in the bulk fluid, which means that this phenomenon can be interpreted as a pseudo-sound property of the system.

The travelling wave-like motion is illustrated in Fig. 21, where we show simulation snapshots, together with the time evolution of the (local) density ρ , perpendicular polar order parameter Q_1 and velocity v_t , as a function of the height in the channel (computed within parallel slabs of width 2Δ), for a dilute suspension of squirmers (volume fraction of 13%). These simulations are performed in a rectangular simulation box, with periodic boundaries in the x and z directions, but confined between two flat parallel walls along the y direction (at $y = 1\Delta$ and 159Δ). Here, for simplicity, the walls are constructed out of (inert) spherical particles of equal radius to the swimmers, which are pinned in place and unable to move or rotate from their initial configuration. Simulations for various α values are performed, with the most interesting results obtained for weak pullers satisfying $0 < \alpha < 1$. Fig. 21 shows that the pullers with $\alpha = \pm 0.5$ show strong spatiotemporal density fluctuations,



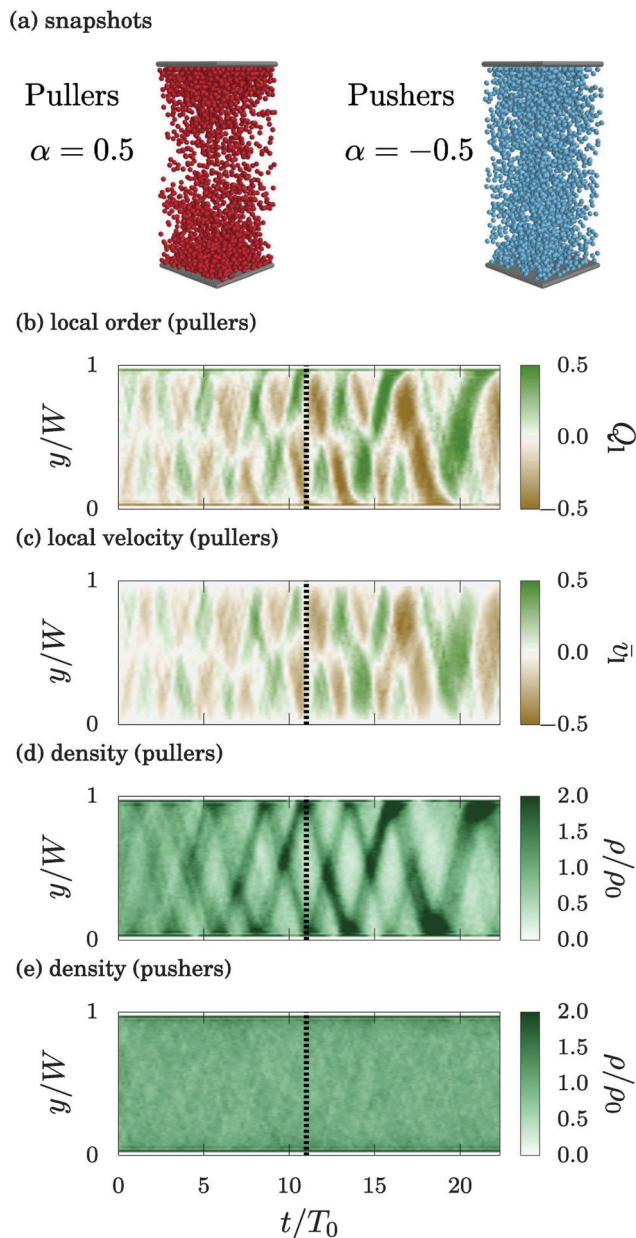


Fig. 21 Simulation results for pullers and pushers ($\alpha = \pm 0.5$) at a volume fraction of 13% and wall separation $W/a = 40$. (a) Simulation snapshots at $T = 11T_0$. (b) local order of pullers defined as $Q_1 = \langle \bar{e}_y \rangle_{\text{plane}}$. (c) local velocity of pullers in the y direction (perpendicular to the walls) defined as $\bar{v}_1 = \langle V_y/U_0 \rangle_{\text{plane}}$. (d and e) plane averaged density for pushers and pullers at each height y/W . The density is normalized by the global average value, ρ_0 , and time and velocity are normalized by $T_0 = W/U_0$ and U_0 , where W represents the separation of parallel flat walls. The snapshots are at approximately $t = 11T_0$, as marked by dashed lines. Reproduced from *Phys. Rev. E*, **93**, 043114,⁵⁷ Copyright 2016, with permission from the American Physical Society.

first developing two waves travelling in opposite directions, before they merge into a single persistent propagating wave, which bounces back and forth between the top and bottom walls. No such behaviour is observed for the pushers. The onset of this nontrivial collective behaviour is due purely to the differences in the hydrodynamic flow fields generated by the

swimmers and their corresponding hydrodynamic interactions, as no direct alignment potential is used.

Recently, we have extended this model to include the rotlet term, in addition to the pusher/puller term, and DNS were performed to study the single particle motion of a swimmer near a flat wall.⁶⁰

4 Conclusions

We have developed the SP method to simulate the motion of hydrodynamically interacting particles in various kinds of host fluids. By utilizing a SP for the particle–fluid boundaries, the hydrodynamic interactions acting between the particles can be fully considered, yielding both accurate and efficient simulations. The reliability and performance of the method were confirmed to be very satisfactory through several critical tests. The SP method can be easily applied to many-particle systems and arbitrarily shaped particles. In the present paper, the high applicability of the SP method was illustrated for various examples of particle suspensions.

For Brownian particles, we have developed a numerical method for consistently implementing the thermal fluctuation in an incompressible host fluid.³⁵ The validity of the method was confirmed by comparing our numerical results against the fluctuation–dissipation theorem for a single spherical system. Simulations for concentrated dispersions, as well as for a polymeric chain, were then performed. For the former, we found that the hydrodynamic long-time tail in the velocity auto-correlation function, which is clearly observed for a single-particle dispersion, becomes weaker as the volume fraction is increased. For the latter case, we found very good agreement with the theoretical predictions of the Zimm model.³⁵ We have also investigated the rate of rapid Brownian coagulation over a range of volume fractions from $\phi = 0.003$ to $\phi = 0.1$. In the dilute regime the rate of rapid Brownian coagulation is reduced to approximately 0.3–0.5 times the theoretical value predicted by Smoluchowski. This is consistent with previous experimental and theoretical results taking the hydrodynamic effects into account. Because we explicitly include the exact hydrodynamic interactions in our simulations, the fact that we can reproduce this reduction in the coagulation rate is clear evidence for their hydrodynamic origin.³⁹

We have considered non-Brownian sedimenting particles at small Reynolds number ($Re \approx 0.14$) over a wide range of volume fractions ($0.01 \leq \phi \leq 0.5$). The good agreement between our simulations and other theoretical, experimental and simulation results further illustrates the validity of our method.⁴⁰ Upon increasing the Re , the inertial forces give rise to a drafting–kissing–tumbling (DKT) mechanism that results in a deficit of neighboring particles. This entails significant phenomenological changes and strongly affects the transport properties of the suspension. At small Reynolds number, $Re = 0.1$, the fluid exhibits a fore-aft symmetry around the particle, whereas at high Reynolds number, $Re > 1$, an asymmetric behaviour is clearly observed. The theoretical predictions



for the settling velocity in the Stokes regime are no longer applicable when these inertial effects are relevant. To extend the predictive capabilities of previously proposed relations, we proposed an empirical formula valid for $Re \leq 10$, which captures the rapid decay of the average sedimentation velocity at low volume fractions and the strong influence of the anisotropic local structure.⁴³

To study the rheological behaviour of colloidal dispersions we have extended the SP method to systems under steady or oscillatory shear flow, by using the Lees–Edwards boundary conditions.^{49,51} In this way, all the relevant physical quantities, such as the local and total shear stress, can be directly computed during the simulation. We simulated three systems under simple-shear to test the validity of our model: a spherical particle, a rigid-bead chain, and the collision of two spherical particles. We compared the viscosity predicted by the simulations to theoretical predictions and Stokesian dynamics calculations and found good overall agreement. We are also able to capture the shear-thinning behaviour of concentrated colloidal dispersions.⁵¹

Hydrodynamic interactions are propagated by both viscous diffusion and sound propagation. To study the time evolution of the hydrodynamic interactions, and the relative importance of these two mechanisms, we have extended the SP method to perform DNS of particles in compressible media. In an incompressible fluid, with an infinite speed of sound, hydrodynamic interactions propagate instantaneously, followed by a temporal evolution due to viscous diffusion. On the other hand, in a compressible fluid, sound propagates at a finite speed, which affects the time evolution of the hydrodynamic interactions. This effect can be quantified by measuring the ratio of the time scales associated with viscous diffusion and sound propagation,⁶² which defines a compressibility factor. We quantify hydrodynamic interactions for a two-particle system in a compressible fluid through the velocity correlation of the particles. We observe excellent agreement with theoretical predictions.

We have considered multi-phase fluids, consisting of particles dispersed in an A/B fluid mixture, in order to study the attachments/detachments of particles to/from the fluid–fluid interfaces.⁶⁶ We extended the SP method, within a Cahn–Hilliard framework, in order to simulate such multi-phase flows. The method was applied to perform DNS of a flexible fibre, represented as a chain of spherical beads, interacting with a fluidic interface. The fibre can undergo stretching, bending, and twisting deformations. The capillary force, acting at the three-phase contact line, is calculated using a ternary diffuse-interface model. First we validated the fibre deformation and ternary diffuse-interface model against theoretical solutions. We then performed 2D and 3D simulations for the elasto-capillary bending of the fibre by an immersed droplet. We were able to simulate both partial wrapping and complete encapsulation. We found that the fibre curvature increases linearly with the square of the elasto-capillary length, regardless of the degree of structural deformation.⁶⁹

We have simulated electrohydrodynamic phenomena in charged colloidal dispersions through a suitable extension of

the SP method. The time evolution of the colloidal particles, ions, and host fluid were simultaneously computed by solving the Newton–Euler, advection–diffusion, and Navier–Stokes equations, allowing us to fully capture the electrohydrodynamic coupling of the system.¹³ We have calculated the electrophoretic mobilities of charged spherical particles under several conditions. Comparisons with approximate theories showed quantitative agreement for dilute dispersions, without requiring any fitting parameters; however, our predictions exhibit considerable deviations for dense dispersions.³¹ Next, we considered the field-induced anisotropic interactions between like-charged colloidal particles, where the polarization of the electric double layer was explicitly computed under external AC electric fields.³⁴ These interactions were found to depend on the magnitude E_0 and frequency ω of the applied field, as well as the zeta potential, the Debye length, and the relative orientation of the particles. We also performed simulations for systems of six and twelve colloidal particles to study the stability of pearl-chain-like configurations.

We have simulated particle dispersions in viscoelastic media. The shear-thickening behaviour in dilute suspensions was investigated utilizing an Oldroyd-B model.⁶⁴ Here, the fluid elasticity is determined by the Weissenberg number Wi and the relative contribution of the polymer stress that is measured by the viscosity ratio $1 - \beta = \eta_p / (\eta_s + \eta_p)$, where η_p and η_s are the polymer and solvent viscosities, respectively. As $1 - \beta$ increases, while the suspension viscosity increases, the growth rate of the normalized polymer stress with Wi is suppressed. An analysis of the flow and the conformation dynamics around a particle reveals that, for large values of $1 - \beta$, the conformation stretching is suppressed because of the modulated flow by the polymer stress. This effect of β on the polymer stress is indicative of a complex coupling between the fluid elasticity and the flow. The experimental shear thickening in a Boger fluid matrix was quantitatively reproduced by multi-particle calculations using an Oldroyd-B fluid matrix up to $\varphi \leq 1$.⁶⁵

The hydrodynamic interactions of a suspension of self-propelled particles were studied using a modified version of the SP method that represents micro-swimmers as squirmers.⁵⁴ The diffusive behaviour that arises due to the swimming motion of the particles reveals that there are two basic mechanisms at play: the hydrodynamic interactions caused by the squirming motion of the particles and the particle–particle collisions. This dual nature gives rise to two distinct time and length scales, and thus to two distinct diffusion coefficients, which we obtained by a suitable analysis of the swimming motion within the co-rotating reference frame of the particles. These results have allowed us to gain a better understanding of the complex hydrodynamic interactions of self-propelled swimmers. In addition, simulations were performed to study the collective motion of model swimmers in confinement.⁵⁷ We showed that certain swimming mechanisms can lead to travelling wave-like collective motion, even without any direct alignment interactions between the particles. It was also shown that, by varying the swimming mechanism, this collective motion can be suppressed, contrary to the common perception



that hydrodynamic effects are completely screened at high volume fractions. From an analysis of bulk systems, it was shown that this travelling wave-like motion, which can be characterized as a pseudo-acoustic mode, is due mainly to the intrinsic swimming property of the particles.

Conflicts of interest

There are no conflicts to declare.

Appendix A: numerical implementation

We briefly describe the basic computational implementation for a single-component fluid, as found in the KAPSEL simulation package.¹⁹⁶

Fluid solver

As mentioned in the Simulation Method section, we use a fractional step approach. First, the modified Navier–Stokes equation without the ϕf_p term is evolved to determine \mathbf{u}^* . This allows us to solve for the advection and hydrodynamic viscous stress. However, for computational simplicity, we do not solve for the fluid velocity \mathbf{u} directly but for the vorticity $\boldsymbol{\omega} = \nabla \times \mathbf{u}$. Assuming a fixed Cartesian coordinate system, under periodic boundary conditions, the corresponding vorticity equation for an incompressible fluid ($\nabla \cdot \mathbf{u} = 0$) is given by

$$\begin{aligned} \partial_t \boldsymbol{\omega} &= -\nabla \times \nabla \cdot (\mathbf{u}\mathbf{u}) + \rho^{-1} \nabla \times \nabla \cdot \boldsymbol{\sigma} \\ \partial_t \hat{\boldsymbol{\omega}} &= \mathbf{k} \times [\mathbf{k} \cdot \mathcal{F}_k(\mathbf{u}\mathbf{u})] - \rho^{-1} \mathbf{k} \times [\mathbf{k} \cdot \hat{\boldsymbol{\sigma}}] \end{aligned} \quad (75)$$

where $\mathcal{F}_k(f) = \hat{f}(\mathbf{k})$ denotes a Fourier transform, with \mathbf{k} being the wave vector. The fluid velocity is obtained from the definition of the vorticity and the divergence-free condition as

$$\hat{\mathbf{u}} = i \frac{\mathbf{k} \times \hat{\boldsymbol{\omega}}}{|\mathbf{k}|^2} \quad (76)$$

The benefit of solving for the vorticity comes from the fact that we do not need to consider the Poisson equation for the pressure whose only role is to ensure that the final velocity field is incompressible. This can be enforced directly in Fourier space by projecting out the components of $\hat{\mathbf{u}}$ parallel to \mathbf{k} such that

$$\hat{\mathbf{u}} \rightarrow \left[\mathbf{I} - \frac{\mathbf{k}\mathbf{k}}{|\mathbf{k}|^2} \right] \cdot \hat{\mathbf{u}} \quad (77)$$

Furthermore, to reduce the memory requirements of the code, we can take advantage of the fact that the three components of the curl are not linearly independent and solve for only two of them (for every given wave vector). Let $\hat{\mathbf{u}} = \mathcal{F}_k(\nabla \times \mathbf{A}) = i\mathbf{k} \times \hat{\mathbf{A}}$ be the Fourier transform of the curl of some arbitrary

vector field \mathbf{A} . We define the following invertible mapping ($\dagger: C^3 \rightarrow C^2$) such that

$$(\hat{\mathbf{a}})^\dagger = (\hat{a}_1, \hat{a}_2, \hat{a}_3)^\dagger: \begin{cases} (\hat{a}_2, \hat{a}_3) & k_1 \neq 0 \\ & \hat{a}_1 = -(k_3 \hat{a}_3 + k_2 \hat{a}_2)/k_1 \\ (\hat{a}_3, \hat{a}_1) & k_1 = 0, k_2 \neq 0 \\ & \hat{a}_2 = -k_3 \hat{a}_3/k_2 \\ (\hat{a}_1, \hat{a}_2) & k_1 = k_2 = 0, k_3 \neq 0 \\ & \hat{a}_3 = 0 \end{cases} \quad (78)$$

for all $\mathbf{k} \neq 0$. The value of $\hat{\mathbf{a}}(\mathbf{k} = 0)$, which corresponds to the volume integral of the total velocity field, cannot be obtained from $\hat{\mathbf{a}}^\dagger$ and should therefore be propagated independently. We apply the mapping to both sides of eqn (75) to yield an equation for $\hat{\boldsymbol{\zeta}} = \hat{\boldsymbol{\omega}}^\dagger$ and a subsequent one-third reduction in the computational requirements needed to update the fluid velocity.

The form of the integrator depends on the particular stress tensor s that is used. For the case of a Newtonian fluid, for which $\nabla \cdot \mathbf{s} = \eta \nabla^2 \mathbf{u}$, the vorticity equation becomes

$$\partial_t \hat{\boldsymbol{\omega}} = -\nu k^2 \hat{\boldsymbol{\omega}} + \mathbf{k} \times [\mathbf{k} \cdot \mathcal{F}_k(\mathbf{u}\mathbf{u})] \quad (79)$$

which is of the form

$$\partial_t a = \mathcal{L}a - \mathcal{N}(t, a(t)) \quad (80)$$

with \mathcal{L} being a time-independent linear operator and \mathcal{N} being a non-linear operator. This equation has a general solution given by

$$a(t_n + h) = e^{\mathcal{L}h} a(t_n) - e^{\mathcal{L}h} \int_0^h d\tau e^{-\mathcal{L}\tau} \mathcal{N}(t_n + \tau, a(t_n + \tau)) \quad (81)$$

in which the linear part is solved exactly. The integral over the non-linear term can be approximated in many ways, giving rise to the family of exponential time difference (ETD) methods.^{197,198} In particular, a first-order approximation $N(t_n + \tau, a(t_n + \tau)) = N(t_n, a(t_n))$ results in

$$a(t_n + h) = e^{h\mathcal{L}} [a(t_n) - \mathcal{L}^{-1}(1 - e^{-h\mathcal{L}}) \mathcal{N}(t_n, a(t_n))] \quad (82)$$

$$= a(t_n) + (e^{-h\mathcal{L}} - 1) a(t_n) + \mathcal{L}^{-1} \mathcal{N}(t_n, a(t_n)) \quad (83)$$

which reduces to the Euler method in the limit when $|\mathcal{L}| \rightarrow 0$.

Particle solver

The particle configurations (position, orientation, velocity, and angular velocity) are updated using a two-step Adams–Bashforth method (and Euler method for the initial step). Let \mathbf{Y}_I denote the dynamical variable of interest, with $\mathbf{Y}_I^n = \mathbf{Y}_I(t_n)$

$$\mathbf{Y}^{n+1} = \mathbf{Y}^n + \frac{h}{2} (3\dot{\mathbf{Y}}^n - \dot{\mathbf{Y}}^{n-1}) \quad (84)$$



The Euler equations are solved for in the body (principal-axis) reference frame, in which the moment of inertia \tilde{I} is diagonal, with⁷⁴

$$\begin{pmatrix} \dot{\omega}^1 \\ \dot{\omega}^2 \\ \dot{\omega}^3 \end{pmatrix} = \begin{pmatrix} \tilde{\tau}^1 + \tilde{\omega}^2 \tilde{\omega}^3 (\tilde{I}^{22} - \tilde{I}^{33}) \\ \tilde{\tau}^2 + \tilde{\omega}^3 \tilde{\omega}^1 (\tilde{I}^{33} - \tilde{I}^{11}) \\ \tilde{\tau}^3 + \tilde{\omega}^1 \tilde{\omega}^2 (\tilde{I}^{11} - \tilde{I}^{22}) \end{pmatrix} \quad (85)$$

Furthermore, for improved numerical accuracy, the orientations are updated using rotation quaternions q (normalized at the end of every step) instead of rotational matrices R . The dynamical equations for the orientation are then given by¹⁹⁹

$$\dot{q} = \frac{1}{2} \omega_I \circ q = \frac{1}{2} q \circ \tilde{\omega} \quad (86)$$

where \circ denotes quaternion multiplication and $\tilde{\omega} = (0, \omega)$ and $\omega = (0, \omega)$ are the quaternion equivalents of the angular velocity in the lab ω and body reference frames $\tilde{\omega} = (R', \omega)$, respectively.

B Validation

The validity of our method to describe the hydrodynamic interactions of non-spherical particle dispersions in complex host solvents is established by comparing our results with exact analytical expressions (when available) as well as with the results obtained using alternative high-precision simulations. To verify that we are able to accurately account for the fluid-particle interactions, we compute the mobility/friction factors for a wide variety of geometrical shapes and compare them with exact solutions to the Stokes equation (SE). As is well known, in the over-damped stationary limit, the force/torque exerted by the fluid on the particles is linear in the velocities. For a system with N particles, this is expressed as²⁰⁰

$$F = Z \cdot U \quad (87)$$

where $F = (F_1, \dots, F_N, N_1, \dots, N_N)$ and $U = (V_1, \dots, V_n, W_1, \dots, W_N)$ are the $6 - N$ -dimensional force and velocity vectors, respectively, and $Z = M^{-1}$ is the friction matrix (M is the mobility matrix). The friction/mobility matrices couple the translational (T) and rotational (R) motions of all the particles; in block form, they can be expressed as

$$Z = \begin{pmatrix} Z^{TT} & Z^{TR} \\ (Z^{TR})^t & Z^{RR} \end{pmatrix} \quad (88)$$

For the special case of a single spherical particle (radius a) in an unbounded fluid, under stick-boundary conditions, the friction matrix can be obtained from an exact solution to the SE as

$$Z^{\text{single}} = \begin{pmatrix} \zeta^T & 0 \\ 0 & \zeta^R \end{pmatrix} \quad (89)$$

where $\zeta^T = 6\pi\eta a$ and $\zeta^R = 8\pi\eta a^3$ are the translational and rotational friction coefficients, respectively.

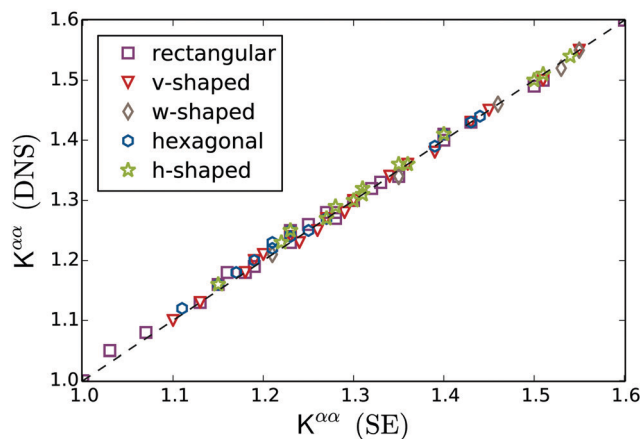
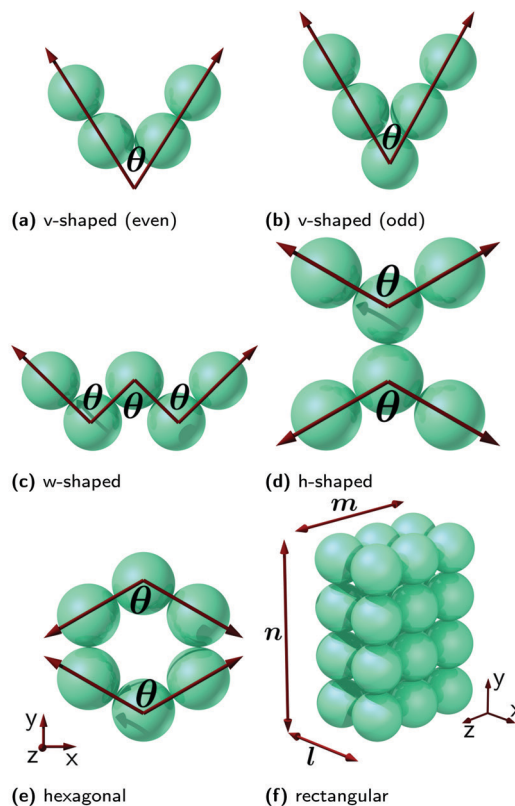


Fig. 22 (a–f) Non-spherical regular-shaped agglomerates used in the simulations. (g) Correlation between the friction coefficients obtained from the SP method (DNS) simulations and the exact solutions to the SE (as given by HYDROLIB). Adapted from *J. Chem. Phys.*, **139**, 234105,⁵² Copyright 2013, with the permission of AIP publishing.

Simulations at $Re \simeq 0$ for a single non-spherical particle, constructed as a rigid assembly of non-overlapping beads of equal radius a , are performed with a fixed particle velocity $U = (V^x, V^y, V^z, 0, 0, 0)$. The hydrodynamic forces at steady-state F are measured to compute the friction coefficients. We consider six families of axisymmetric regularly shaped particle agglomerates: (even/odd) v-shaped, h-shaped, hexagonal, and rectangular arrays (see Fig. 22(1–f)). Except for the v- and w-shaped particles, for which there is a weak coupling between translation and rotation, the friction matrices are all diagonal. In all cases, however, the translational friction matrix K^{TT} is diagonal.



We vary the number of beads and relative bead configuration while keeping the same geometrical shape for a total of 84 different geometric configurations. For simplicity, we report the kinetic form factors K , defined in terms of the friction coefficients by

$$Z = \begin{pmatrix} K^{TT} \zeta_c^T & K^{TR} \zeta_c^R / \zeta_c^T \\ (K^{TR})^T \zeta_c^R / \zeta_c^T & K^{RR} \zeta_c^R \end{pmatrix} \quad (90)$$

with $\zeta_c^{T,R}$ being the friction coefficients for a single spherical particle of equal volume (with effective radius a_e), translating (rotating) with the same velocity (angular velocity) and subject to the same boundary conditions. We compare our results with those of the HYDROLIB package, which uses an induced force method truncated to third order.²⁰¹ When compared with experimental results, the HYDROLIB results show errors less than 1%²⁰² and can be considered to correspond to the exact solution of the SE for the current purposes. Fig. 22(g) shows our results for the friction coefficient with respect to the exact solution to the SE. We obtain excellent agreement, with an error $\lesssim 2\%$. A similar level of agreement is obtained for chiral structures, as well as close-packed (HCP and FCC) arrays of spherical particles (with up to 167 constituent beads), allowing us to resolve the difference in the friction factors for particles that differ in volume by only a few percent.⁵²

We now consider the lubrication interactions between nearby particles moving relative to each other. These are one of the most important and difficult to capture hydrodynamic effects. We computed the squeeze lubrication interaction between two approaching spheres in a finite system. The velocity and pressure distributions are shown in Fig. 23(a). Fig. 23(b) shows the normalized approach velocity for a pair of particles of equal radius (a), versus the normalized gap distance (h/a) between them, obtained using the SP method (black circles) as well as three different theoretical predictions. Our simulation data accurately reproduce the expected crossover from the near-field ($h/a < 1$)²⁰⁴ to the far-field ($h/a > 1$)^{2,203} behaviour around $h/a \sim 0.7$. It is found that SD⁵ tends to underestimate the mobility in the crossover regime. The validity of the SP method has been further confirmed using other critical tests, such as the friction coefficient of chiral objects⁵² where the coupling between translational and rotational motions becomes important, the volume fraction¹³ and Reynolds number⁴³ dependence of the drag coefficient, the motion and stresslet of a sphere under shear flow,⁵¹ the electrokinetics in charged colloidal systems,^{13,31} and the pair interaction between two squirmers,⁵⁴ among others.

C Software availability

We have developed the DNS software KAPSEL that implements the SP method. KAPSEL is designed to simulate the dynamics of solid particles dispersed in simple and complex fluids in various situations, and we performed all the simulations presented in this paper using KAPSEL. The source code of KAPSEL is fully open to the public on KAPSEL-HP¹⁹⁶ and can be freely

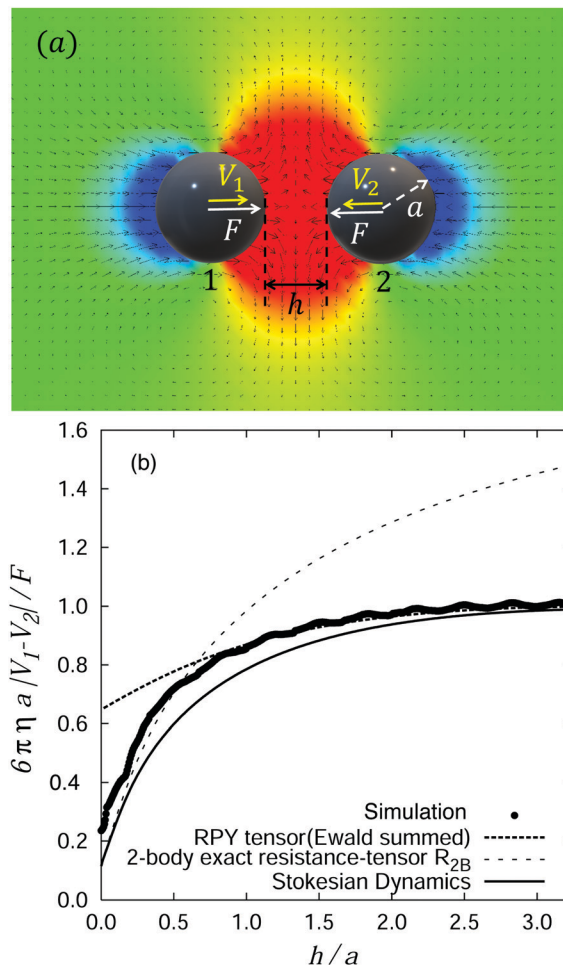


Fig. 23 (a) Snapshot of two approaching colloidal particles of radius $a = 4$, under a constant attractive force F . The black arrows indicate the velocity field and density map represents the pressure field (a change in color from red to blue corresponds to a change from high to low pressure). (b) The normalised relative velocity of approaching spheres versus the normalised gap distance between them (h/a). A small oscillating behaviour seen in the present simulation data (black circles) is due to the numerical artifacts of using a finite grid size (Δ). The solid curves correspond to three different theoretical predictions: far-field asymptotics computed using the Ewald summed Rotne–Prager–Yamakawa tensor (dotted line),^{2,203} near-field exact solution (dashed line),²⁰⁴ and the Stokesian Dynamics predictions (solid line).⁵ Reproduced from *Eur. Phys. J. E Soft Matter*, **26**, 361–368,¹³ Copyright 2008, with kind permission of The European Physical Journal (EPJ).

downloaded and used by anyone who agrees to the license. KAPSEL works with the GUI library Gourmet, which is included in the integrated simulator package OCTA²⁰⁵ for soft materials, to provide input/output of simulation parameters and visualize the data. For details on how to obtain and install KAPSEL and OCTA, see KAPSEL-HP.¹⁹⁶

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